



®

宇 | 星 | 模 | 王

宇 星 车 模

MODELS  NO. 4 **LIKEN** 莱肯

13190

4070+Pcs/Pza





QR Code APP (APP二维码)
QR-Code-App
Application Code QR
App Codice QR
Aplicación de Código QR
QRコードアプリ

Need the apple version 9.0 and above, the android version 5.0 and above.

Erfordert iOS Version 9.0 oder höher, Android Version 5.0 oder höher.

Nécessite la version 9.0 ou supérieure pour Apple, et la version 5.0 ou supérieure pour Android.

Richiede la versione 9.0 o superiore per Apple, e la versione 5.0 o superiore per Android.

Requiere versión 9.0 o superior para Apple, y versión 5.0 o superior para Android.

Appleはバージョン9.0以上、Androidはバージョン5.0以上が必要です。

*This APP supports most of the mainstream Android models on the market, but due to the large number of Android models, different models of systems and hardware reasons, there may be some models do not supported, specific according to the actual test!

*Diese App unterstützt die meisten gängigen Android-Modelle auf dem Markt. Aufgrund der großen Anzahl von Android-Modellen und unterschiedlicher System- und Hardwarebedingungen kann es jedoch sein, dass einige Modelle nicht unterstützt werden. Die Kompatibilität hängt vom tatsächlichen Test ab!

*Cette application prend en charge la plupart des modèles Android populaires sur le marché, mais en raison du grand nombre de modèles Android, de différents systèmes de modèles et de raisons matérielles, certains modèles peuvent ne pas être pris en charge, selon le test réel !

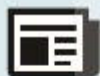
*Questa app supporta la maggior parte dei modelli Android mainstream sul mercato, ma a causa del grande numero di modelli Android, diversi modelli di sistemi e motivi hardware, potrebbero esserci alcuni modelli che non sono supportati, specifici secondo il test effettivo!

*Esta aplicación es compatible con la mayoría de los modelos Android principales en el mercado, pero debido al gran número de modelos de Android, diferentes modelos de sistemas y razones de hardware, puede haber algunos modelos que no son compatibles, específicos según la prueba real!

*このアプリは市場に出ている主流のAndroidモデルのほとんどをサポートしていますが、Androidモデルの数が非常に多く、システムやハードウェアの違いにより、サポートされないモデルが存在する可能性があります。実際のテストによります！



广东宇星科技
Mould King



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Produktinformation
Information sur le produit
Informazioni sul prodotto
Información del producto
製品情報



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After-sales Service
Kundendienst nach dem Kauf
Service après-vente
Servizio post-vendita
Servicio postventa
アフターサービス



积木补件
Brick Replacement Service
Ziegelstein-Ersatzdienst
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Customer Service

客户服务



www.mk-brick.com



"酷砖家"是宇星模王设立的特殊标识，代表着产品的独特性和原创性。每一款带有"酷砖家"标志的积木套装，都由宇星的原创团队或者与宇星有密切合作的全球顶尖设计师亲自设计或授权。这个标识是我们对消费者的承诺，确保他们可以享受到独一无二且高品质的积木拼搭体验。

"Bri X pert" is a special mark established by MOULD KING, representing the uniqueness and originality of the product. Every building set with the "Bri X pert" logo is personally designed or authorized by MOULD KING's innovative team or world-class designers who work closely with MOULD KING. This logo is our commitment to consumers, ensuring that they can enjoy a unique and high-quality building experience.

"Bri X pert" ist ein spezielles Kennzeichen von MOULD KING, das die Einzigartigkeit und Originalität des Produkts repräsentiert. Jedes Bauset mit dem "Bri X pert"-Logo wird persönlich von MOULD KINGs innovativem Team oder von weltklasse Designern, die eng mit MOULD KING zusammenarbeiten, entworfen oder autorisiert. Dieses Logo ist unser Versprechen an die Verbraucher, sicherzustellen, dass sie ein einzigartiges und hochwertiges Bauerlebnis genießen können.

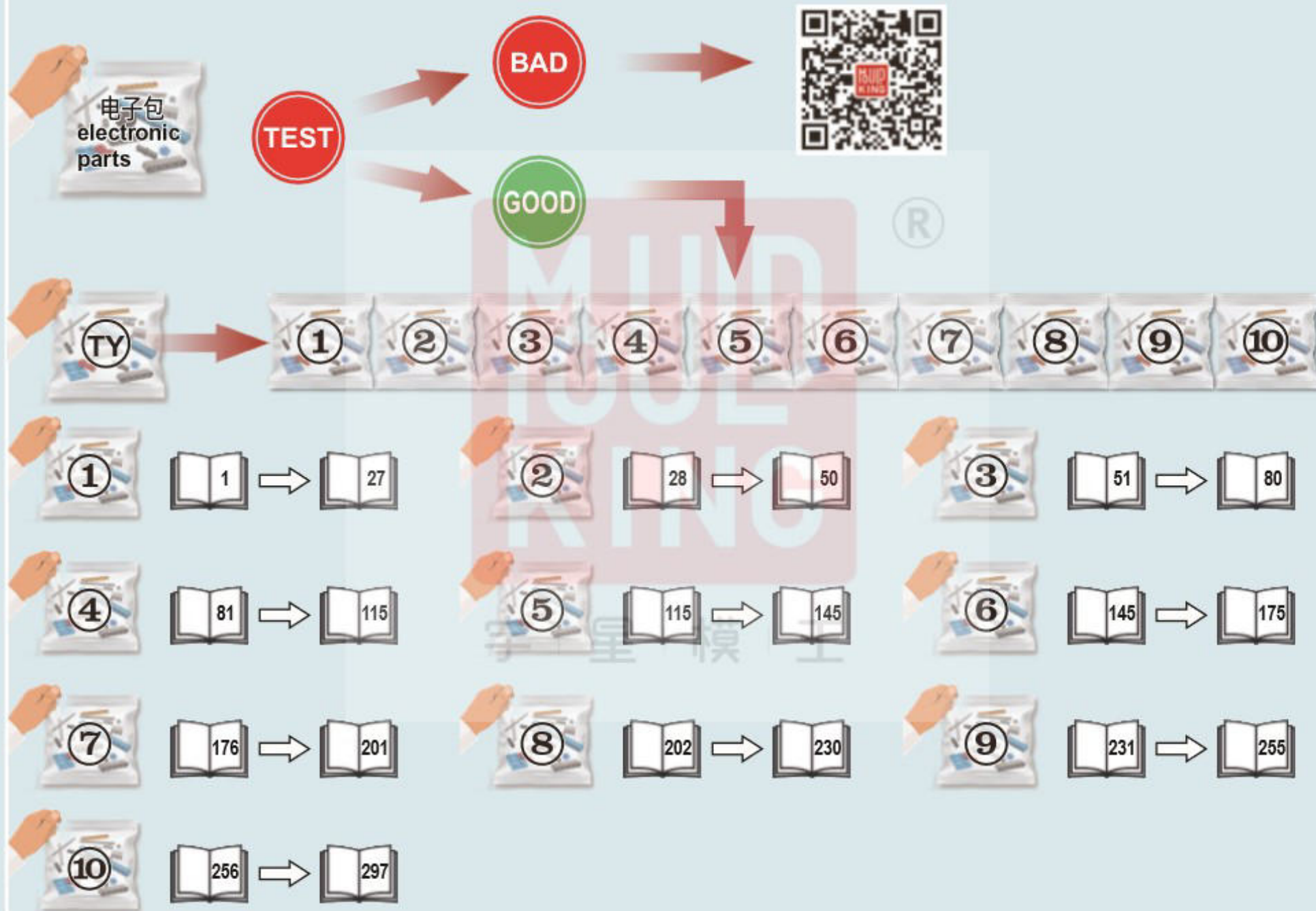
"Bri X pert" est une marque spéciale établie par MOULD KING, représentant l'unicité et l'originalité du produit. Chaque ensemble de construction portant le logo "Bri X pert" est conçu ou autorisé personnellement par l'équipe innovante de MOULD KING ou par des designers de classe mondiale travaillant étroitement avec MOULD KING. Ce logo est notre engagement envers les consommateurs, garantissant qu'ils peuvent profiter d'une expérience de construction unique et de haute qualité.

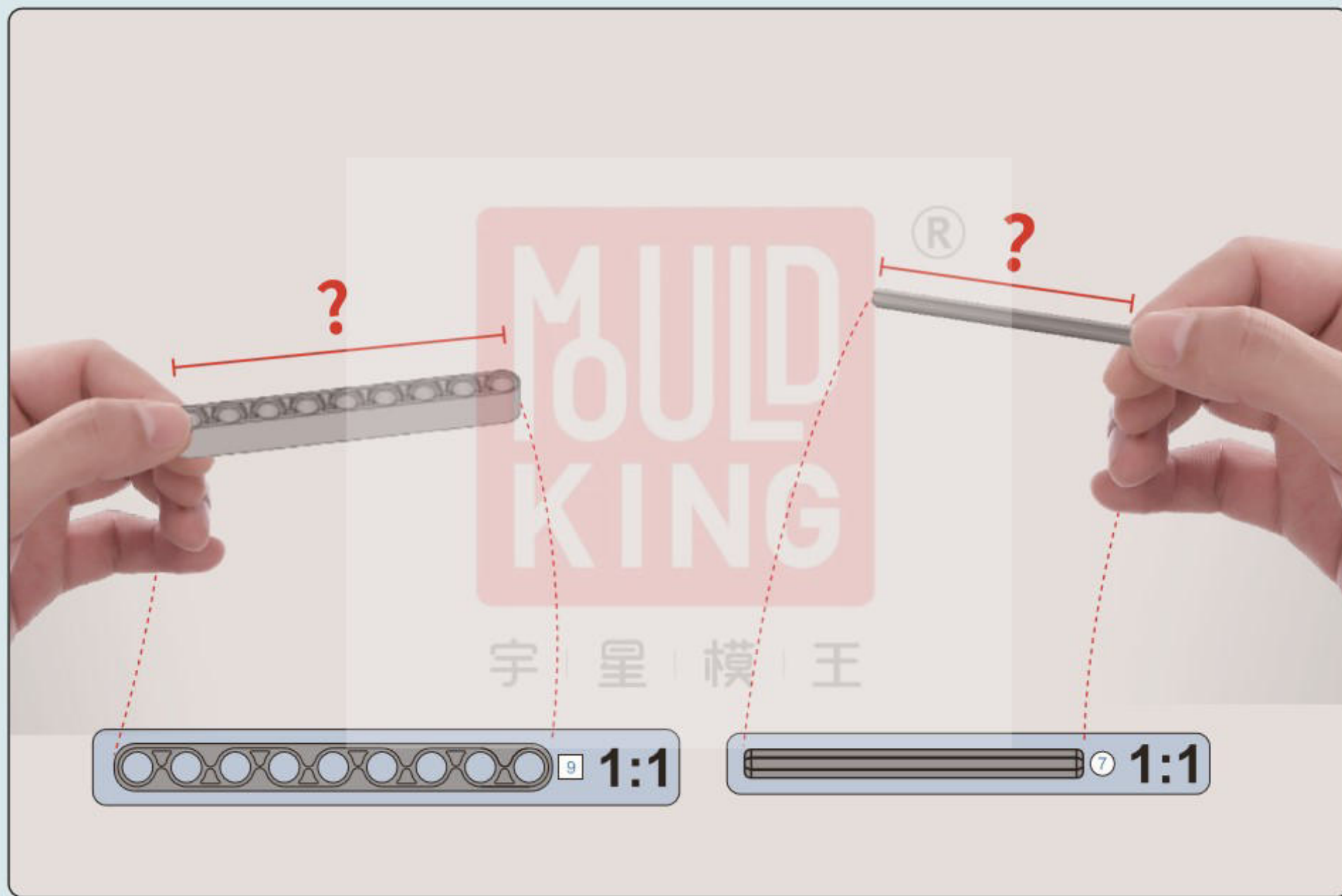
"Bri X pert" è un marchio speciale stabilito da MOULD KING, che rappresenta l'unicità e l'originalità del prodotto. Ogni set di costruzione con il logo "Bri X pert" è progettato o autorizzato personalmente dal team innovativo di MOULD KING o da designer di fama mondiale che lavorano a stretto contatto con MOULD KING. Questo logo è il nostro impegno nei confronti dei consumatori, assicurando che possano godere di un'esperienza di costruzione unica e di alta qualità.

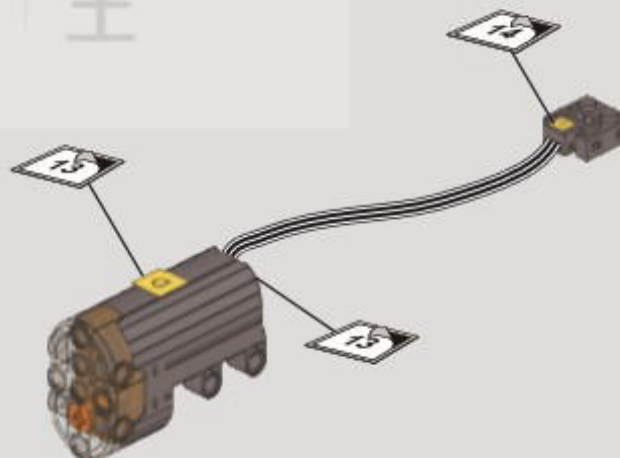
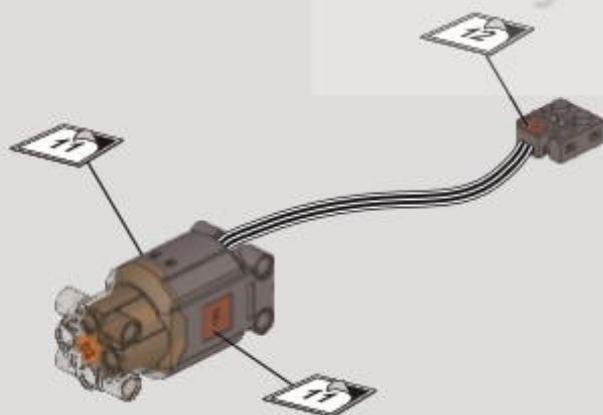
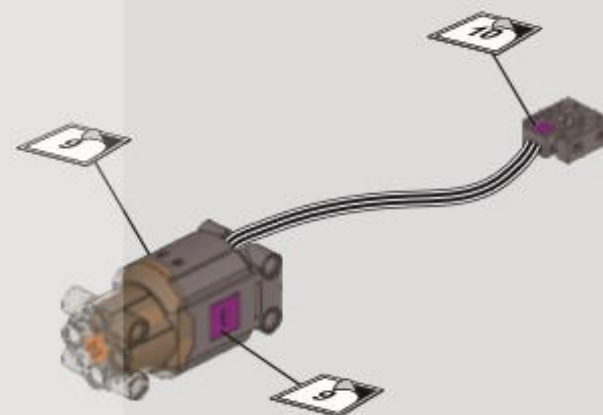
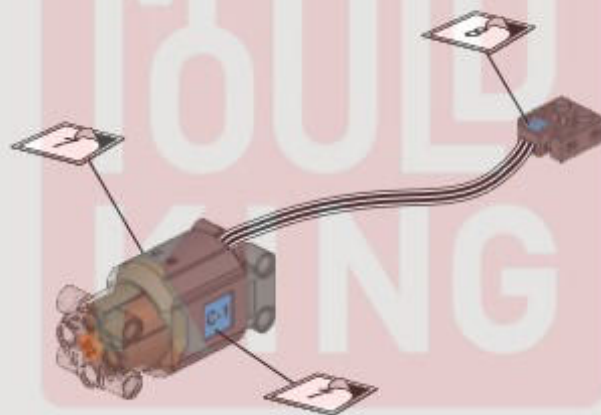
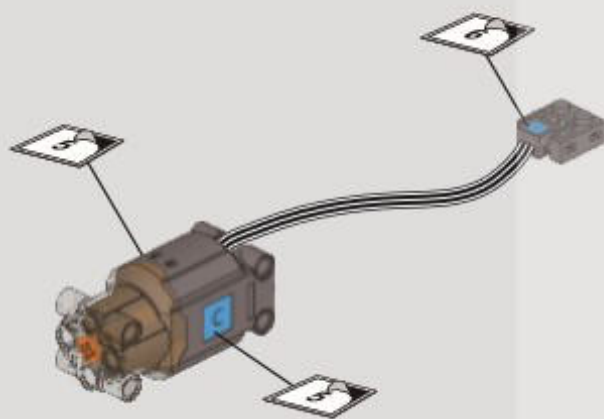
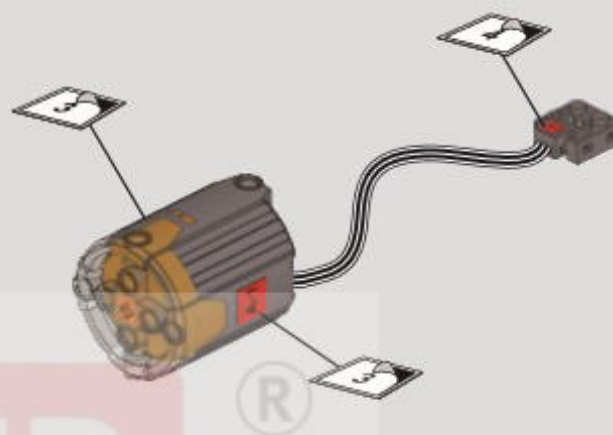
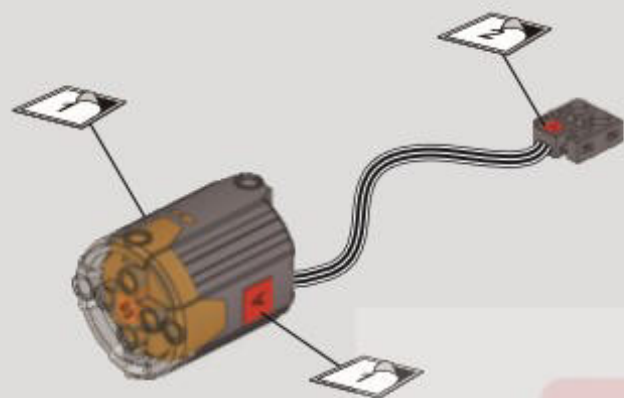
"Bri X pert" es una marca especial establecida por MOULD KING, representando la unicidad y originalidad del producto. Cada conjunto de construcción con el logo de "Bri X pert" es diseñado o autorizado personalmente por el equipo innovador de MOULD KING o diseñadores de clase mundial que trabajan en estrecha colaboración con MOULD KING. Este logo es nuestro compromiso con los consumidores, asegurando que puedan disfrutar de una experiencia de construcción única y de alta calidad.

「Bri X pert」はMOULD KINGによって設立された特別なマークであり、製品のユニークさとオリジナリティを代表しています。「Bri X pert」ロゴの付いた各建築セットは、MOULD KINGのイノベティブチームまたはMOULD KINGと密接に協力する世界クラスのデザイナーによって個人的に設計されたり、認可されています。このロゴは、消費者に対する私たちの

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Otestuj všechny elektronické součástky před sestavením.
Test all electronic components for functionality before assembly.
Testen Sie alle elektronischen Komponenten auf Funktionalität vor der Montage.
Testez toutes les composantes électroniques pour leur fonctionnalité avant l'assemblage.
Testare tutti i componenti elettronici per la funzionalità prima dell'assemblaggio.
Prueba todos los componentes electrónicos para verificar su funcionalidad antes del ensamblaje.
組み立て前にすべての電子部品の機能をテストしてください。



Prosím, naskenuj tento QR kod pro získání a prostudování ovládacího manuálu k 6.0 modulu.

Please scan this QR code to obtain and carefully review the operation manual for the 6.0 module.

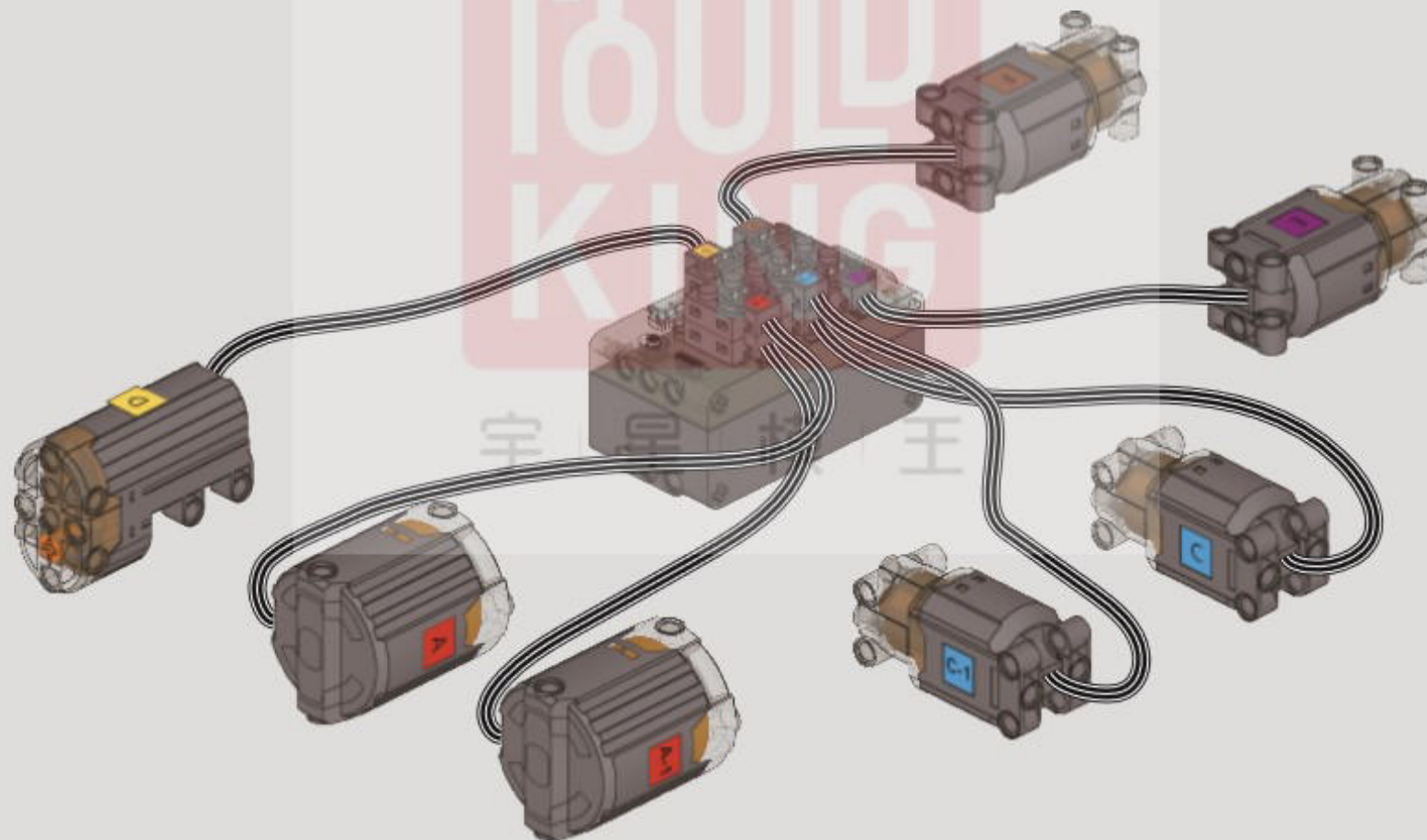
Bitte scannen Sie diesen QR-Code, um die Bedienungsanleitung für das Modul 6.0 zu erhalten und sorgfältig zu überprüfen.

Veuillez scanner ce code QR pour obtenir et examiner attentivement le manuel d'utilisation du module 6.0.

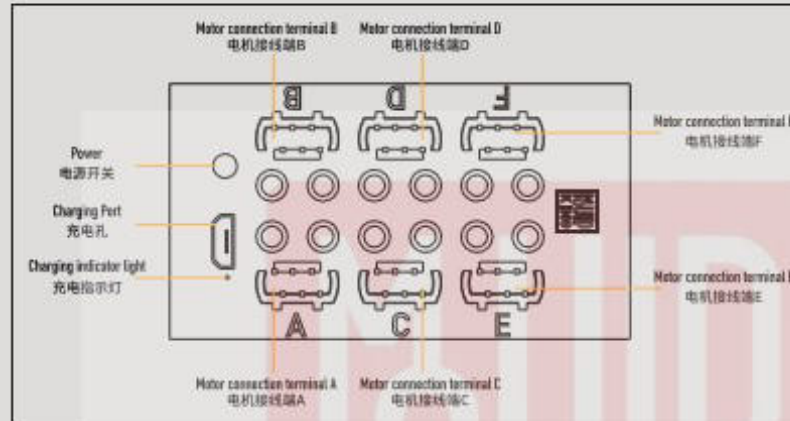
Si prega di scansionare questo codice QR per ottenere e esaminare attentamente il manuale operativo del modulo 6.0.

Por favor, escanee este código QR para obtener y revisar cuidadosamente el manual de operación del módulo 6.0.

このQRコードをスキャンして、6.0モジュールの操作マニュアルを入手し、注意深く確認してください。



Main control module | 6.0模块



- ① Svorka motoru: lze připojit k různým motorům, přijímačům, reverzním spínačům, světlům, atomizérům, zvukovým modulům atd.
- ② Kontrolka napájení: Režim baterie se určuje barvou a blikáním kontrolky
- ③ Vypínač: Zapnutí nebo vypnutí lithiové baterie, přepínání modulů
- ④ Nabíjecí port: připojte nabíjecí kabel přes rozhraní micro-USB (výstupní napětí USB by nemělo překročit 1A
- ⑤ Indikátor nabíjení: " červené světlo při nabíjení bliká a při plném nabití svítí nepřetržitě, doba nabíjení je od 2,5 do 3hod.

- ① **Motor Connection Terminals: Can connect to various motors, receivers, reversing switches, lights, atomizers, sound modules, etc.**
- ② **Power Indicator: Distinguish battery modes by the color and flashing status of the indicator light.**
- ③ **Power Switch: Turn on or off the lithium battery; switch modules.**
- ④ **Charging Port: Connect the charging cable via a micro-b USB interface (the output voltage of the USB transformer should not exceed 5V, and the current should not exceed 1A).**
- ⑤ **Charging Indicator: The red light flashes when charging and remains solid when fully charged; charging time is 2.5 to 3 hours.**

- ① **Motoranschlusssterminals: Anschlussmöglichkeiten für verschiedene Motoren, Empfänger, Wendeschalter, Lampen, Vernebler, Soundmodule usw.**
- ② **Leistungsanzeige: Unterscheidung der Batteriemodi anhand der Farbe und des Blinkzustands der Anzeigeleuchte.**
- ③ **Stromschalter: Lithiumbatterie ein- oder ausschalten; Module wechseln.**
- ④ **Ladeanschluss: Verbinden des Ladekabels über einen Micro-B-USB-Anschluss (die Ausgangsspannung des USB-Transformators darf 5V nicht überschreiten, der Strom darf 1A nicht überschreiten).**
- ⑤ **Ladeanzeige: Die rote Leuchte blinkt beim Laden und leuchtet durchgehend bei voller Ladung; Ladezeit beträgt 2,5 bis 3 Stunden.**

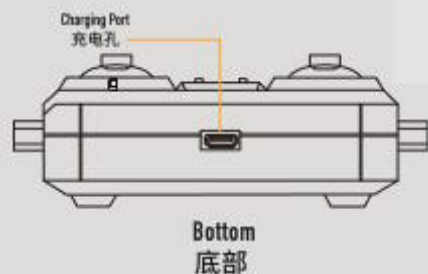
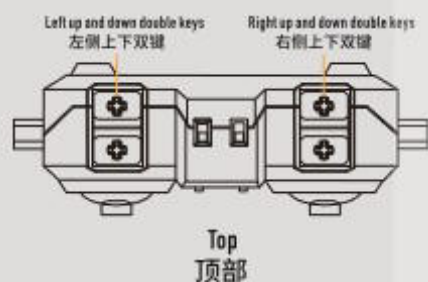
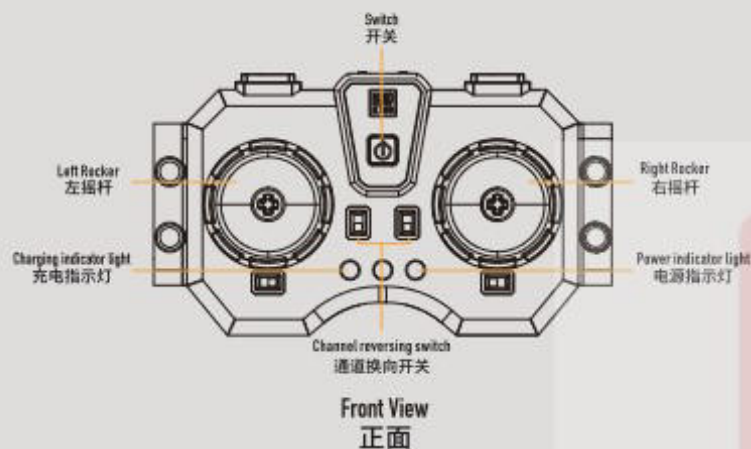
- ① Bornes de connexion moteur : Peut se connecter à divers moteurs, récepteurs, commutateurs de renversement, lumières, atomiseurs, modules sonores, etc.
- ② Indicateur de puissance : Distinguer les modes de batterie par la couleur et l'état de clignotement de l'indicateur lumineux.
- ③ Interrupteur d'alimentation : Activer ou désactiver la batterie au lithium ; changer les modules.
- ④ Port de charge : Connectez le câble de charge via une interface micro-b USB (la tension de sortie du transformateur USB ne doit pas dépasser 5V, et le courant ne doit pas dépasser 1A).
- ⑤ Indicateur de charge : La lumière rouge clignote lors de la charge et reste allumée lorsque la charge est complète ; temps de charge de 2,5 à 3 heures.

- ① Terminali di collegamento motore: Può connettersi a vari motori, ricevitori, interruttori di inversione, luci, atomizzatori, moduli sonori, ecc.
- ② Indicatore di alimentazione: Distingui le modalità della batteria attraverso il colore e lo stato lampeggiante dell'indicatore luminoso.
- ③ Interruttore di alimentazione: Accendi o spegni la batteria al litio; cambia moduli.
- ④ Porta di ricarica: Collegare il cavo di ricarica tramite un'interfaccia micro-b USB (la tensione di uscita del trasformatore USB non deve superare i 5V e la corrente non deve superare 1A).
- ⑤ Indicatore di carica: La luce rossa lampeggia durante la carica e rimane accesa quando è completamente carica; tempo di carica da 2,5 a 3 ore.

- ① Terminales de conexión del motor: Puede conectar varios motores, receptores, interruptores de inversión, luces, atomizadores, módulos de sonido, etc.
- ② Indicador de energía: Distinguir los modos de batería por el color y el estado de parpadeo del indicador.
- ③ Interruptor de energía: Encender o apagar la batería de litio; cambiar módulos.
- ④ Puerto de carga: Conectar el cable de carga a través de una interfaz micro-b USB (el voltaje de salida del transformador USB no debe exceder 5V, y la corriente no debe exceder 1A).
- ⑤ Indicador de carga: La luz roja parpadea al cargar y permanece encendida cuando está completamente cargada; tiempo de carga de 2,5 a 3 horas.

- ① モーター接続端子: 様々なモーター、受信機、逆転スイッチ、ライト、霧化器、サウンドモジュールなどに接続可能。
- ② 電源インジケータ: インジケータライトの色と点滅状態でバッテリーモードを区別。
- ③ 電源スイッチ: リチウムバッテリーをオンまたはオフにする; モジュールを切り替える。
- ④ 充電ポート: micro-b USBインターフェースを介して充電ケーブルを接続 (USB変圧器の出力電圧は5Vを超えてはならず、電流は1Aを超えてはならない)。
- ⑤ 充電インジケータ: 充電中は赤いライトが点滅し、完全に充電されると赤いライトが点灯する; 充電時間は2.5〜3時間。

Remote Control | 遥控器



- ① Vypínač
- ② Kontrolka napájení: rozpozná, zda je lithiová baterie úspěšně připojena, podle stavu modré kontrolky
- ③ Kontrolka nabíjení: červené světlo svítí během nabíjení a zhasne po plném nabití, doba nabíjení je 1-5-2 hod.
- ④ Levý joystick: pohyb, otáčení motoru kanálu A vpřed a vzad. Pohyb levého joysticku: otáčení motoru kanálu B vpřed a vzad.
- ⑤ Pohyb pravého joysticku: otáčení motoru kanálu C vpřed a vzad. Pohyb pravého joysticku: otáčení motoru kanálu D vpřed a vzad.
- ⑥ Přepínač obrácení kanálu- mění směr otáčení motoru kanálu.
- ⑦ Levé dvojité tlačítko nahoru/dolů: otáčení motoru kanálu E vpřed a vzad.
- ⑧ Pravé dvojité tlačítko nahoru/dolů: otáčení motoru kanálu F vpřed a vzad.
- ⑨ Nabíjecí port: Připojte nabíjecí kabel přes rozhraní micro - USB (výstupní napětí USB transformátoru by nemělo překročit 5V a proud by neměl překročit 1A)

- ① Switch: Turn the remote control on or off.
- ② Power Indicator: Distinguish if the lithium battery is successfully connected through the state of the blue indicator light.
- ③ Charging Indicator: The red light stays on while charging, and turns off when fully charged; charging time is 1.5 to 2 hours.
- ④ Left Joystick ↑ Movement: Forward and reverse rotation of the A channel motor.
Left Joystick ↶ Movement: Forward and reverse rotation of the B channel motor.
- ⑤ Right Joystick ↑ Movement: Forward and reverse rotation of the C channel motor.
Right Joystick ↷ Movement: Forward and reverse rotation of the D channel motor.
- ⑥ Channel Reversing Switch: Changes the rotation direction of the channel motor.
- ⑦ Left Side Up/Down Dual Button: Forward and reverse rotation of the E channel motor.
- ⑧ Right Side Up/Down Dual Button: Forward and reverse rotation of the F channel motor.
- ⑨ Charging Port: Connect the charging cable via a micro-b USB interface (the output voltage of the USB transformer should not exceed 5V, and the current should not exceed 1A).

- ① Schalter: Fernbedienung ein- oder ausschalten.
- ② Stromindikator: Verbindung der Lithiumbatterie anhand des Zustands der blauen Anzeigeleuchte erkennen.
- ③ Ladeanzeige: Rotes Licht bleibt beim Laden an, erlischt bei vollständiger Ladung; Ladezeit beträgt 1,5 bis 2 Stunden.
- ④ Linker Joystick ↑ Bewegung: Vorwärts- und Rückwärtsdrehung des A-Kanal-Motors.
Linker Joystick ↶ Bewegung: Vorwärts- und Rückwärtsdrehung des B-Kanal-Motors.
- ⑤ Rechter Joystick ↑ Bewegung: Vorwärts- und Rückwärtsdrehung des C-Kanal-Motors.
Rechter Joystick ↷ Bewegung: Vorwärts- und Rückwärtsdrehung des D-Kanal-Motors.
- ⑥ Kanalumkehrschalter: Ändert die Drehrichtung des Kanalmotors.
- ⑦ Linke Seite Auf/Ab Doppeltaste: Vorwärts- und Rückwärtsdrehung des E-Kanal-Motors.
- ⑧ Rechte Seite Auf/Ab Doppeltaste: Vorwärts- und Rückwärtsdrehung des F-Kanal-Motors.
- ⑨ Ladeanschluss: Verbinden des Ladekabels über einen Micro-B-USB-Anschluss (die Ausgangsspannung des USB-Transformators darf 5V nicht überschreiten und der Strom darf 1A nicht überschreiten).

- ① Interrupteur : Allumer ou éteindre la télécommande.
- ② Indicateur de puissance : Déterminer si la batterie au lithium est connectée avec succès grâce à l'état de l'indicateur lumineux bleu.
- ③ Indicateur de charge : La lumière rouge reste allumée pendant la charge et s'éteint lorsque la charge est complète ; temps de charge de 1,5 à 2 heures.
- ④ Joystick gauche ↑ Mouvement : Rotation avant et arrière du moteur du canal A.
Joystick gauche ↔ Mouvement : Rotation avant et arrière du moteur du canal B.
- ⑤ Joystick droit ↑ Mouvement : Rotation avant et arrière du moteur du canal C.
Joystick droit ↔ Mouvement : Rotation avant et arrière du moteur du canal D.
- ⑥ Interrupteur de renversement de canal : Change la direction de rotation du moteur du canal.
- ⑦ Double bouton haut/bas côté gauche : Rotation avant et arrière du moteur du canal E.
- ⑧ Double bouton haut/bas côté droit : Rotation avant et arrière du moteur du canal F.
- ⑨ Port de charge : Connecter le câble de charge via une interface micro-b USB (la tension de sortie du transformateur USB ne doit pas dépasser 5V et le courant ne doit pas dépasser 1A).

- ① Interruttore: Accendere o spegnere il telecomando.
- ② Indicatore di alimentazione: Distinguere se la batteria al litio è connessa correttamente attraverso lo stato dell'indicatore luminoso blu.
- ③ Indicatore di carica: La luce rossa rimane accesa durante la carica e si spegne quando la carica è completa; tempo di ricarica da 1,5 a 2 ore.
- ④ Joystick sinistro ↑ Movimento: Rotazione avanti e indietro del motore del canale A.
Joystick sinistro ↔ Movimento: Rotazione avanti e indietro del motore del canale B.
- ⑤ Joystick destro ↑ Movimento: Rotazione avanti e indietro del motore del canale C.
Joystick destro ↔ Movimento: Rotazione avanti e indietro del motore del canale D.
- ⑥ Interruttore di inversione del canale: Cambia la direzione di rotazione del motore del canale.
- ⑦ Doppio pulsante alto/basso sul lato sinistro: Rotazione avanti e indietro del motore del canale E.
- ⑧ Doppio pulsante alto/basso sul lato destro: Rotazione avanti e indietro del motore del canale F.
- ⑨ Porta di carica: Collegare il cavo di carica tramite un'interfaccia micro-b USB (la tensione di uscita del trasformatore USB non deve superare i 5V e la corrente non deve superare 1A).

- ① Interruptor: Encender o apagar el control remoto.
- ② Indicador de energía: Determinar si la batería de litio está conectada exitosamente mediante el estado de la luz indicadora azul.
- ③ Indicador de carga: La luz roja permanece encendida durante la carga y se apaga cuando está completamente cargada; tiempo de carga de 1.5 a 2 horas.
- ④ Joystick izquierdo ↑ Movimiento: Rotación hacia adelante y hacia atrás del motor del canal A.
Joystick izquierdo ↔ Movimiento: Rotación hacia adelante y hacia atrás del motor del canal B.
- ⑤ Joystick derecho ↑ Movimiento: Rotación hacia adelante y hacia atrás del motor del canal C.
Joystick derecho ↔ Movimiento: Rotación hacia adelante y hacia atrás del motor del canal D.
- ⑥ Interruptor de reversa del canal: Cambia la dirección de rotación del motor del canal.
- ⑦ Botón doble arriba/abajo lado izquierdo: Rotación hacia adelante y hacia atrás del motor del canal E.
- ⑧ Botón doble arriba/abajo lado derecho: Rotación hacia adelante y hacia atrás del motor del canal F.
- ⑨ Puerto de carga: Conectar el cable de carga mediante una interfaz micro-b USB (la tensión de salida del transformador USB no debe exceder 5V, y la corriente no debe exceder 1A).

- ① スイッチ: リモコンをオンまたはオフにする。
- ② 電源インジケータ: 青色のインジケータライトの状態でリチウム電池が正常に接続されているかを区別します。
- ③ 充電インジケータ: 充電中は赤色のライトが点灯し続け、充電完了時には消灯します。充電時間は1.5〜2時間です。
- ④ 左ジョイスティック↑動作: Aチャンネルモーターの正転と逆転。
左ジョイスティック↔動作: Bチャンネルモーターの正転と逆転。
- ⑤ 右ジョイスティック↑動作: Cチャンネルモーターの正転と逆転。
右ジョイスティック↔動作: Dチャンネルモーターの正転と逆転。
- ⑥ チャンネル逆転スイッチ: 該当チャンネルのモーターの回転方向を変更する。
- ⑦ 左側の上下ダブルボタン: Eチャンネルモーターの正転と逆転。
- ⑧ 右側の上下ダブルボタン: Fチャンネルモーターの正転と逆転。
- ⑨ 充電ポート: micro-b USBインターフェースを介して充電ケーブルを接続します (USB変圧器の出力電圧は5Vを超えてはならず、電流は1Aを超えてはなりません)。

1



Zapněte dálkový ovladač a modulu, aby se úspěšně spárovaly.

**Turn on the remote control power, turn on the module power, and ensure successful pairing.
Schalten Sie die Stromversorgung der Fernbedienung ein, schalten Sie die Stromversorgung des Moduls ein und stellen Sie eine erfolgreiche Kopplung sicher.**

Allumez l' alimentation de la télécommande, allumez l' alimentation du module et assurez-vous que l' appairage est réussi.

Accendi l' alimentazione del telecomando, accendi l' alimentazione del modulo e assicurati che l' accoppiamento sia avvenuto con successo.

Encienda la alimentación del control remoto, encienda la alimentación del módulo y asegúrese de que el emparejamiento sea exitoso.

リモコンの電源を入れ、モジュールの電源を入れ、ペアリングが成功していることを確認してください。

2



vyjměte motor A, připojte jej k portu A modulu, pohněte levým joystickem dálkového ovladače nahoru a motor se otáčí doleva

**Take out an A motor and connect it to the module A interface, move the left joystick upwards, and the motor power hole rotates to the left.
Nehmen Sie einen A-Motor heraus und verbinden Sie ihn mit dem A-Anschluss des Moduls, bewegen Sie den linken Joystick nach oben, und das Motorleistungsloch dreht sich nach links.**

Sortez un moteur A et connectez-le à l' interface A du module, déplacez le joystick gauche vers le haut et le trou de puissance du moteur tourne vers la gauche.

Estrai un motore A e collegalo all' interfaccia A del modulo, muovi il joystick sinistro verso l' alto e il foro di potenza del motore ruota verso sinistra.

Saque un motor A y conéctelo a la interfaz A del módulo, mueva el joystick izquierdo hacia arriba y el orificio de potencia del motor girará hacia la izquierda.

Aモーターを取り出してモジュールのAインターフェースに接続し、左のジョイスティックを上動かしてモーターの動力孔を左に回転させます。

3



Levý joystick dálkového ovladače pohněte dolů a motor se otáčí doprava.

The left joystick of the remote control moves downwards, and the motor power hole rotates to the right.

Bewegen Sie den linken Joystick der Fernbedienung nach unten, und das Motorleistungsloch dreht sich nach rechts.

Déplacez le joystick gauche de la télécommande vers le bas, et le trou de puissance du moteur tourne vers la droite.

Muovi il joystick sinistro del telecomando verso il basso e il foro di potenza del motore ruota verso destra.

Mueva el joystick izquierdo del control remoto hacia abajo y el orificio de potencia del motor girará hacia la derecha.

リモコンの左のジョイスティックを下に動かし、モーターの動力孔を右に回転させます。

4



přepněte směr kanálů, posuntě dálkový ovladač nahoru a motor se otočí doprava.

Turn the channel directional switch, move the remote control upwards, and the motor power hole rotates to the right.

Drehen Sie den Kanalrichtungsschalter, bewegen Sie die Fernbedienung nach oben, und das Motorleistungsloch dreht sich nach rechts.

Tournez l' interrupteur directionnel du canal, déplacez la télécommande vers le haut, et le trou de puissance du moteur tourne vers la droite.

Gira l'interruttore direzionale del canale, muovi il telecomando verso l'alto e il foro di potenza del motore ruota verso destra.

Gire el interruptor direccional del canal, mueva el control remoto hacia arriba y el orificio de potencia del motor girará hacia la derecha.

チャンネル方向スイッチを切り替え、リモコンを上を動かし、モーターの動力孔が右に回転します。

5



Pohněte levým joystickem dolů a motor se otočí doleva.

The left joystick of the remote control moves downwards, and the motor power hole rotates to the left.

Der linke Joystick der Fernbedienung bewegt sich nach unten, und das Motorleistungsloch dreht sich nach links.

Le joystick gauche de la télécommande se déplace vers le bas, et le trou de puissance du moteur tourne vers la gauche.

Il joystick sinistro del telecomando si muove verso il basso, e il foro di potenza del motore ruota verso sinistra.

El joystick izquierdo del control remoto se mueve hacia abajo, y el orificio de potencia del motor gira hacia la izquierda.

リモコンの左ジョイスティックが下に動き、モーターの動力孔が左に回転します。

6

otestujte prosím všechny motory podle výše uvedené metody. Po dokončení testu prosím motory vyjměte pro snadnou montáž v budoucnu. Při testování otestujte odpovídající kanál motoru. Motor A odpovídá kanálu A atd...

Please test all motors according to the above method. After the test is completed, please remove the motors for easy assembly in the future.

When testing, please test the corresponding channel of the motor. An A motor corresponds to channel A, a B motor corresponds to channel B, and so on.

Bitte testen Sie alle Motoren nach der oben genannten Methode. Nach Abschluss des Tests entfernen Sie bitte die Motoren, um die zukünftige Montage zu erleichtern. Beim Testen testen Sie bitte den entsprechenden Kanal des Motors. Ein A-Motor entspricht Kanal A, ein B-Motor entspricht Kanal B usw.

Veuillez tester tous les moteurs selon la méthode ci-dessus. Après le test, veuillez retirer les moteurs pour faciliter l'assemblage ultérieur.

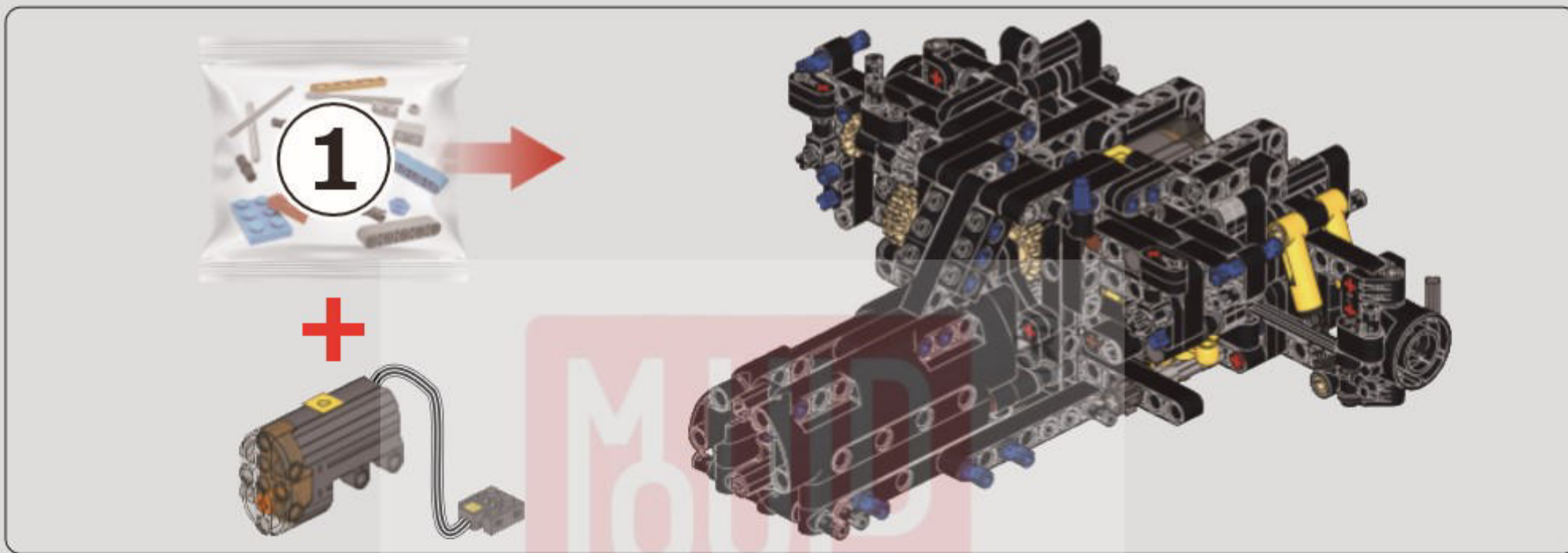
Lors des tests, veuillez tester le canal correspondant du moteur. Un moteur A correspond au canal A, un moteur B correspond au canal B, etc.

Si prega di testare tutti i motori secondo il metodo sopra descritto. Dopo il test, rimuovere i motori per facilitare il futuro assemblaggio.

Durante il test, testare il canale corrispondente del motore. Un motore A corrisponde al canale A, un motore B corrisponde al canale B, ecc.

Por favor, pruebe todos los motores según el método anterior. Después de completar la prueba, retire los motores para facilitar el ensamblaje futuro. Al probar, pruebe el canal correspondiente del motor. Un motor A corresponde al canal A, un motor B corresponde al canal B, etc.

上記の方法ですべてのモーターをテストしてください。テストが完了したら、将来の組み立てを容易にするためにモーターを取り外してください。テスト時には、モーターの対応するチャンネルをテストしてください。AモーターはAチャンネルに、BモーターはBチャンネルに対応します。



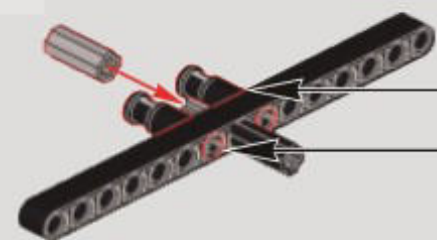
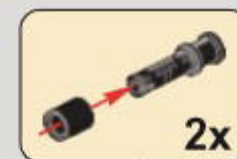
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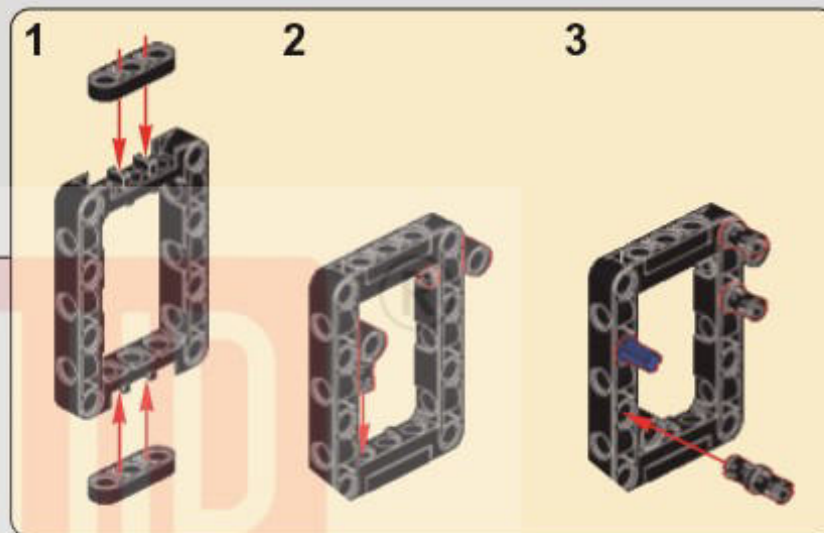
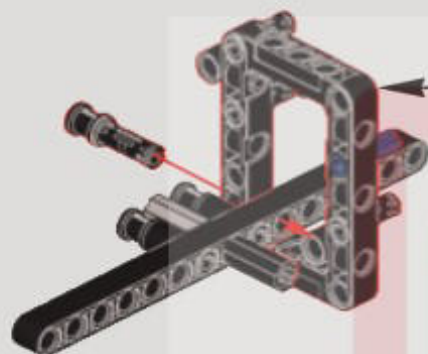


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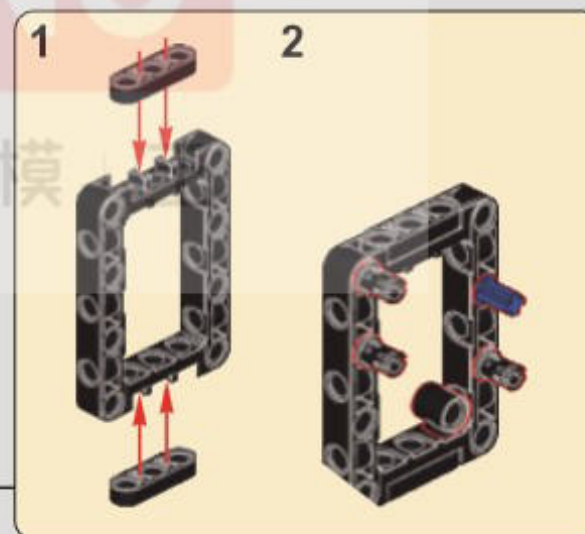
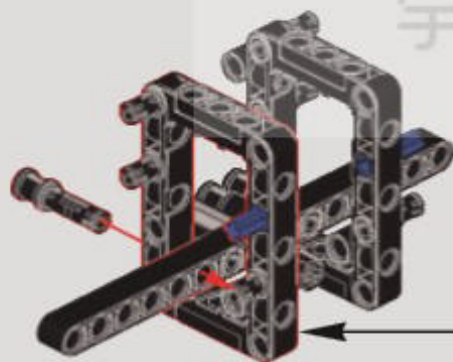


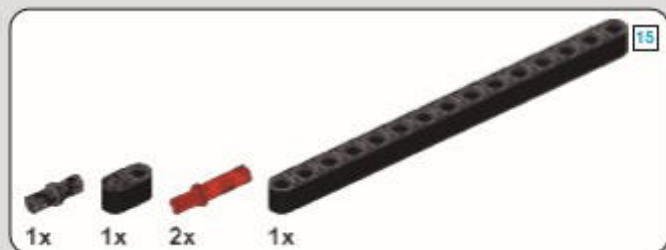


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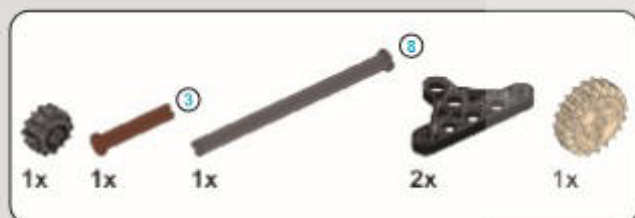
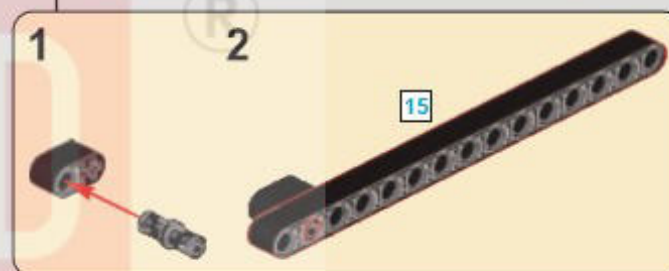
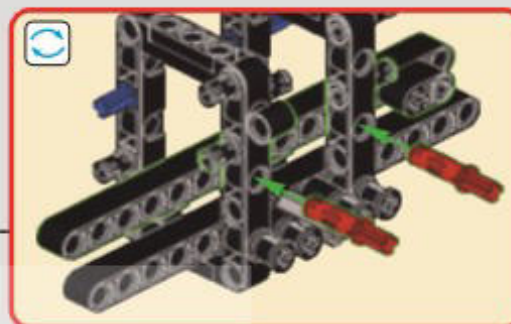
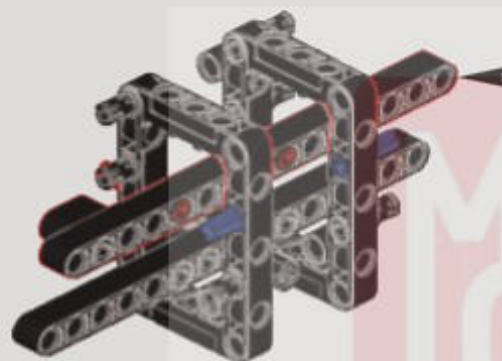


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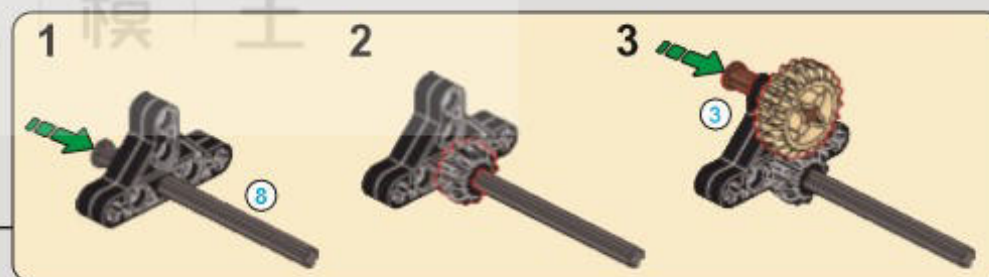
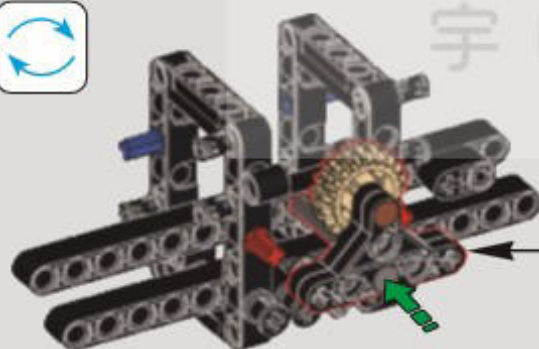


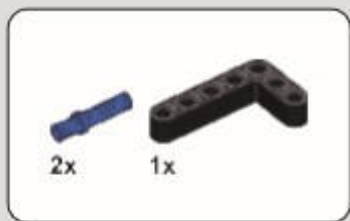


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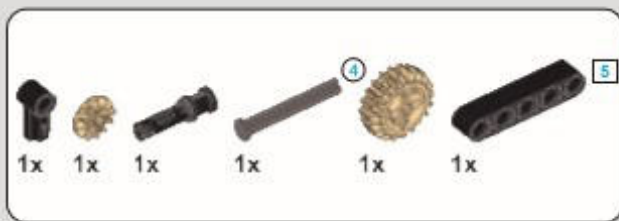
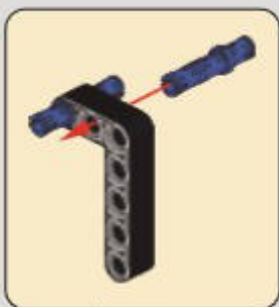


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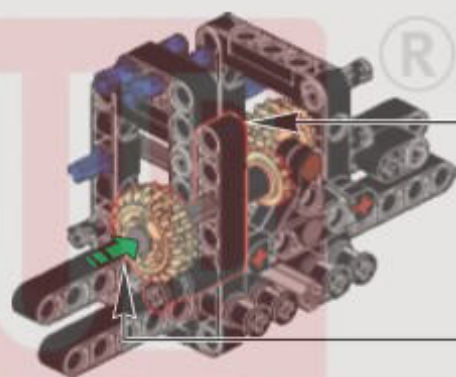
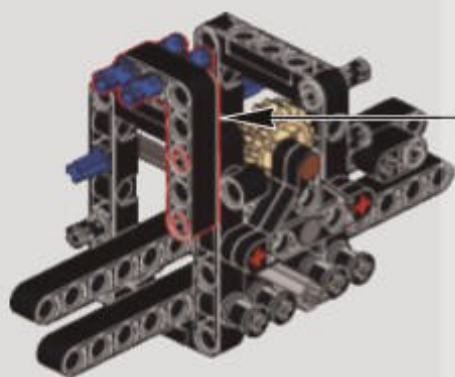
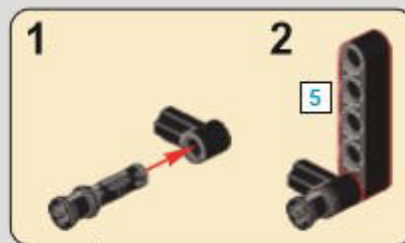




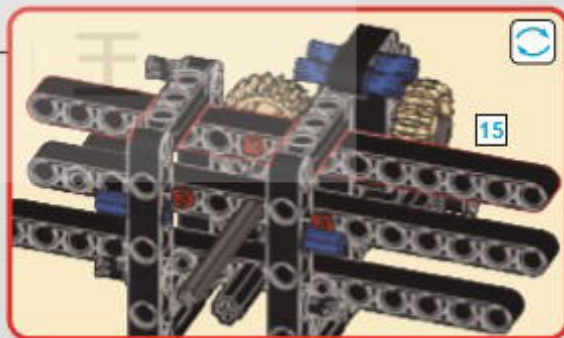
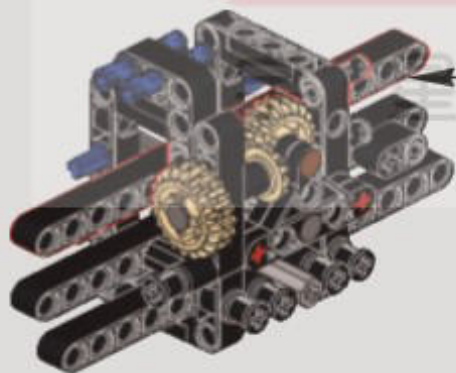
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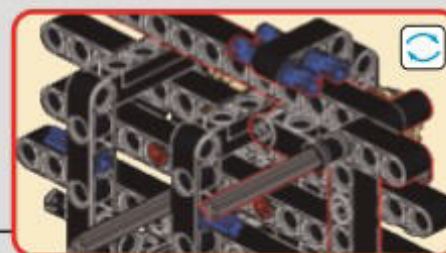
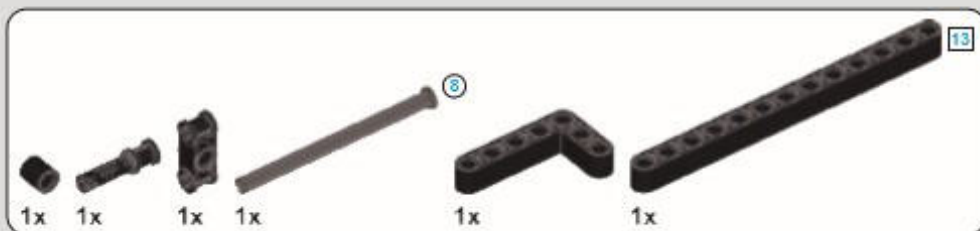
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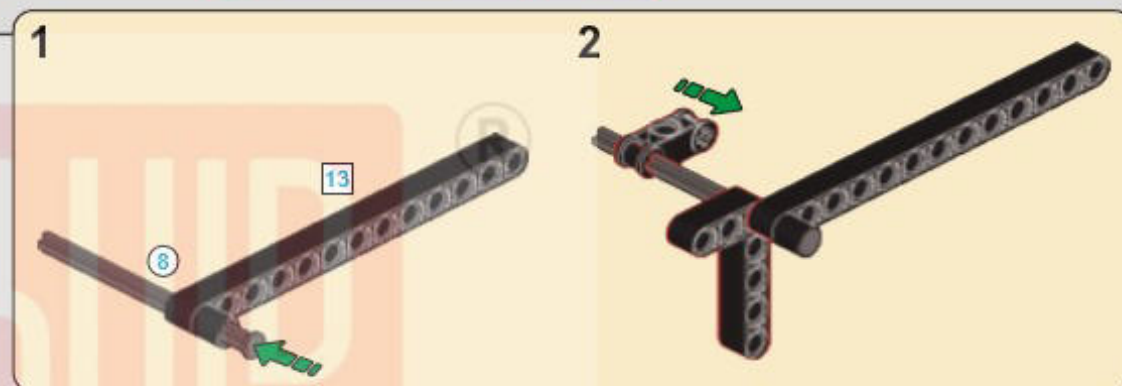
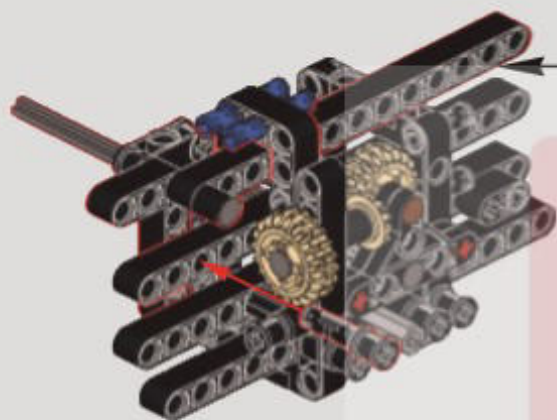
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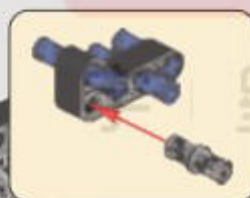
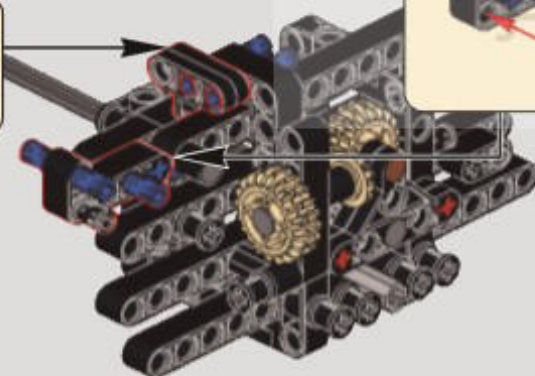
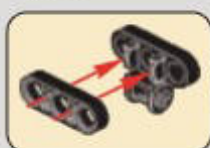
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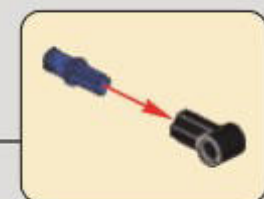
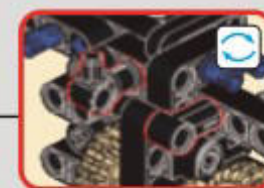
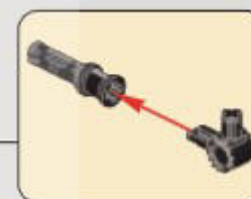
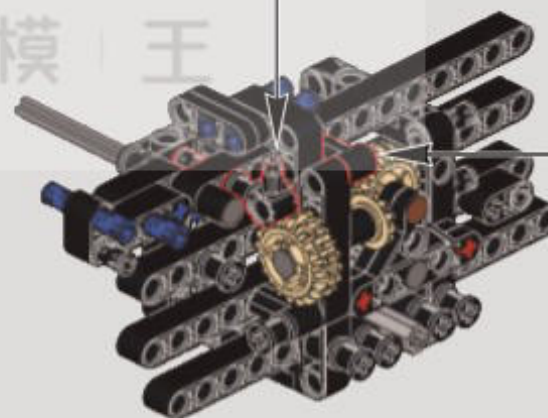
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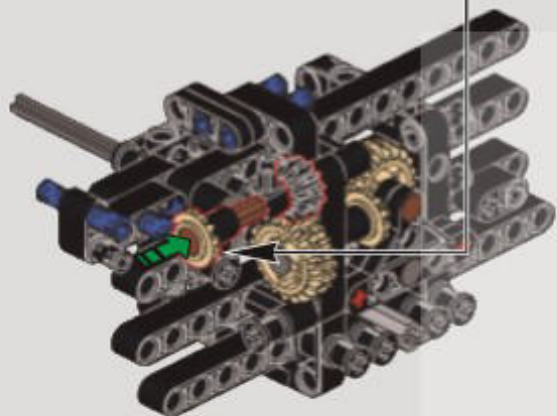


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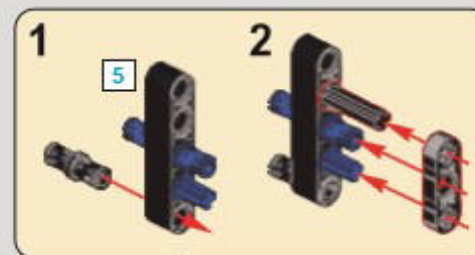
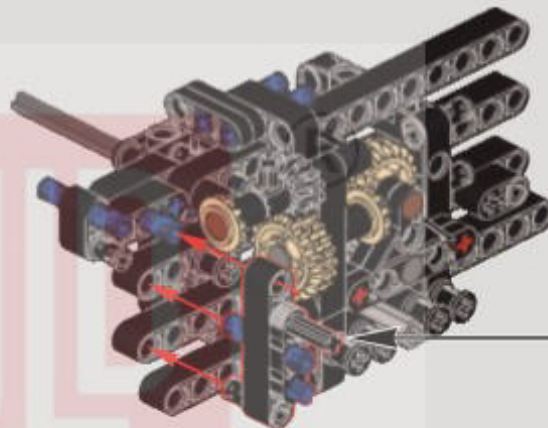




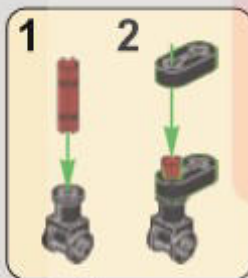
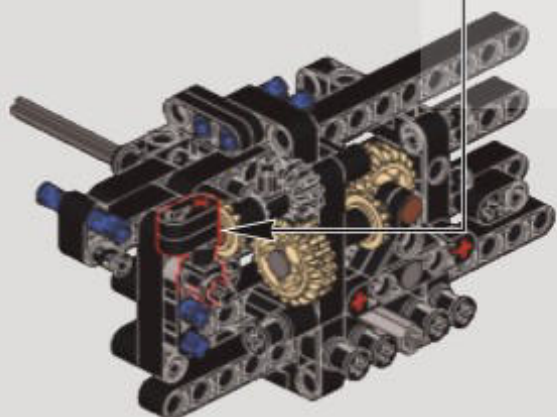
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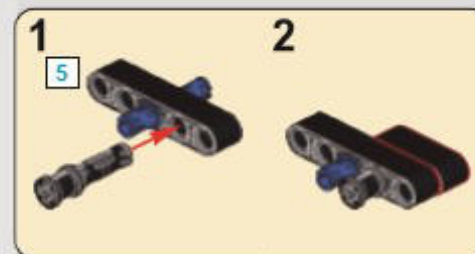
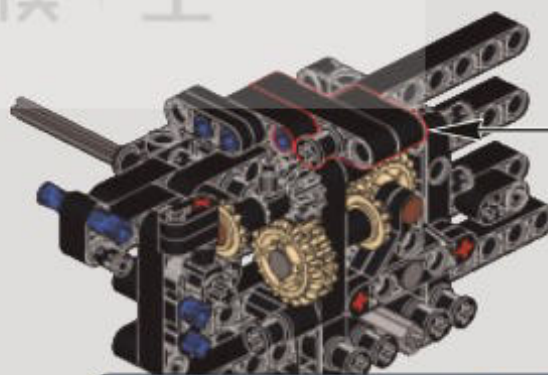
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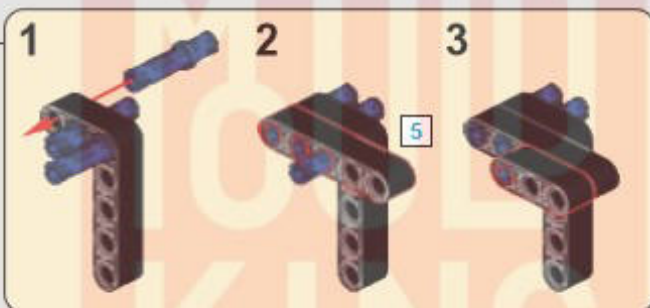
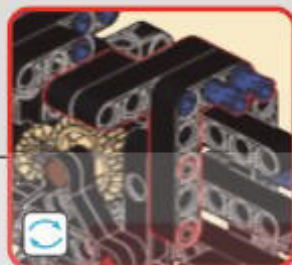
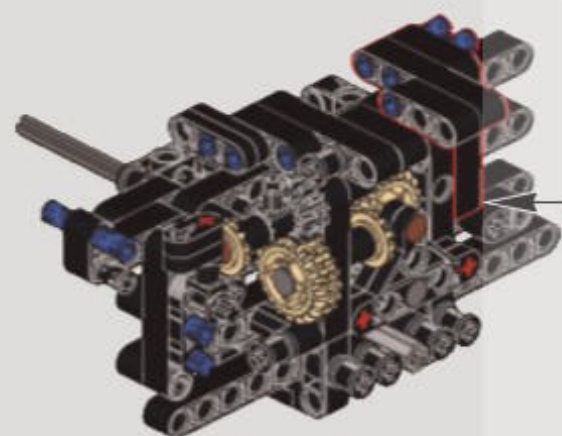


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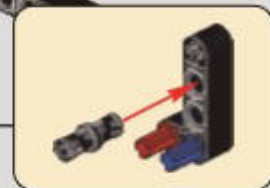
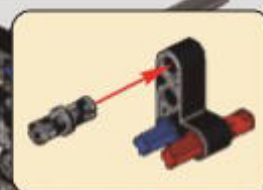
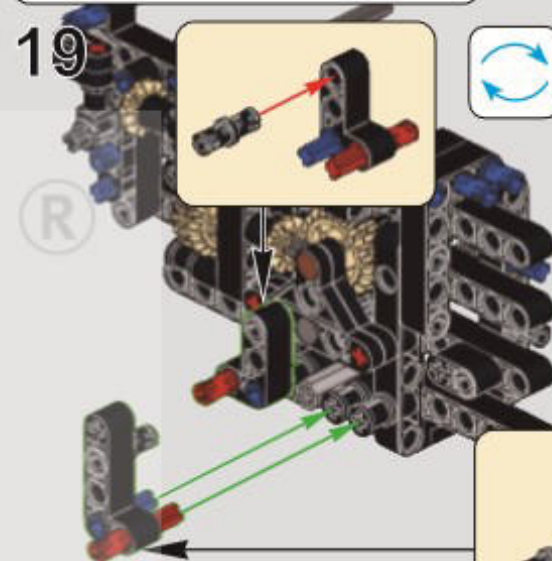




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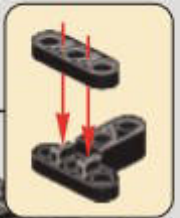
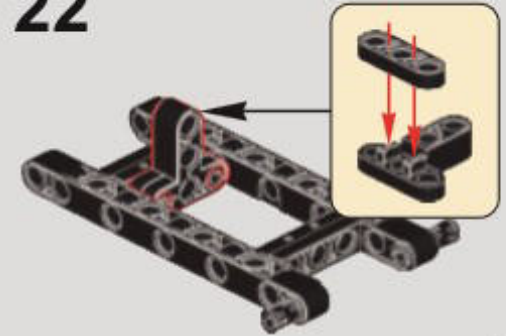
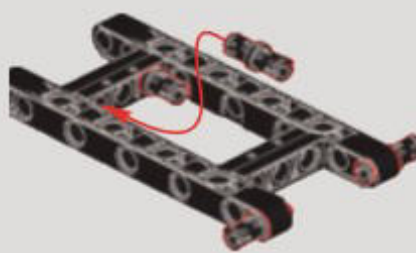
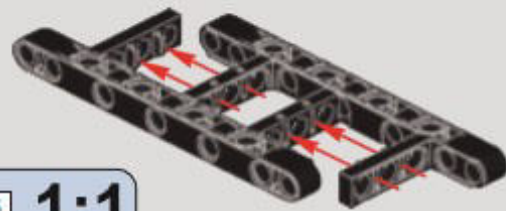
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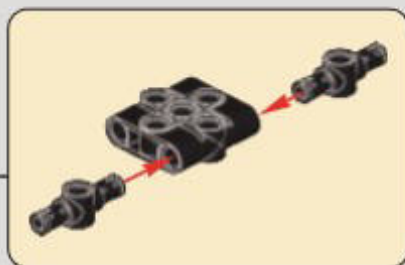


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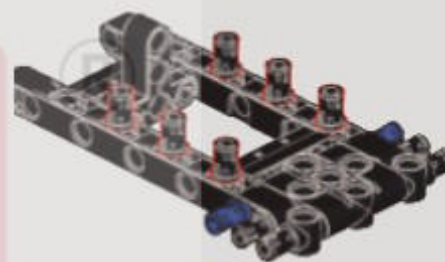
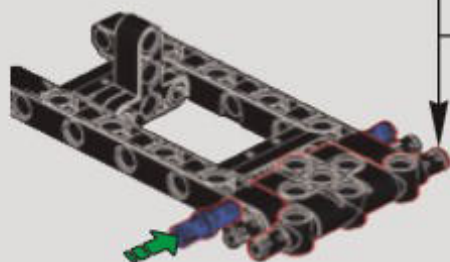




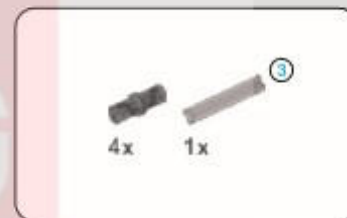
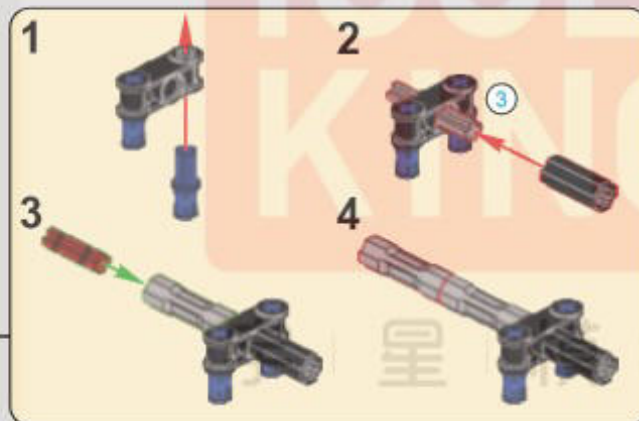
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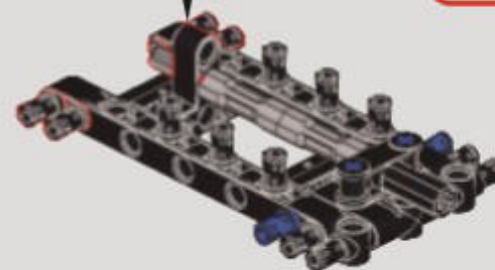
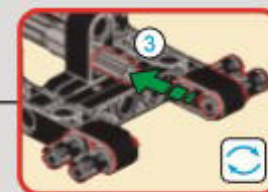
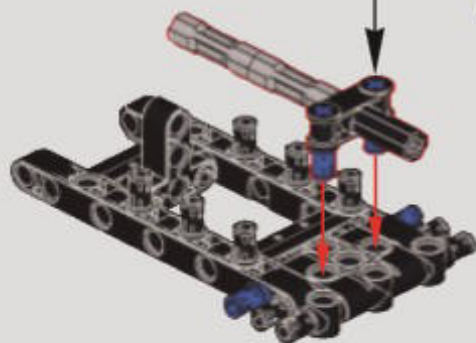
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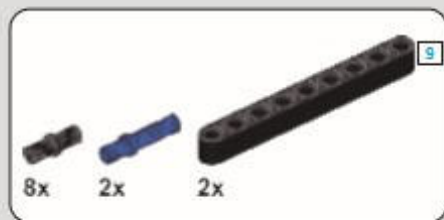


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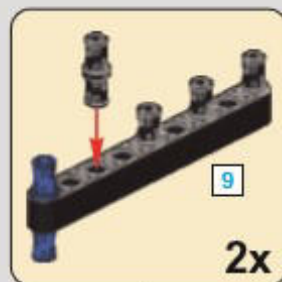
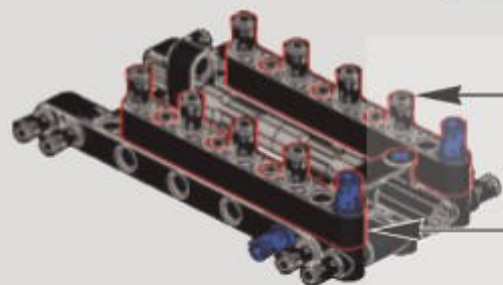


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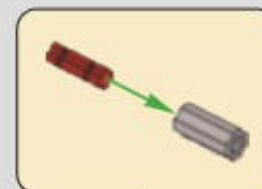
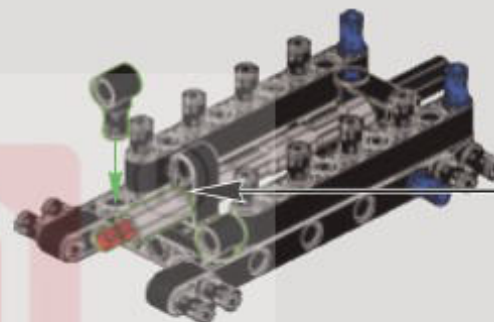
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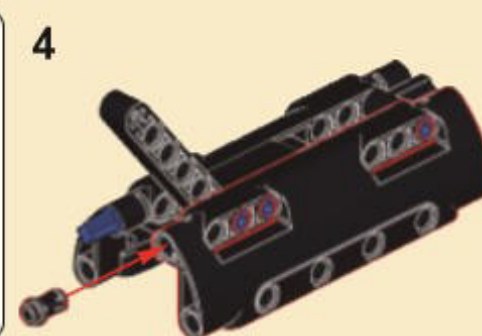
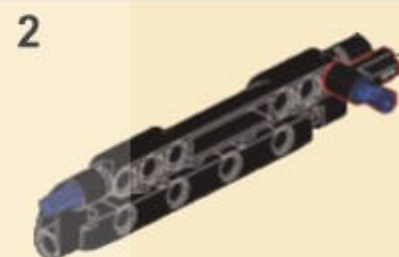
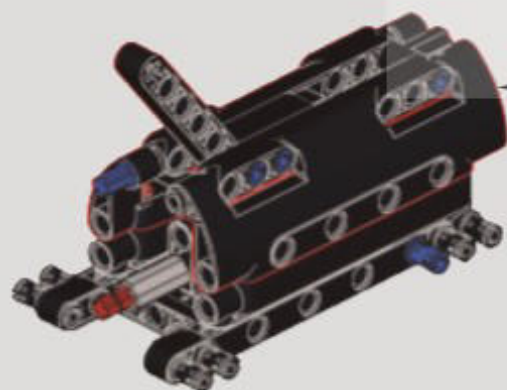
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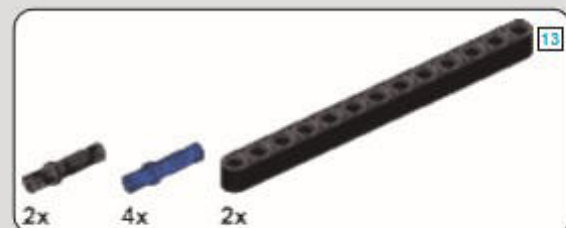
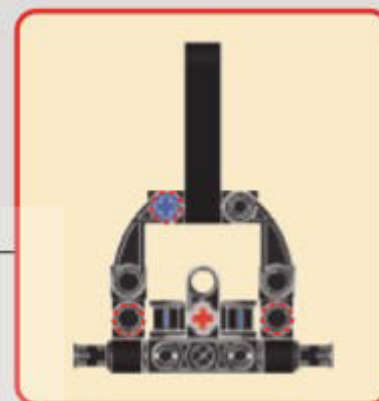
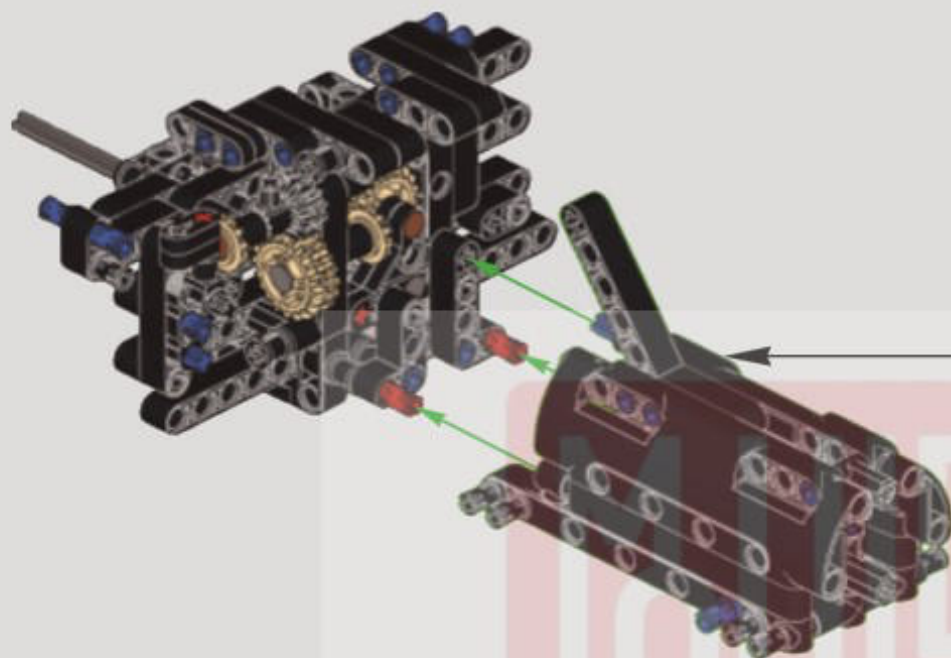
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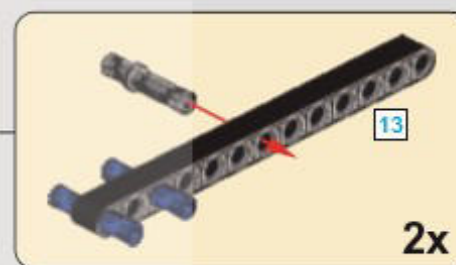
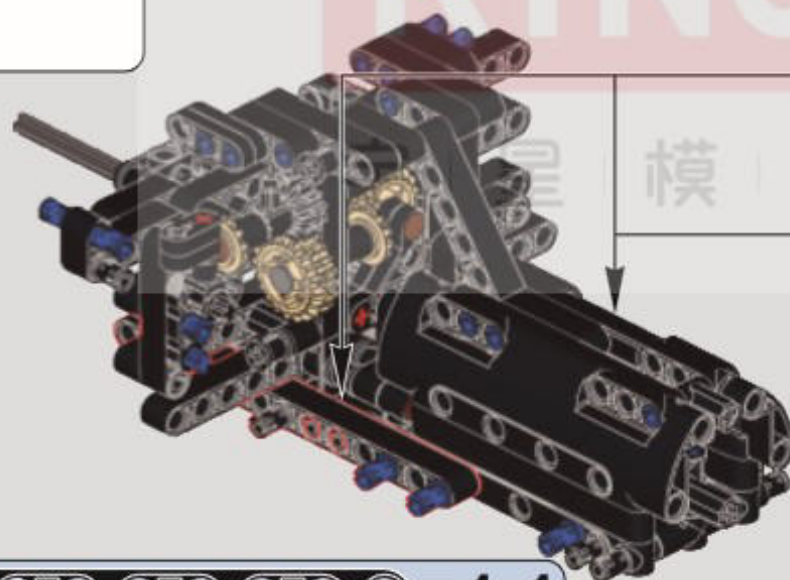
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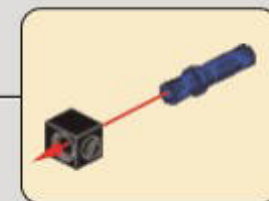
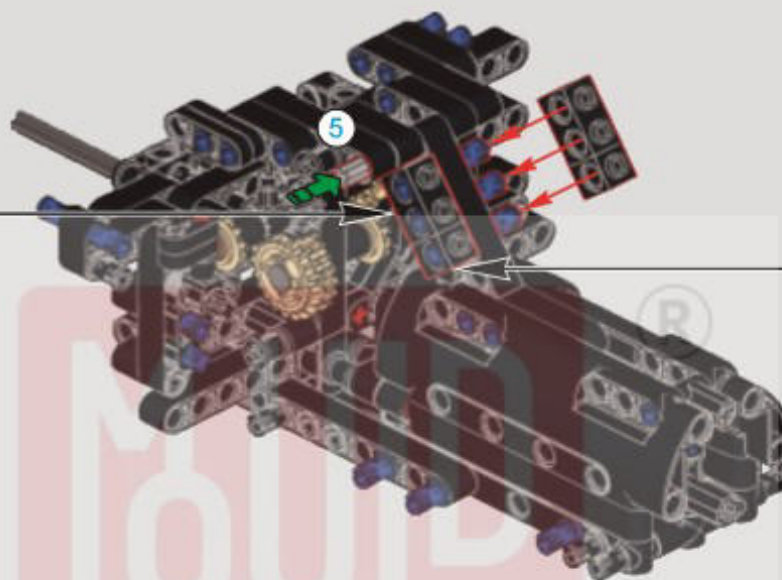
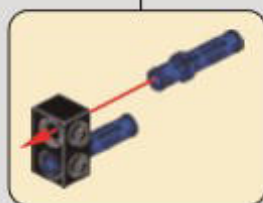


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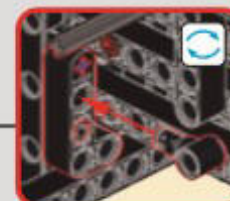
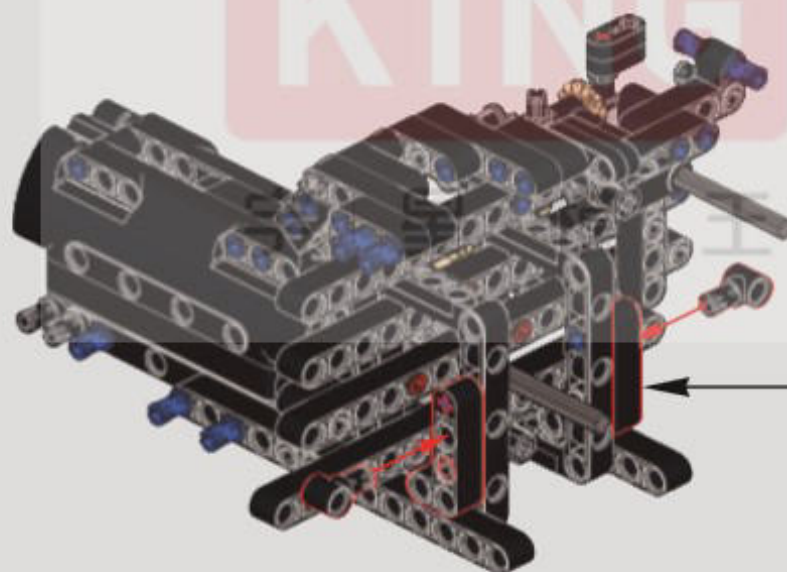




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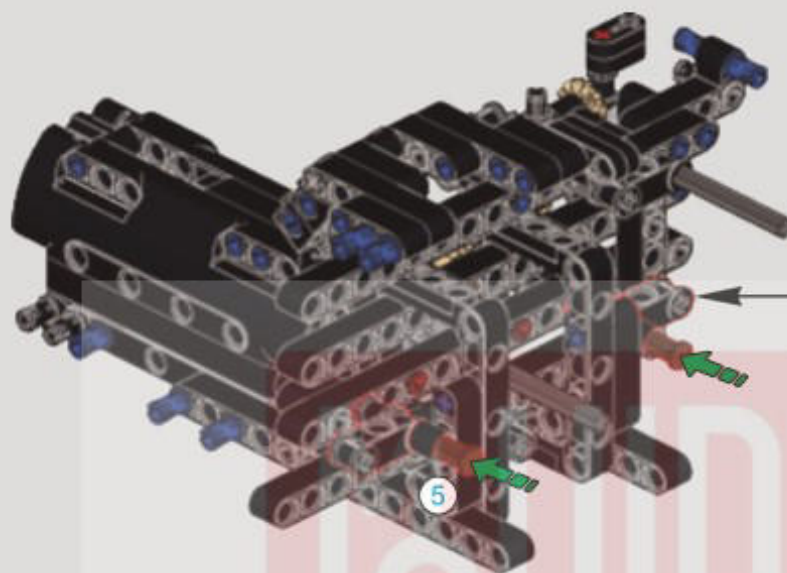


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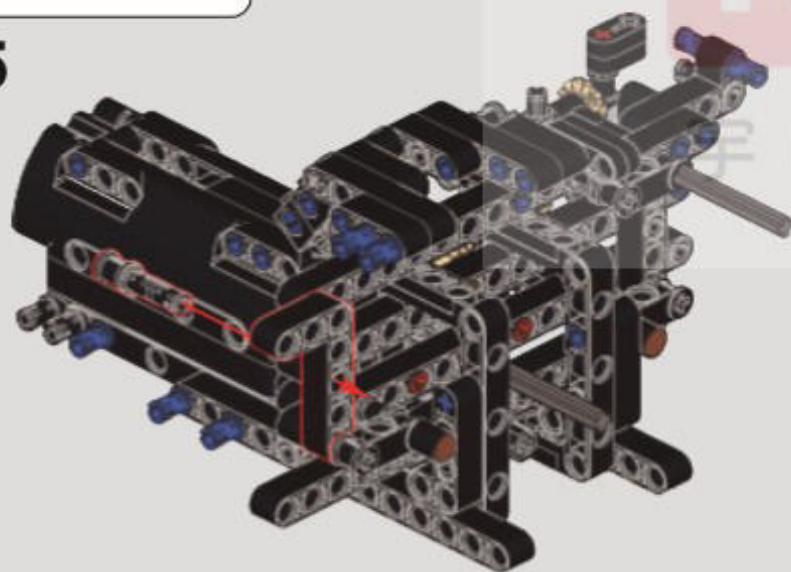




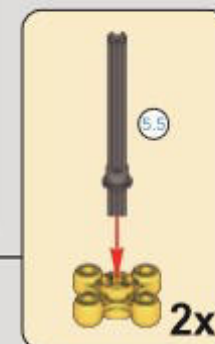
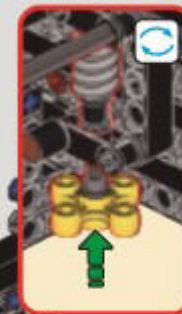
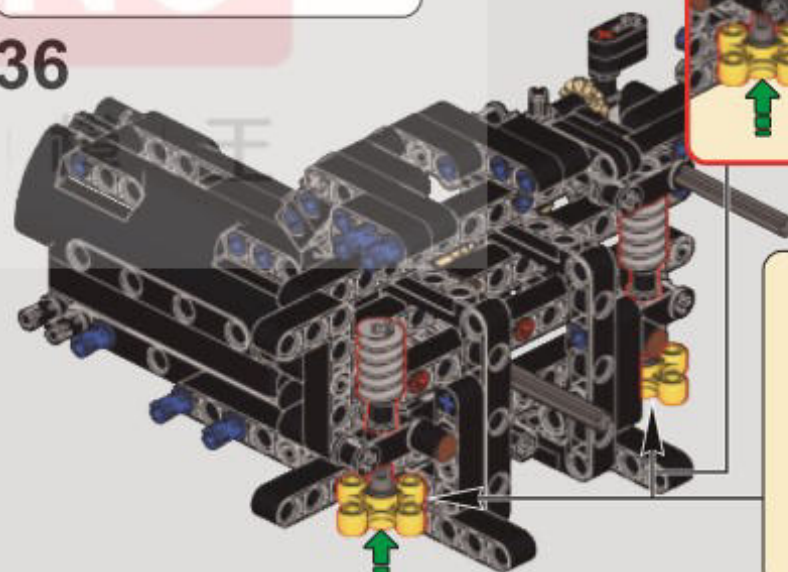
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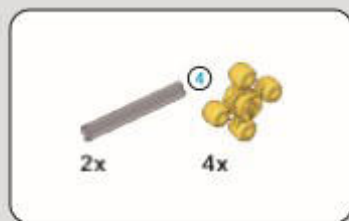


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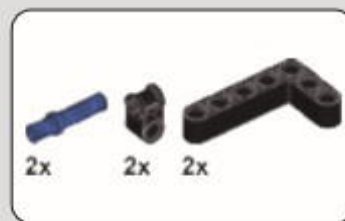
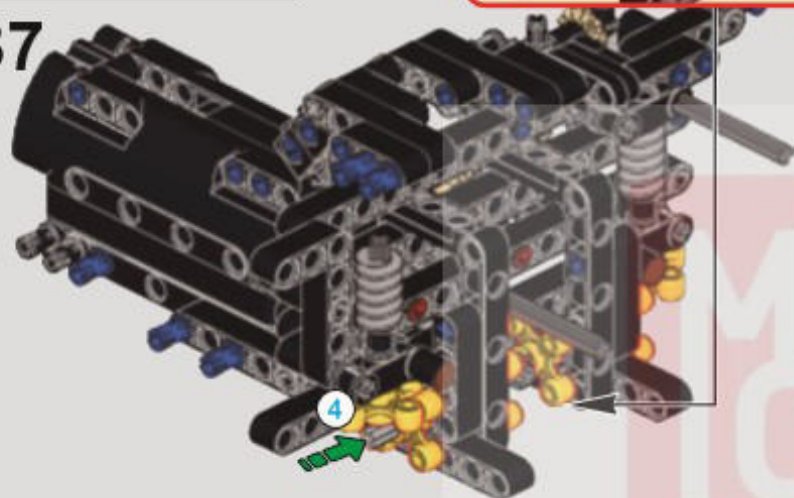


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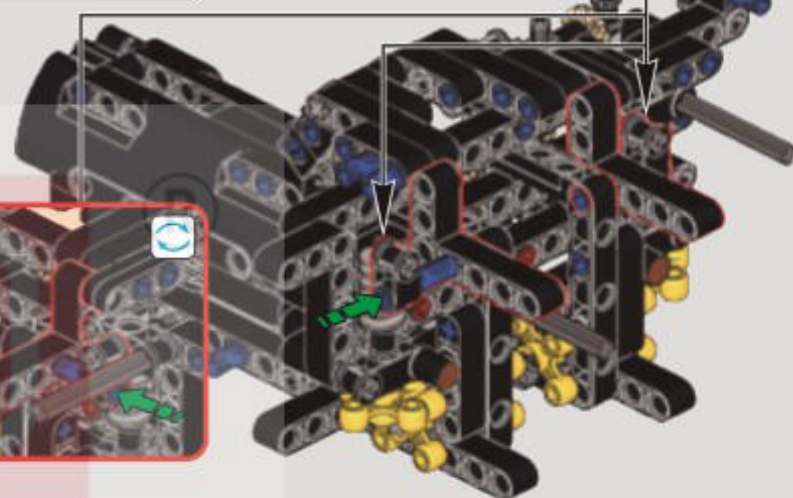




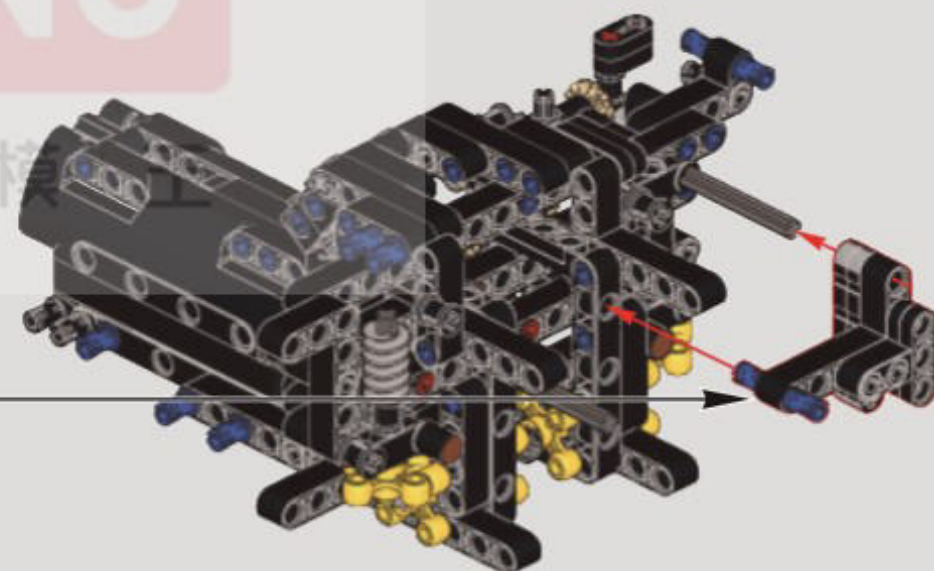
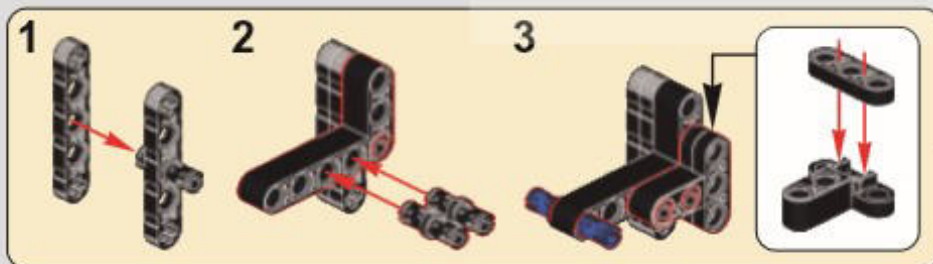
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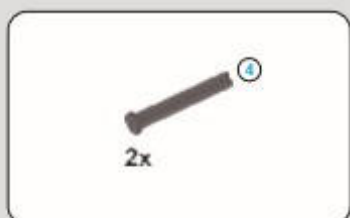
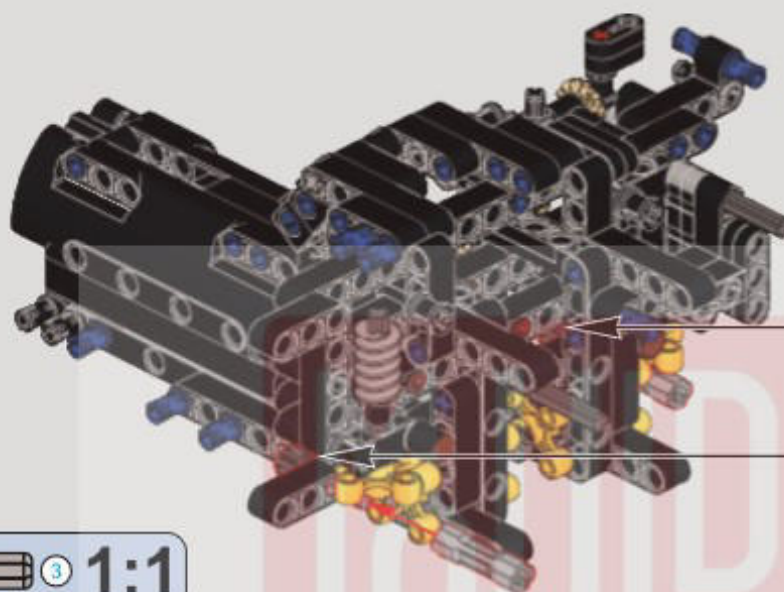


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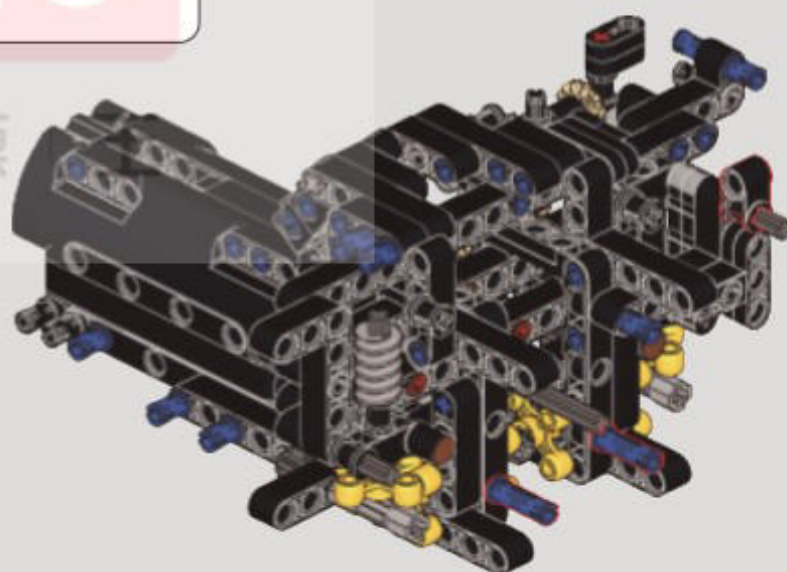
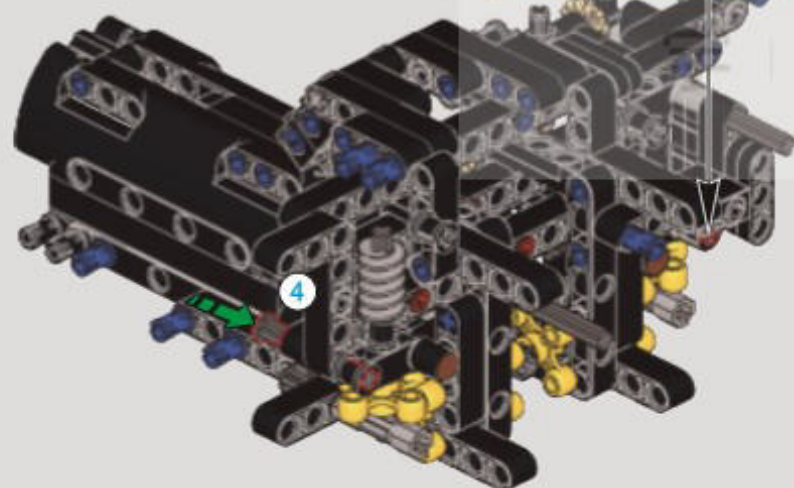
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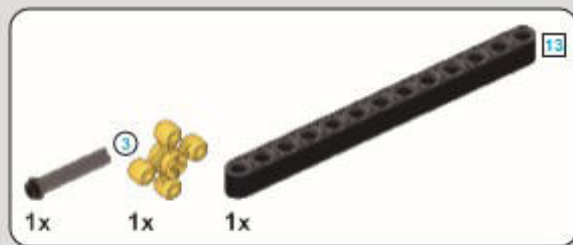


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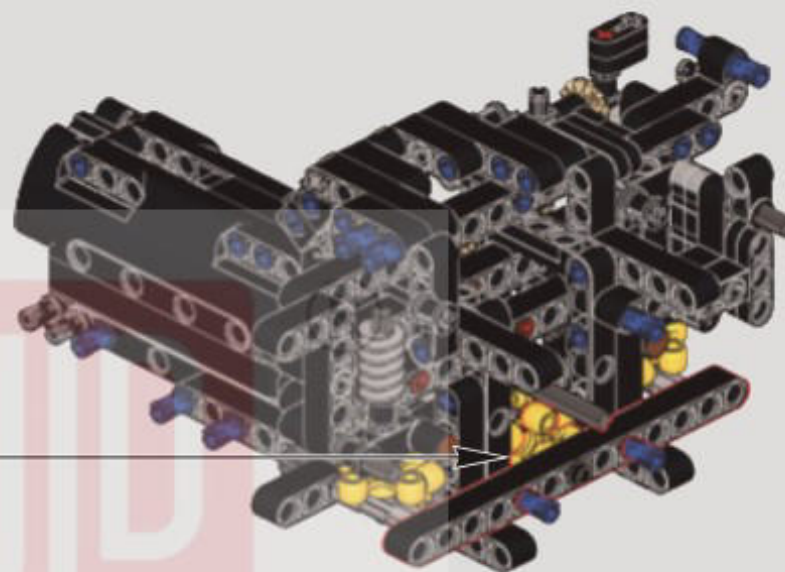
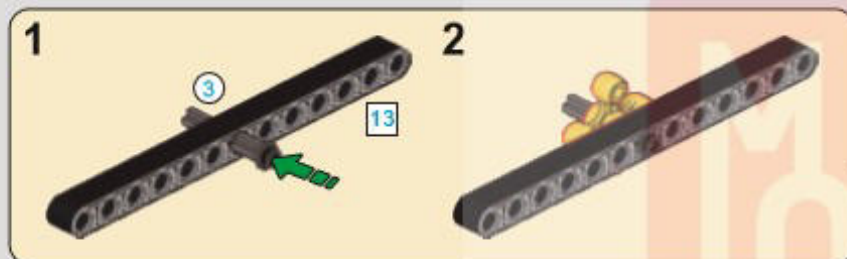


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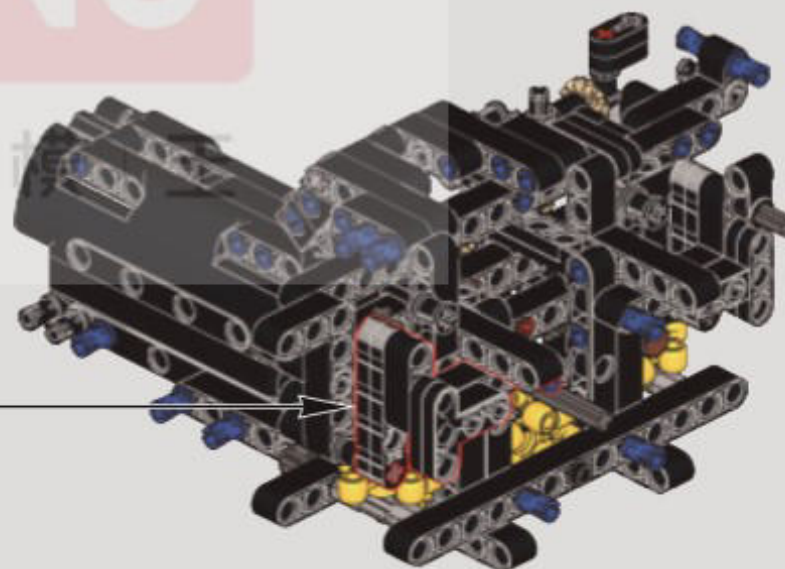
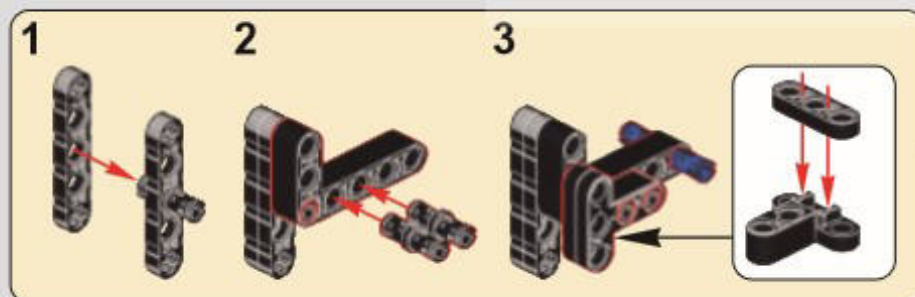


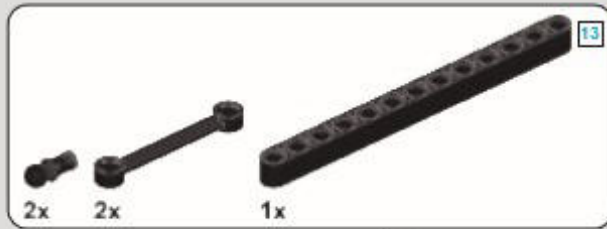


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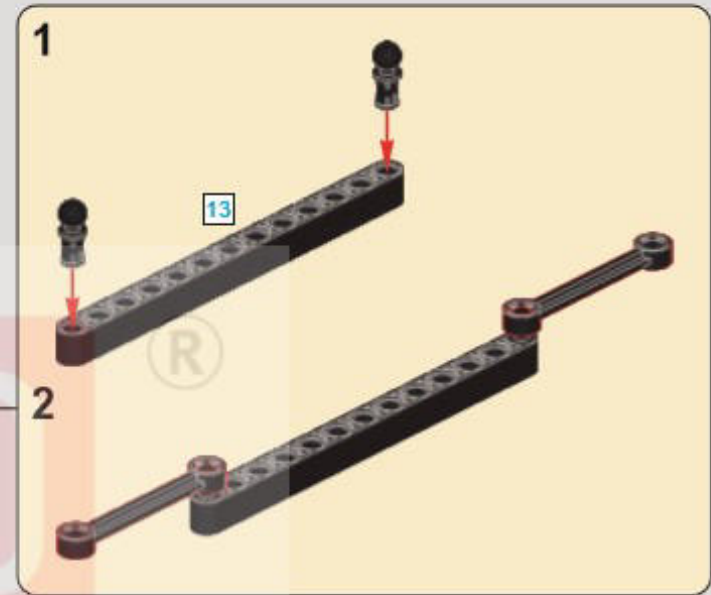
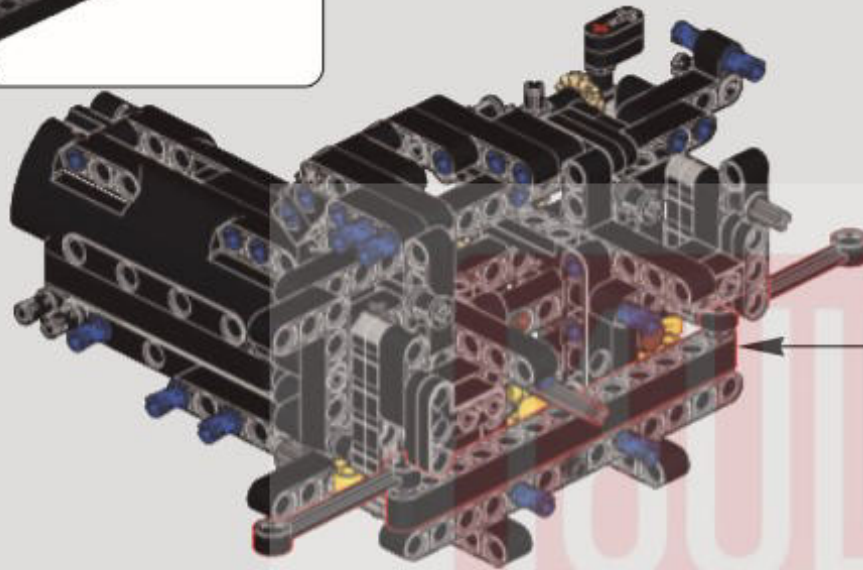


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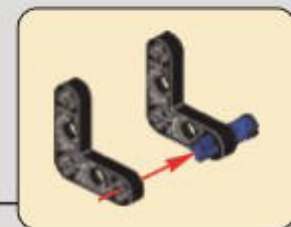
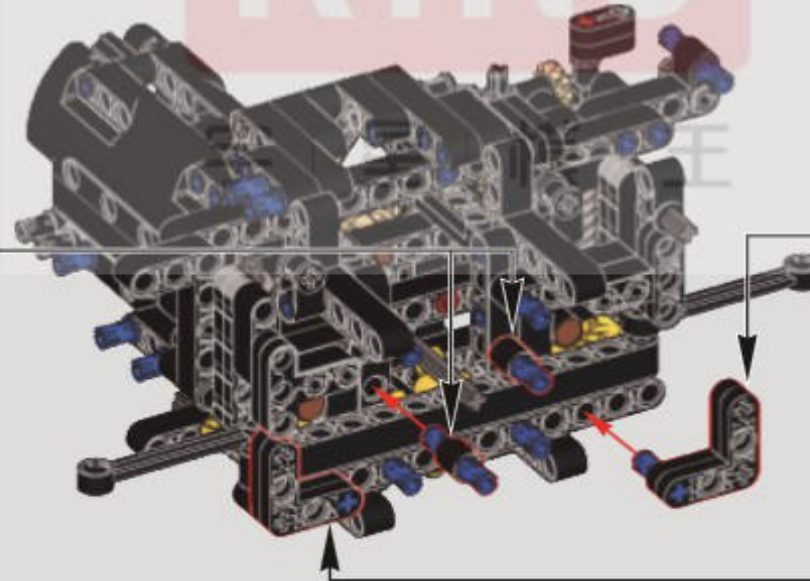


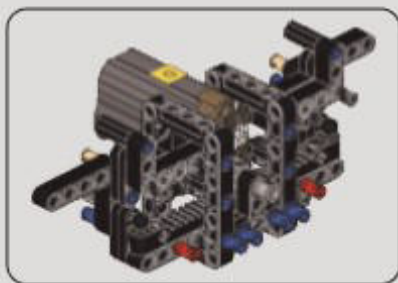


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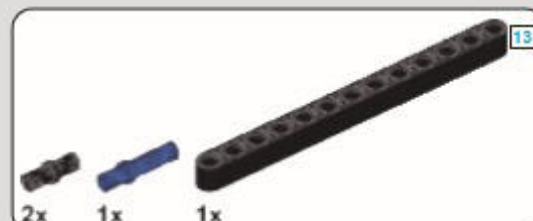


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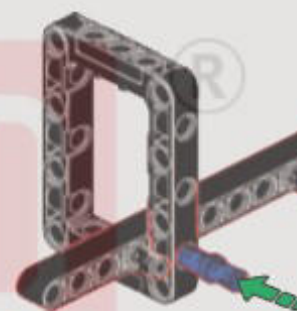
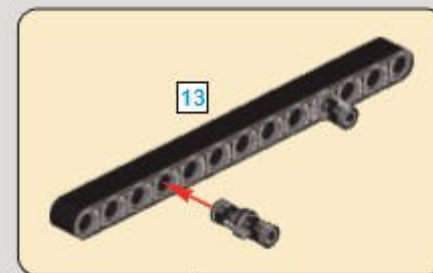




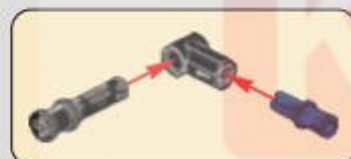
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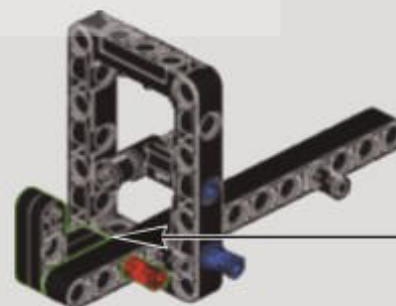
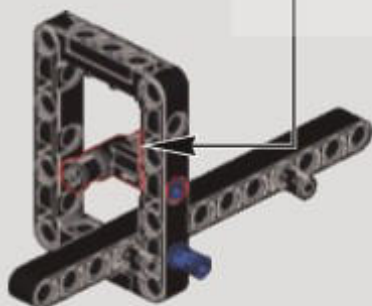
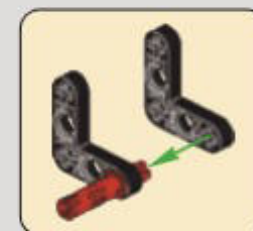
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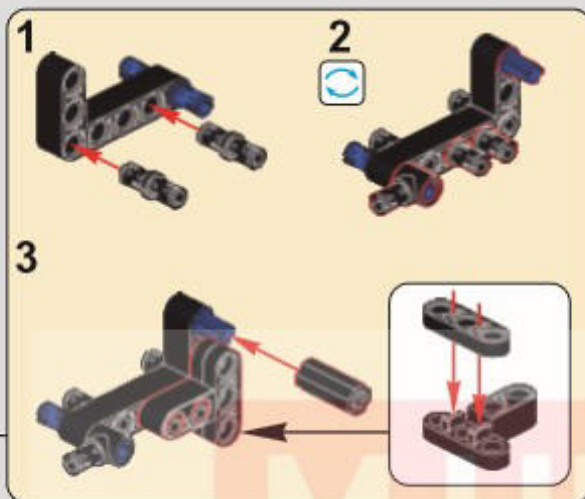
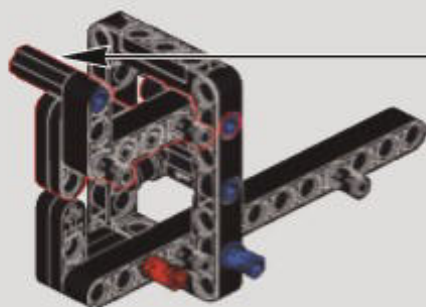


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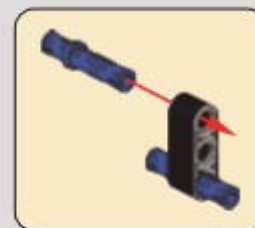
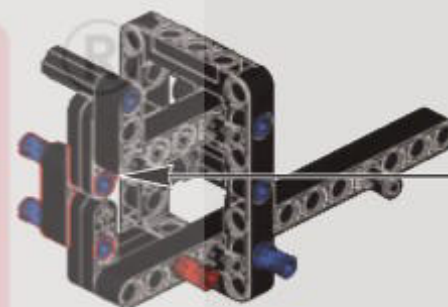




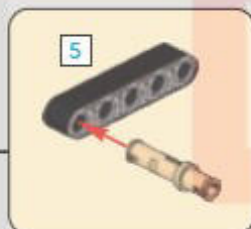
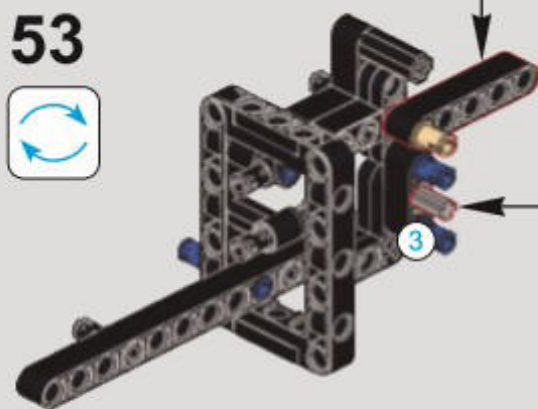
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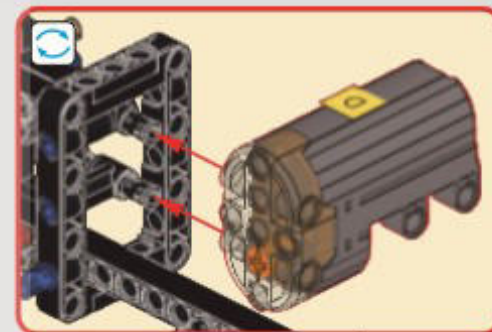
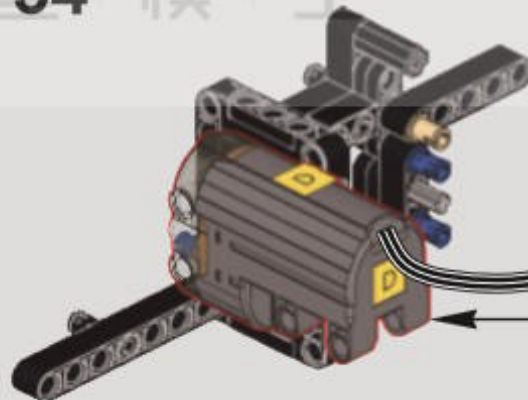
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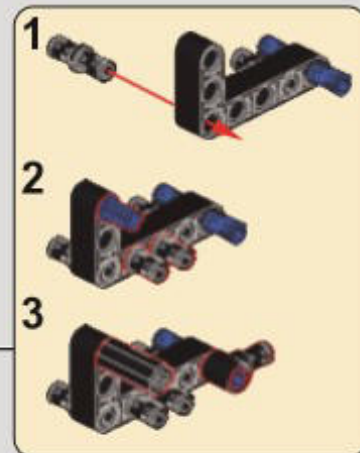
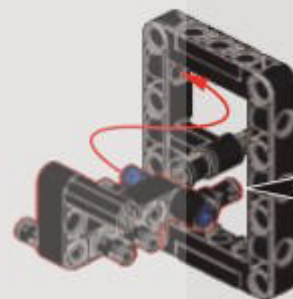




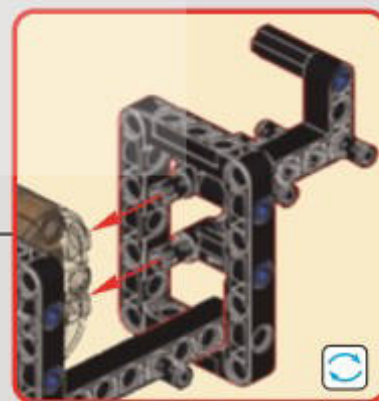
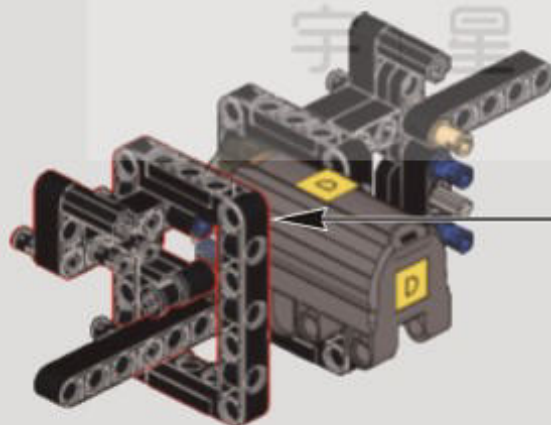
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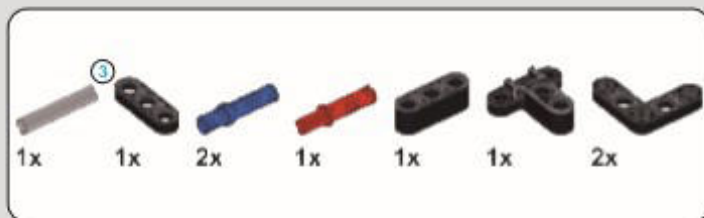


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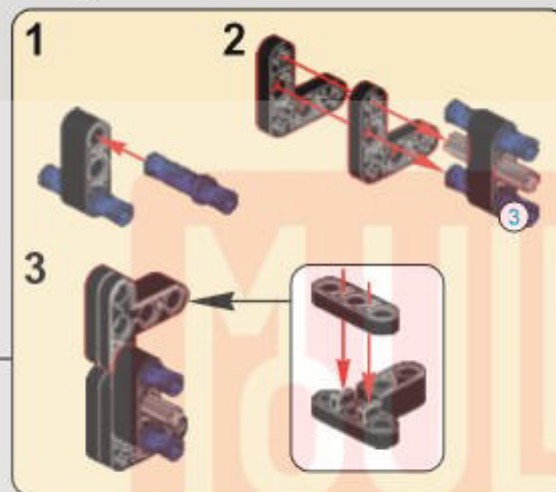
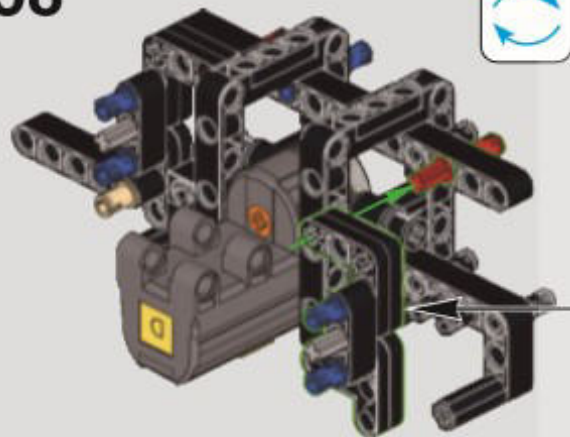


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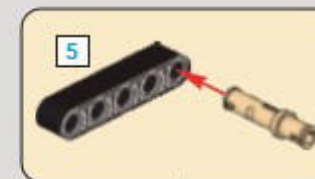
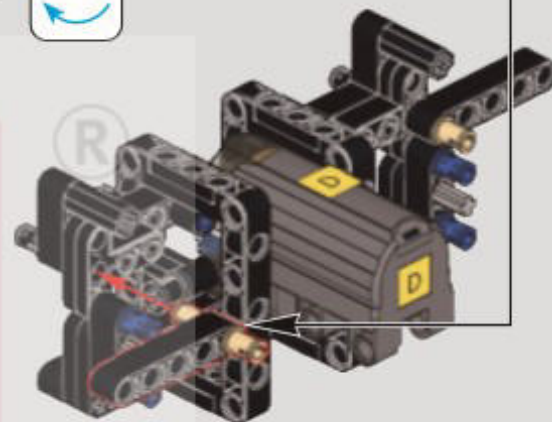




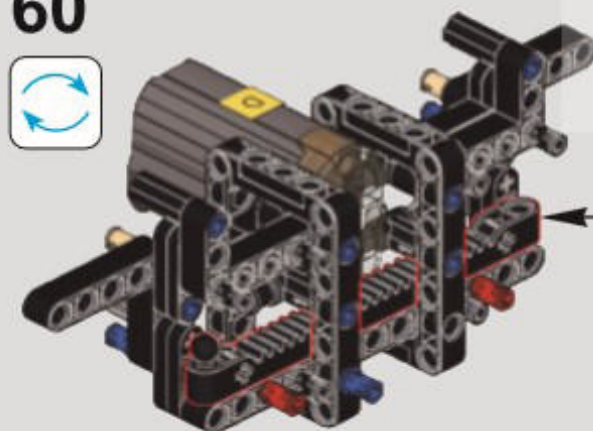
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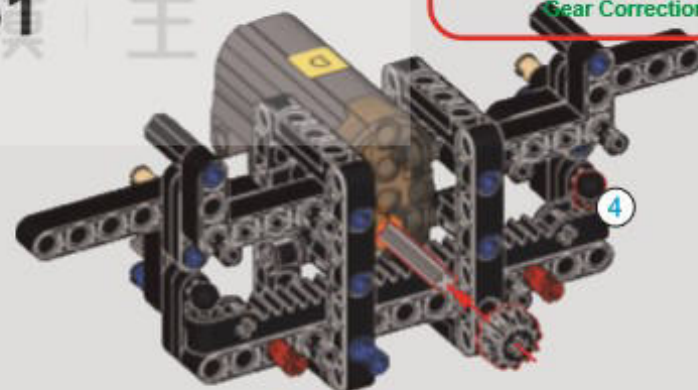
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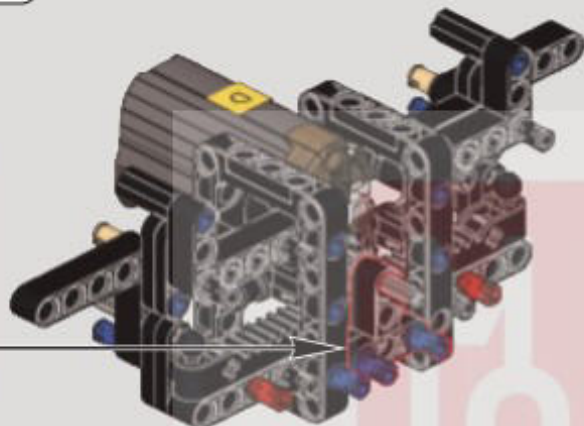
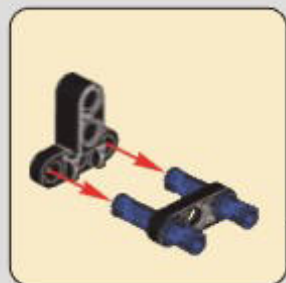


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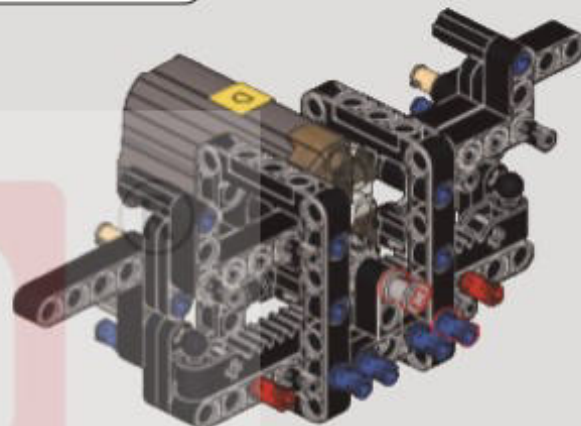




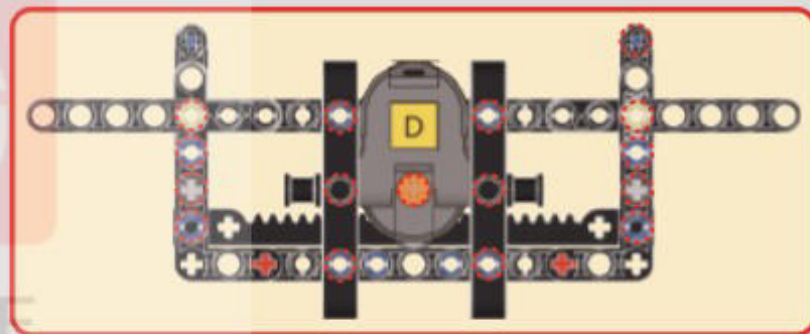
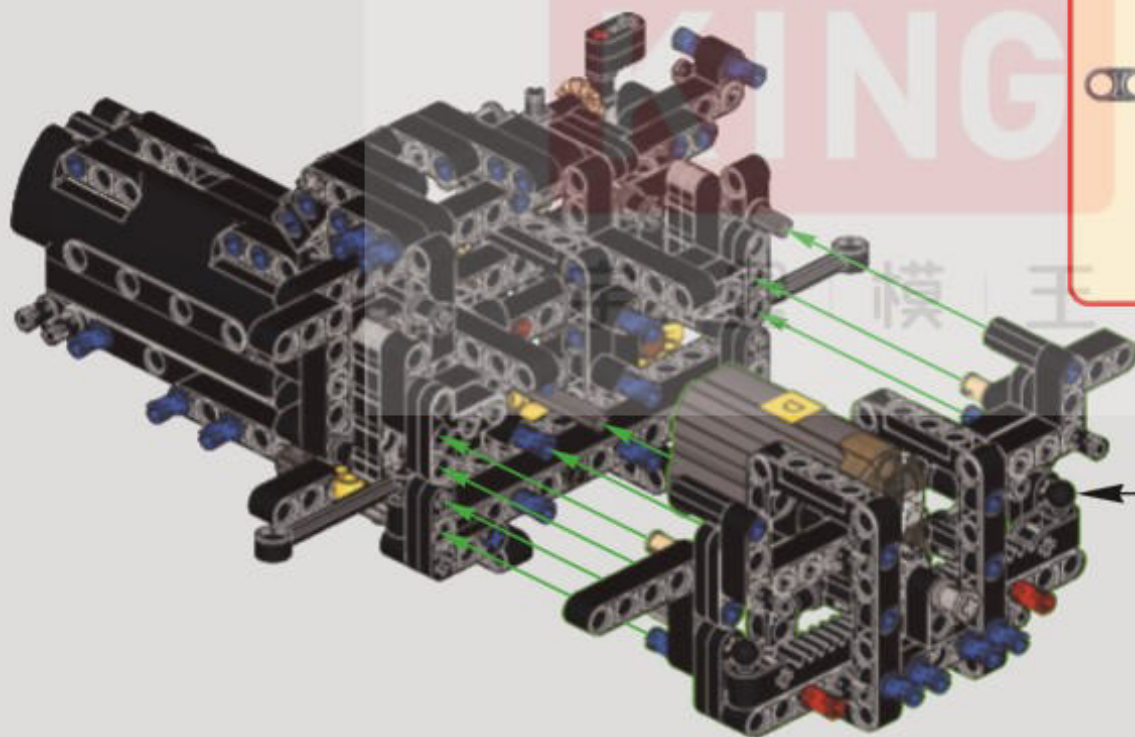
62



63



64



Zapojte kabel motoru do modulu, zapněte modul a připojte dálkové ovládání. Pohybem pravého joysticku dálkového ovládání (kanál D) otestujte, zda se hřebec pohybuje doleva a doprava.

Insert the motor wire into the module, turn on the module and connect the remote control. Move the right joystick left and right (D channel) to test if the rack can move horizontally. If it cannot, please check if the previous steps were assembled correctly. After testing, disconnect the wire and turn off the module and remote control.

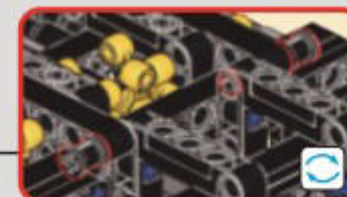
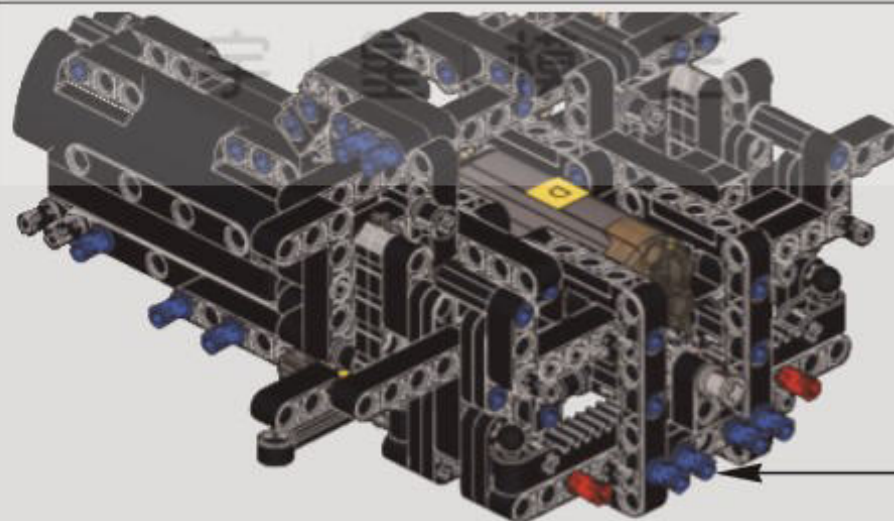
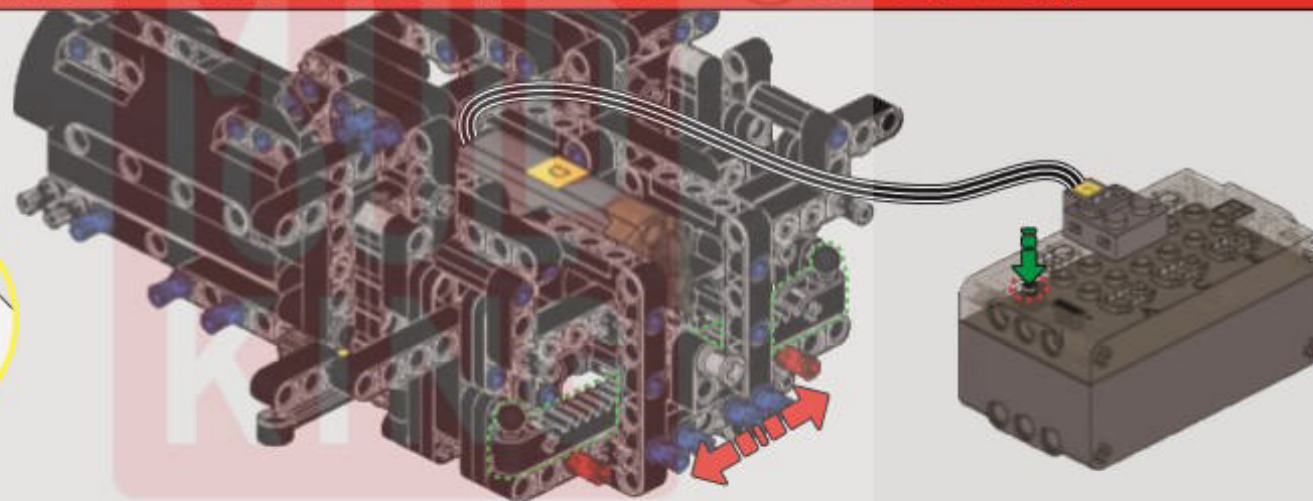
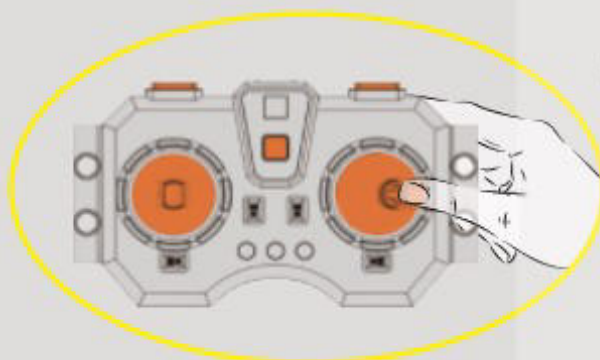
Stecken Sie das Motorkabel in das Modul, schalten Sie das Modul ein und verbinden Sie die Fernbedienung. Bewegen Sie den rechten Joystick nach links und rechts (D-Kanal), um zu testen, ob das Zahnstangengetriebe horizontal bewegt werden kann. Wenn dies nicht möglich ist, überprüfen Sie, ob die vorherigen Schritte richtig montiert wurden. Nach dem Test trennen Sie das Kabel und schalten das Modul und die Fernbedienung aus.

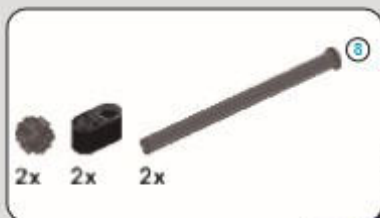
Insérez le fil du moteur dans le module, allumez le module et connectez la télécommande. Déplacez le joystick droit de gauche à droite (canal D) pour tester si la crémaillère peut se déplacer horizontalement. Si ce n'est pas le cas, veuillez vérifier si les étapes précédentes ont été correctement assemblées. Après les tests, déconnectez le fil et éteignez le module et la télécommande.

Inserisci il filo del motore nel modulo, accendi il modulo e collega il telecomando. Muovi la levetta destra da sinistra a destra (canale D) per testare se la cremagliera può muoversi orizzontalmente. Se non è possibile, controlla se i passaggi precedenti sono stati assemblati correttamente. Dopo il test, scollega il filo e spegni il modulo e il telecomando.

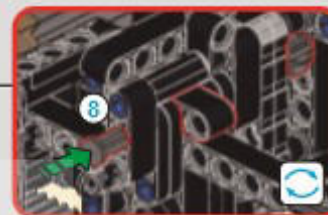
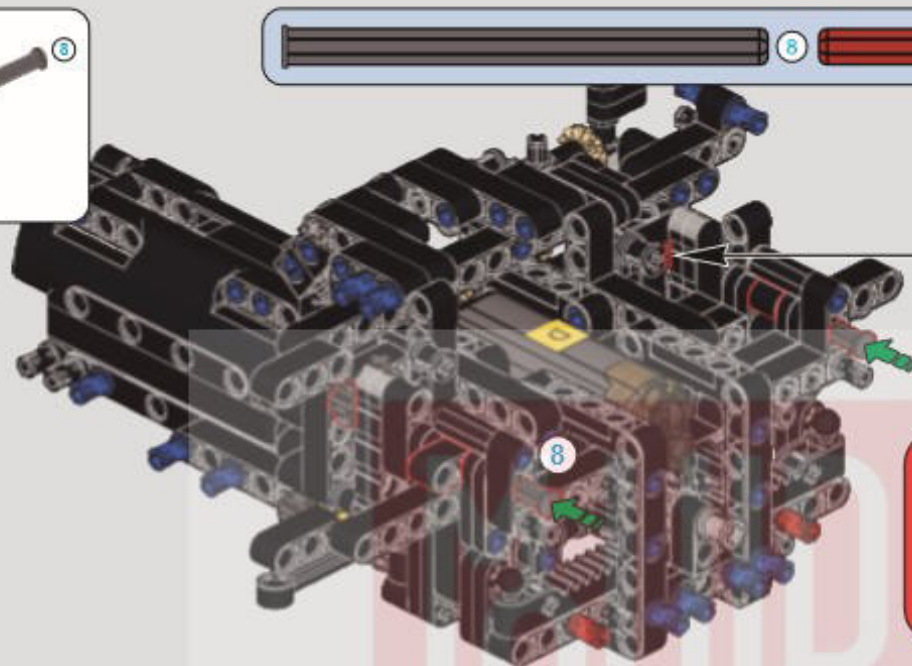
Inserte el cable del motor en el módulo, encienda el módulo y conecte el control remoto. Mueva el joystick derecho hacia la izquierda y hacia la derecha (canal D) para probar si el engranaje puede moverse horizontalmente. Si no puede, verifique si los pasos anteriores fueron ensamblados correctamente. Después de la prueba, desconecte el cable y apague el módulo y el control remoto.

モーターのワイヤーをモジュールに接続し、モジュールを起動してリモコンを接続します。リモコンの右ジョイスティックを左右に動かして（Dチャンネル）、ラックが水平に移動できるかテストします。移動できない場合は、前の手順が正しく組み立てられているか確認してください。テスト後、ワイヤーを抜いてモジュールとリモコンをオフにします。





67

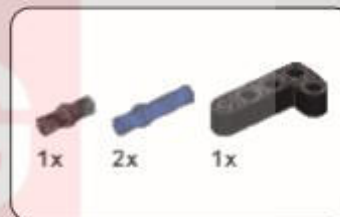
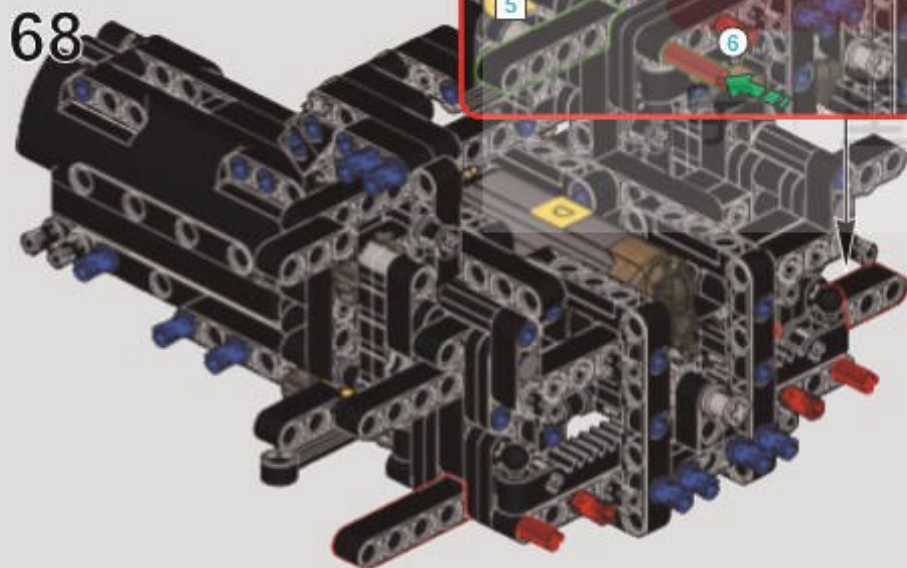


1:1

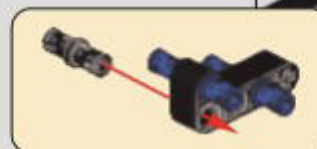
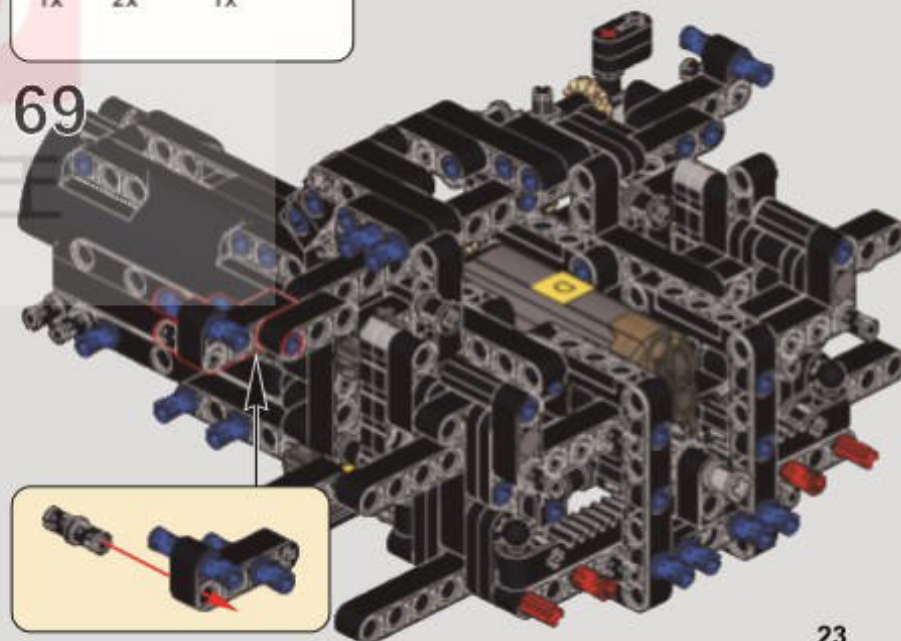
Rameno s otvorem pro čep by mělo být instalováno vodorovně.
The axle pin hole arm should be installed horizontally.
Der Achsstiftlocharm sollte horizontal eingebaut werden.
Le bras de trou d'axe doit être installé horizontalement.
Il braccio del foro per perno d'asse deve essere installato orizzontalmente.
El brazo del orificio del pasador del eje debe instalarse horizontalmente.
軸ピン穴のアームは水平に取り付ける必要があります。



68

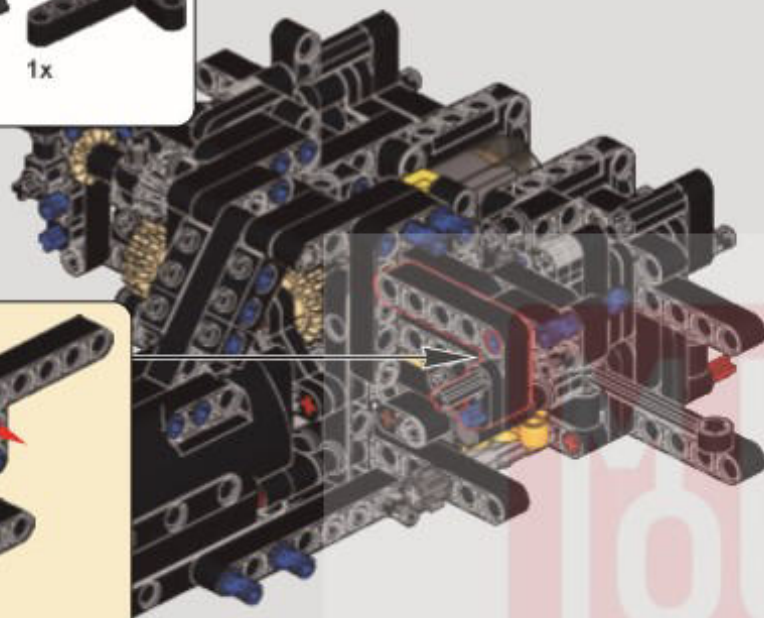
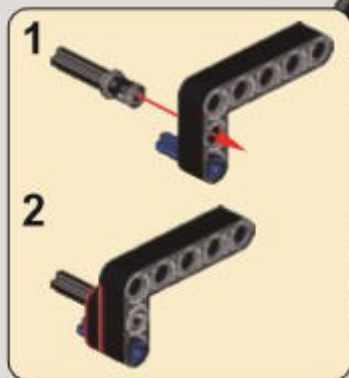


69

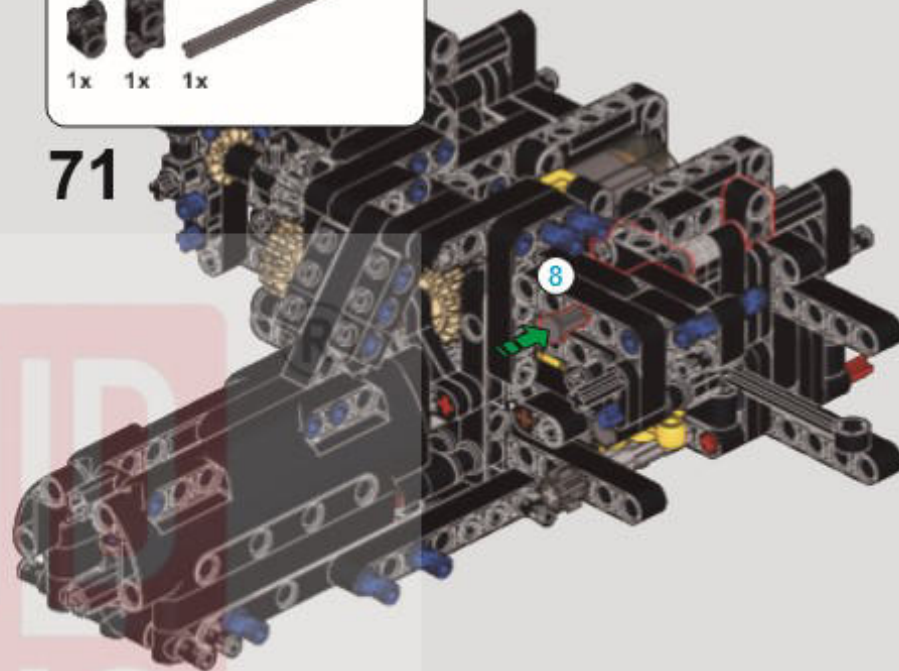




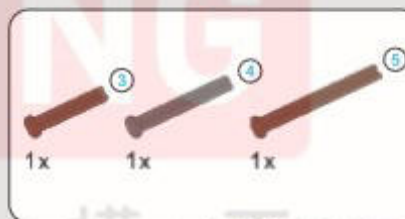
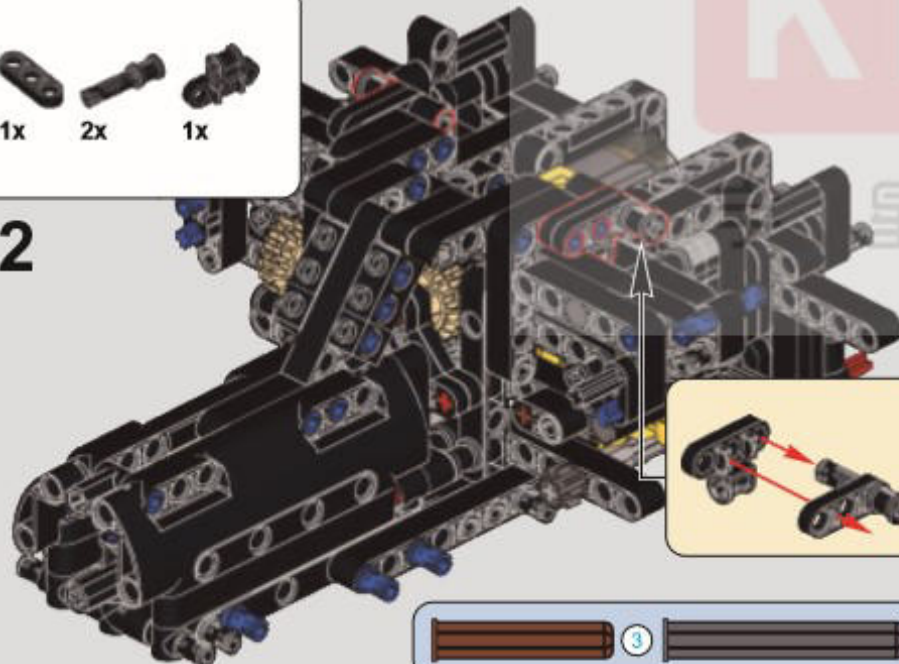
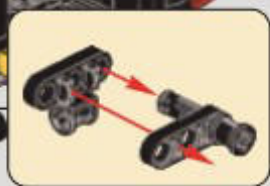
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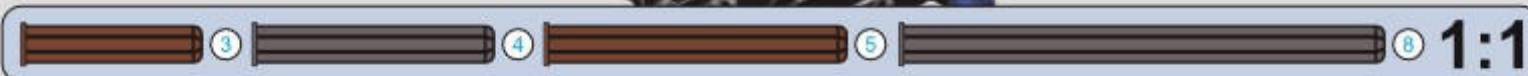
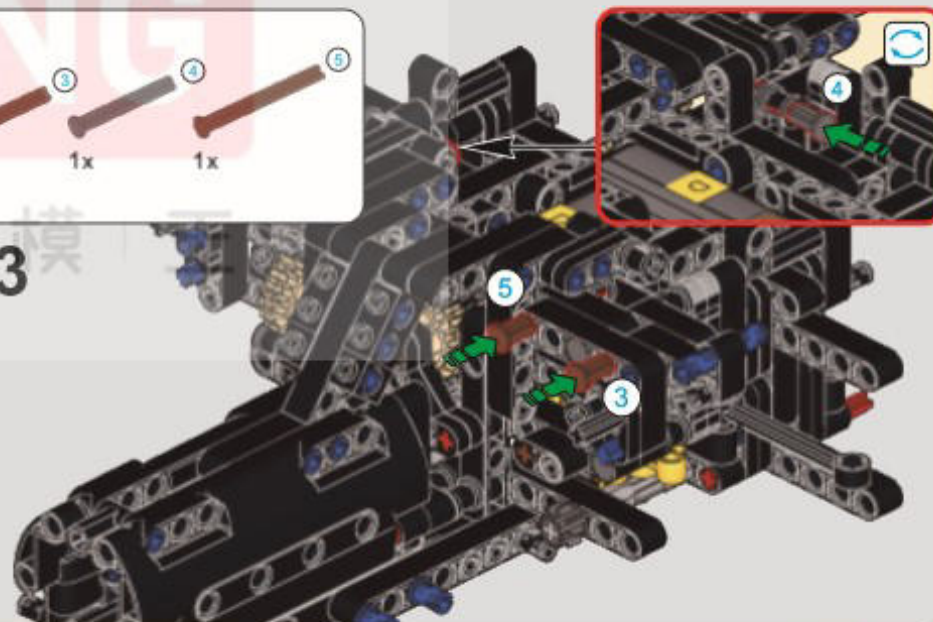
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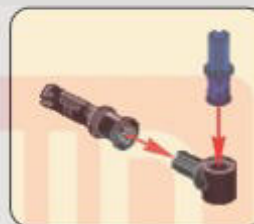
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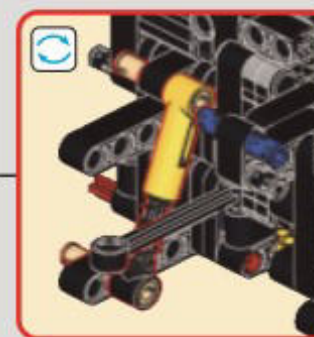
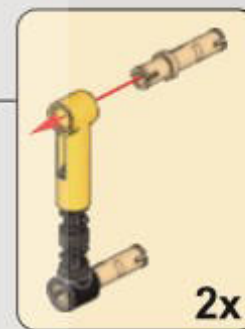
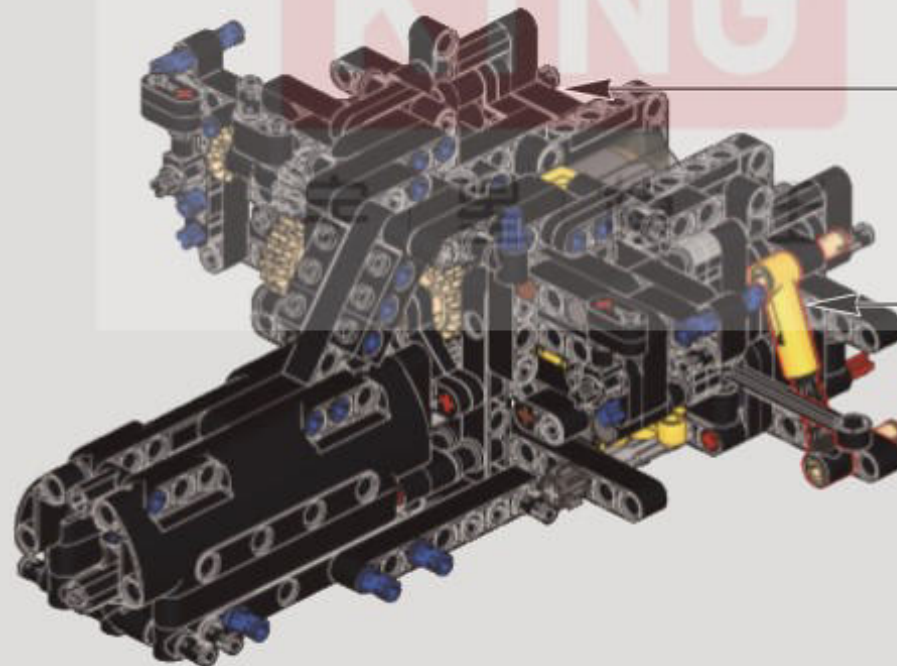
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75



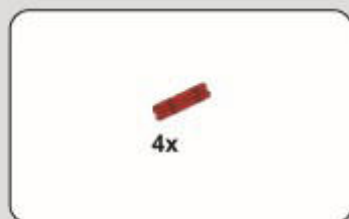
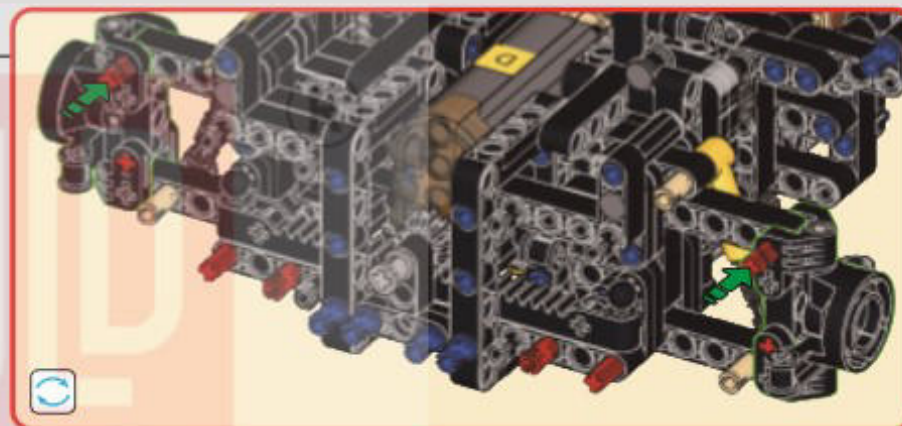
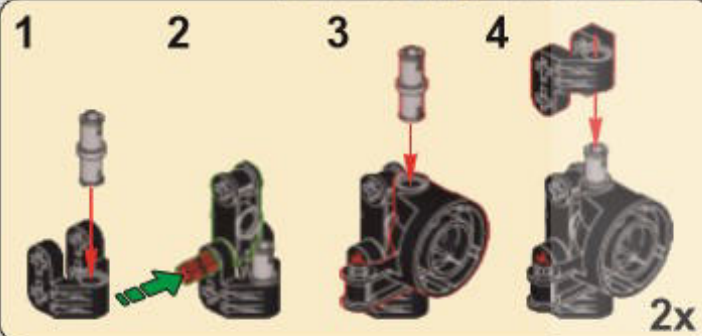
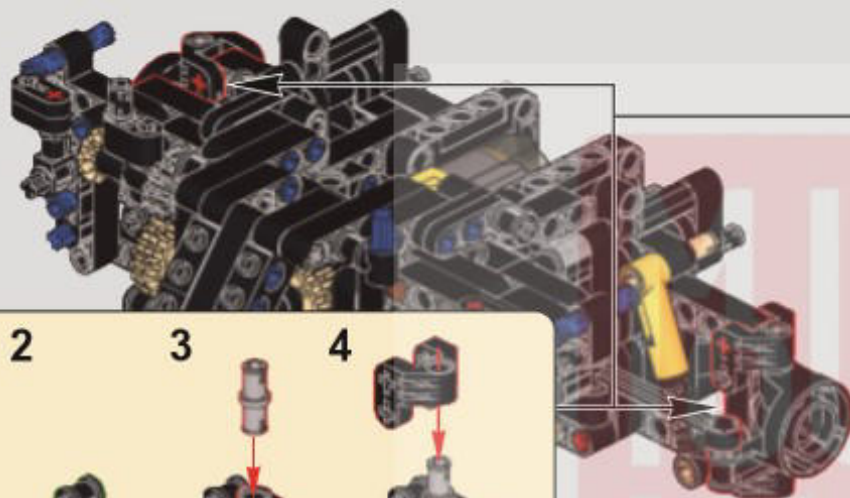
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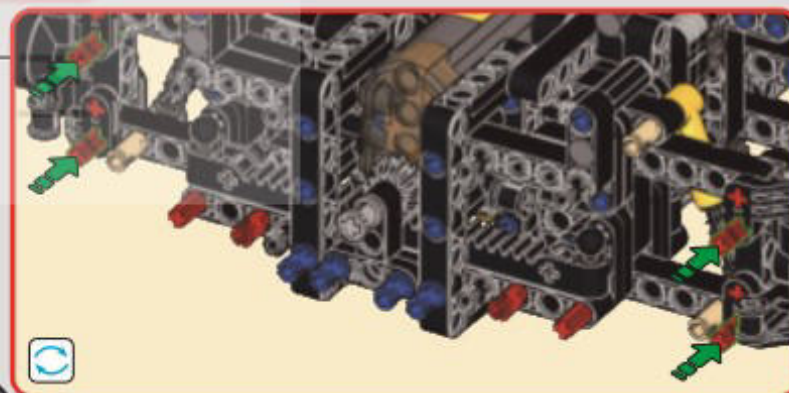
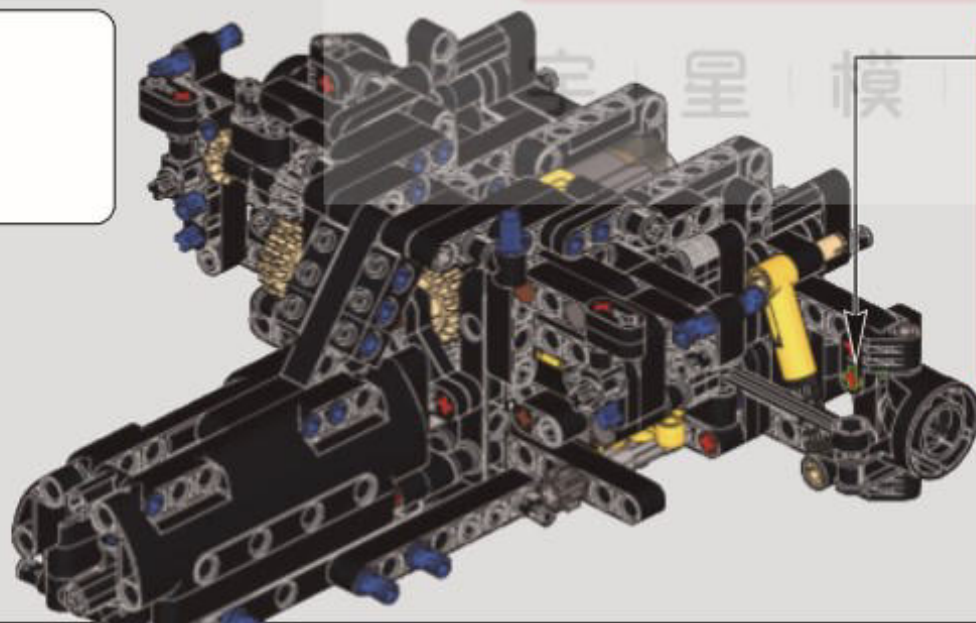
Tech. pin bez tření
(Technic Pin without Friction)



77

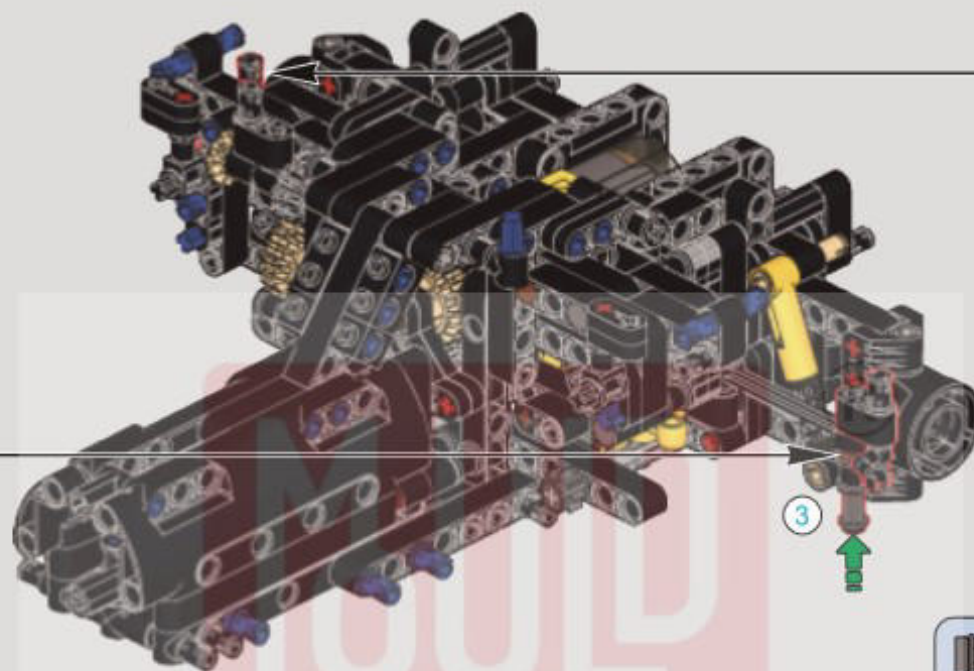
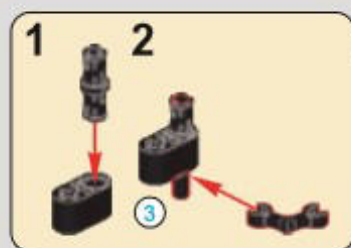


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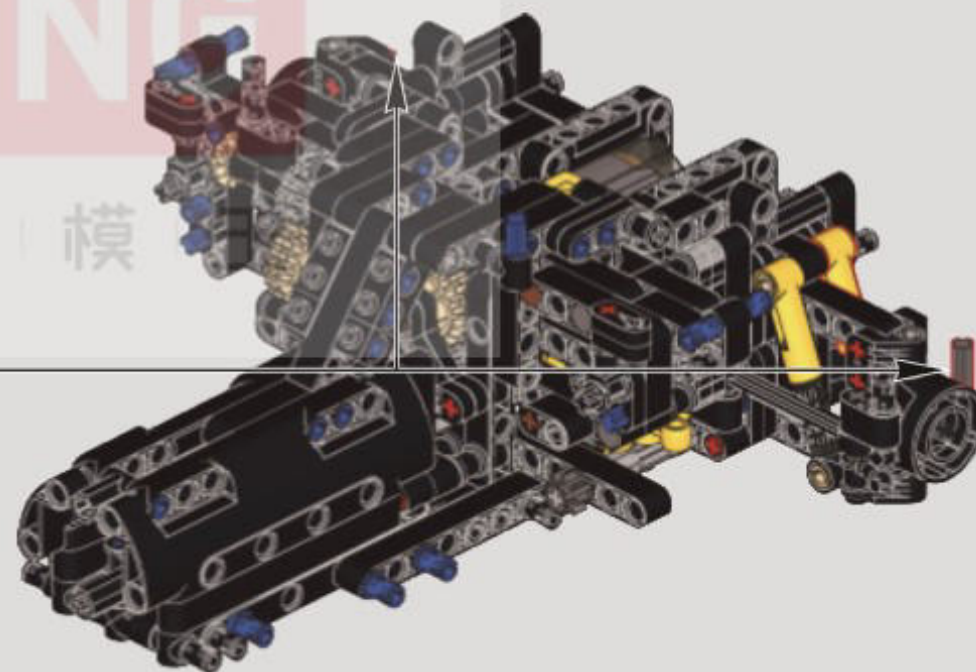
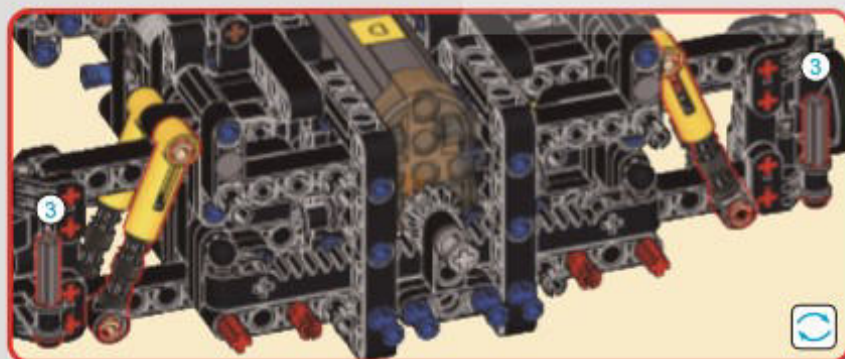


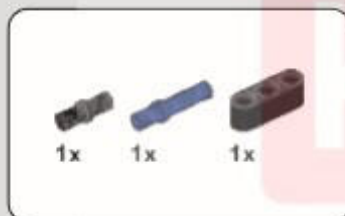
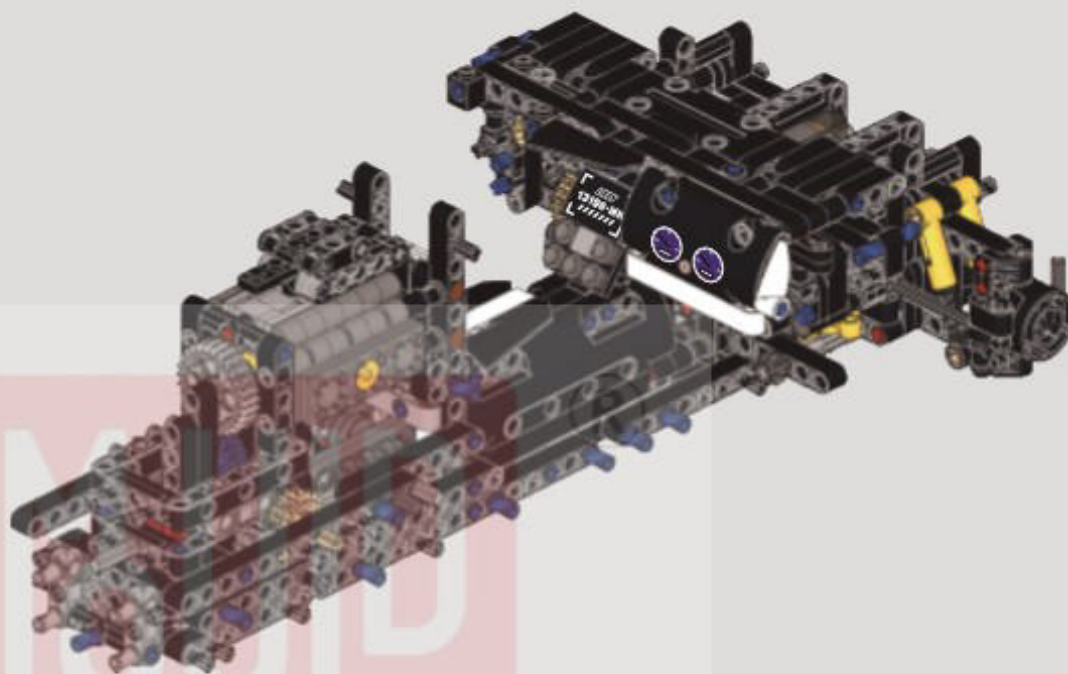


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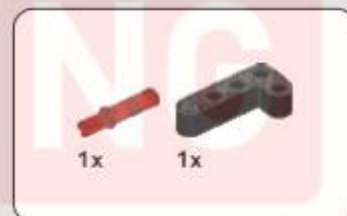


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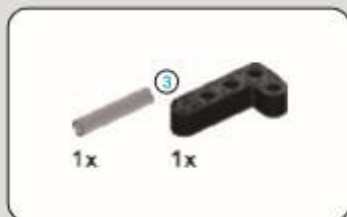
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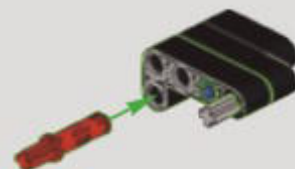
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84

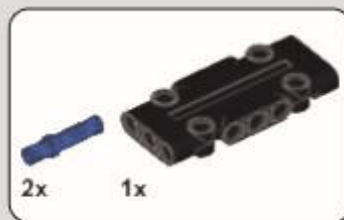


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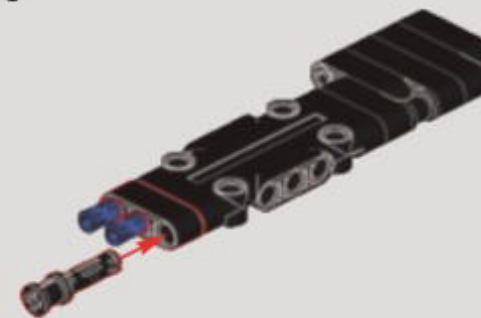
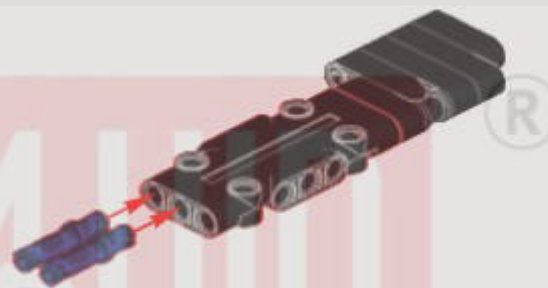
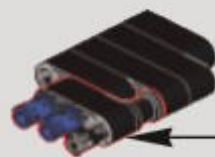
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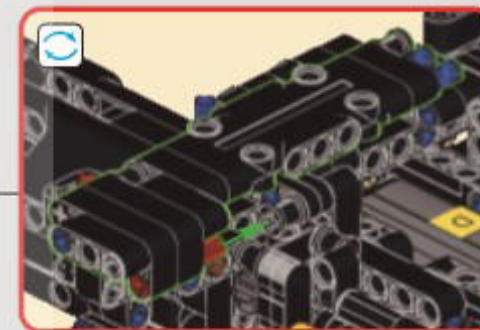
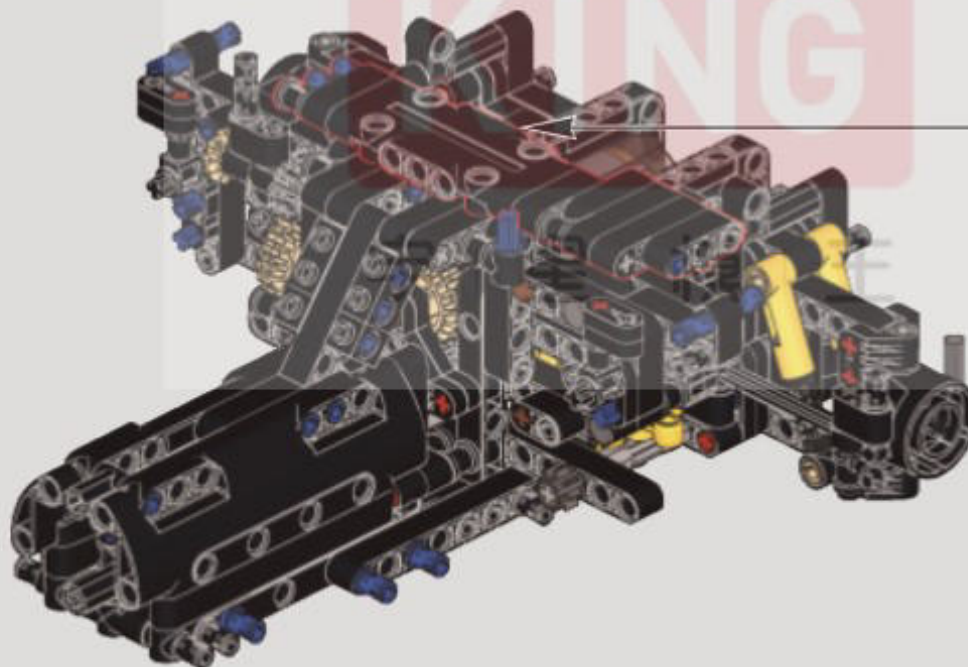
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87

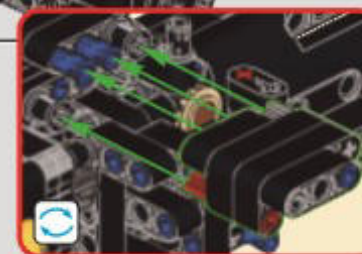
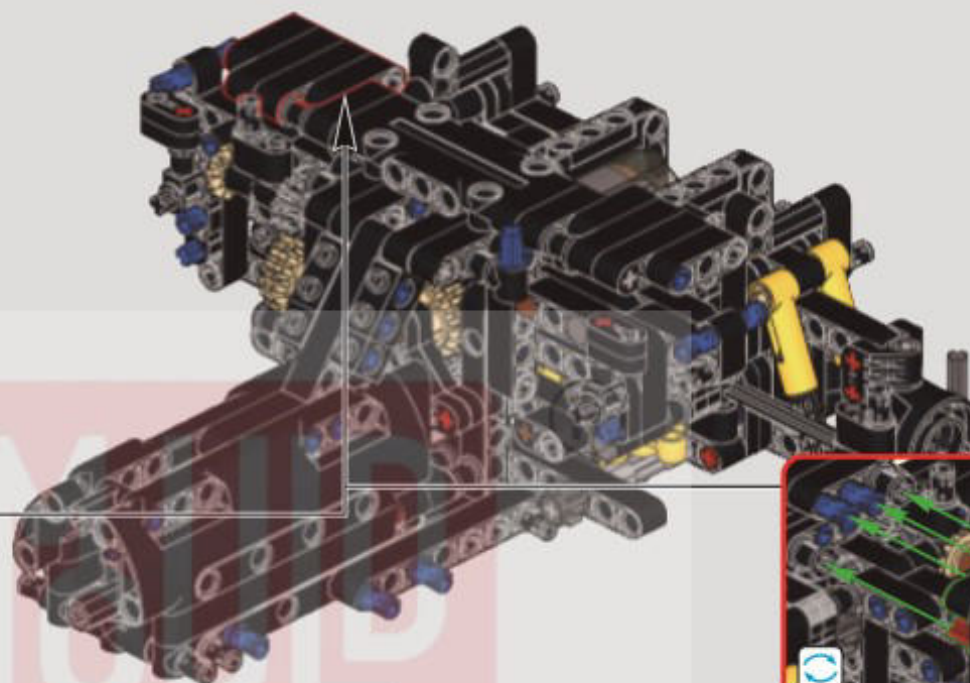
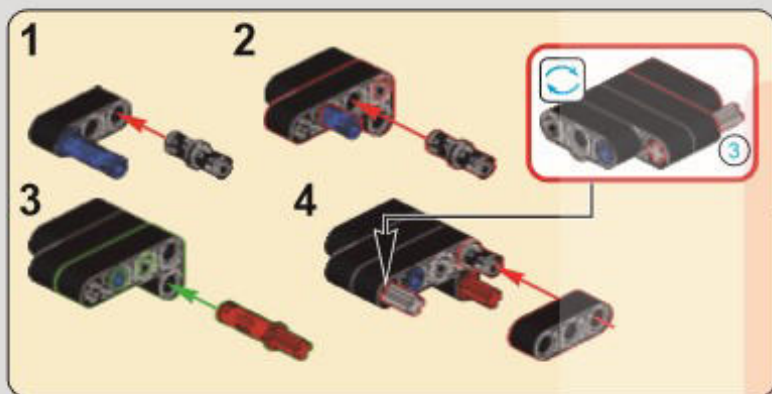


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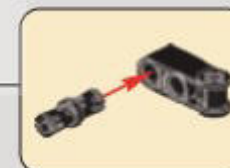
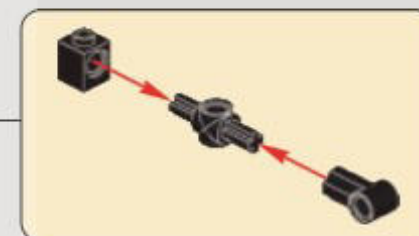
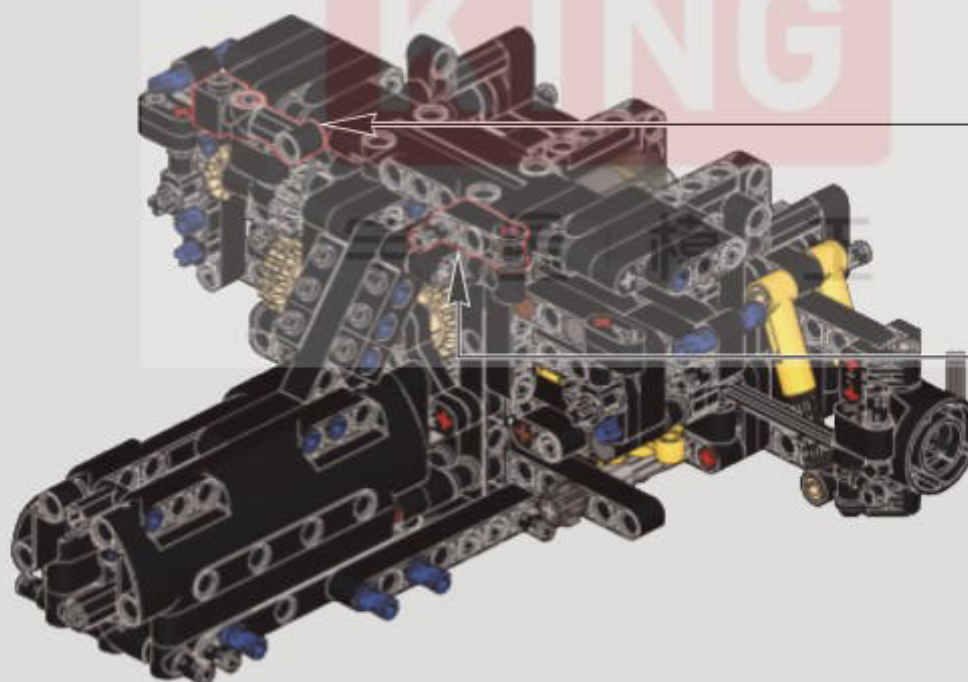




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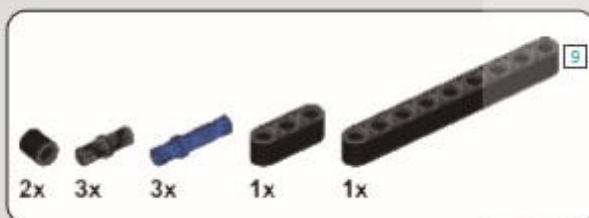
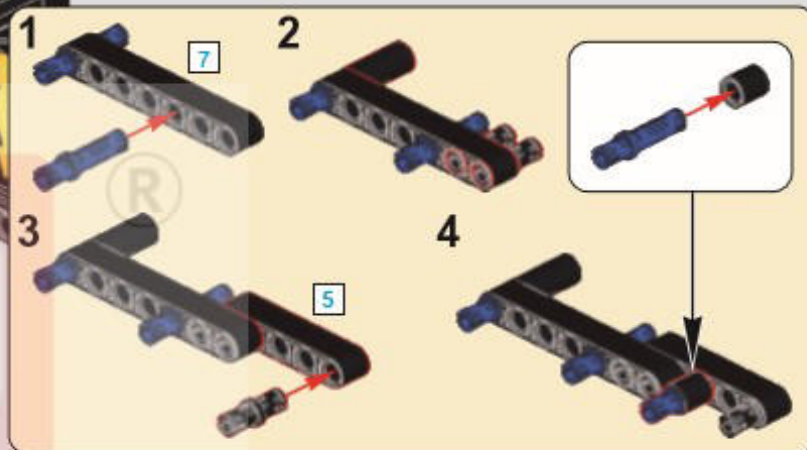
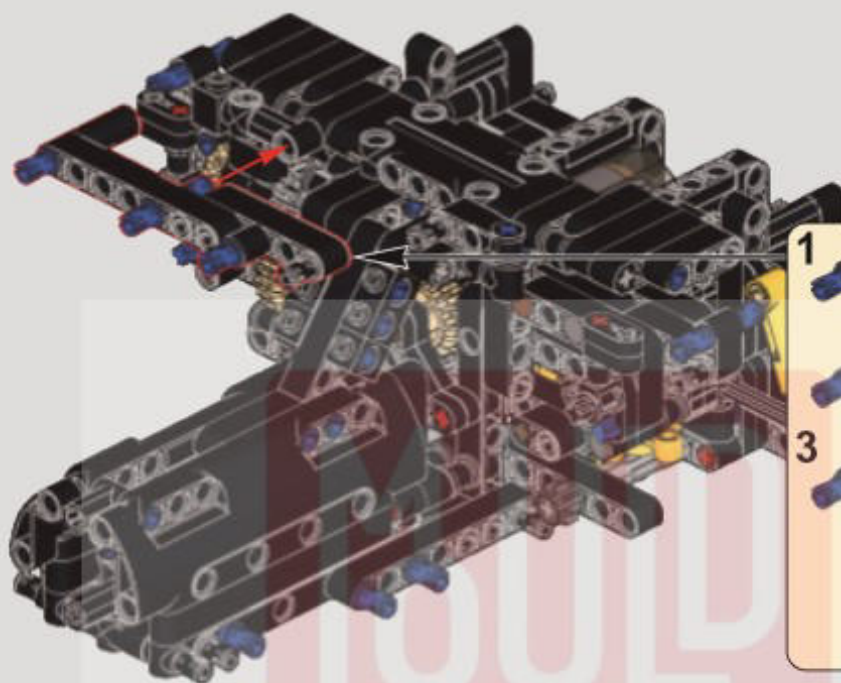


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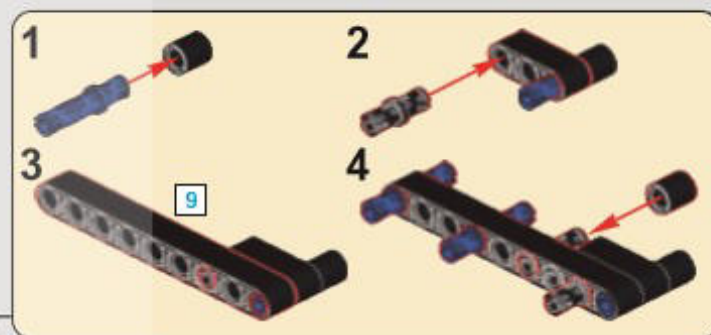
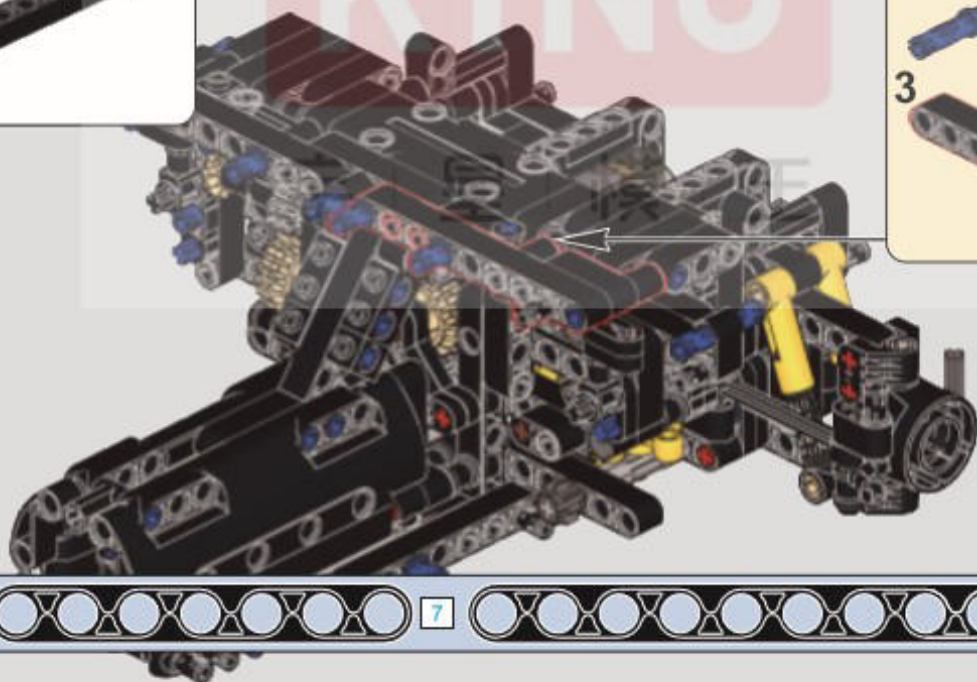




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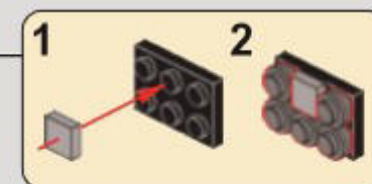
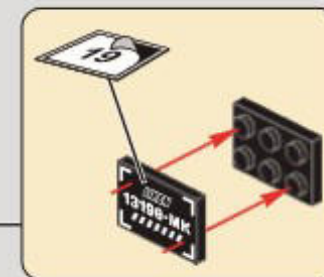
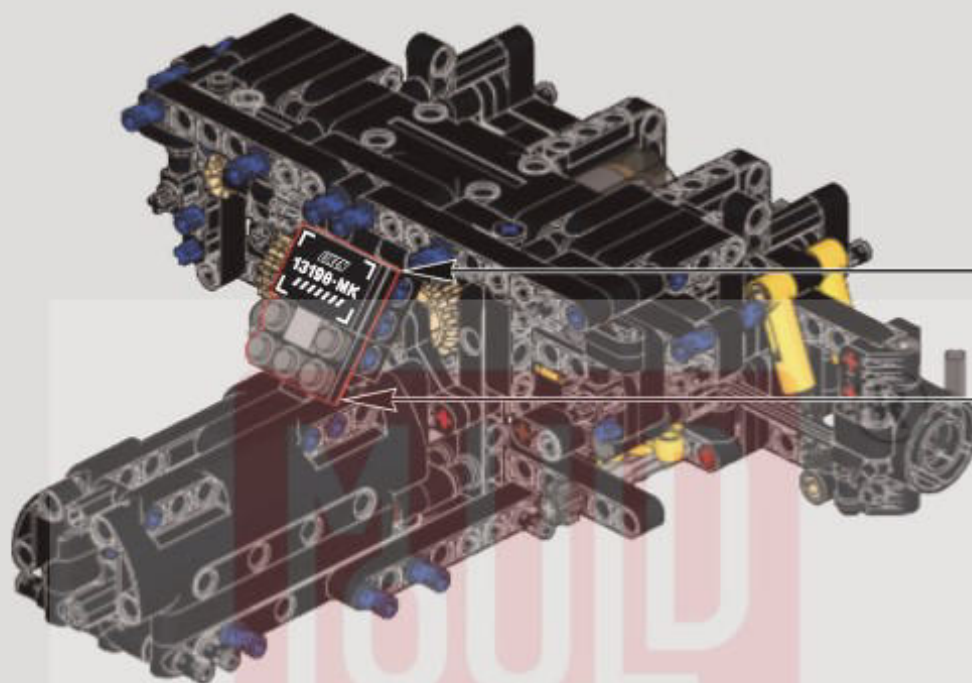


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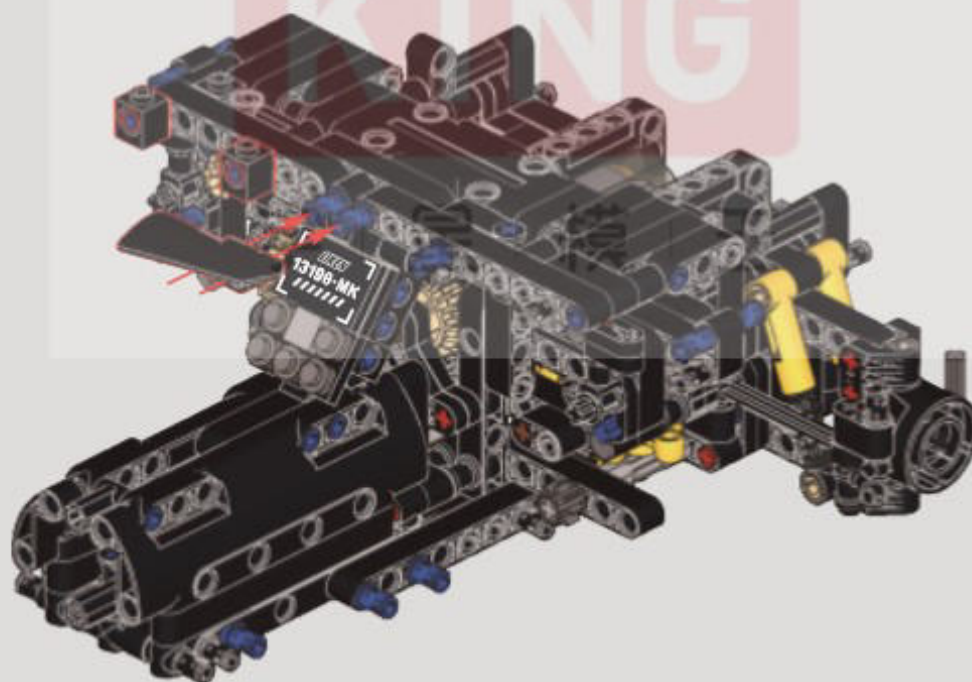


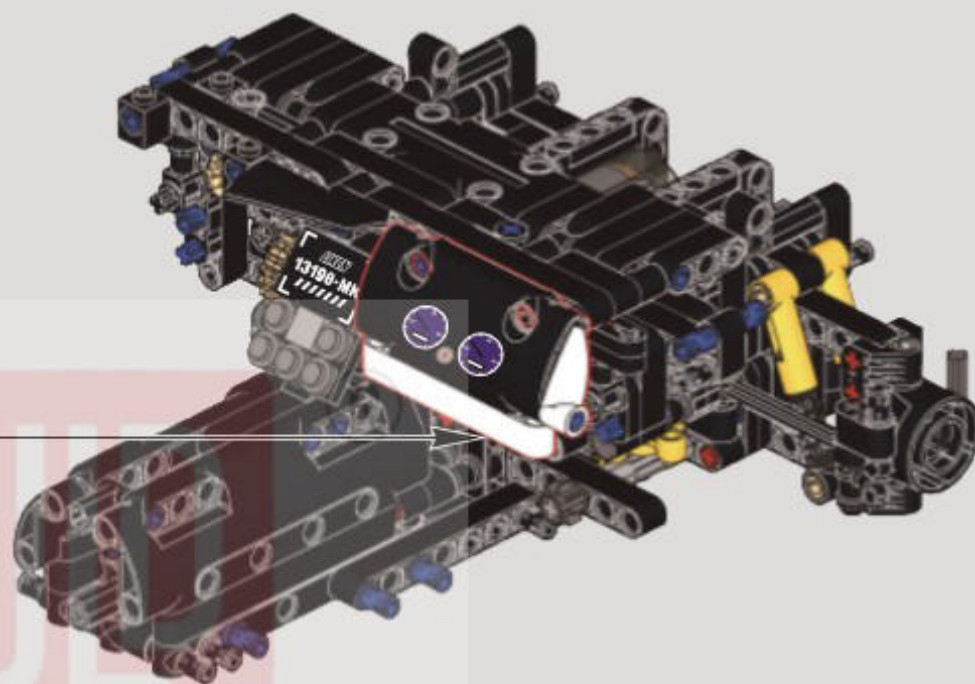


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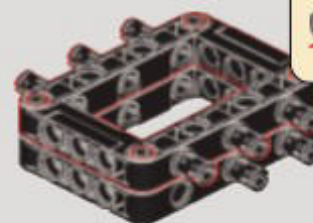
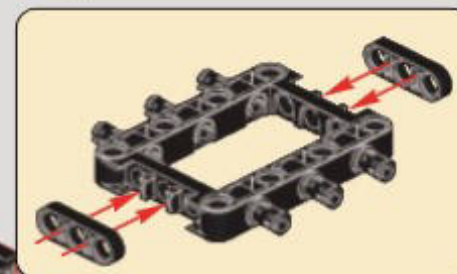
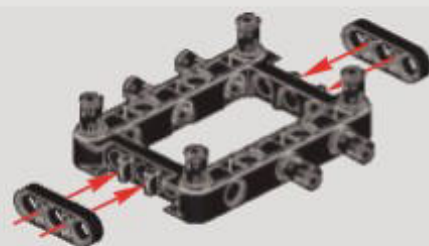
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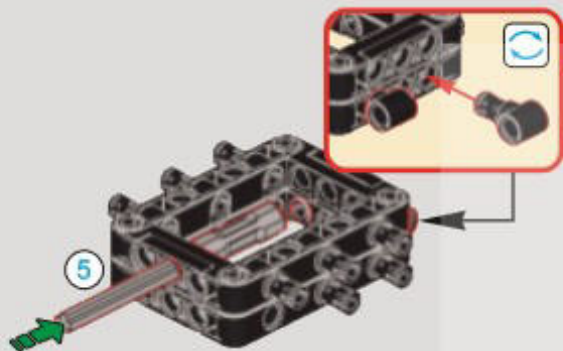
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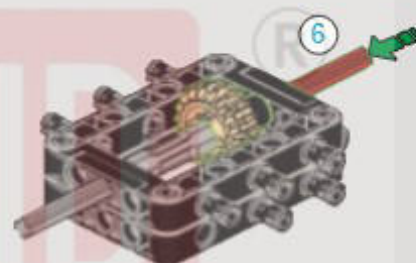




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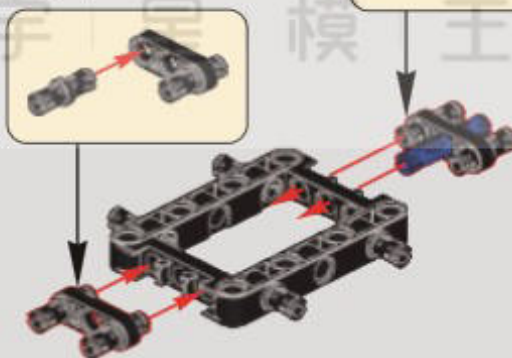
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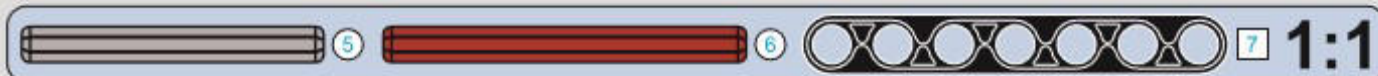
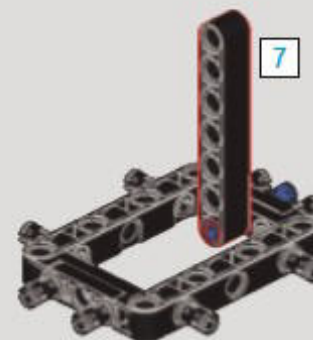
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101

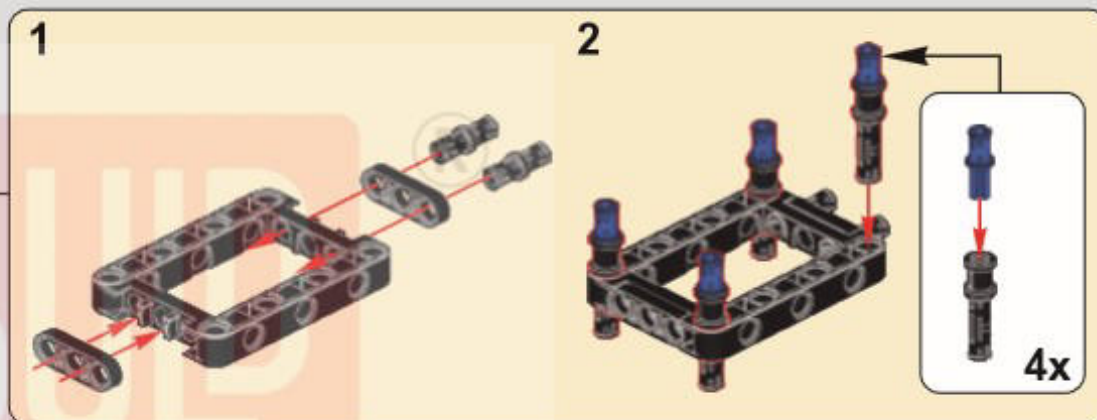
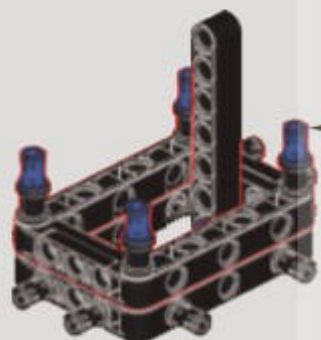


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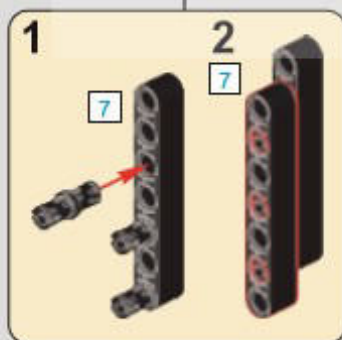
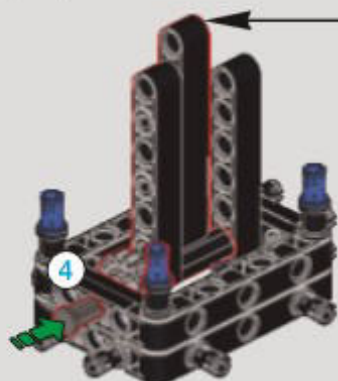




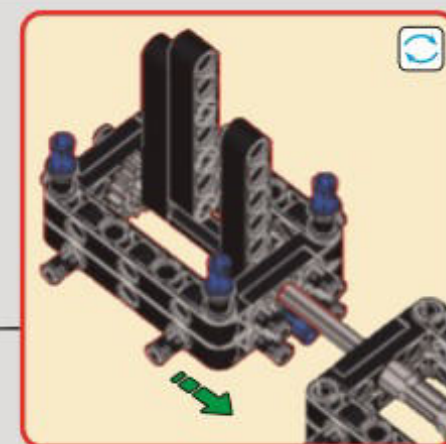
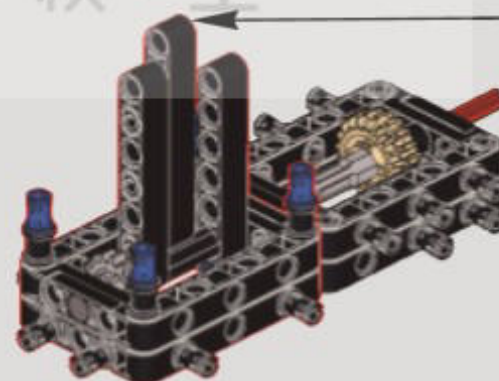
103



104

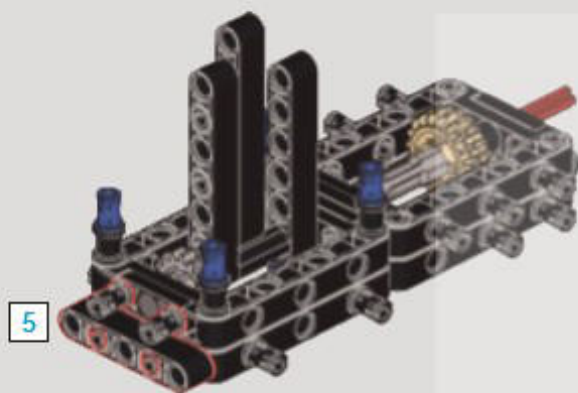


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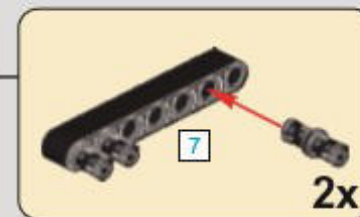
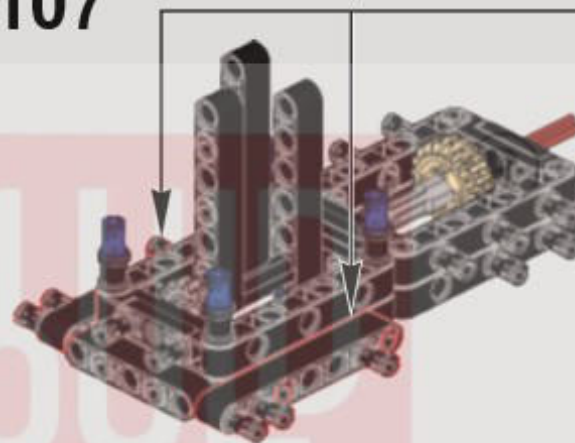




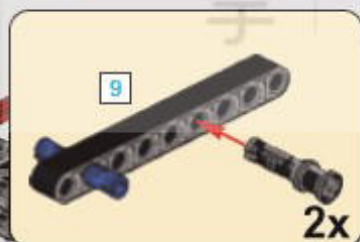
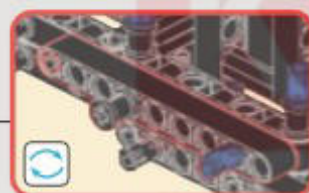
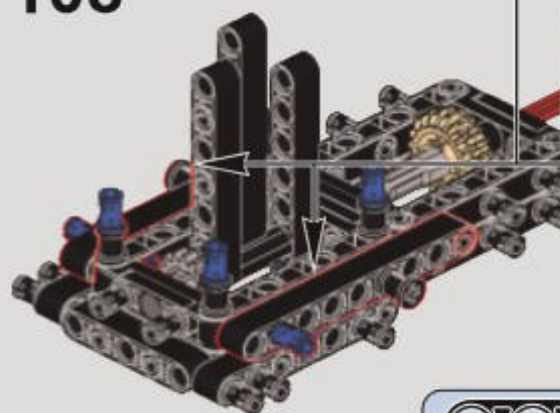
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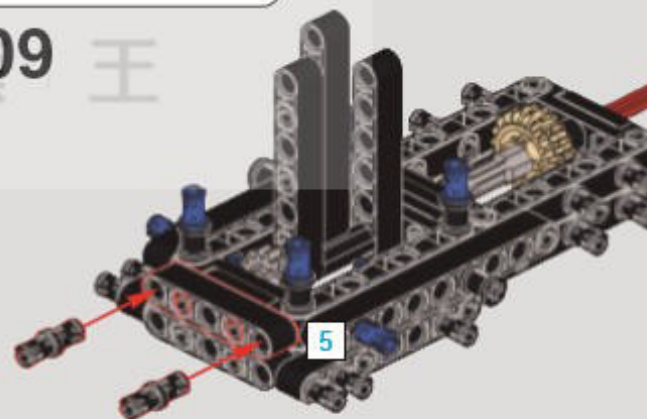
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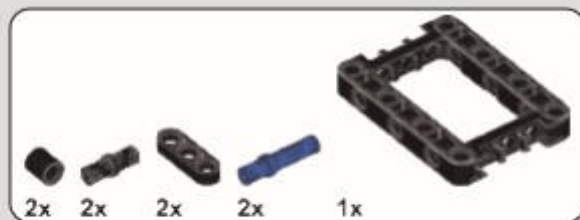


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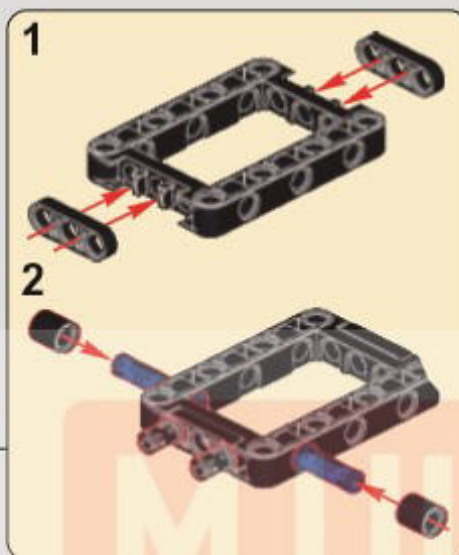
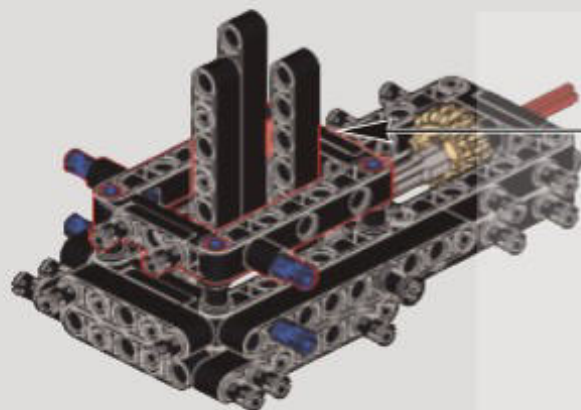


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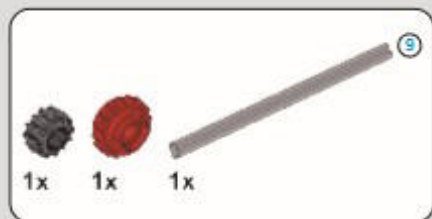
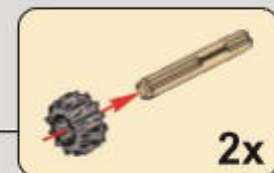
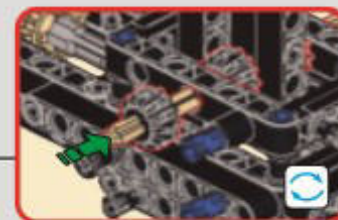
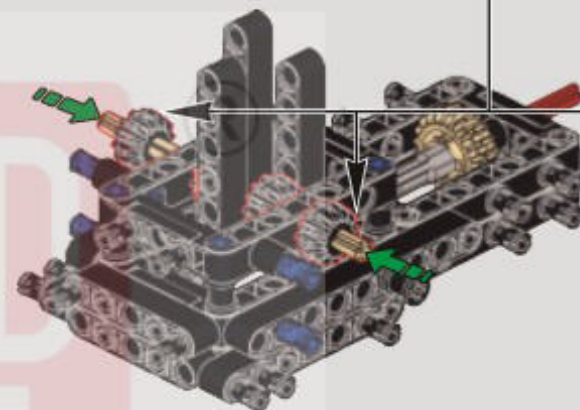




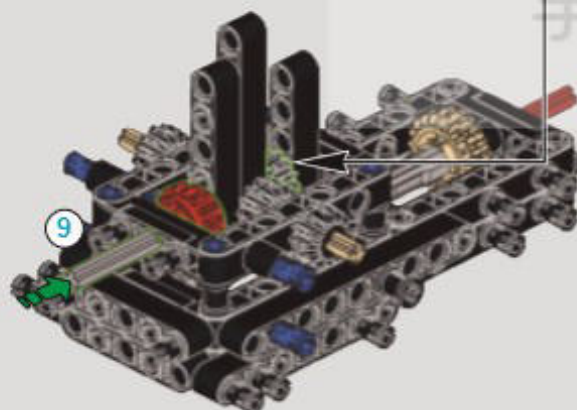
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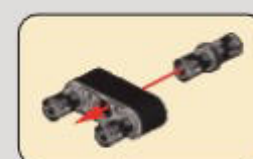
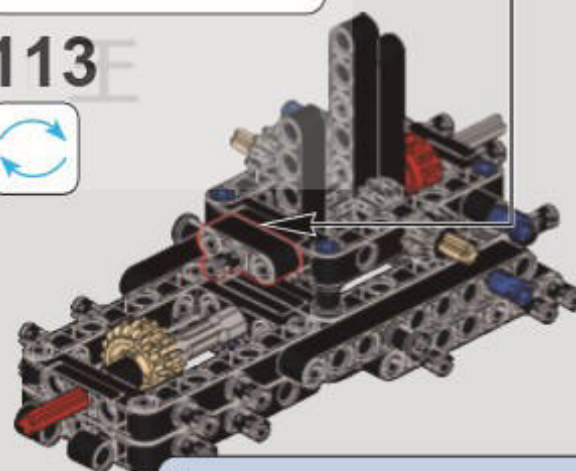
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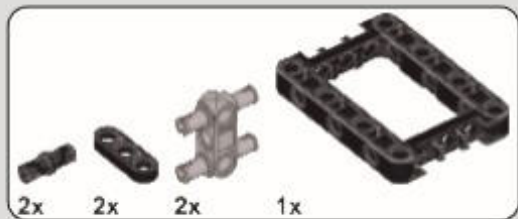


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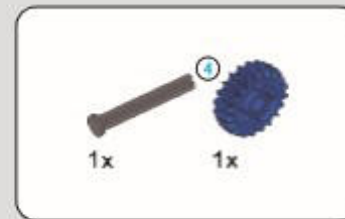
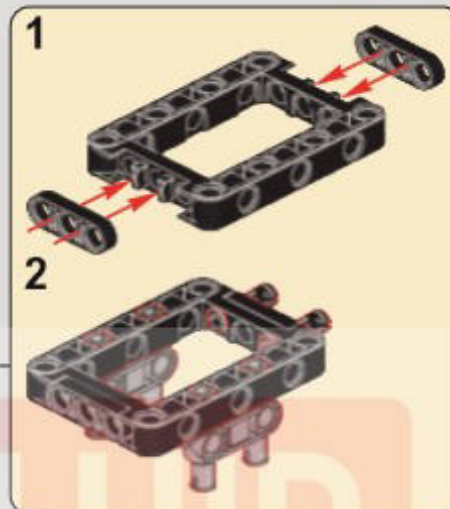
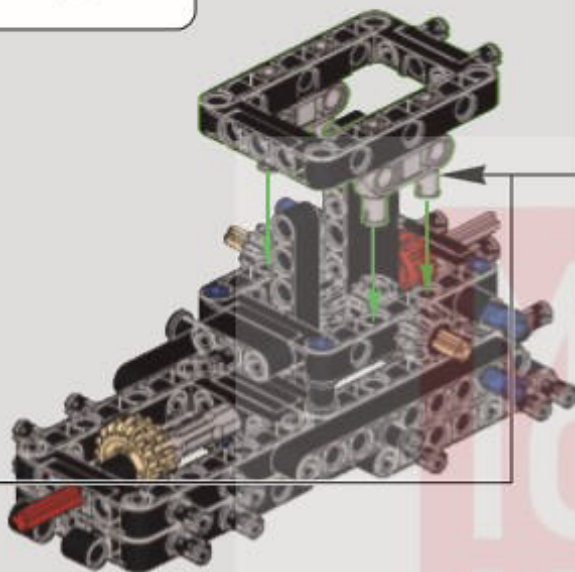
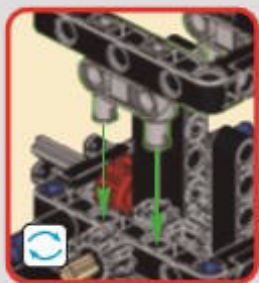


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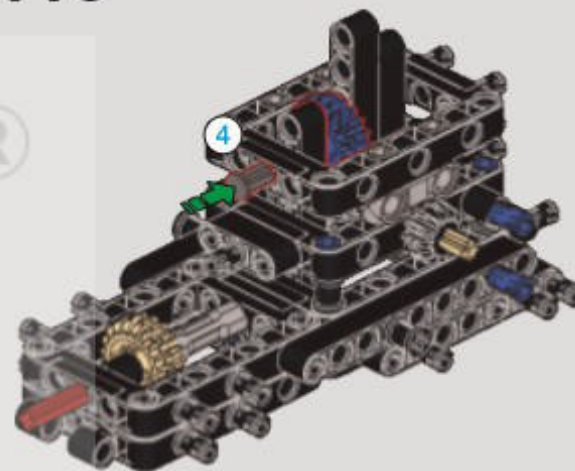




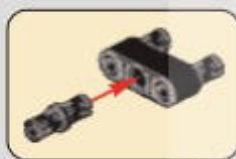
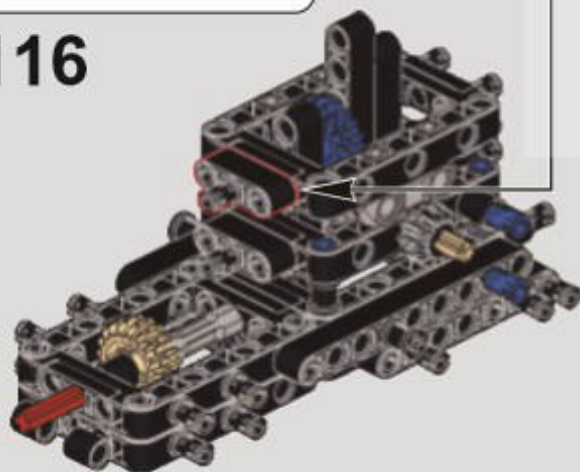
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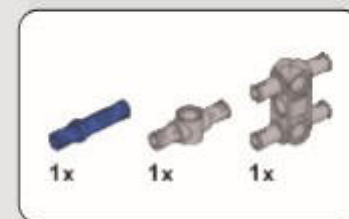
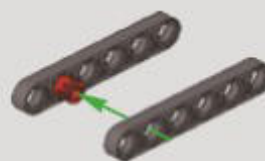
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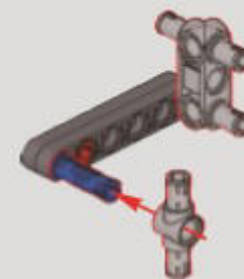
116



117

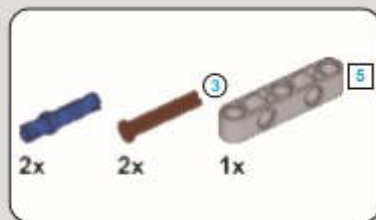


118





119

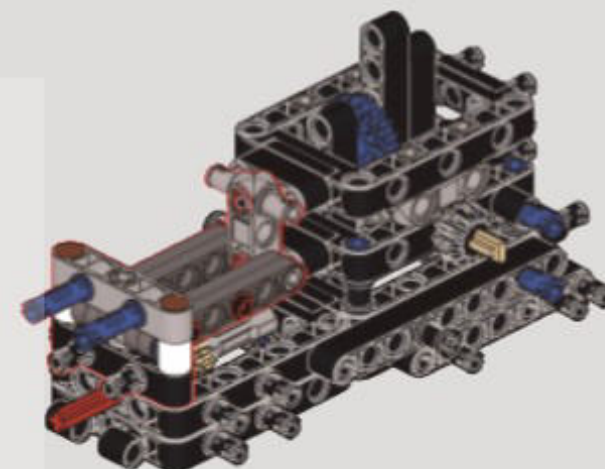
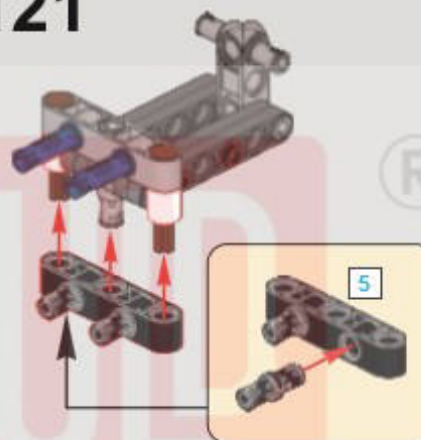
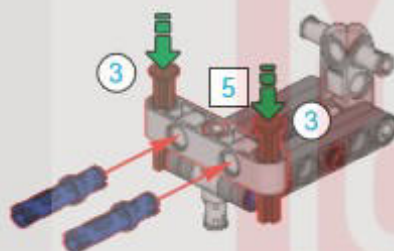
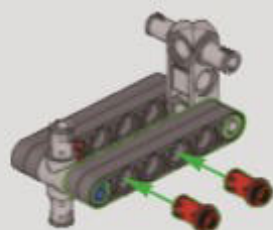


120



121

122



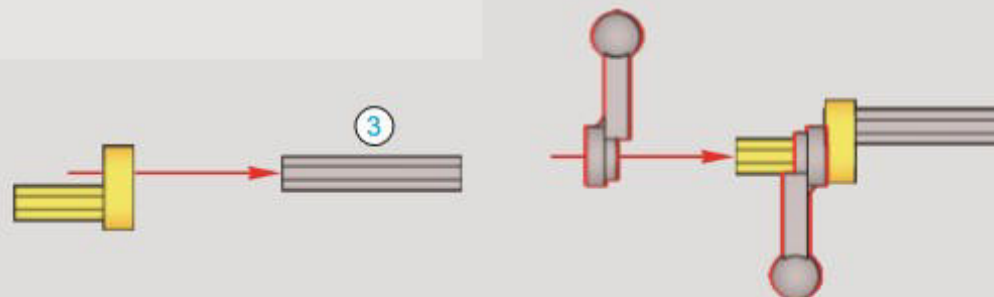
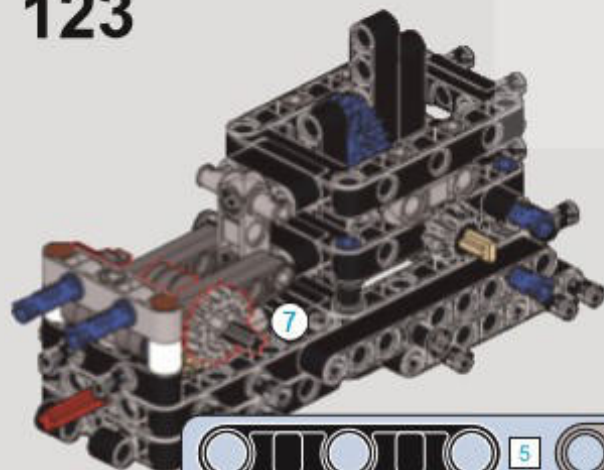
123



124

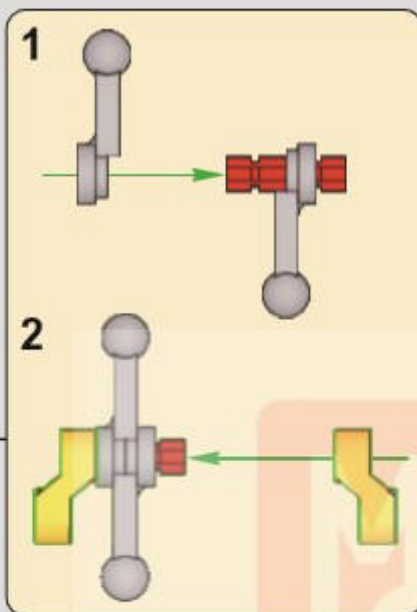


125

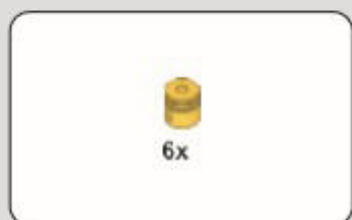
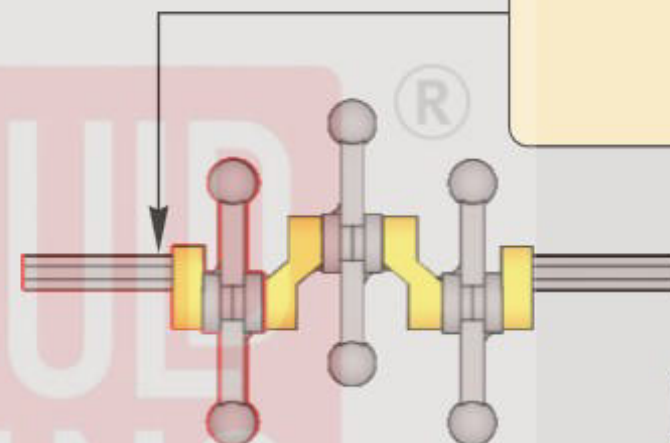
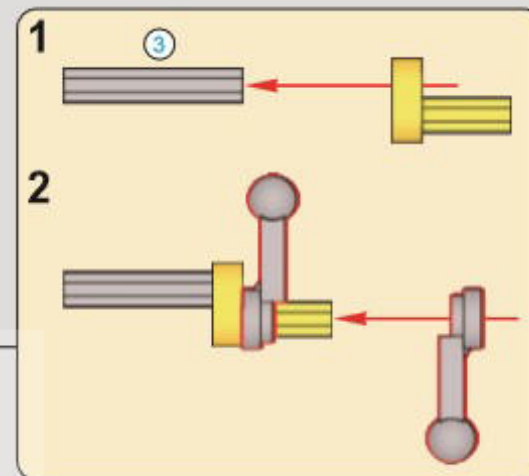




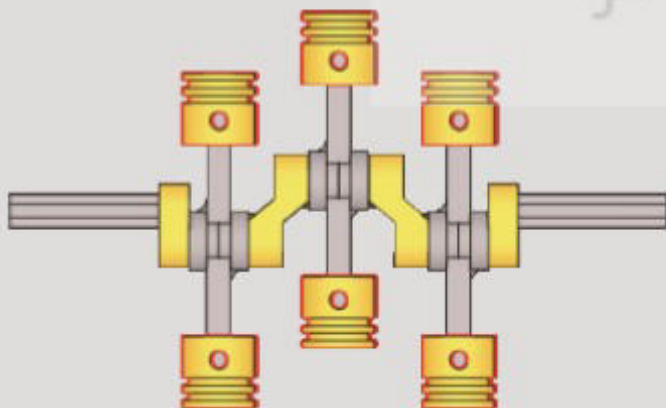
126



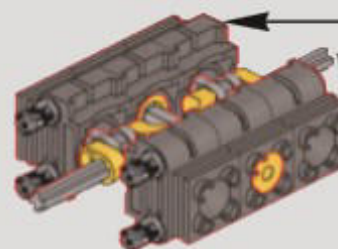
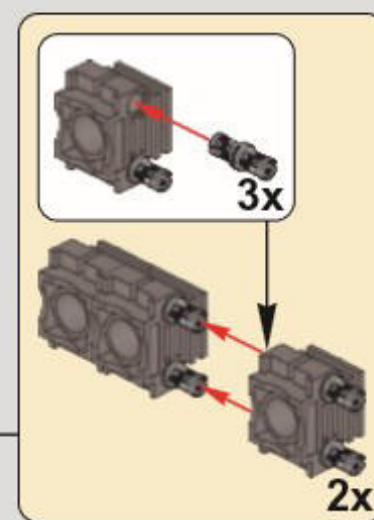
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128

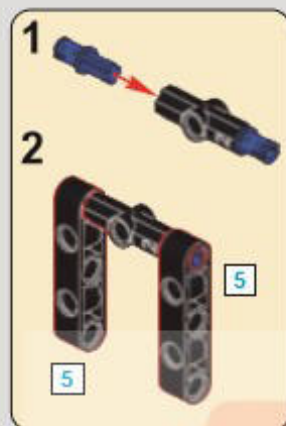
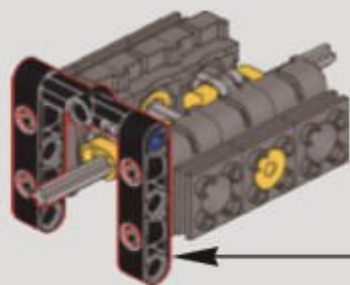


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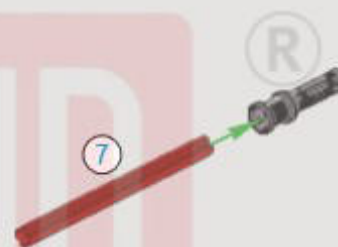




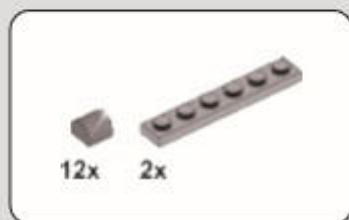
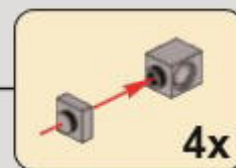
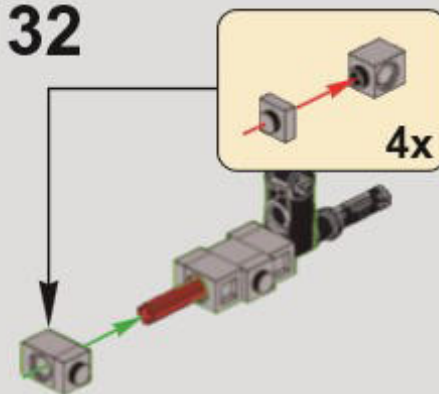
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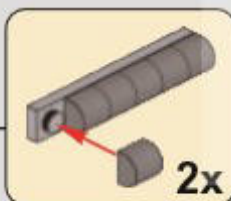
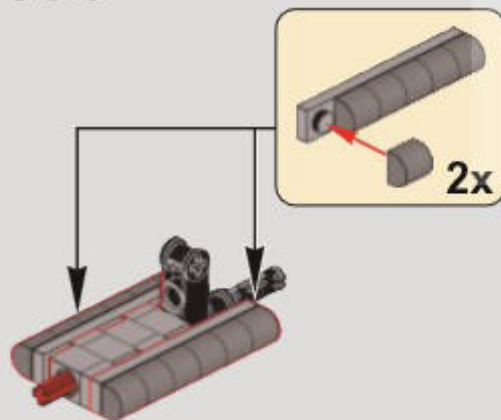
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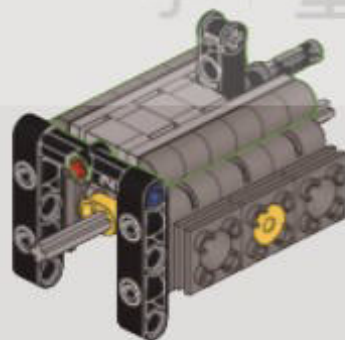
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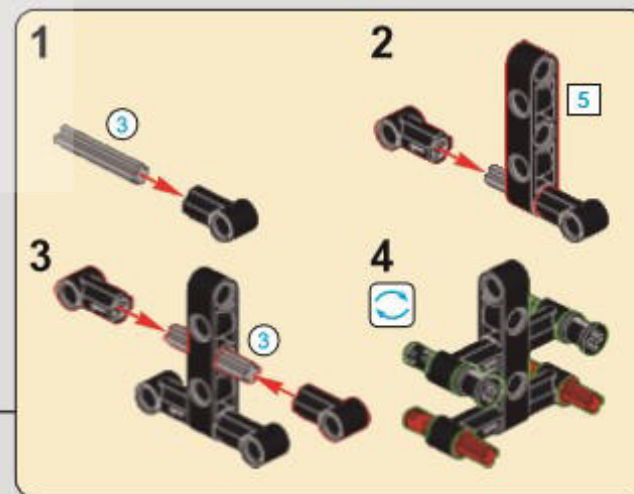
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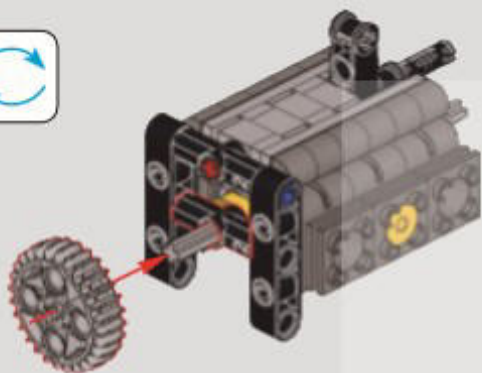


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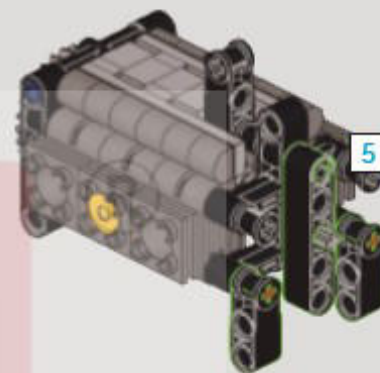




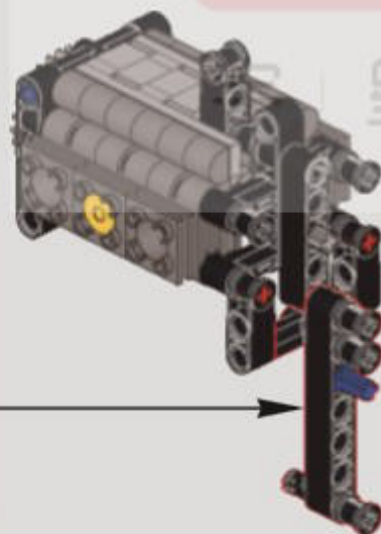
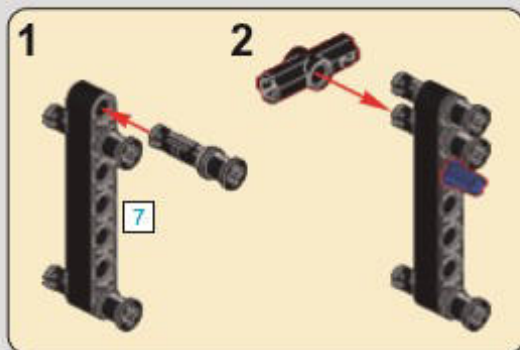
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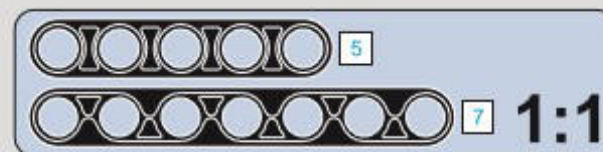
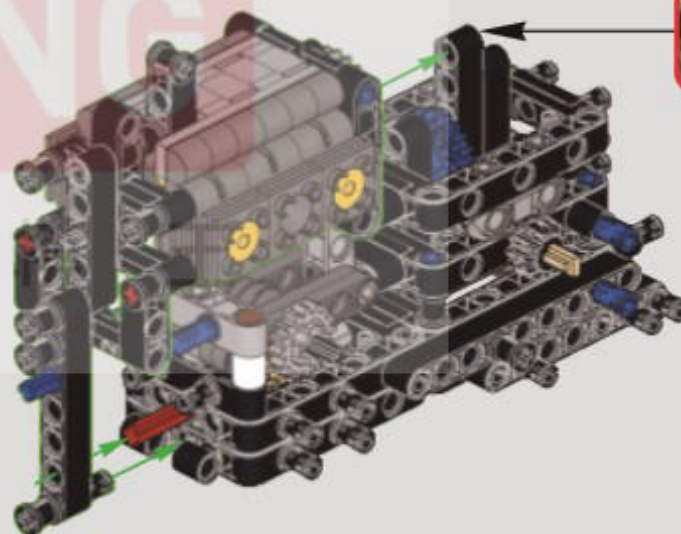
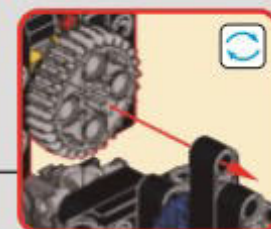
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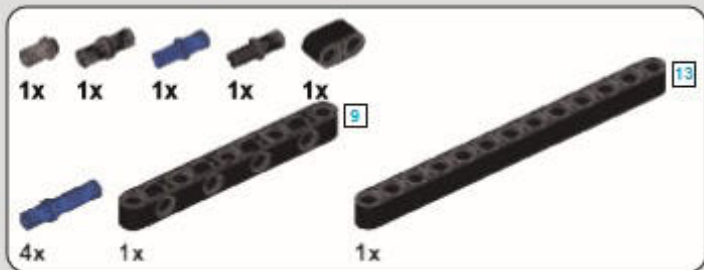


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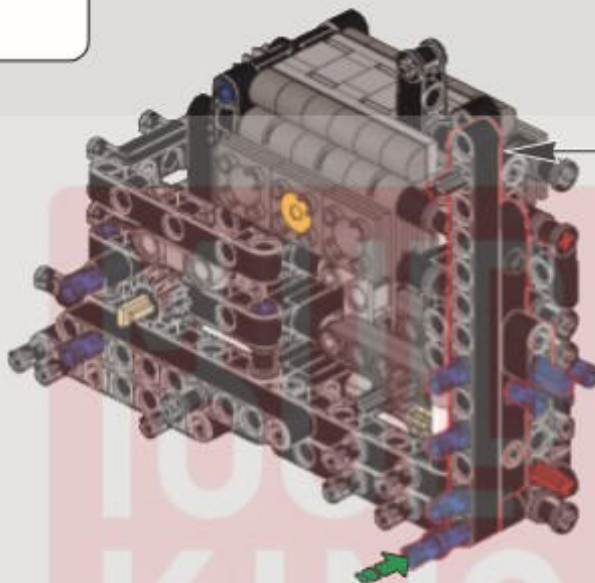
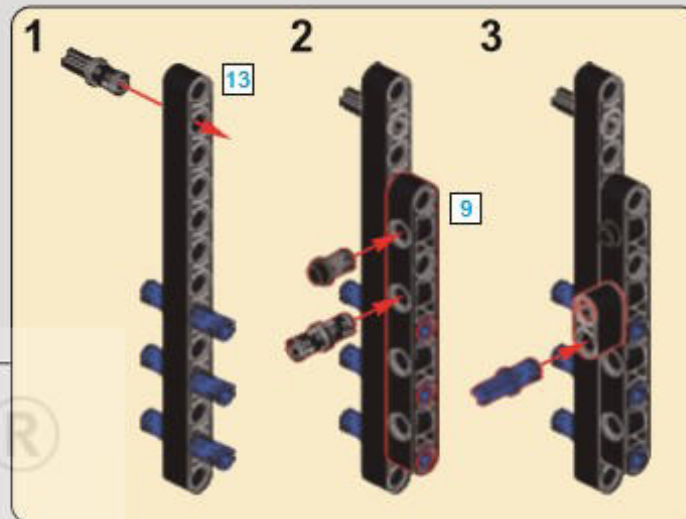


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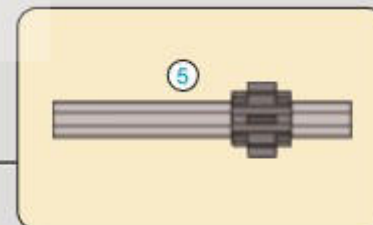
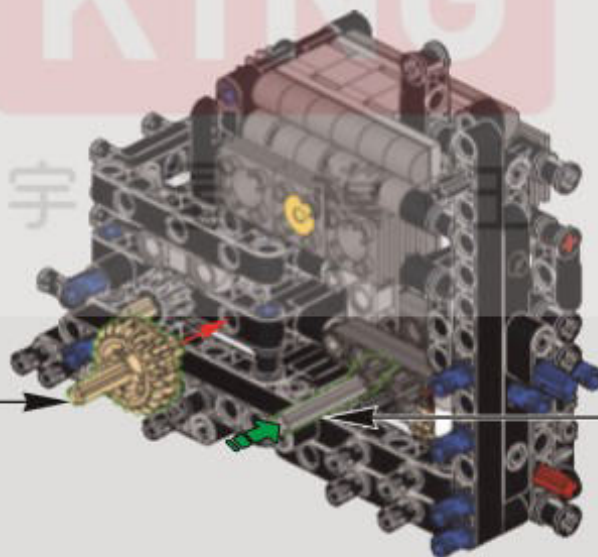
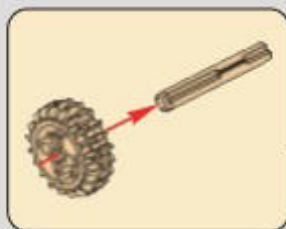


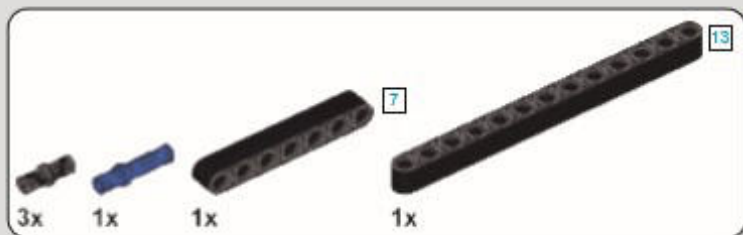


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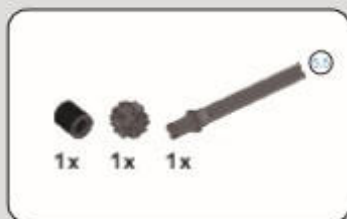
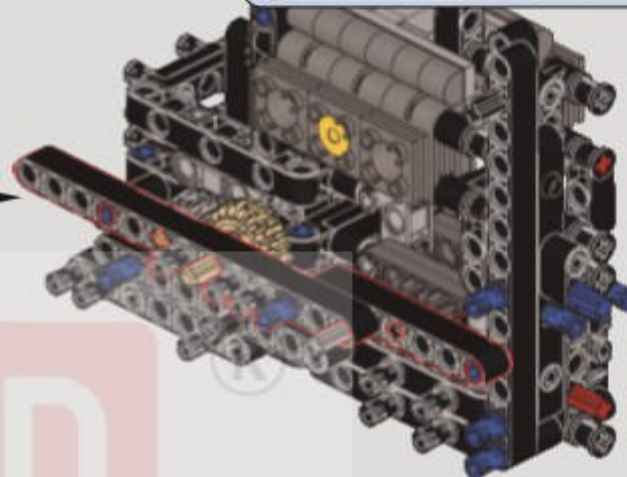


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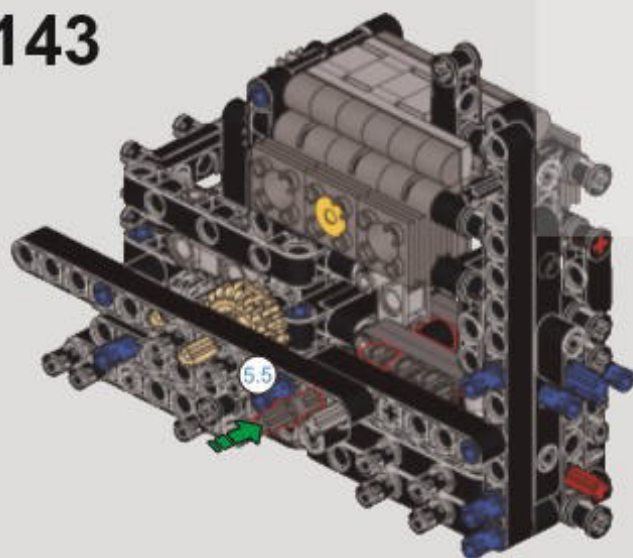




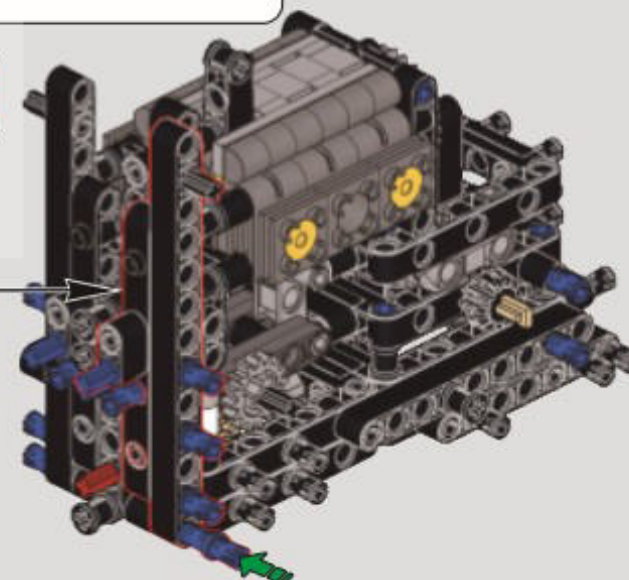
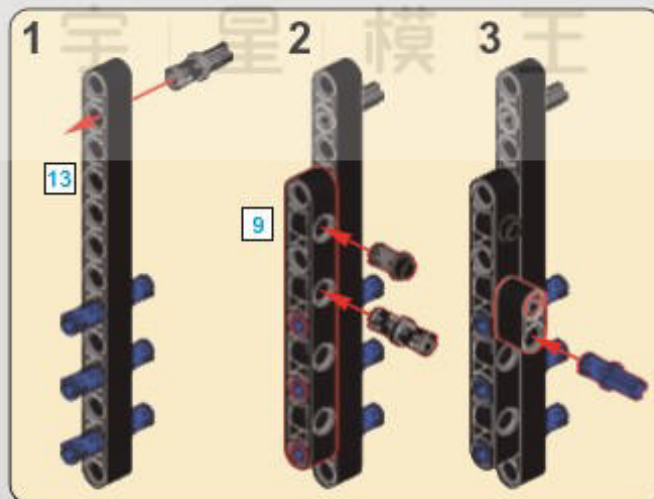
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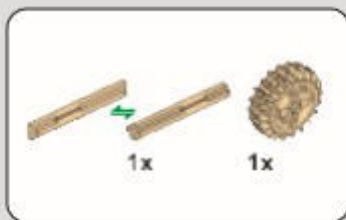


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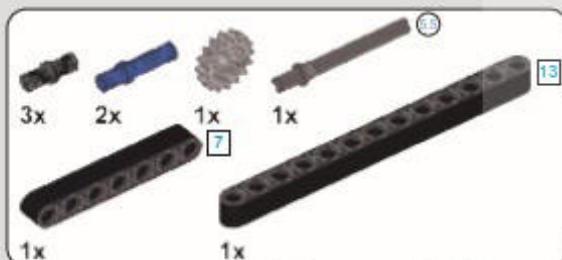
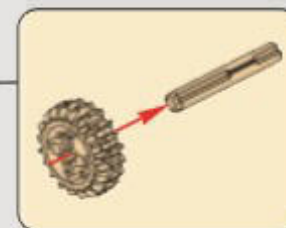
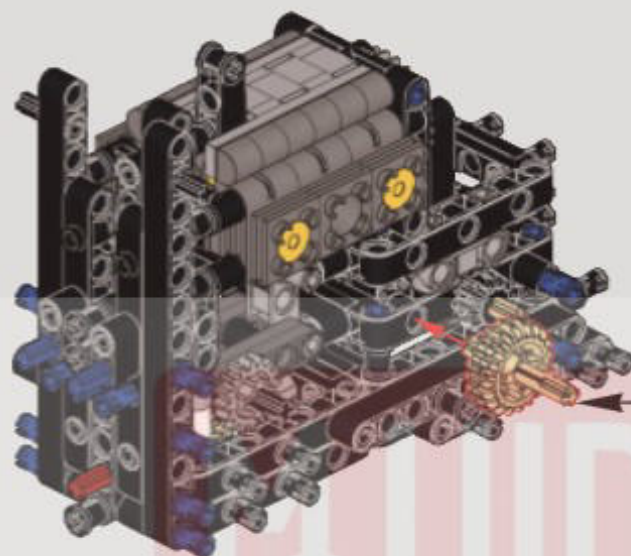


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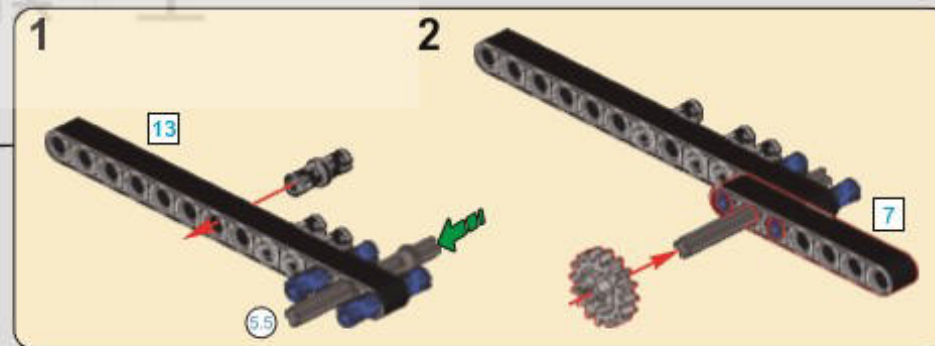
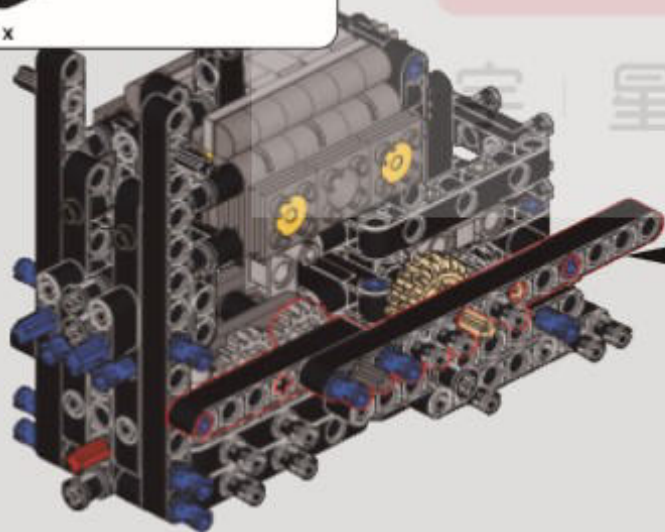


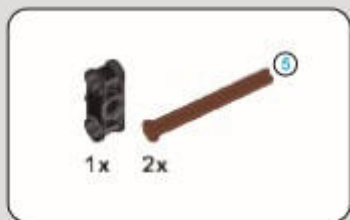


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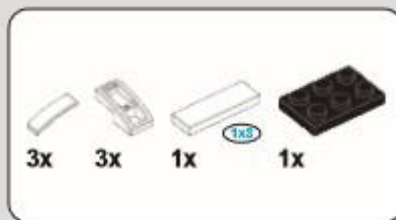
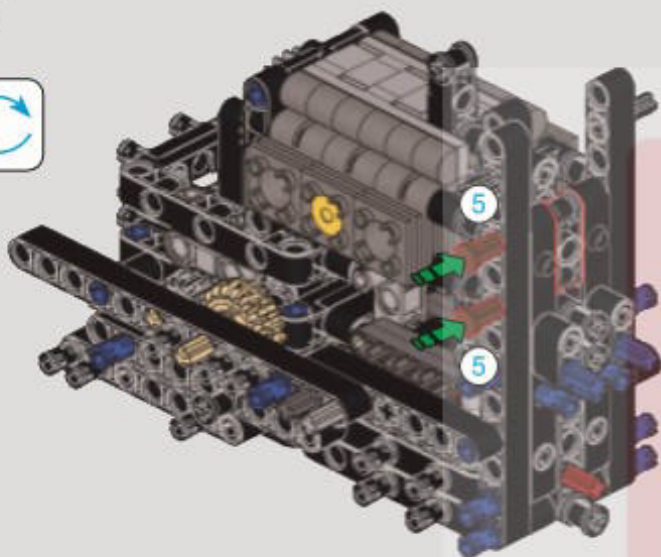


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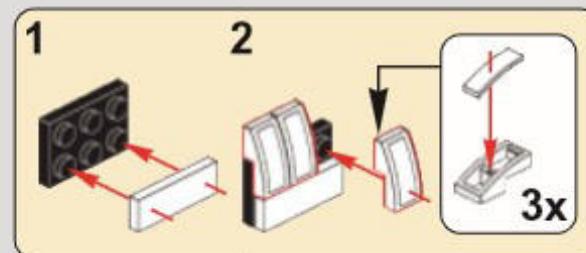
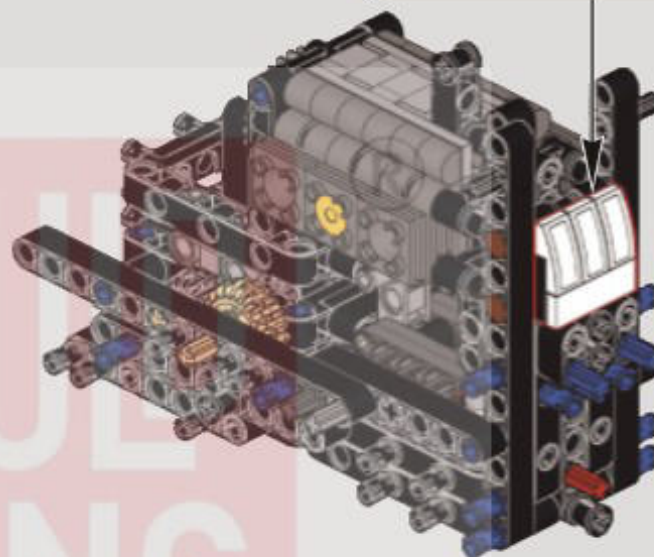




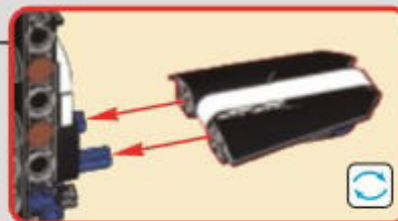
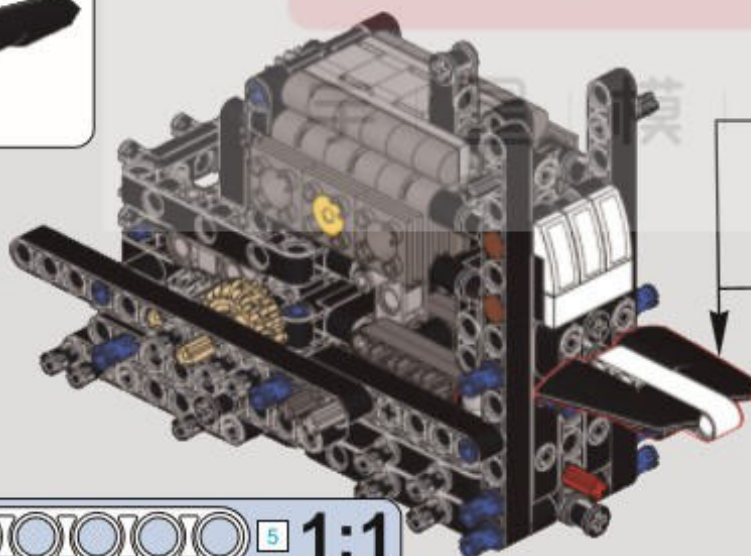
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148

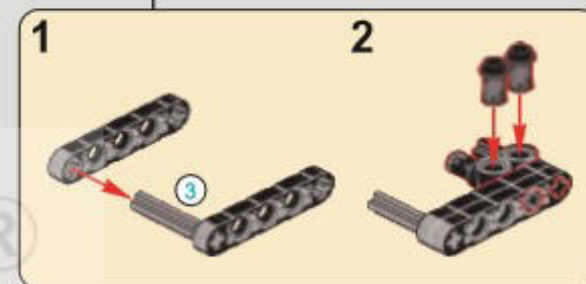
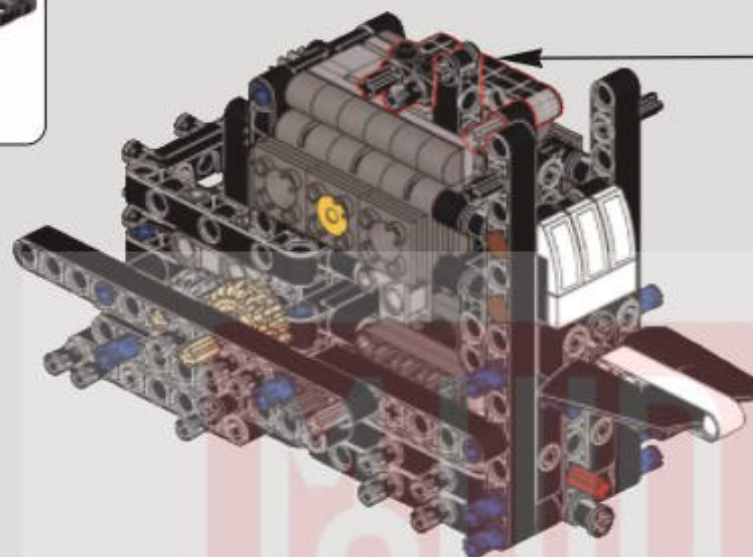


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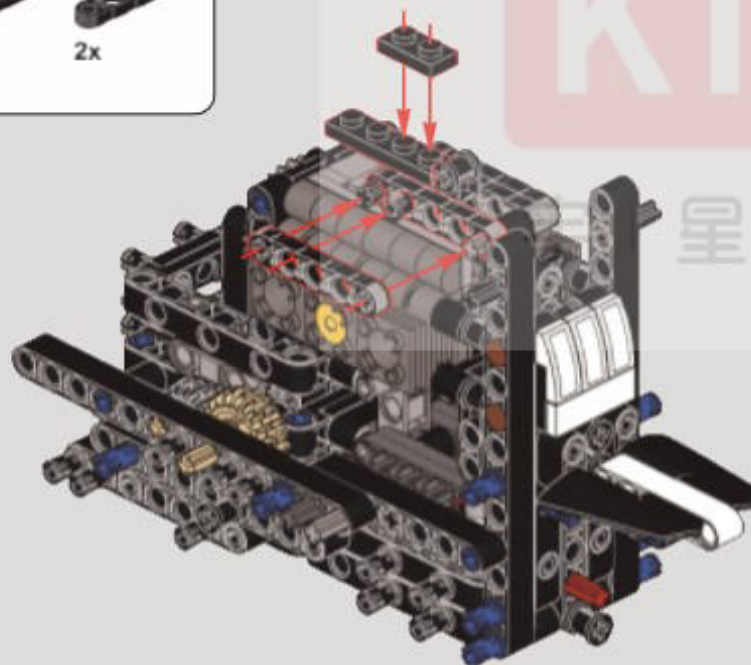




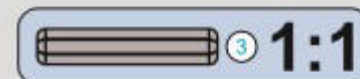
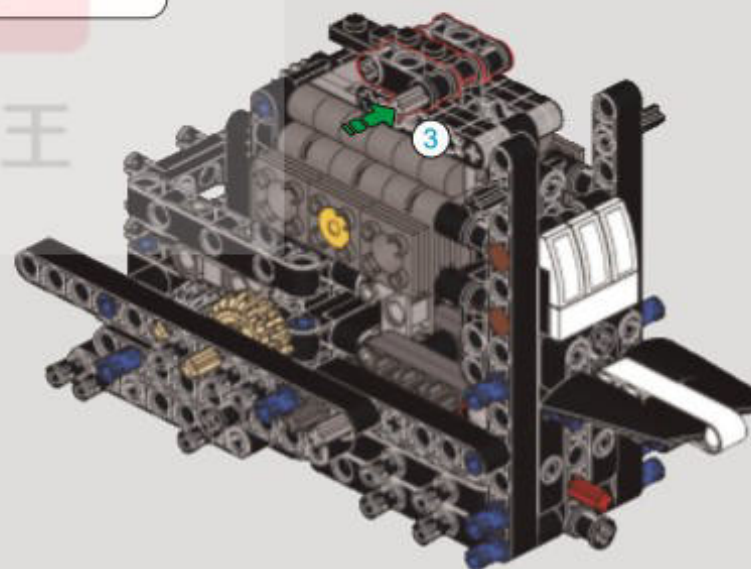
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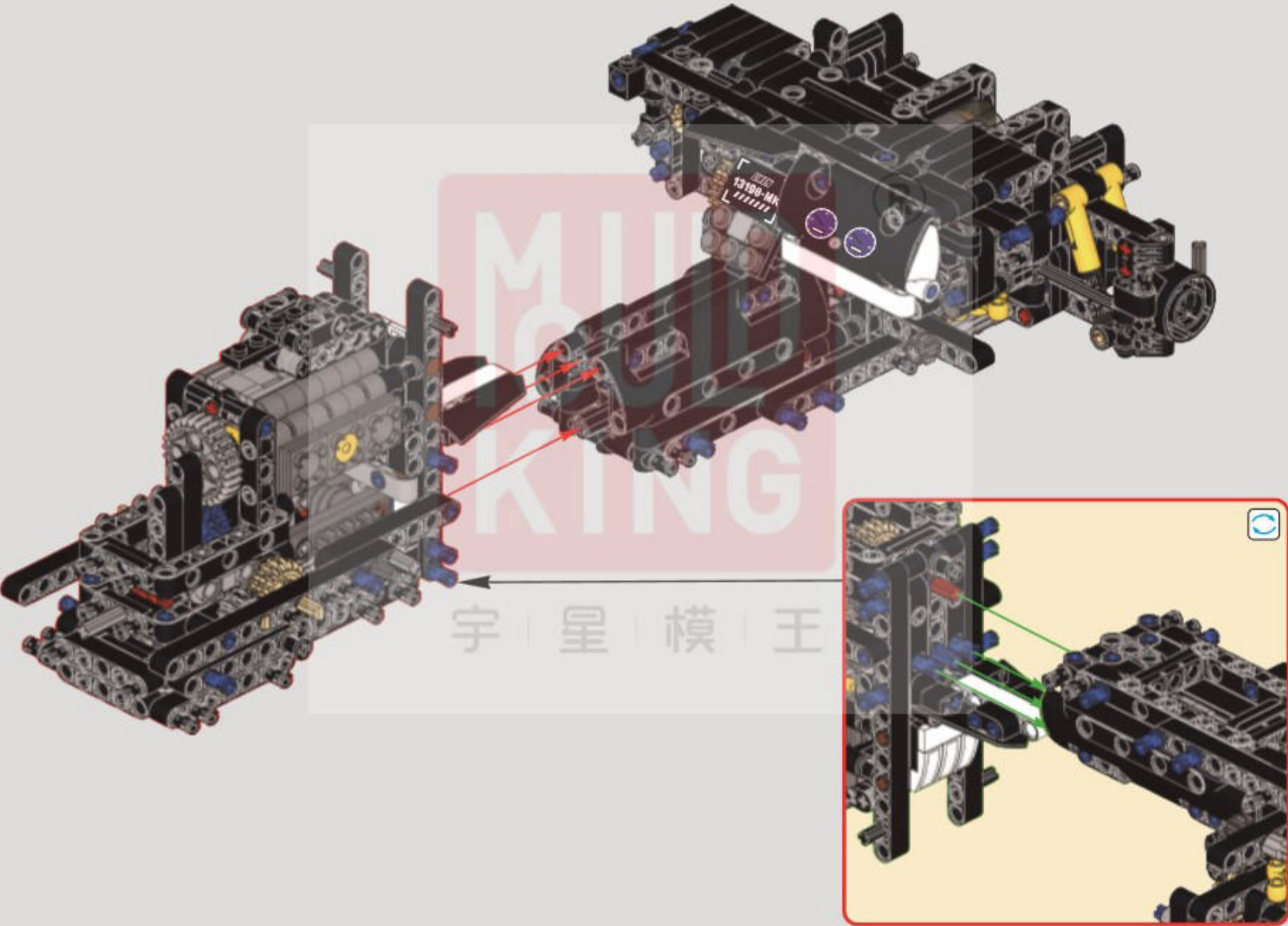


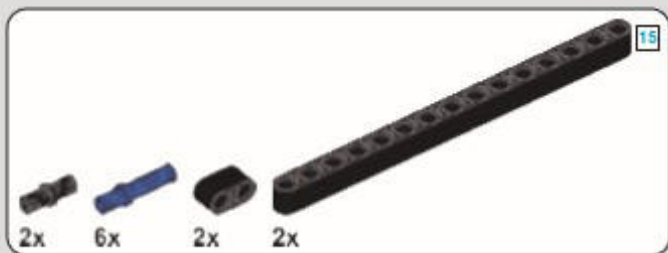
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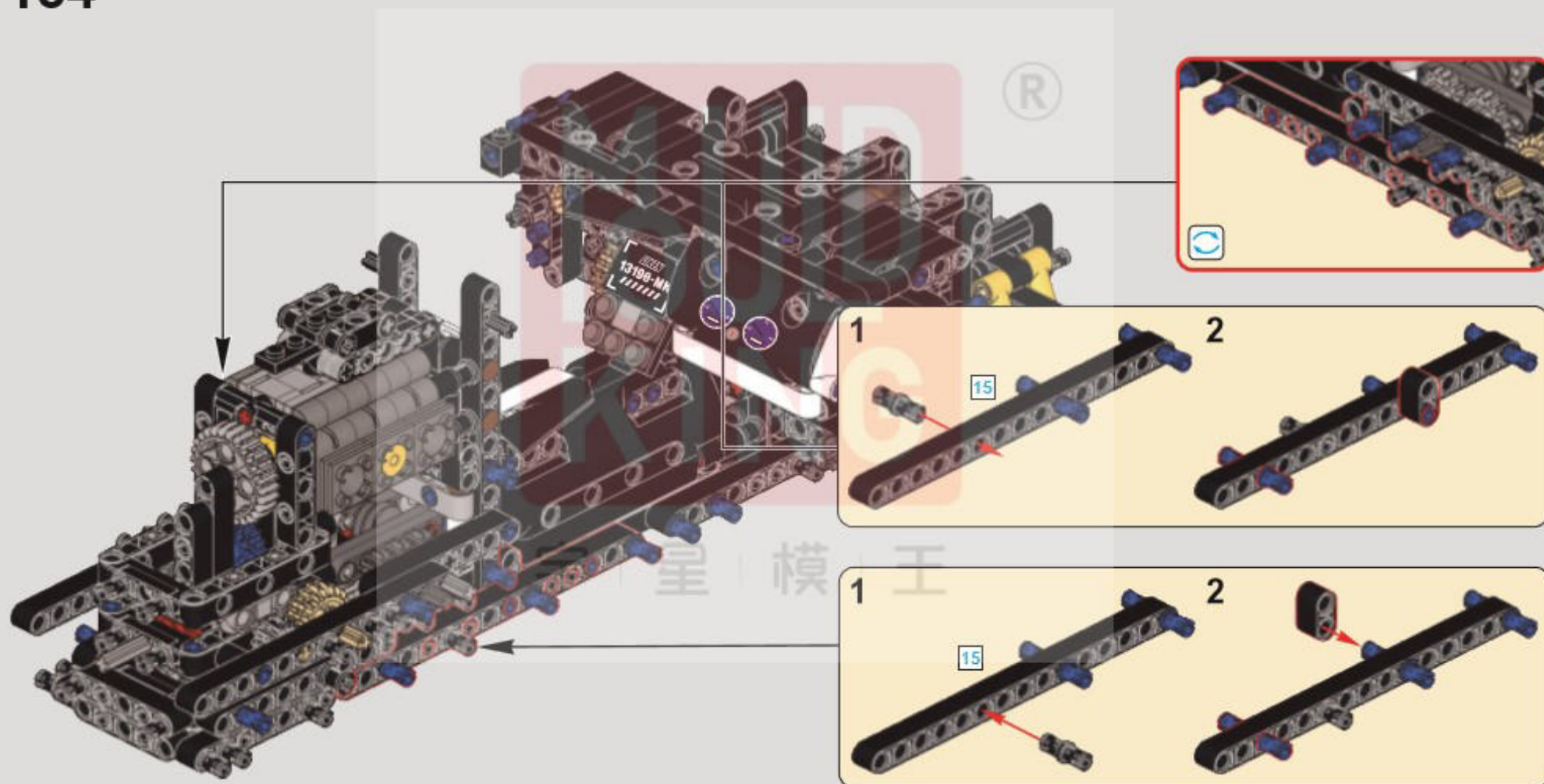
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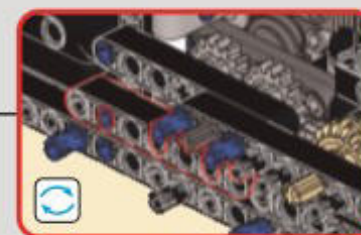
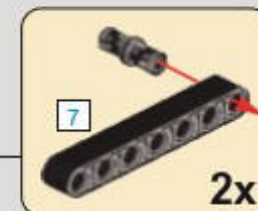
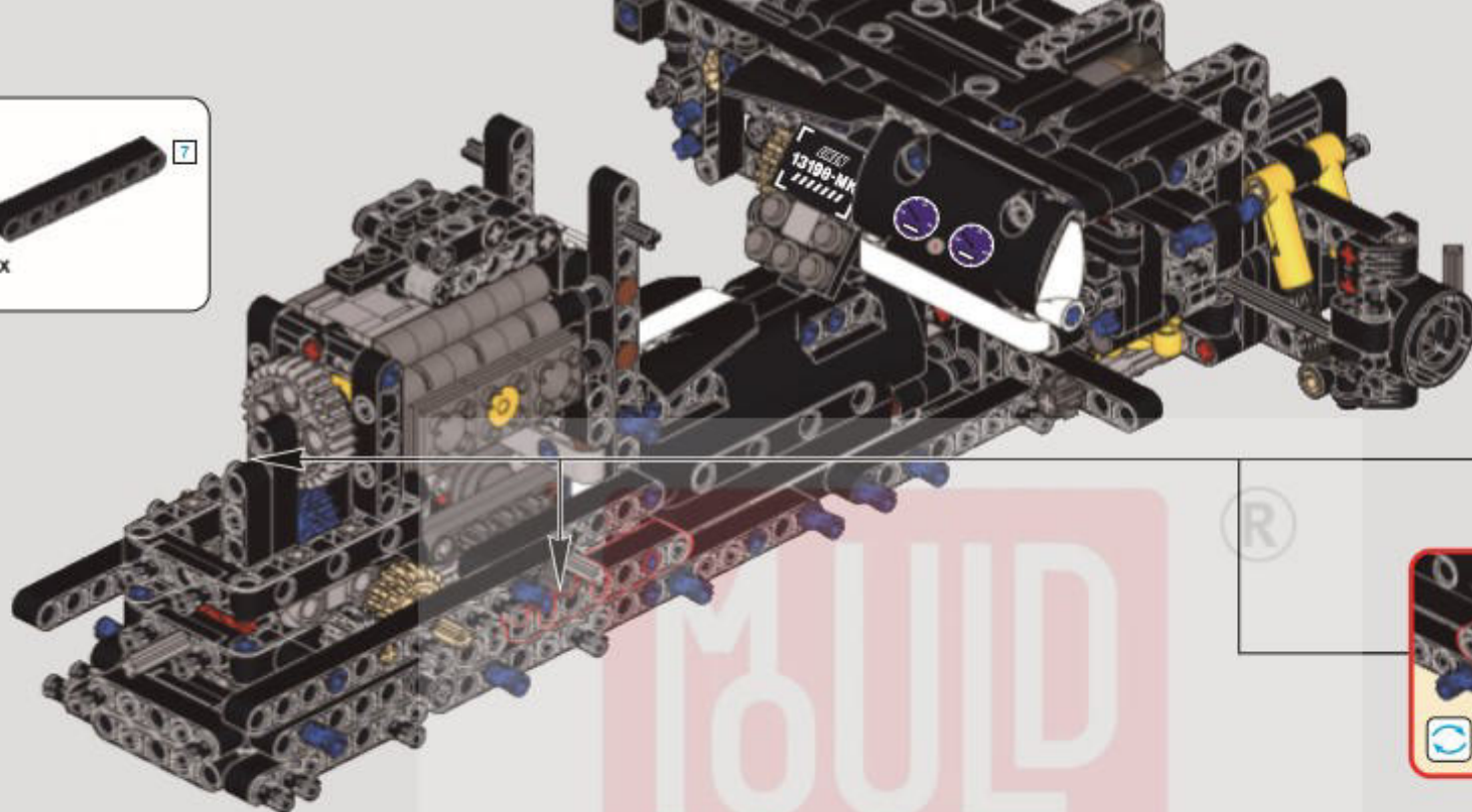


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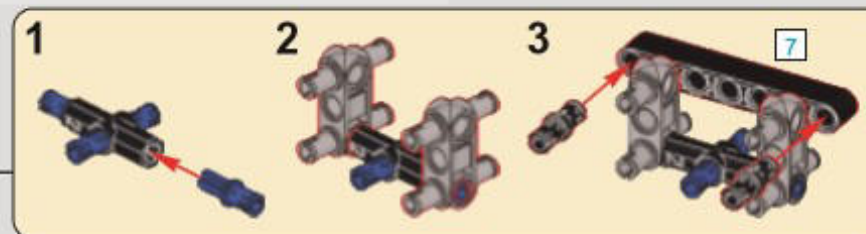
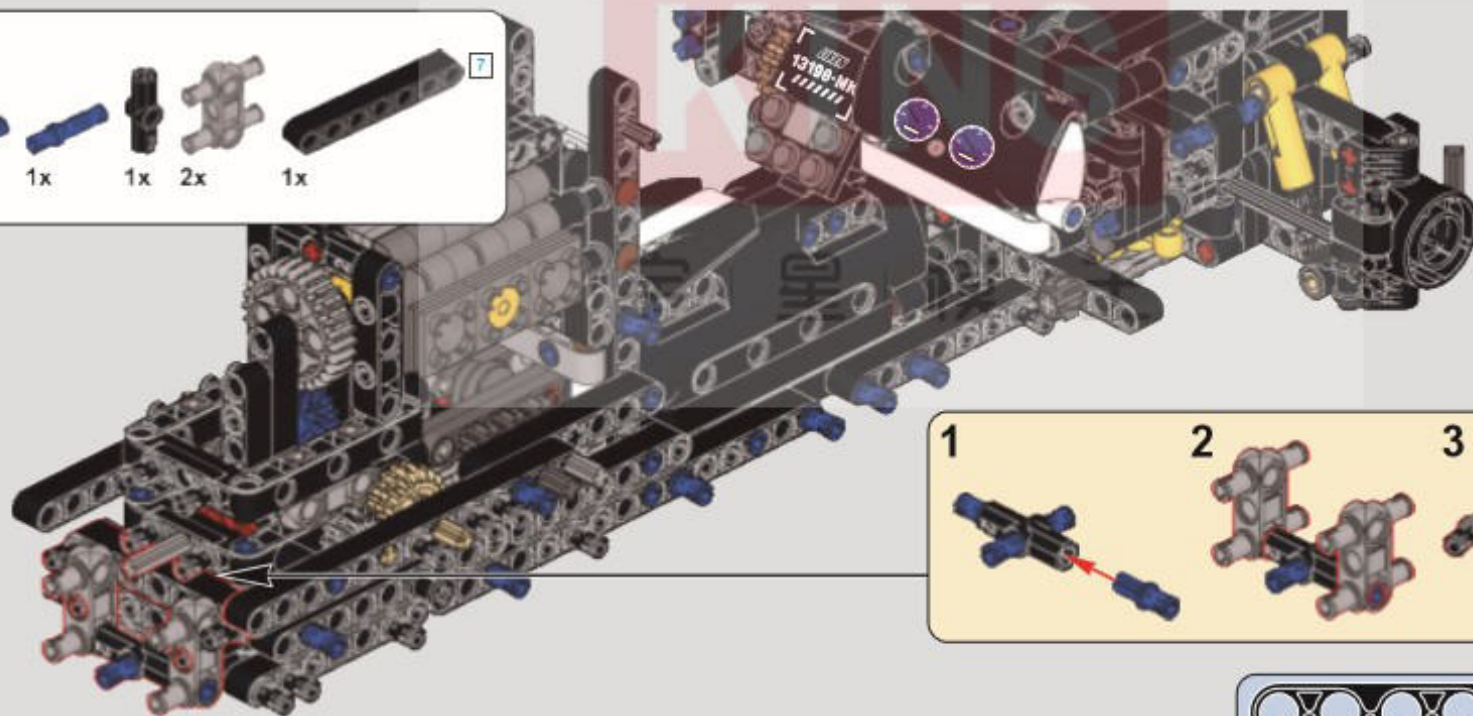


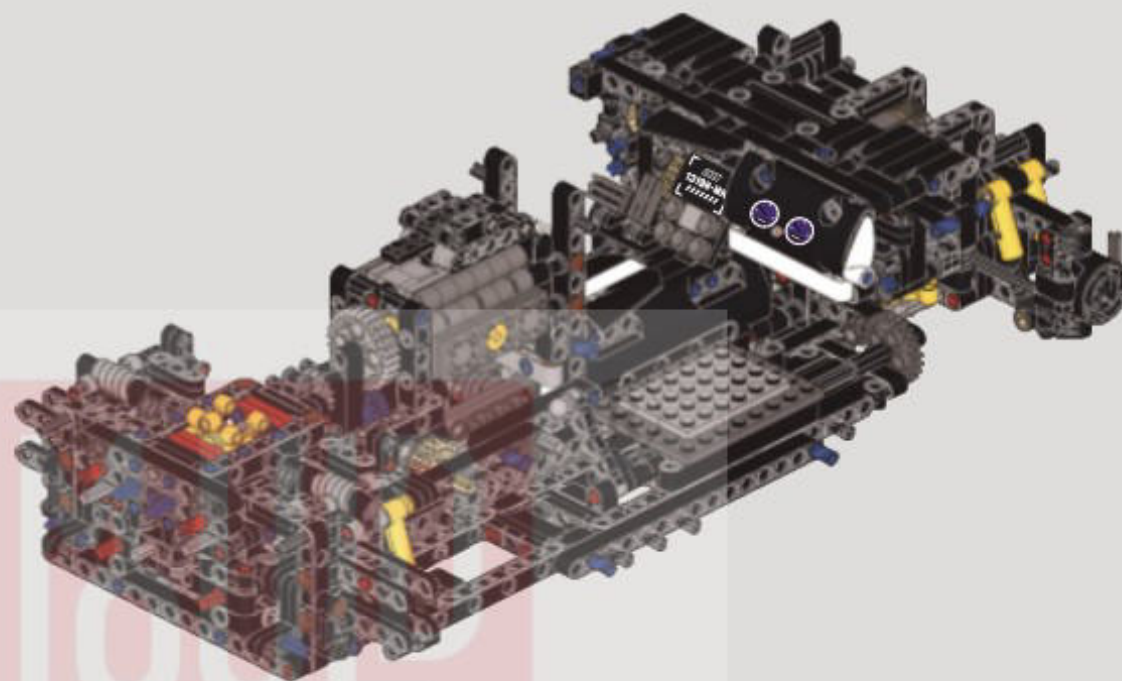


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156





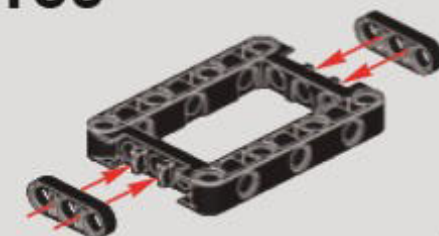
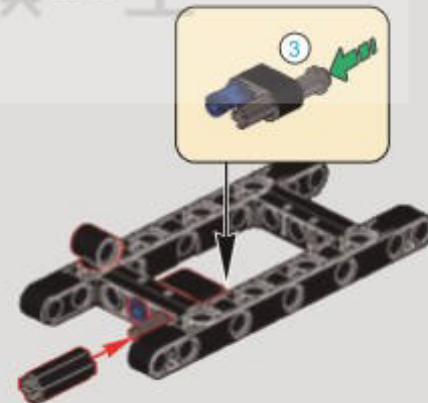
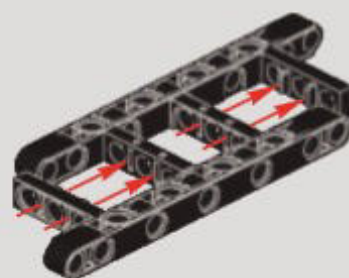
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157



1x 1x 1x 1x 1x
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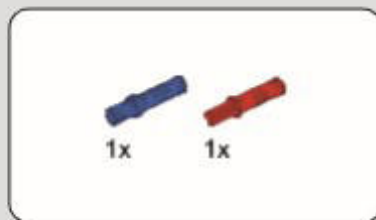
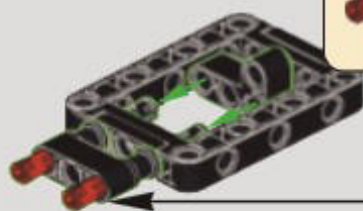
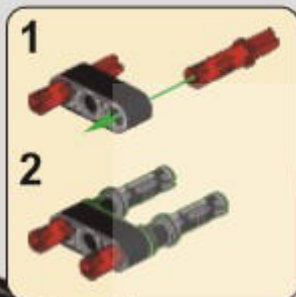


2x 1x
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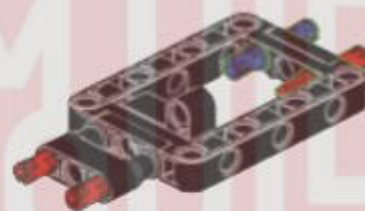




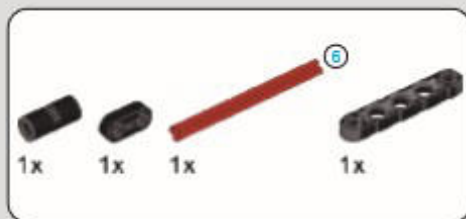
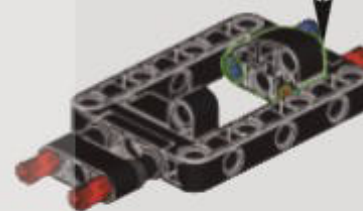
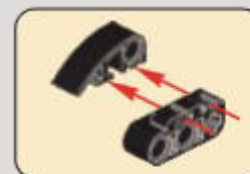
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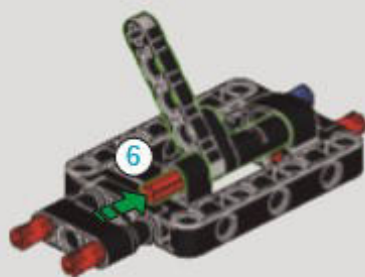
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162



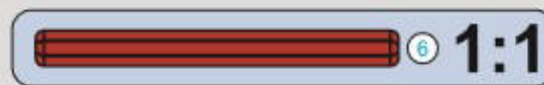
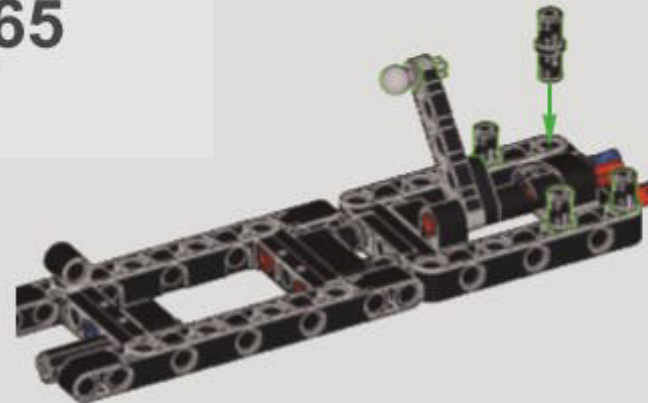
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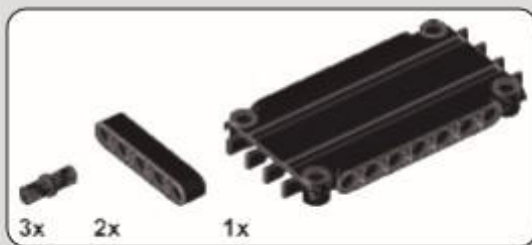


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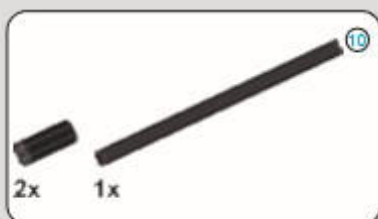
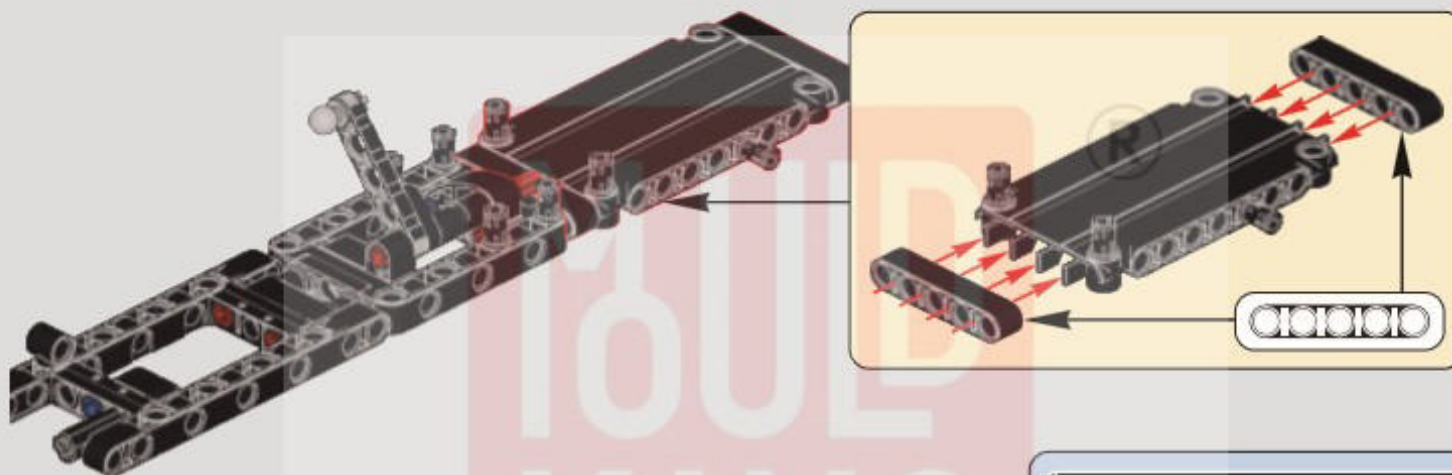


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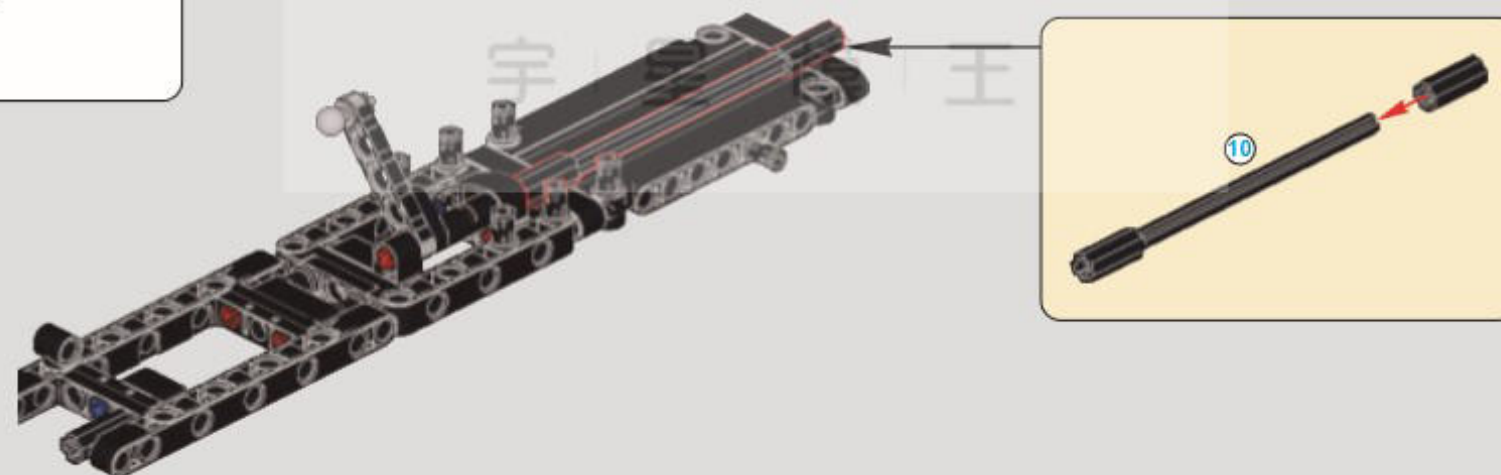




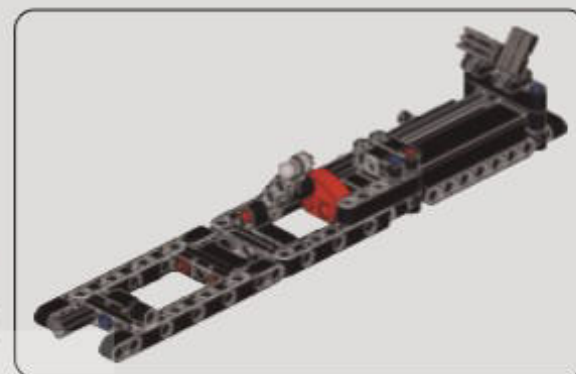
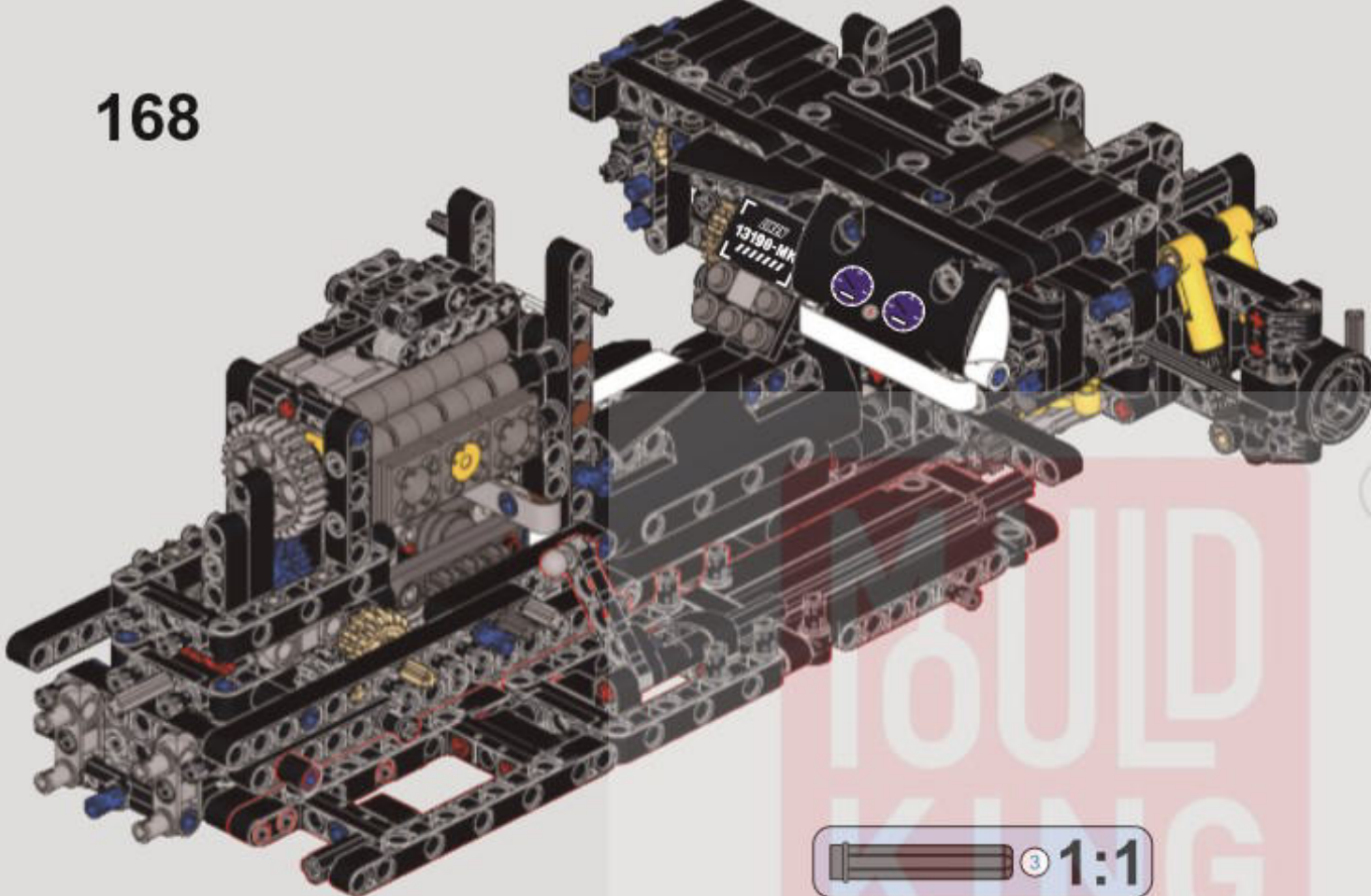
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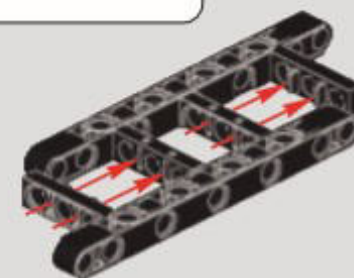
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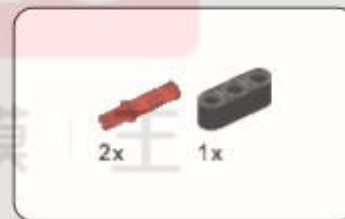
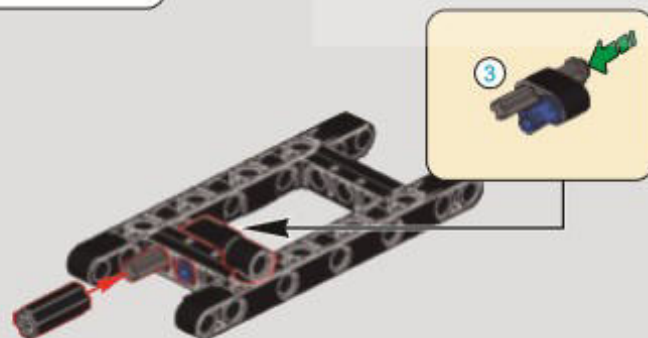
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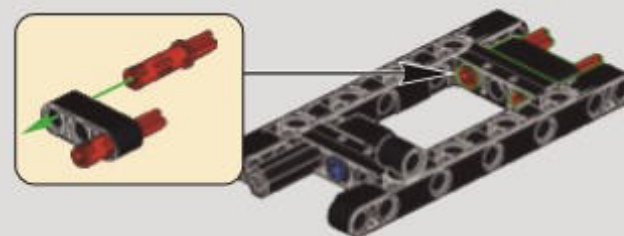
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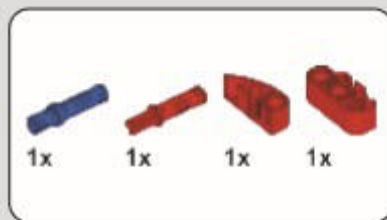
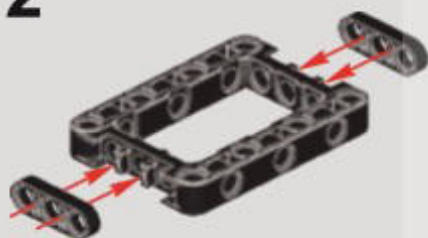


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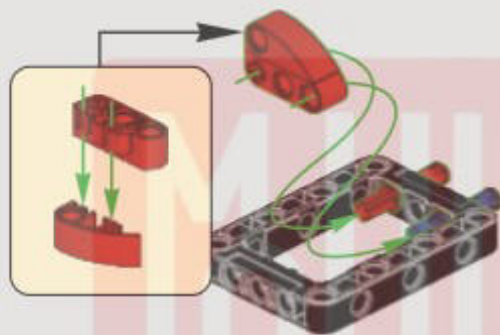




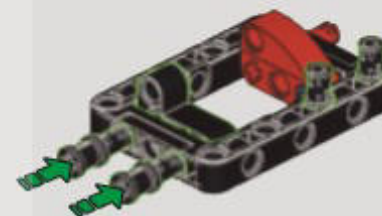
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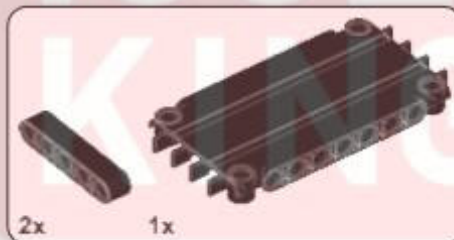
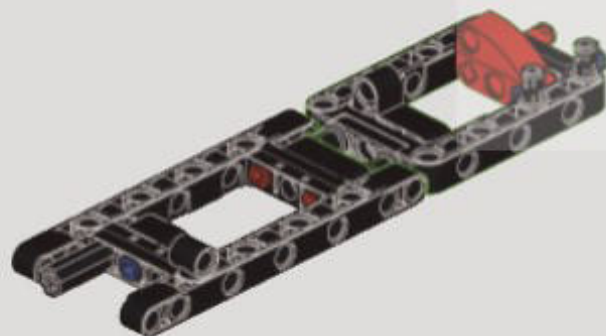
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174

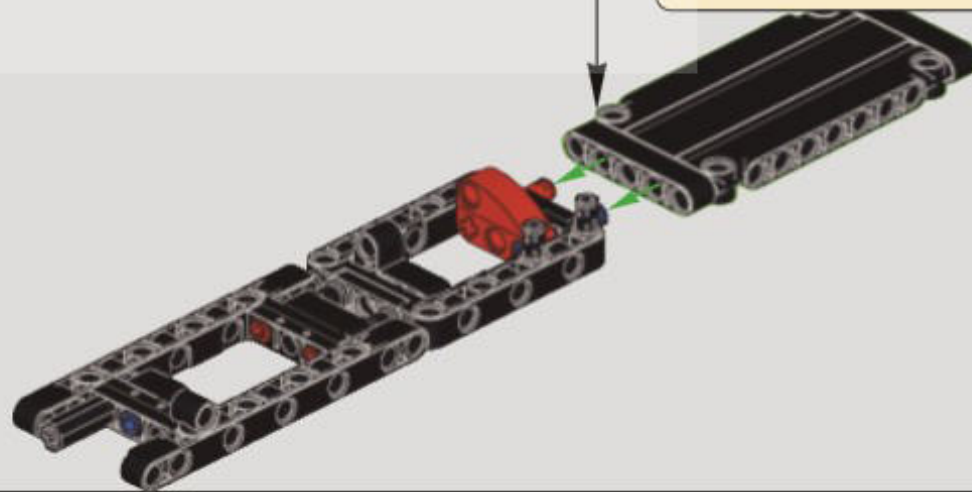
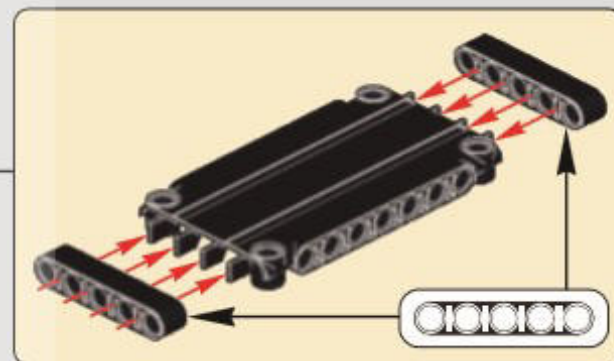


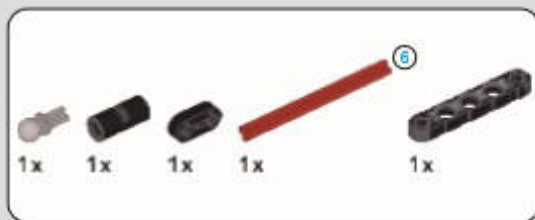
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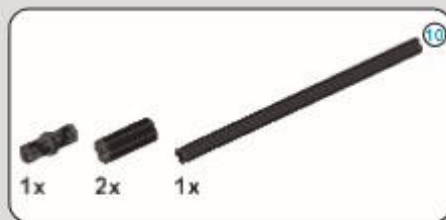
176

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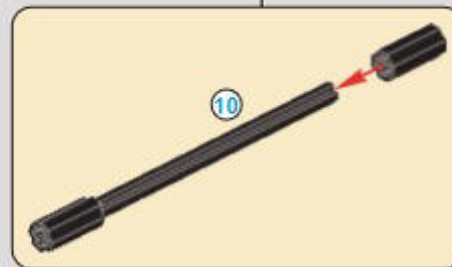
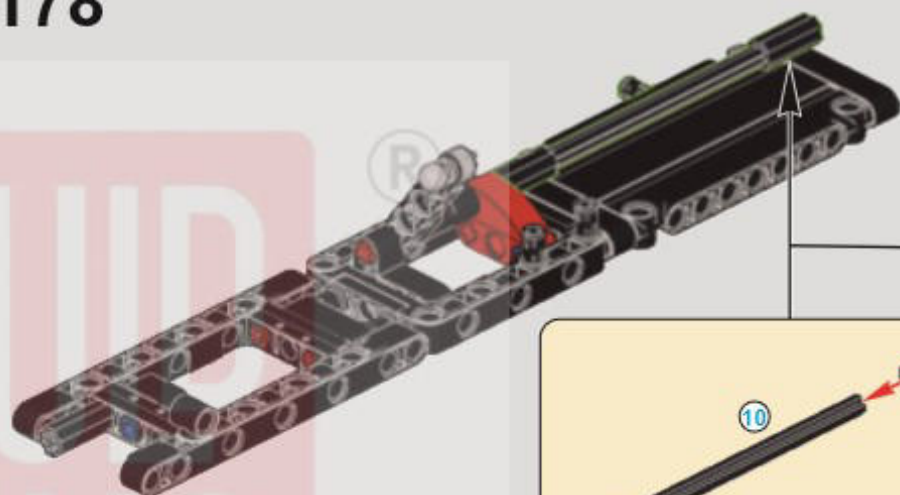
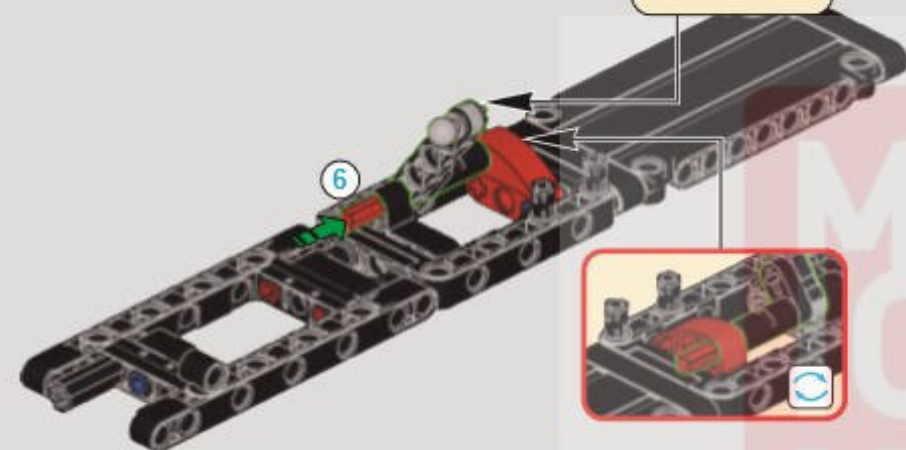




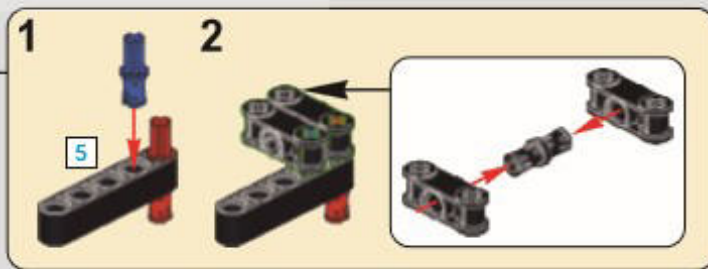
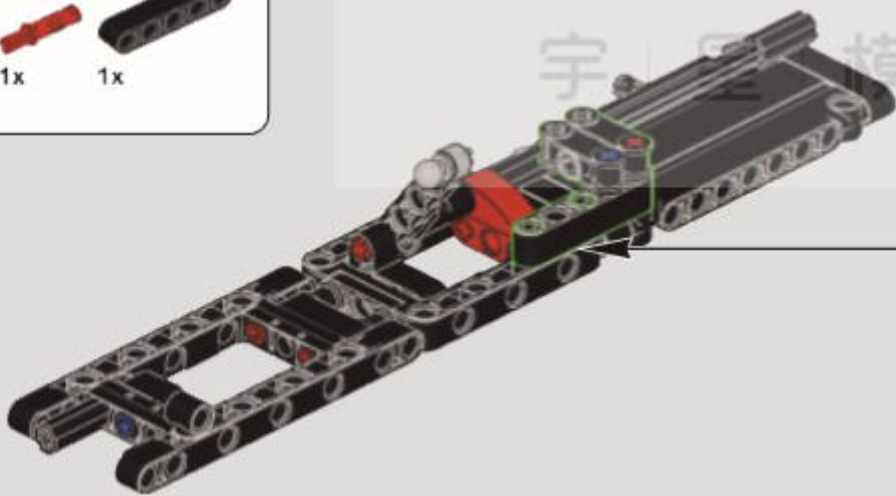
177

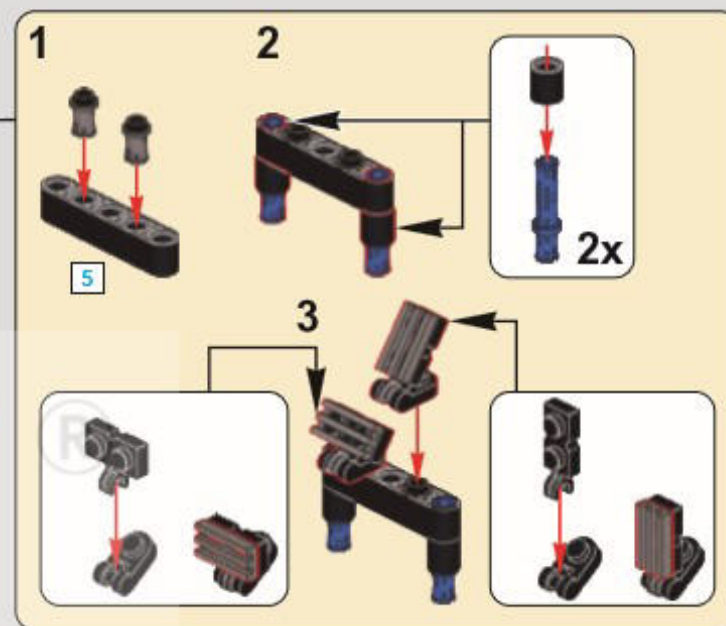
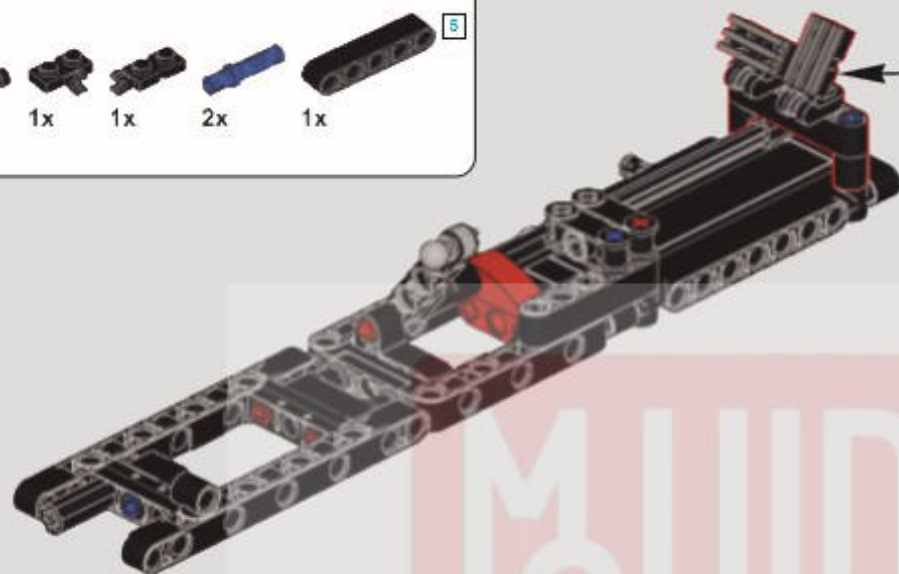


178

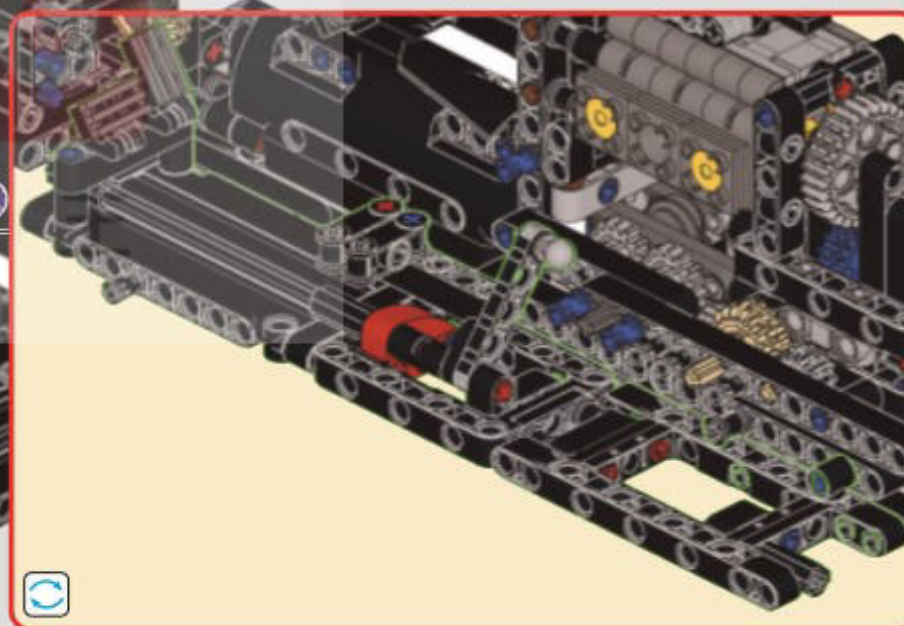
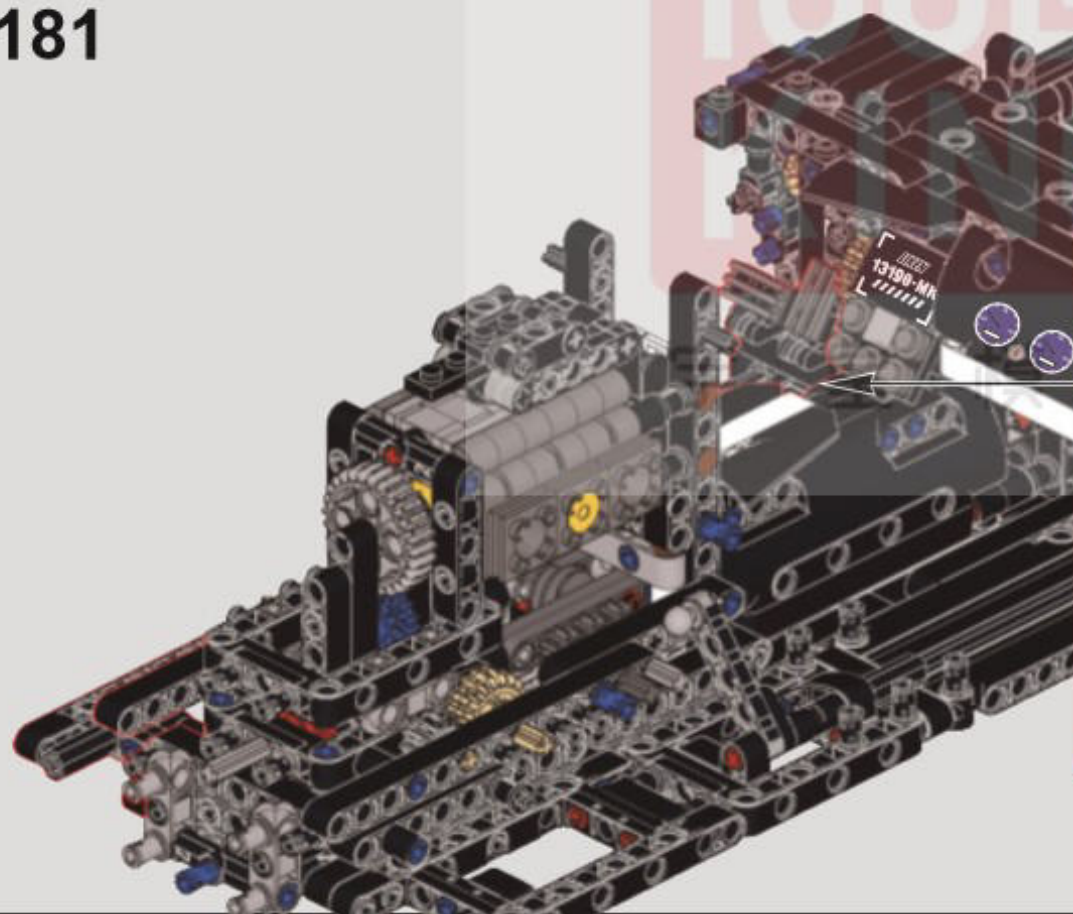


179





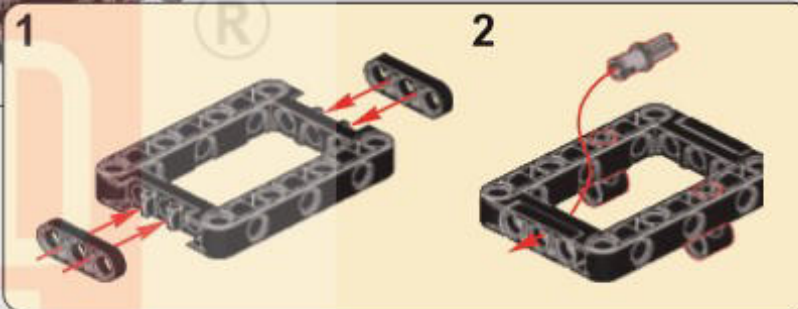
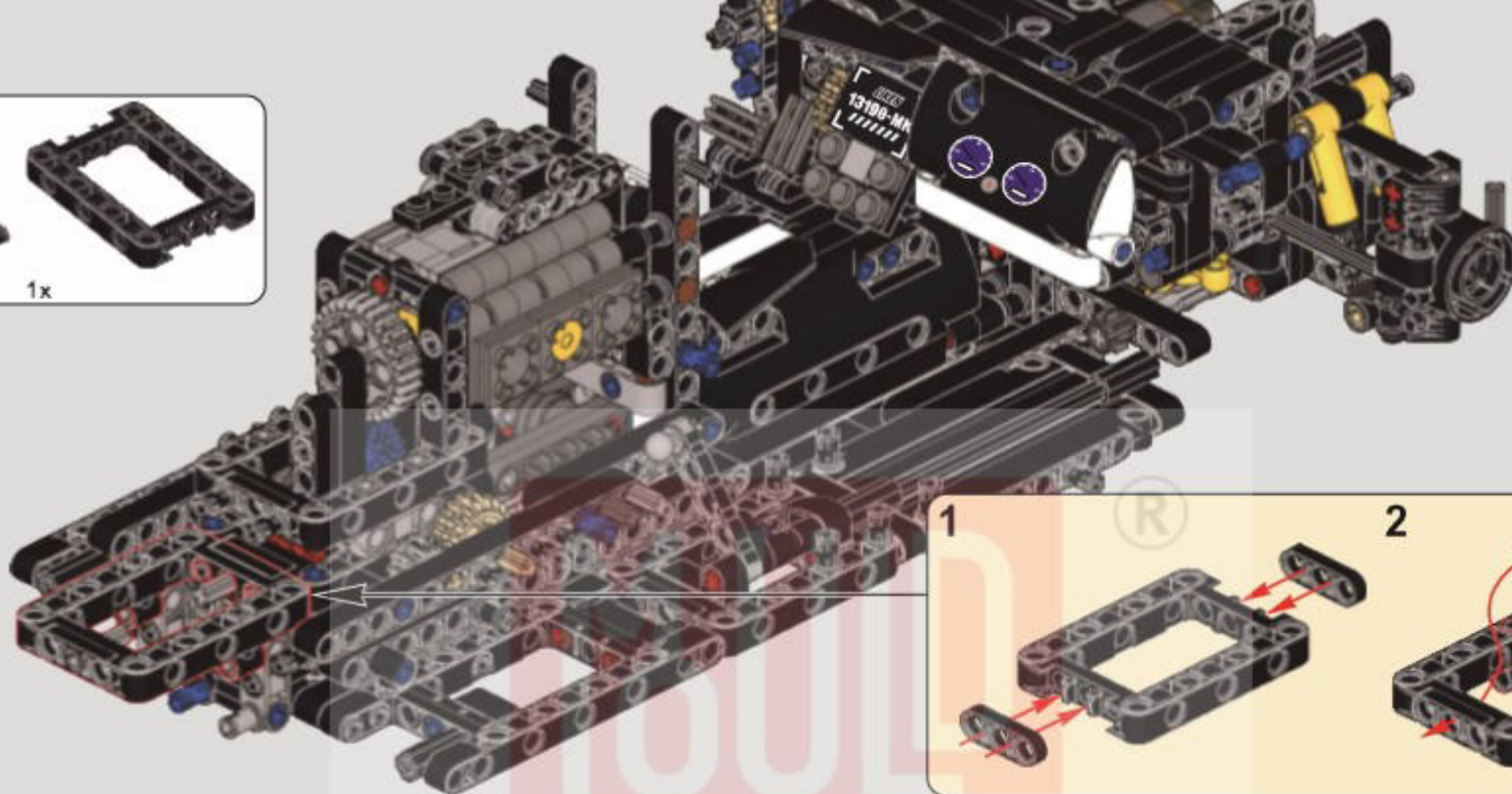
181



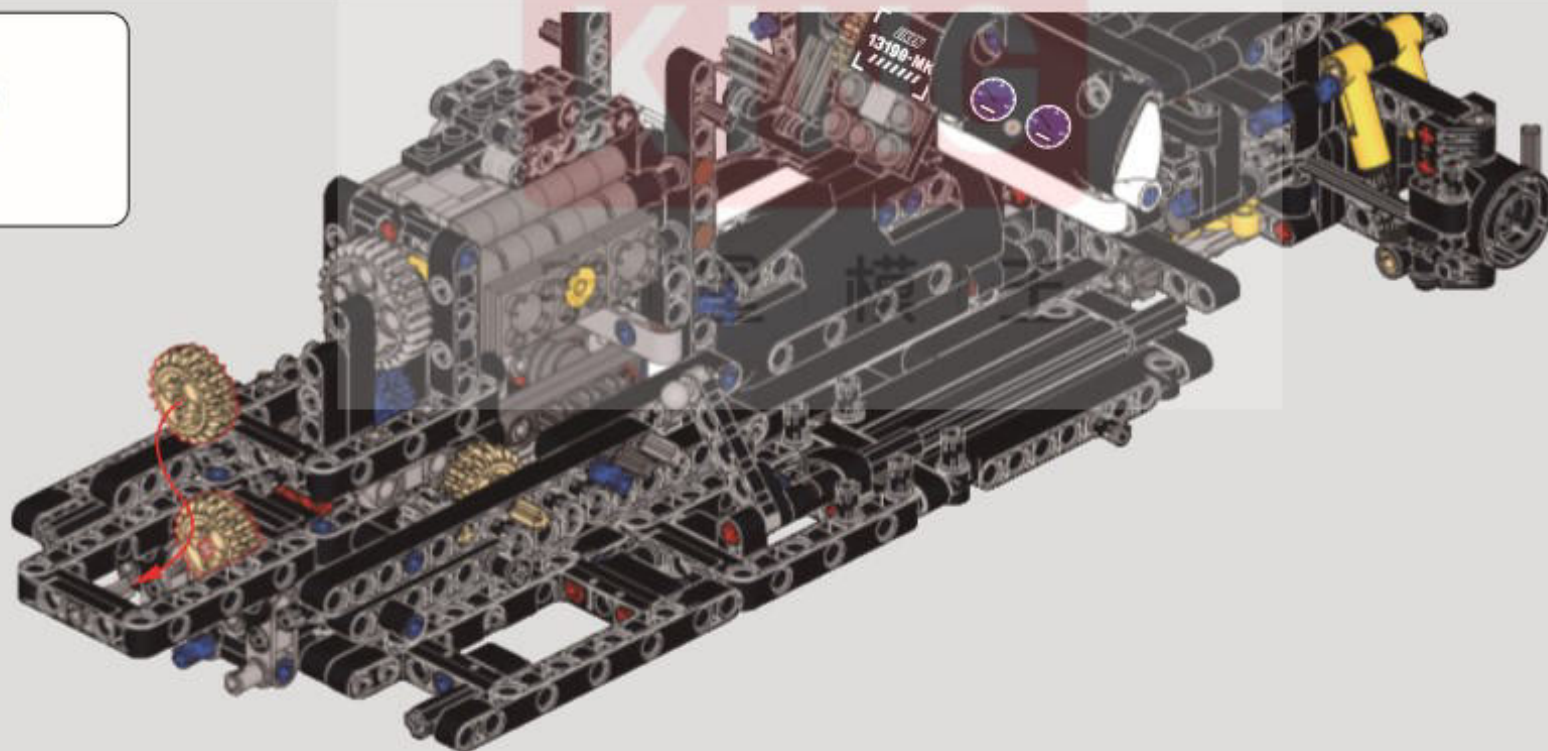
Tech. pin bez tření
(Technic Pin
without Friction)

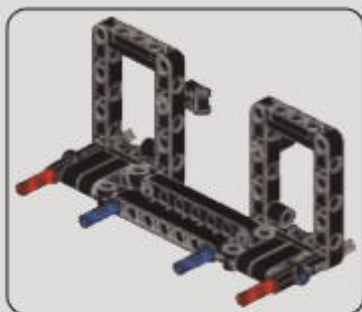


182

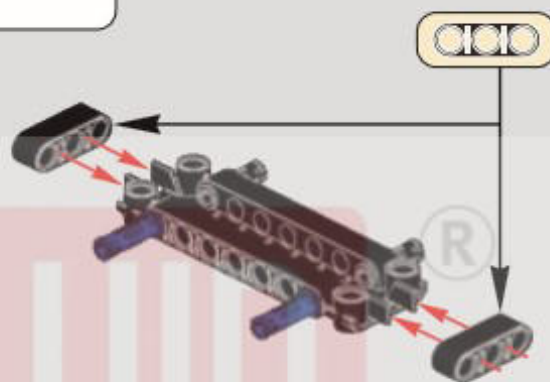


183





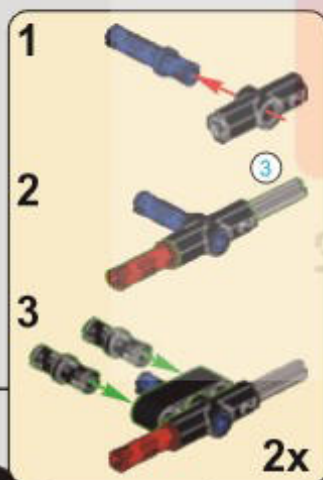
184



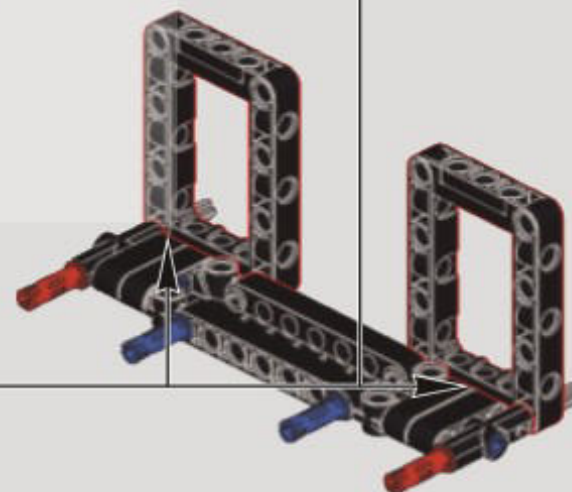
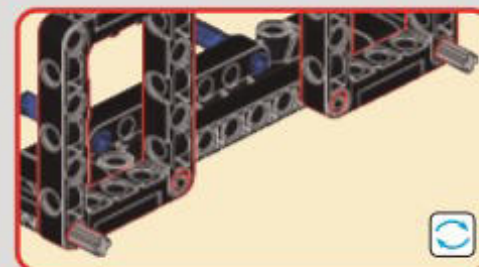
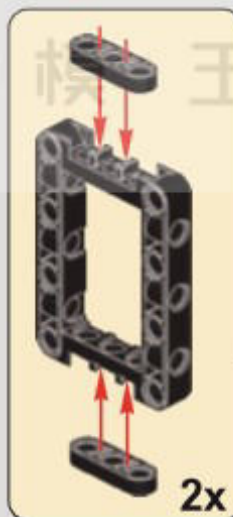
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185

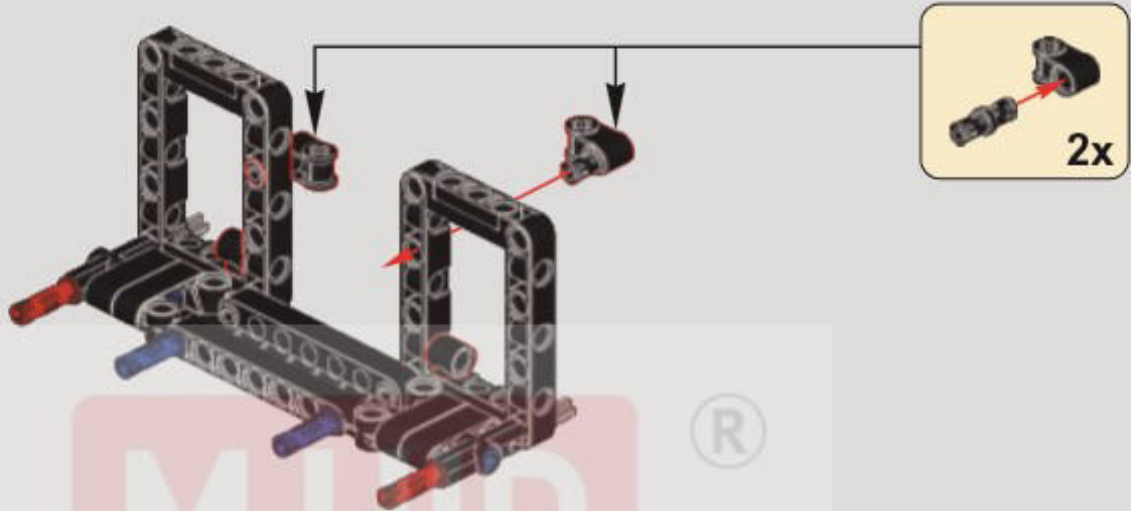


186

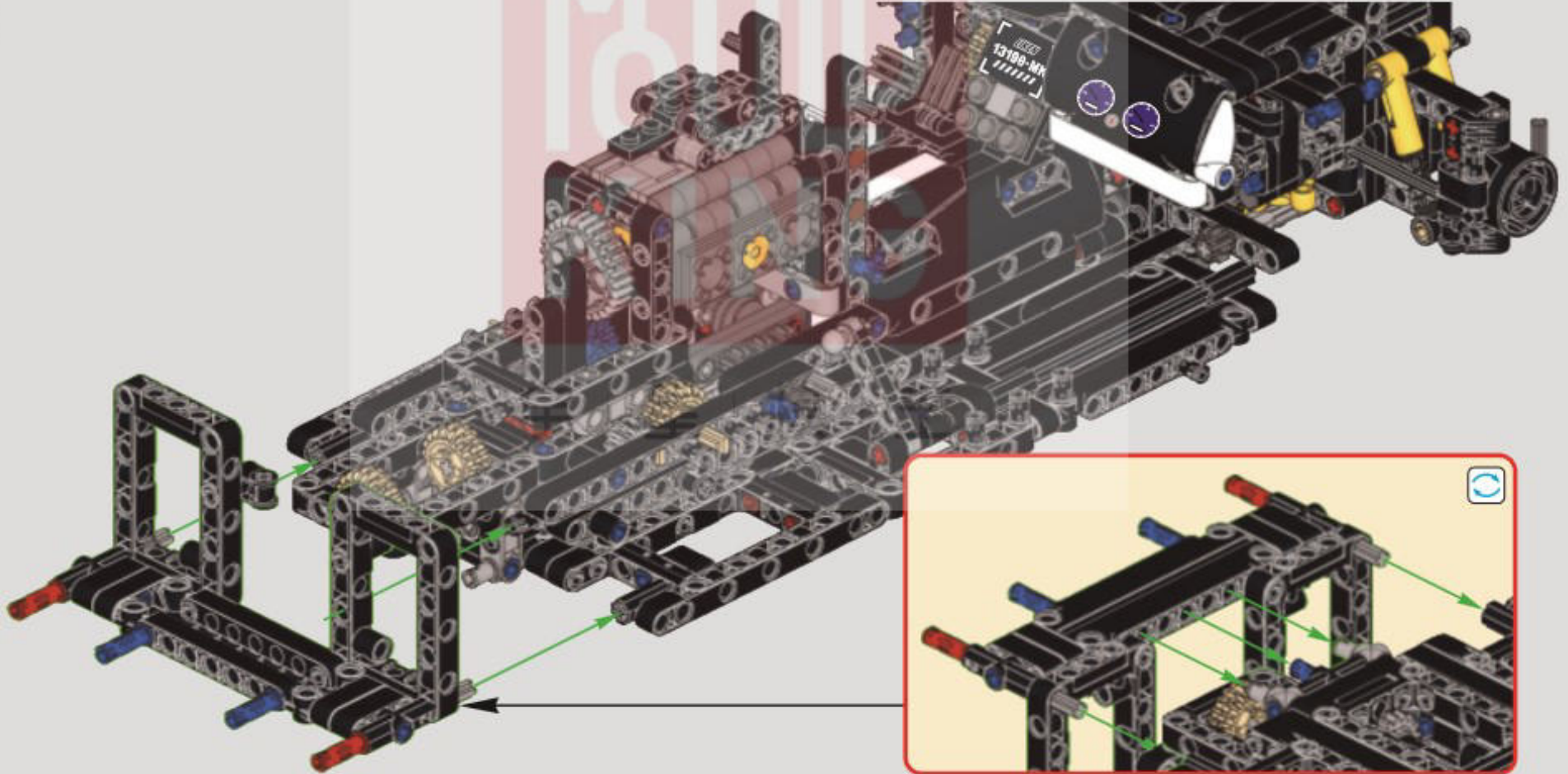




187

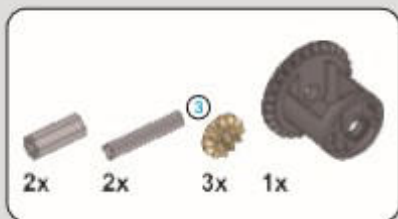
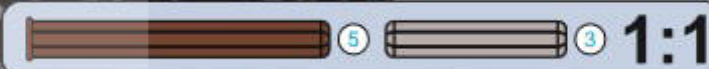
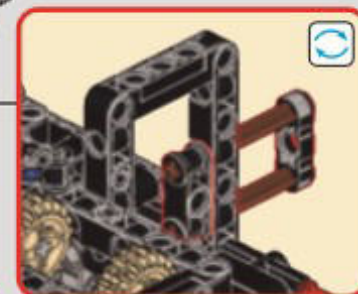
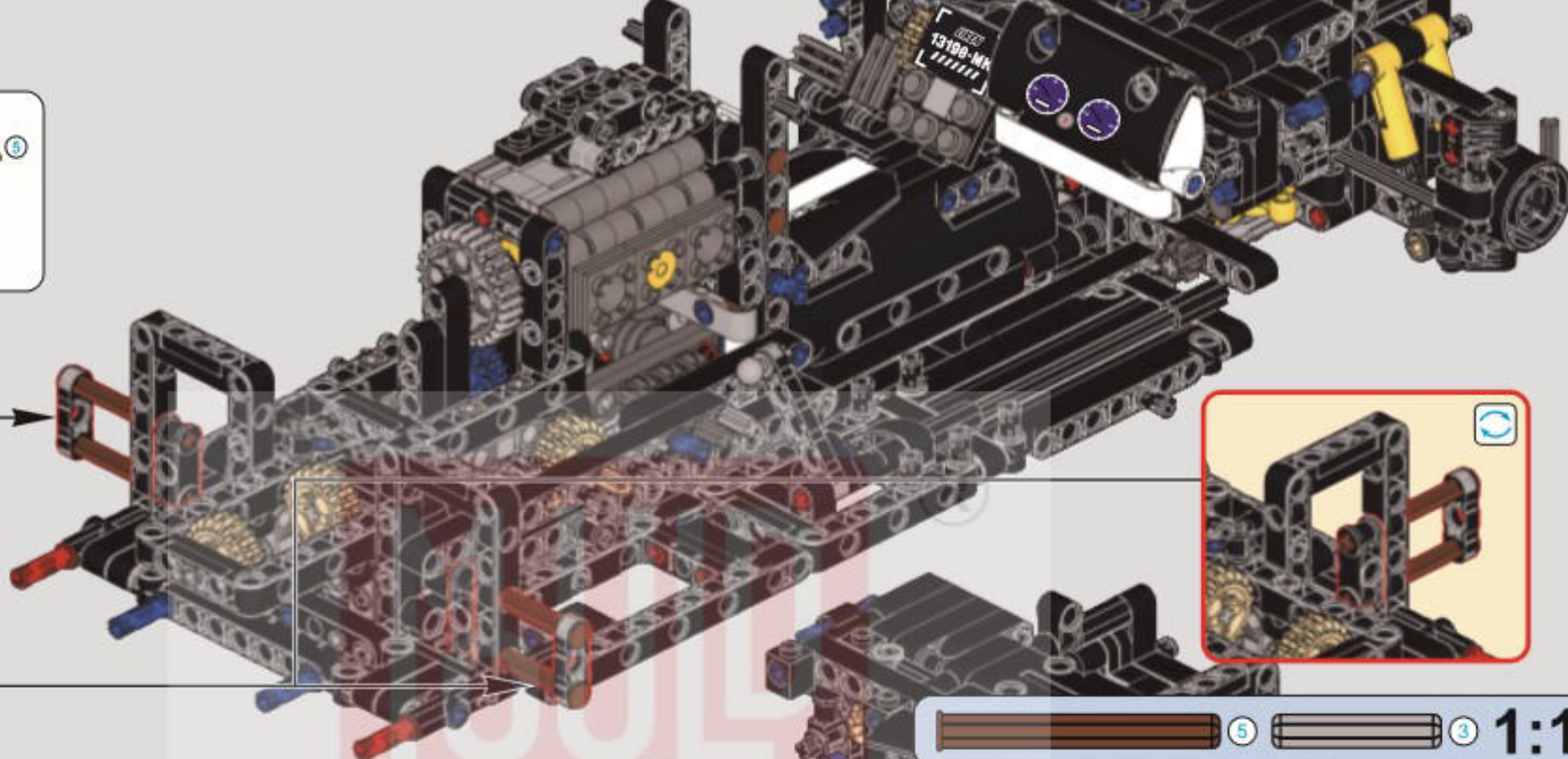


188

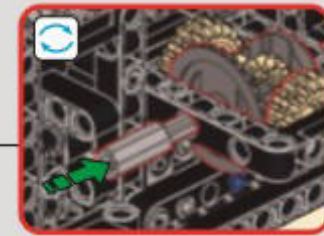
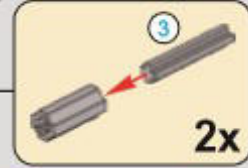
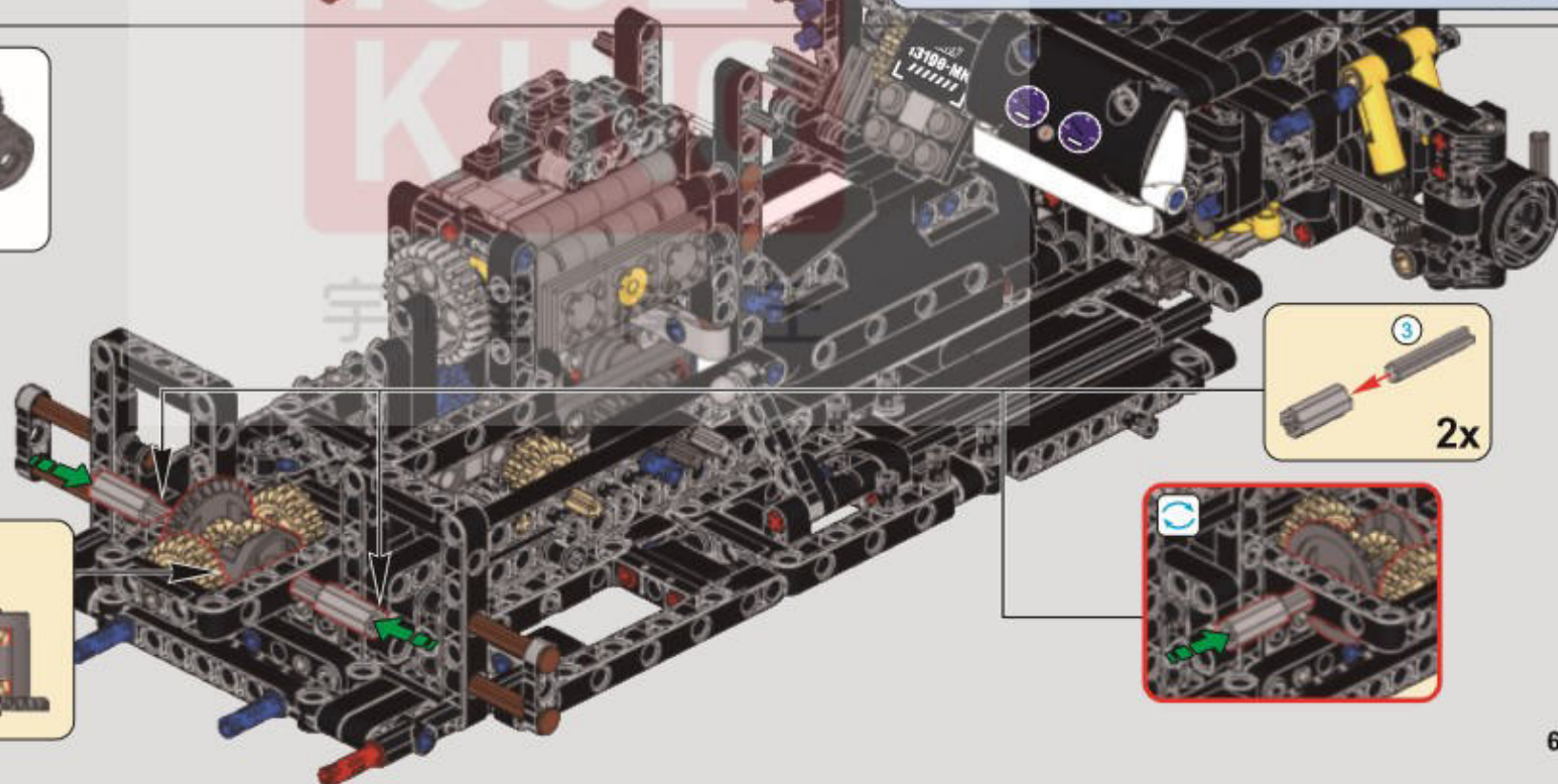
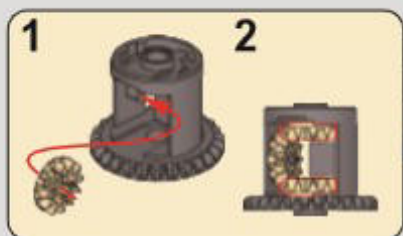




189

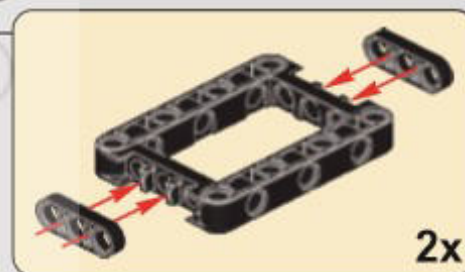
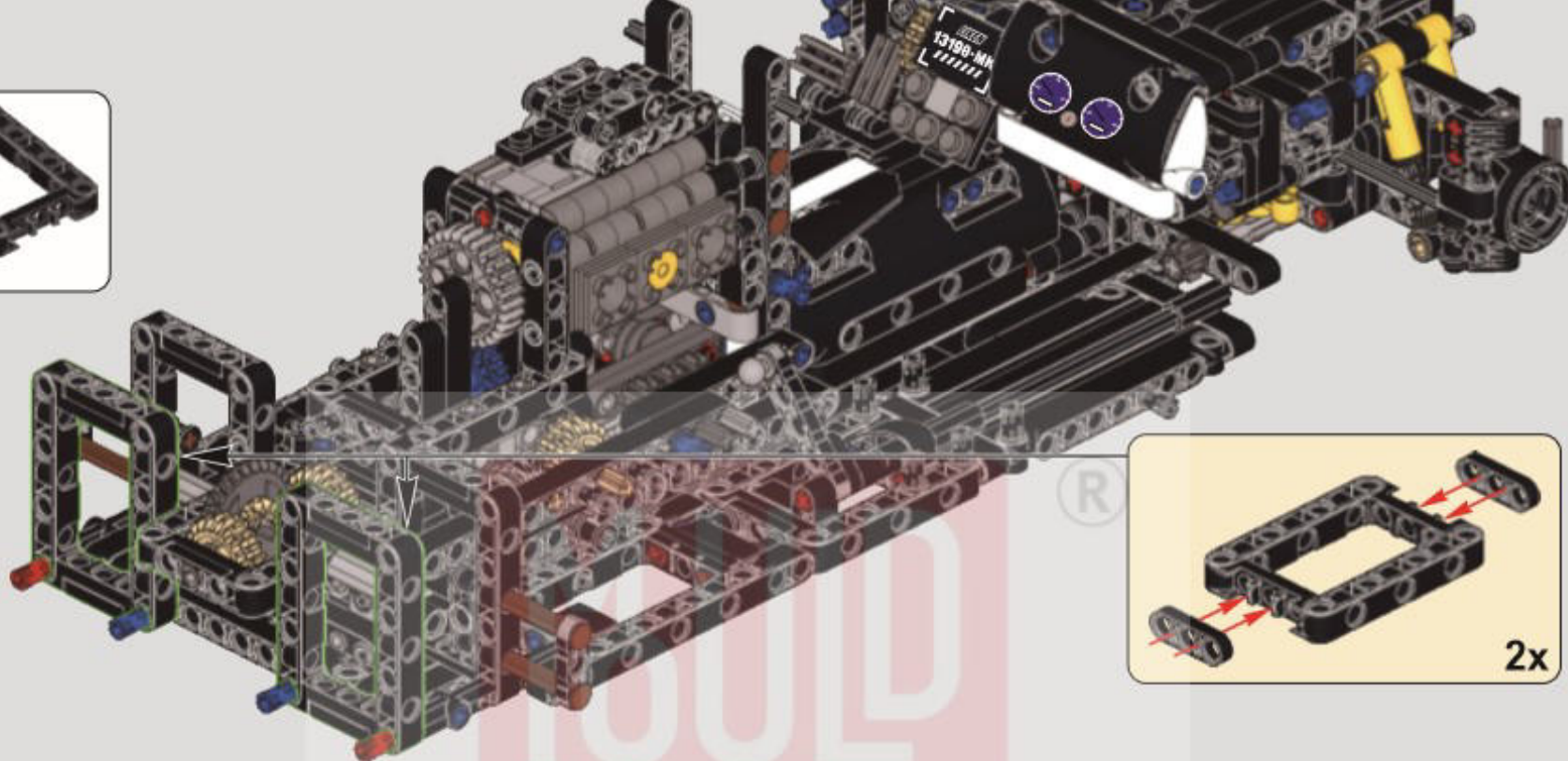


190

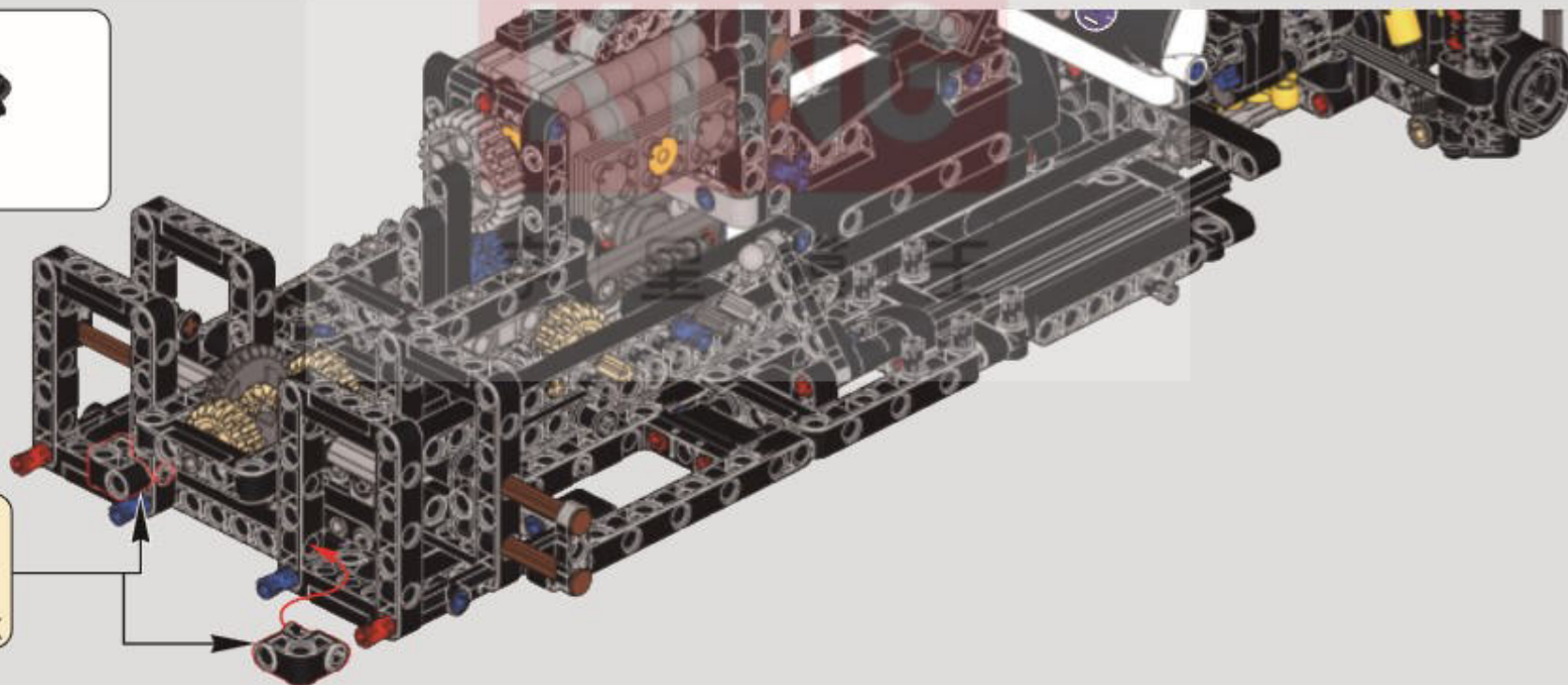


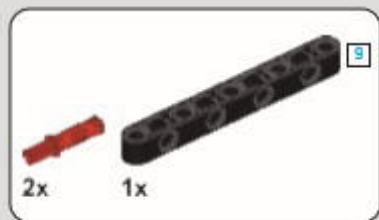


191

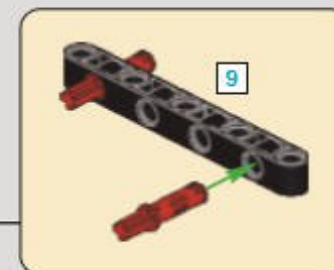
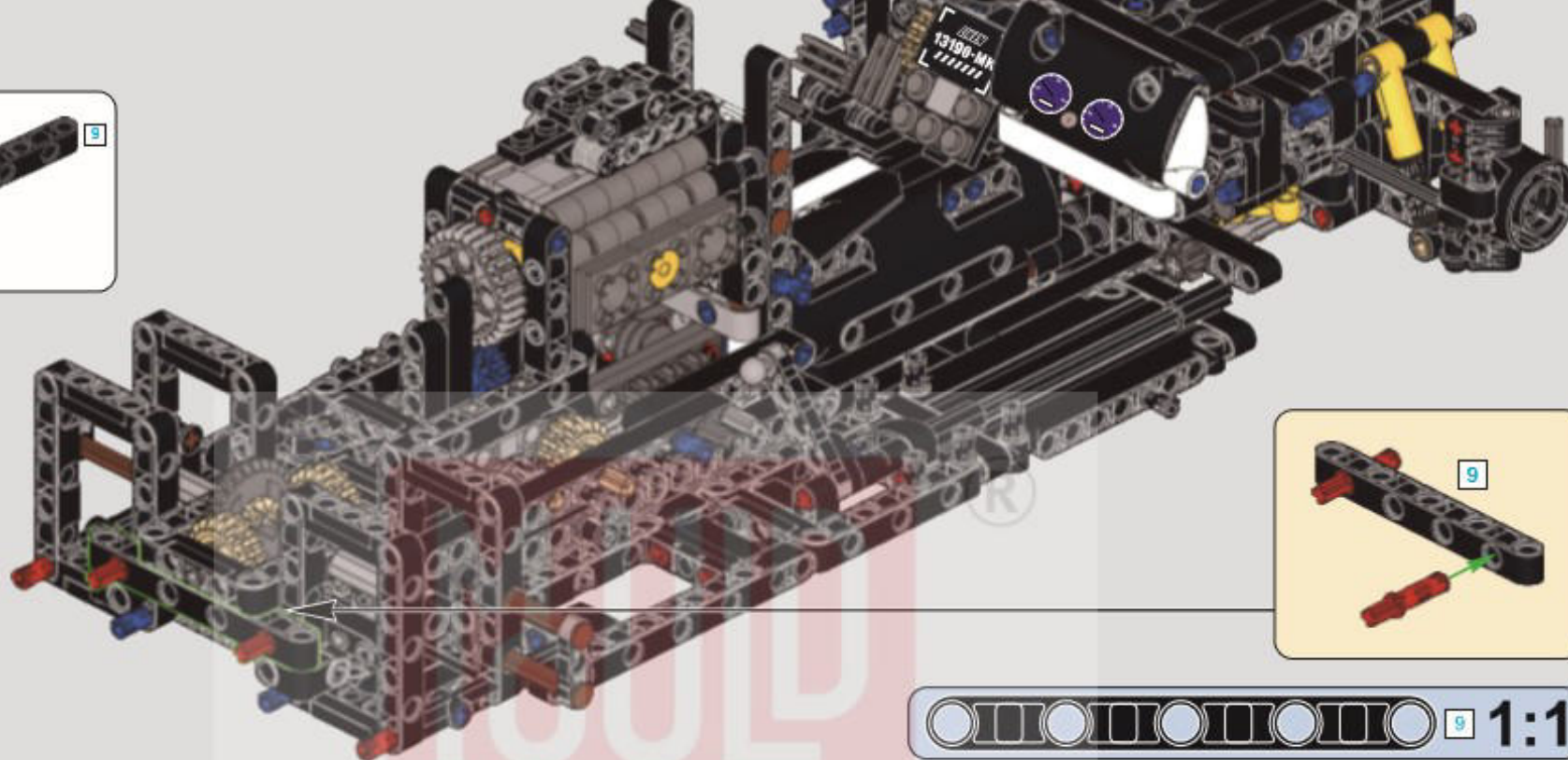


192

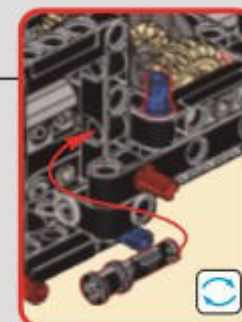
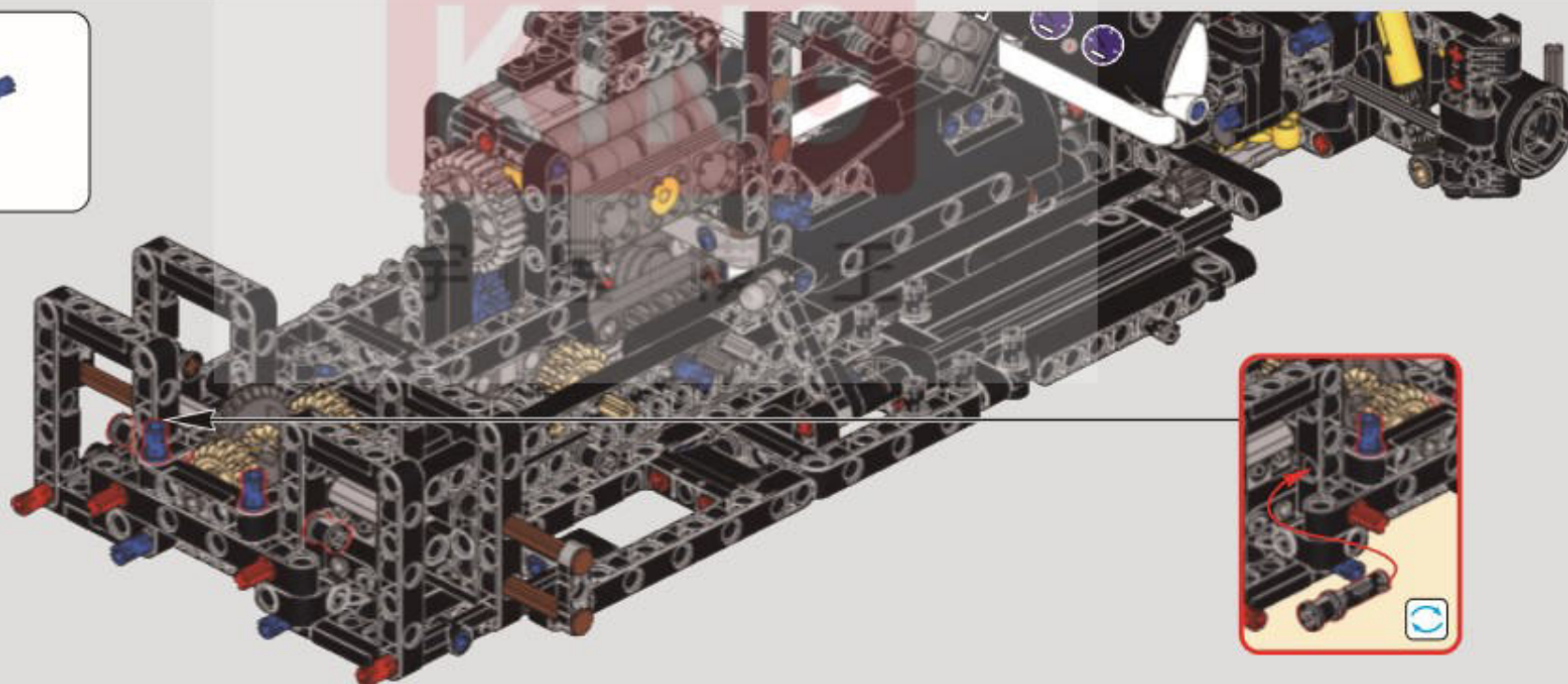


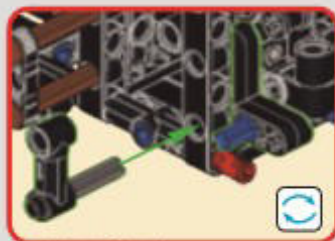


193

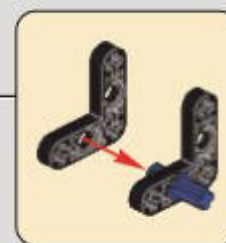
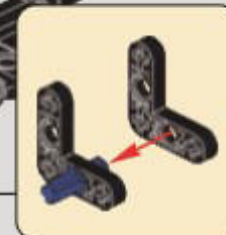


194

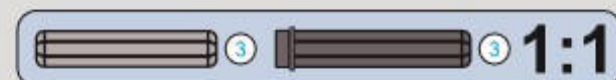
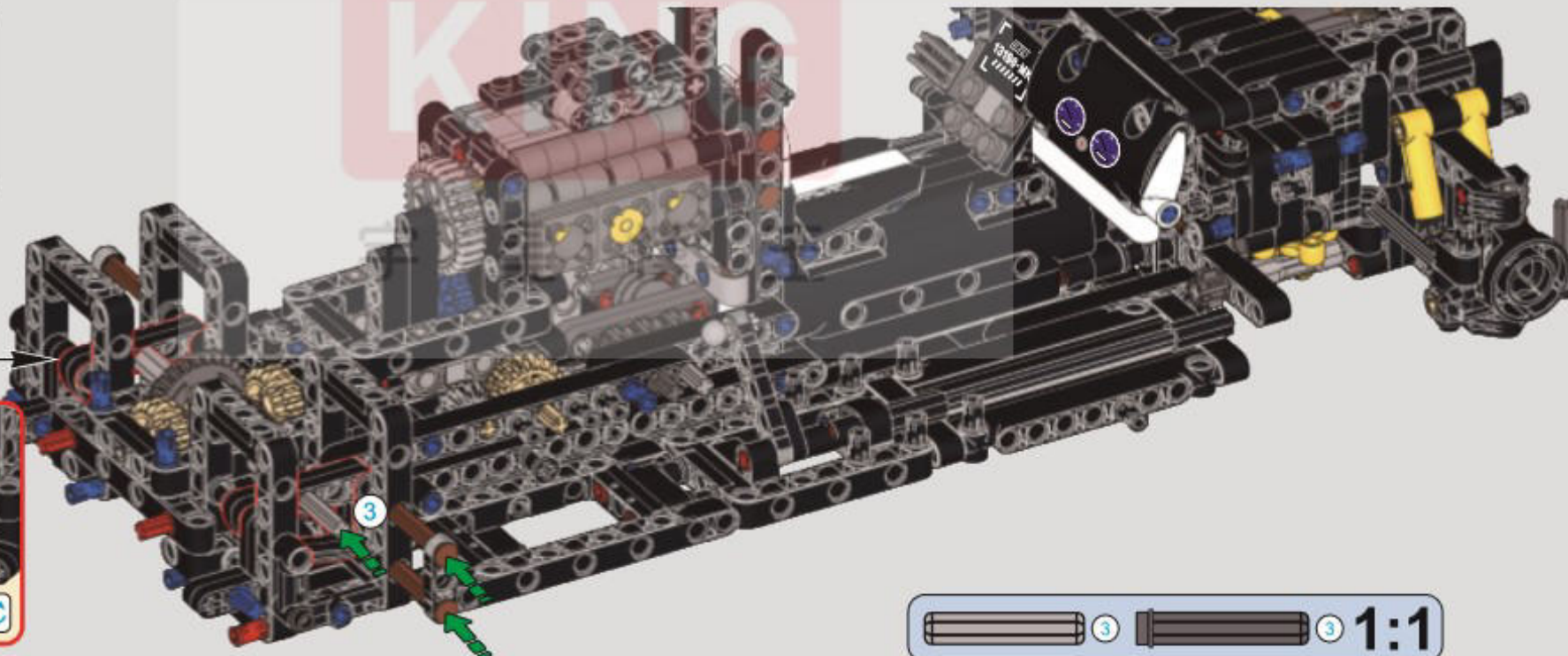
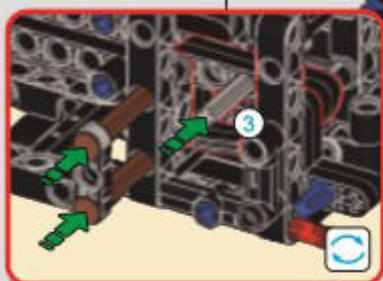


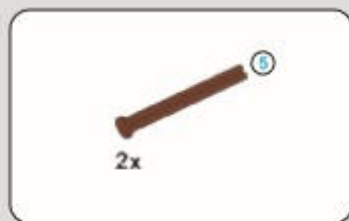


195

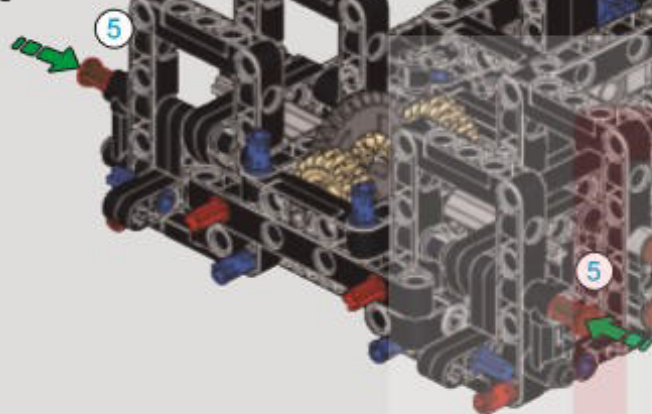


196

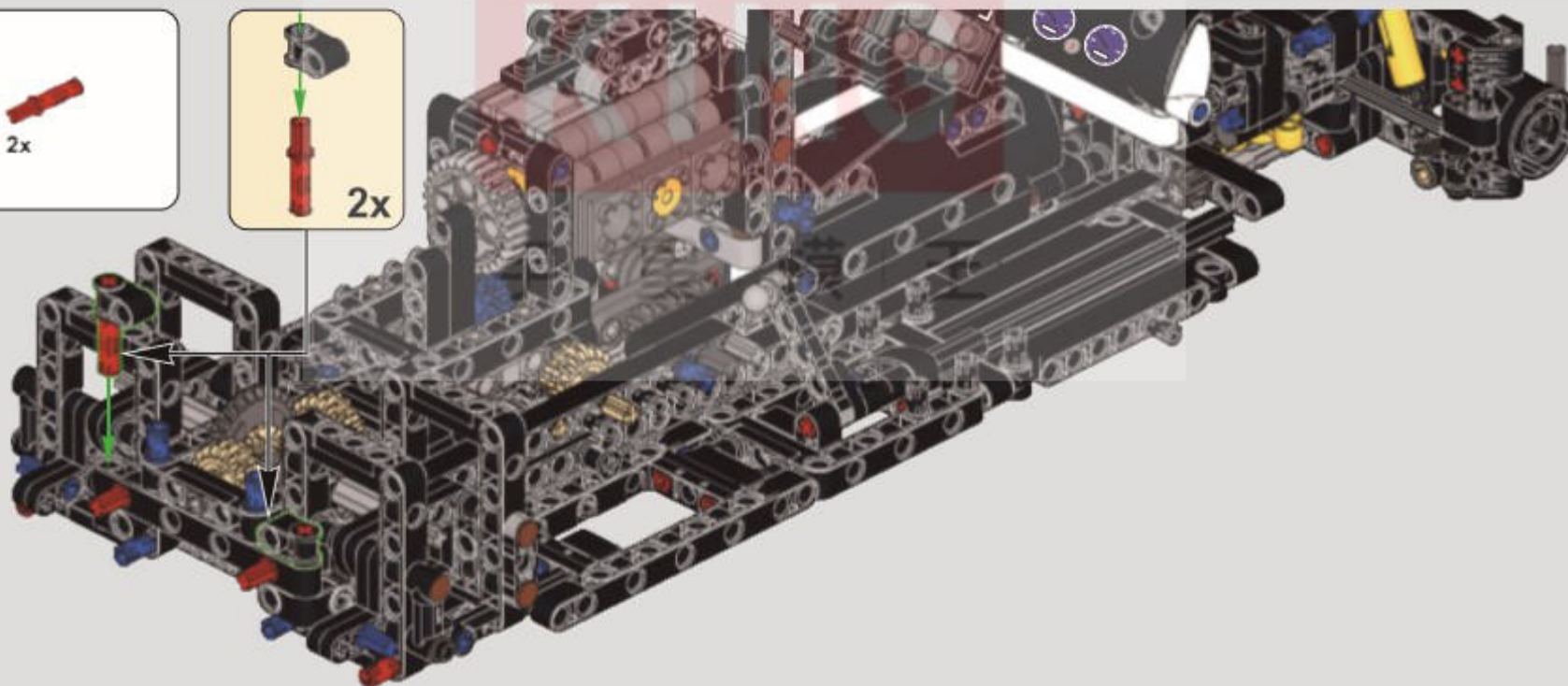
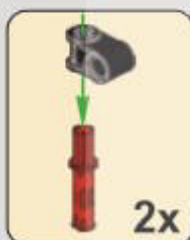




197

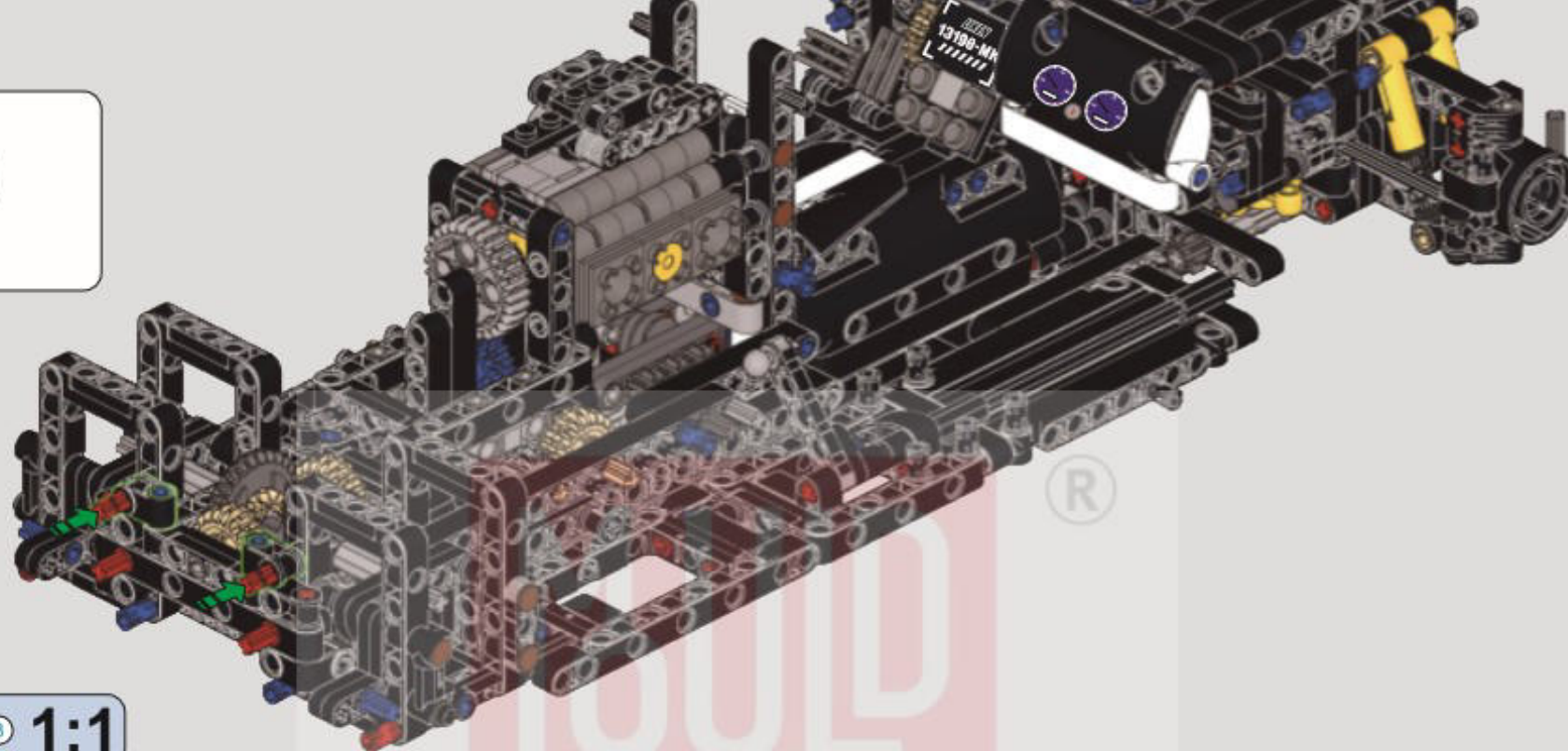


198

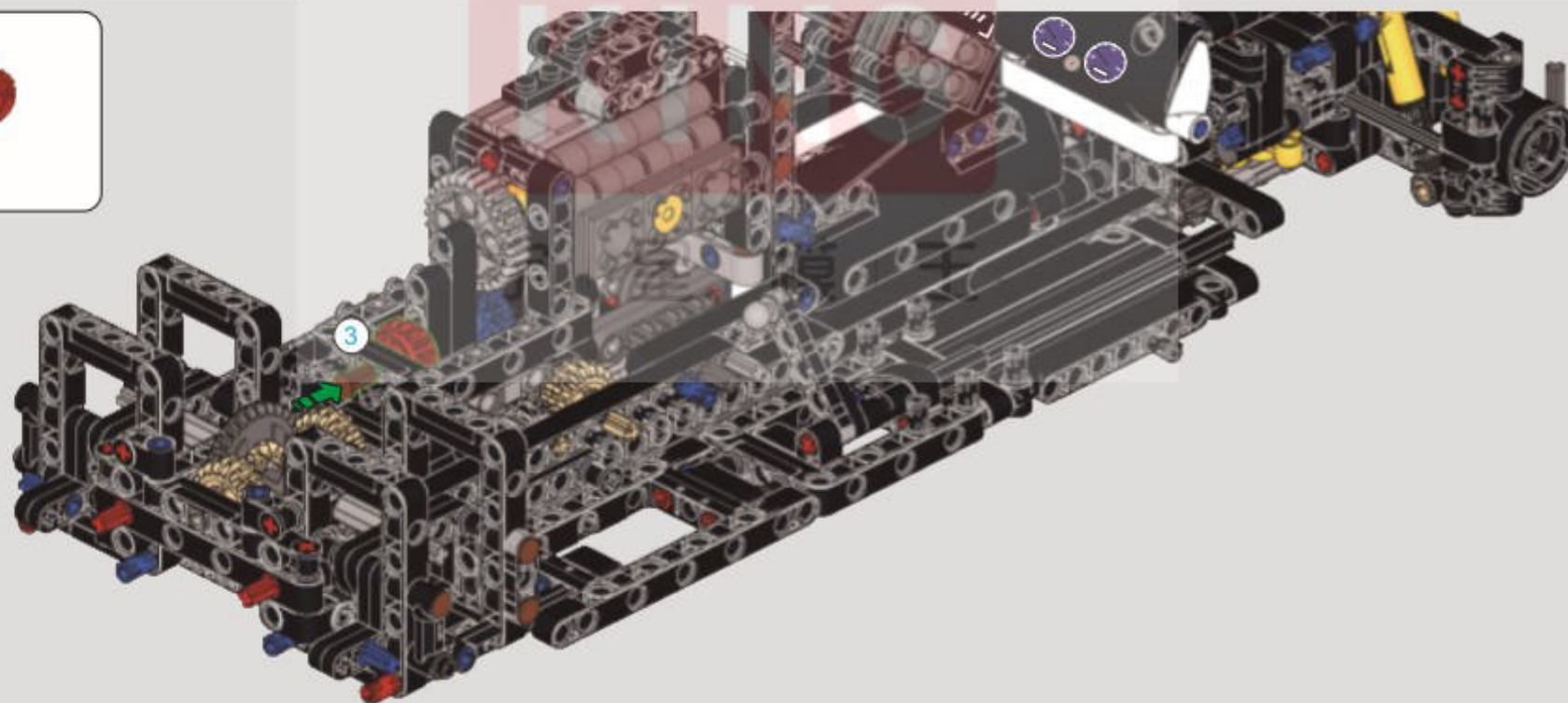


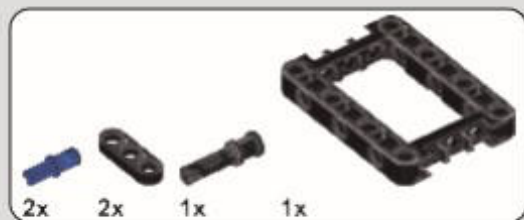


199

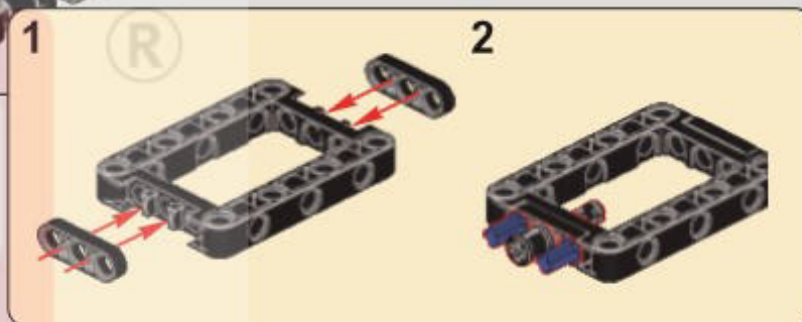
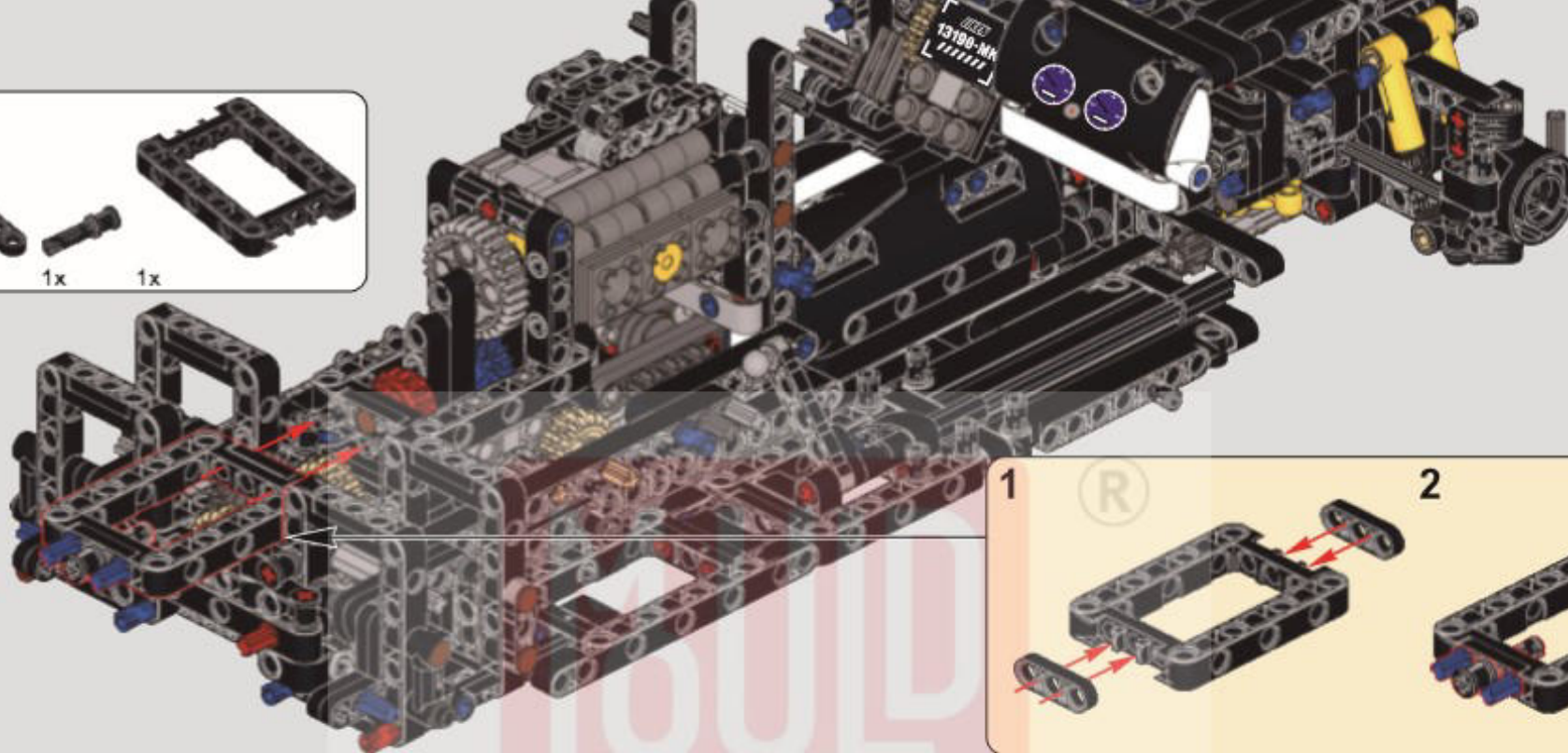


200

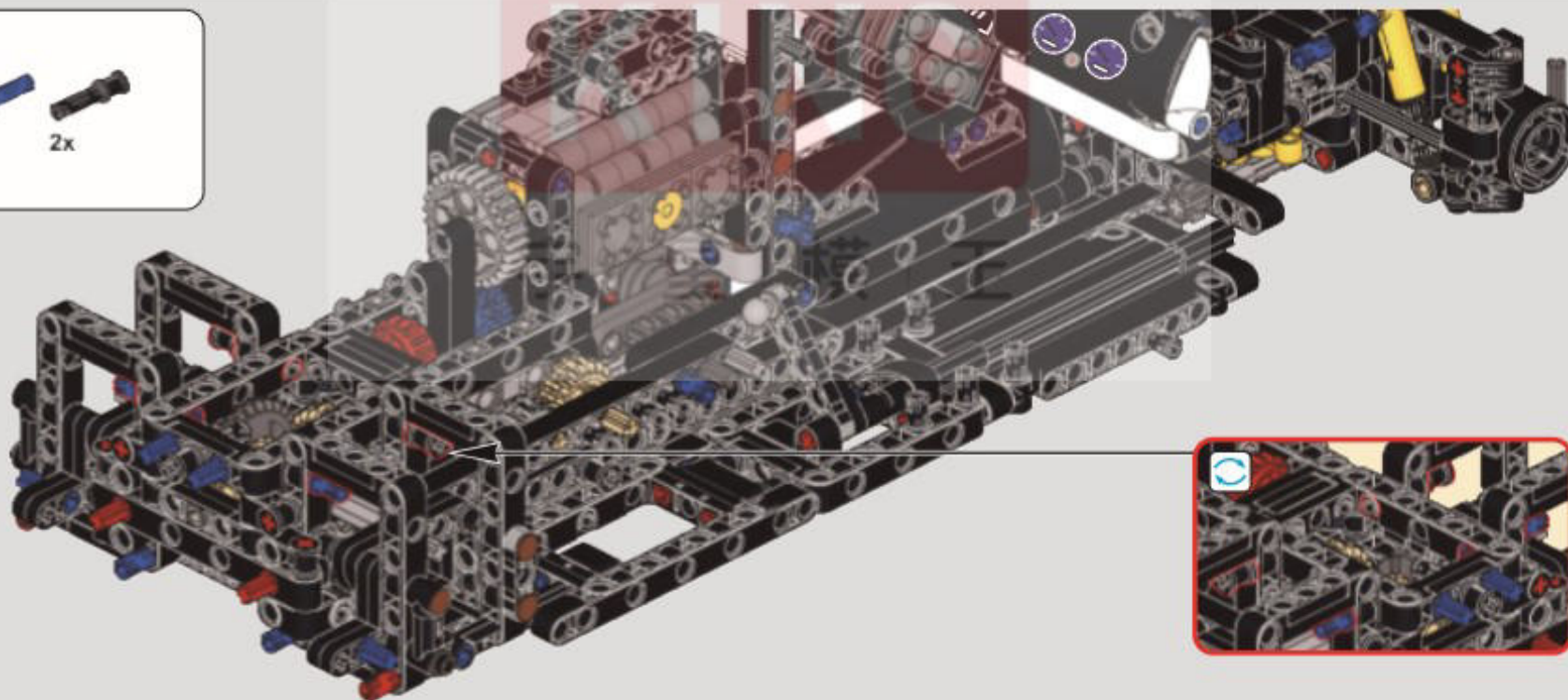




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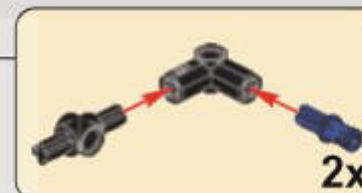
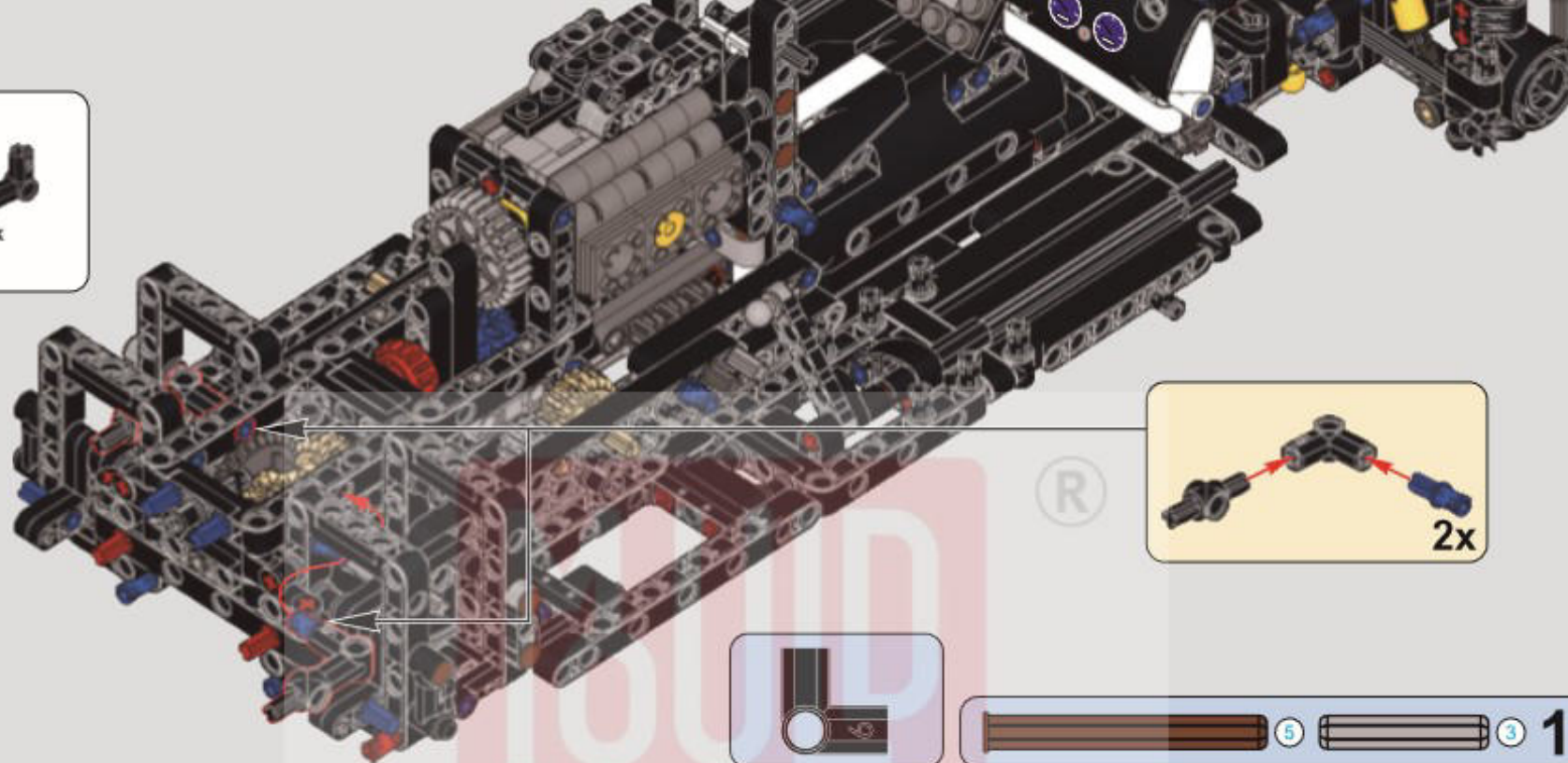


202

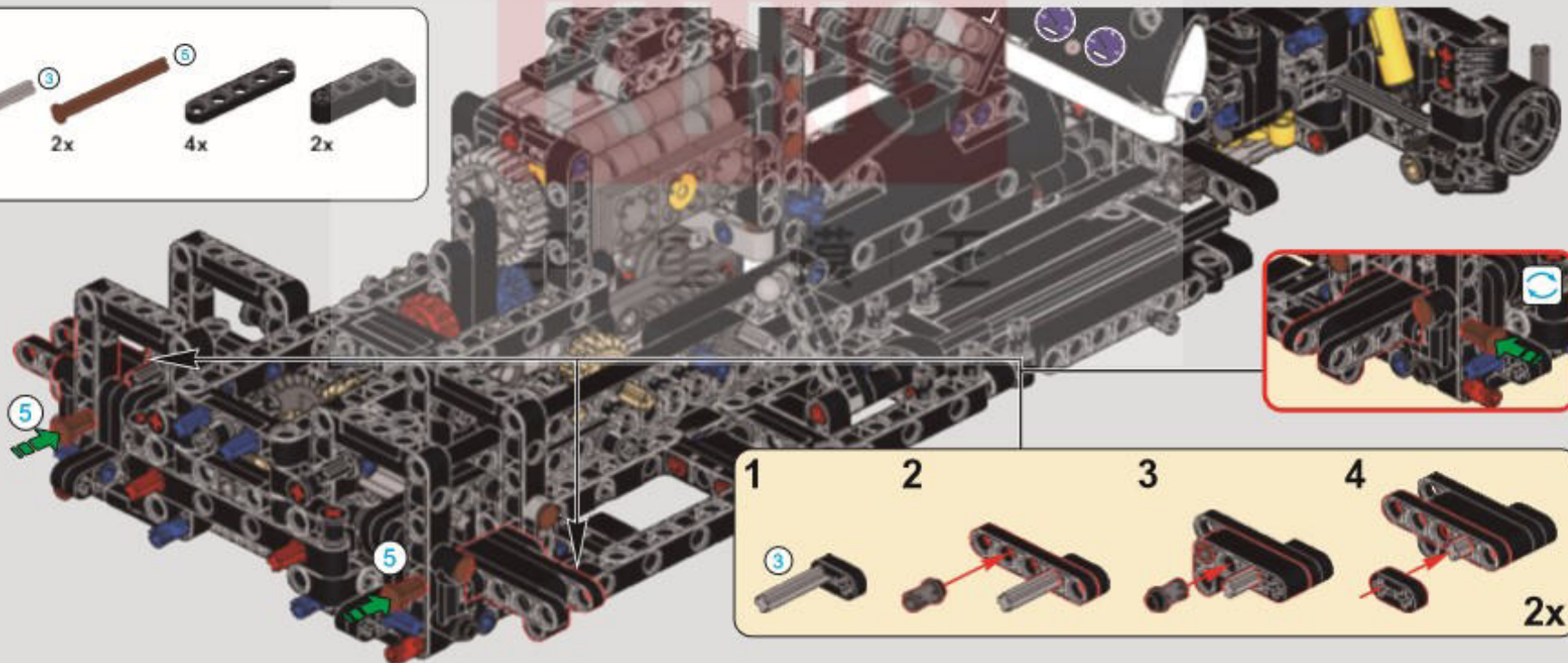




203

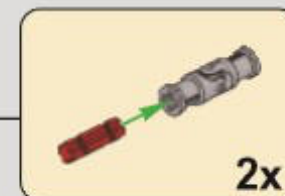
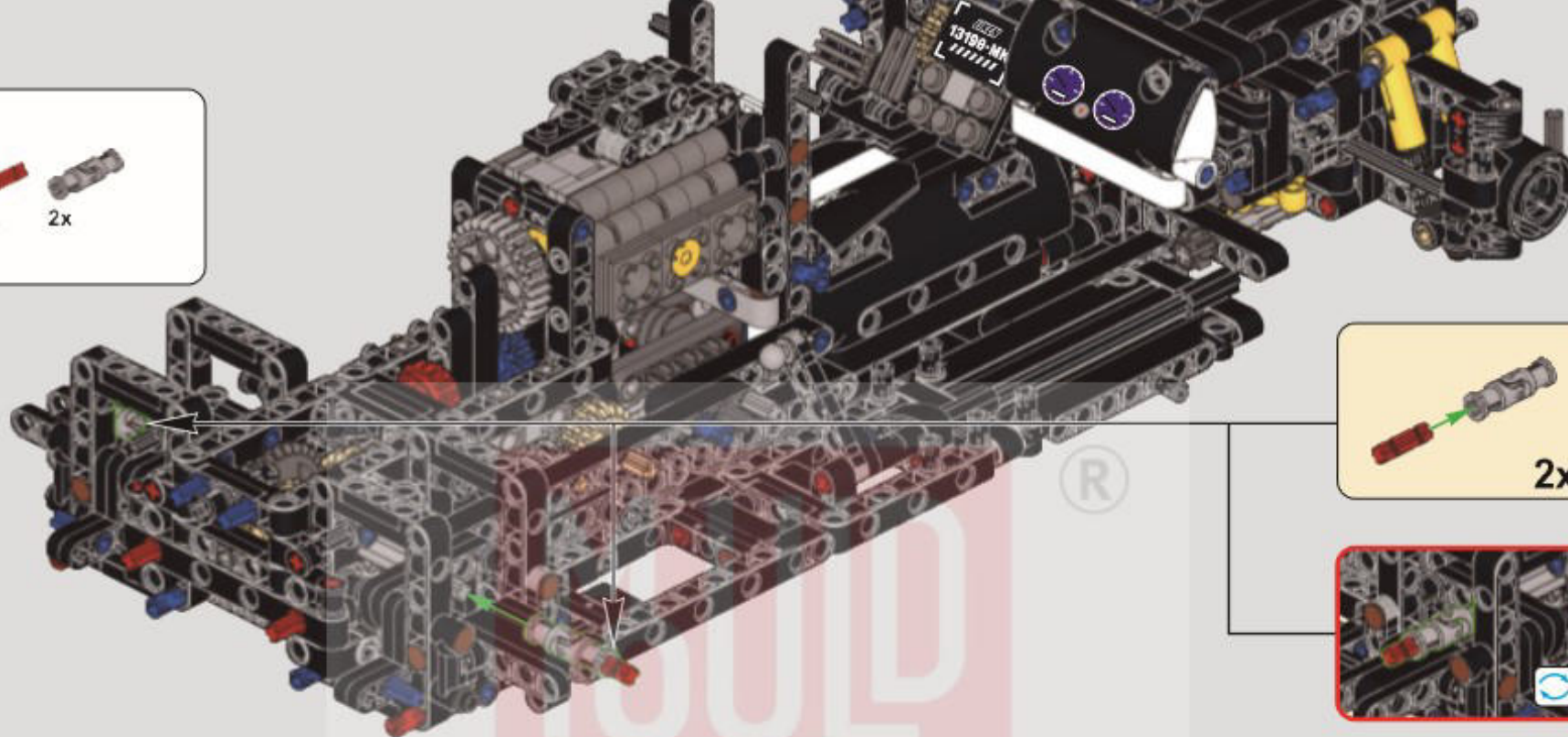


204

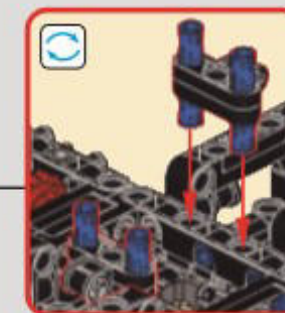
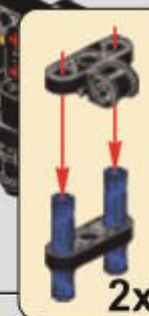
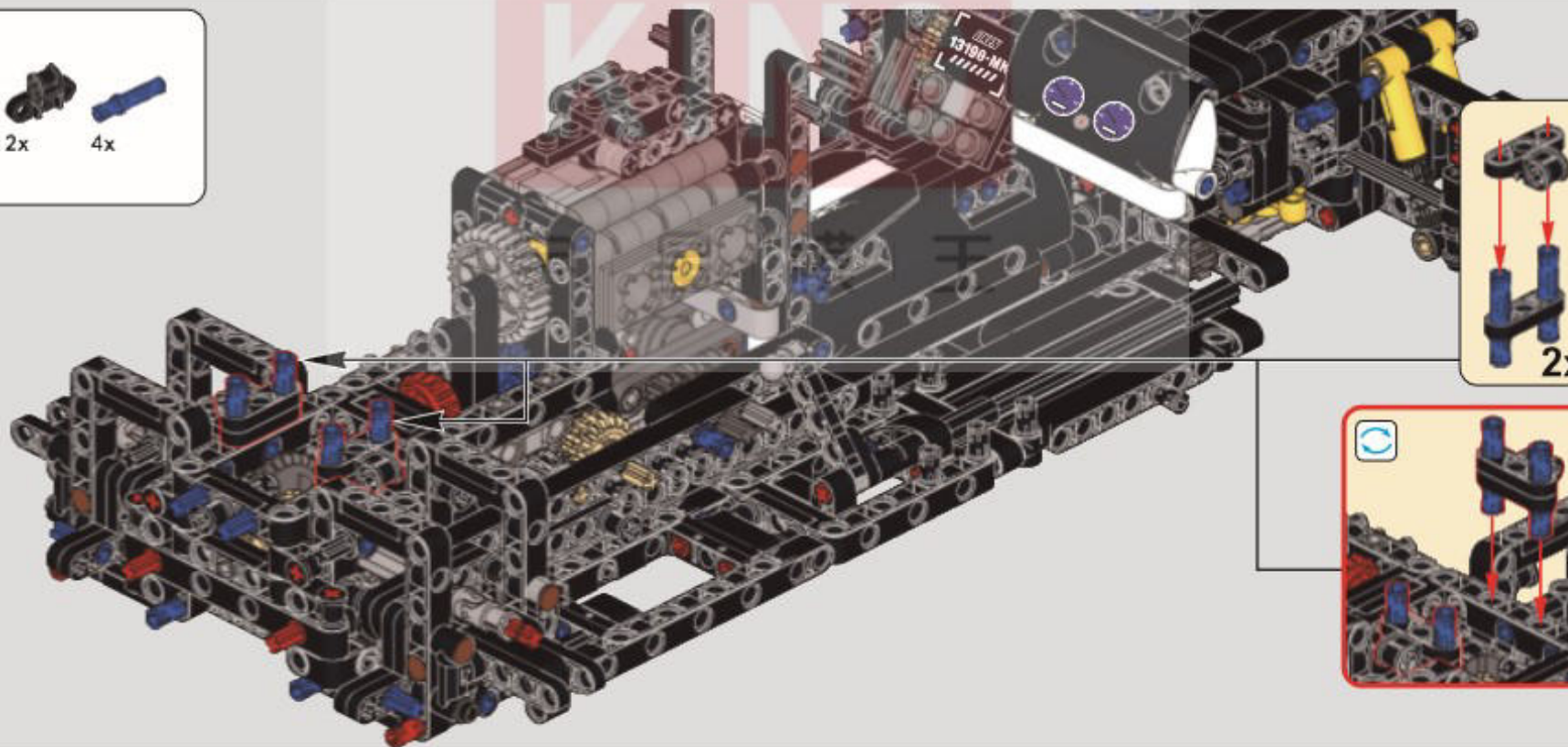




205

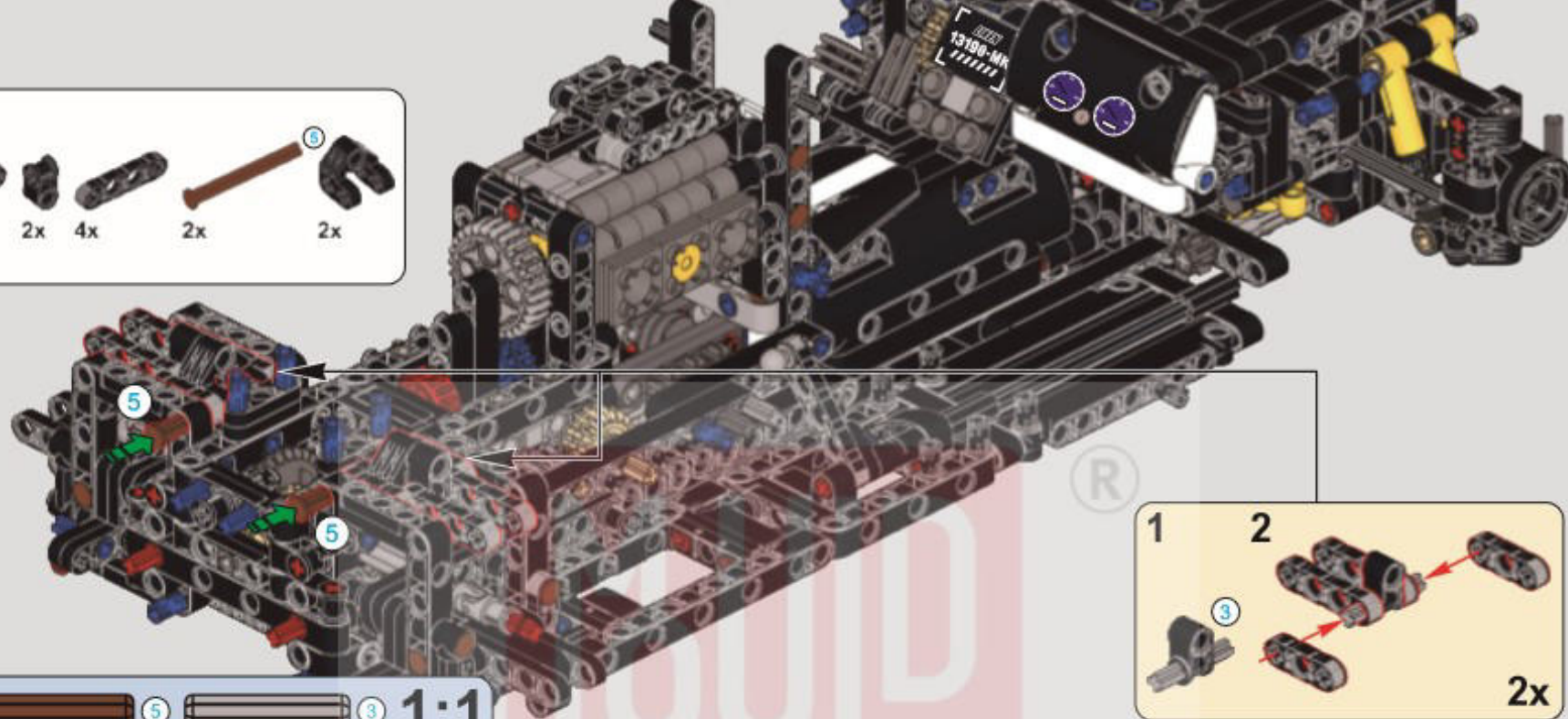


206

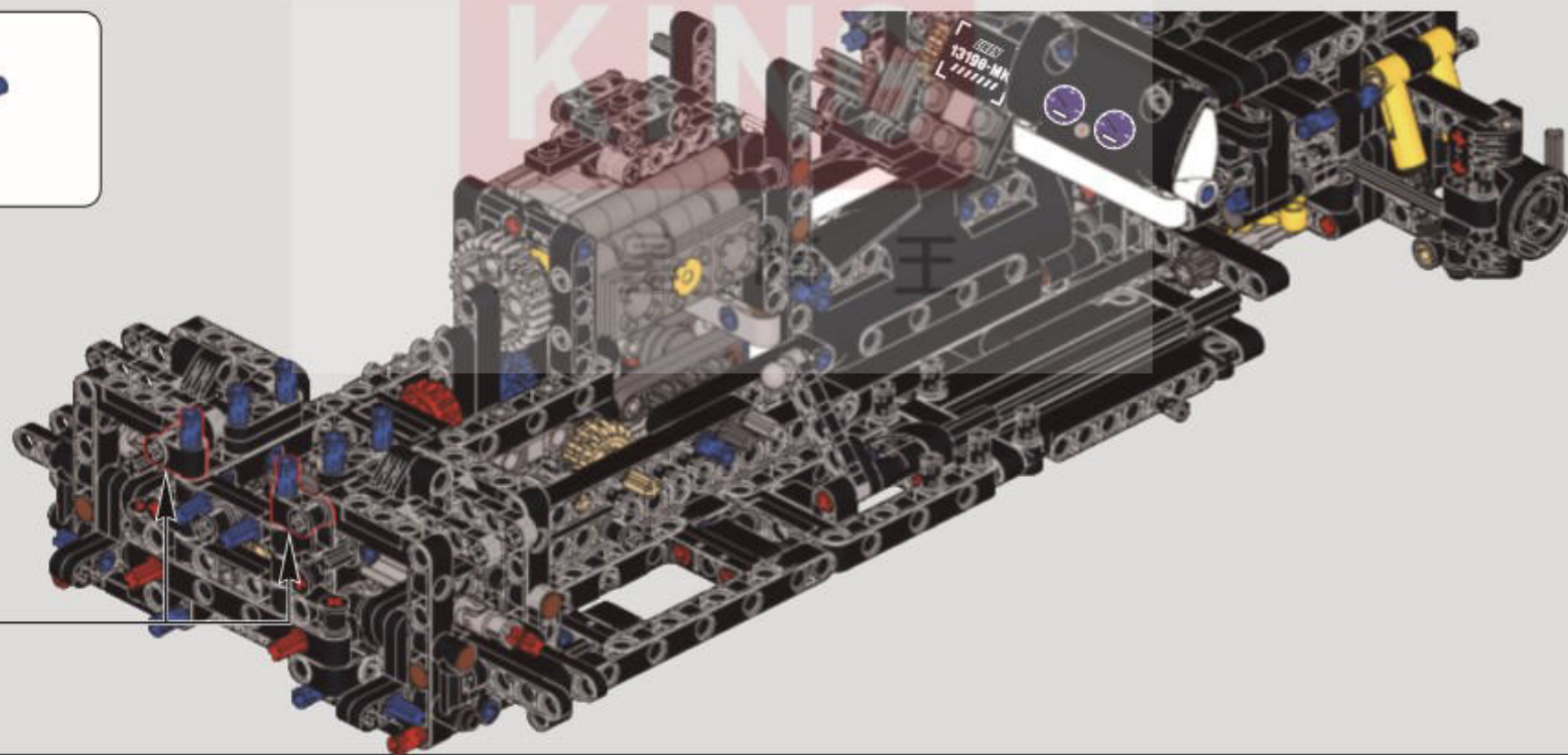




207

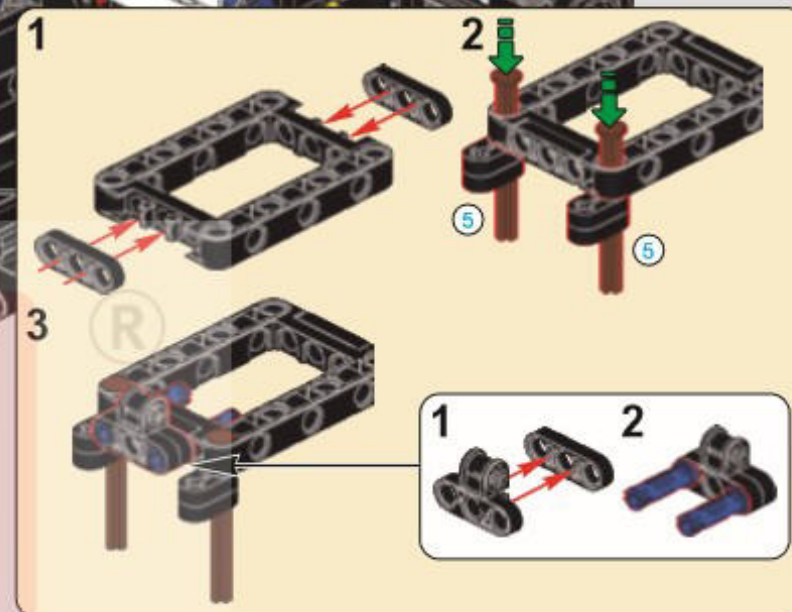
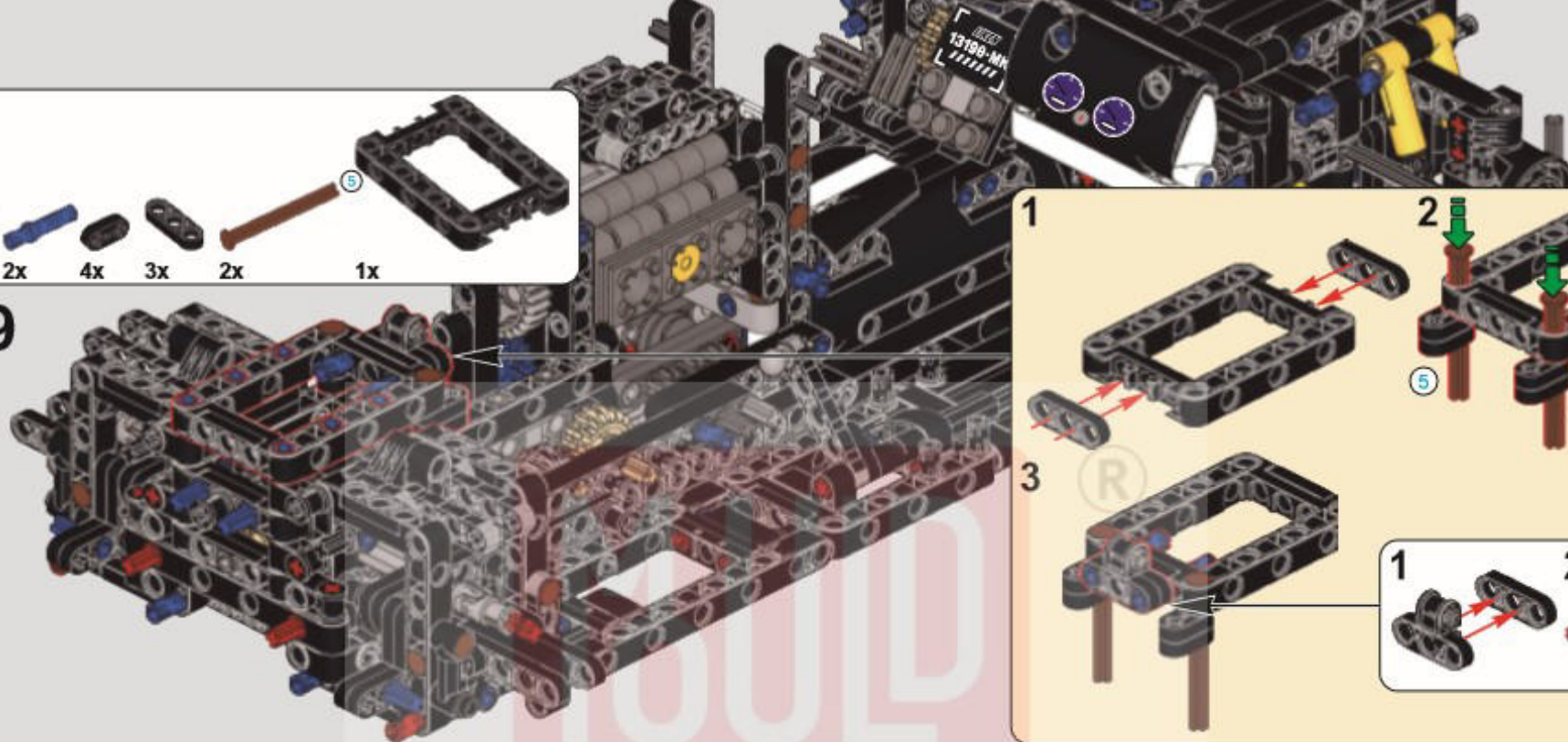


208

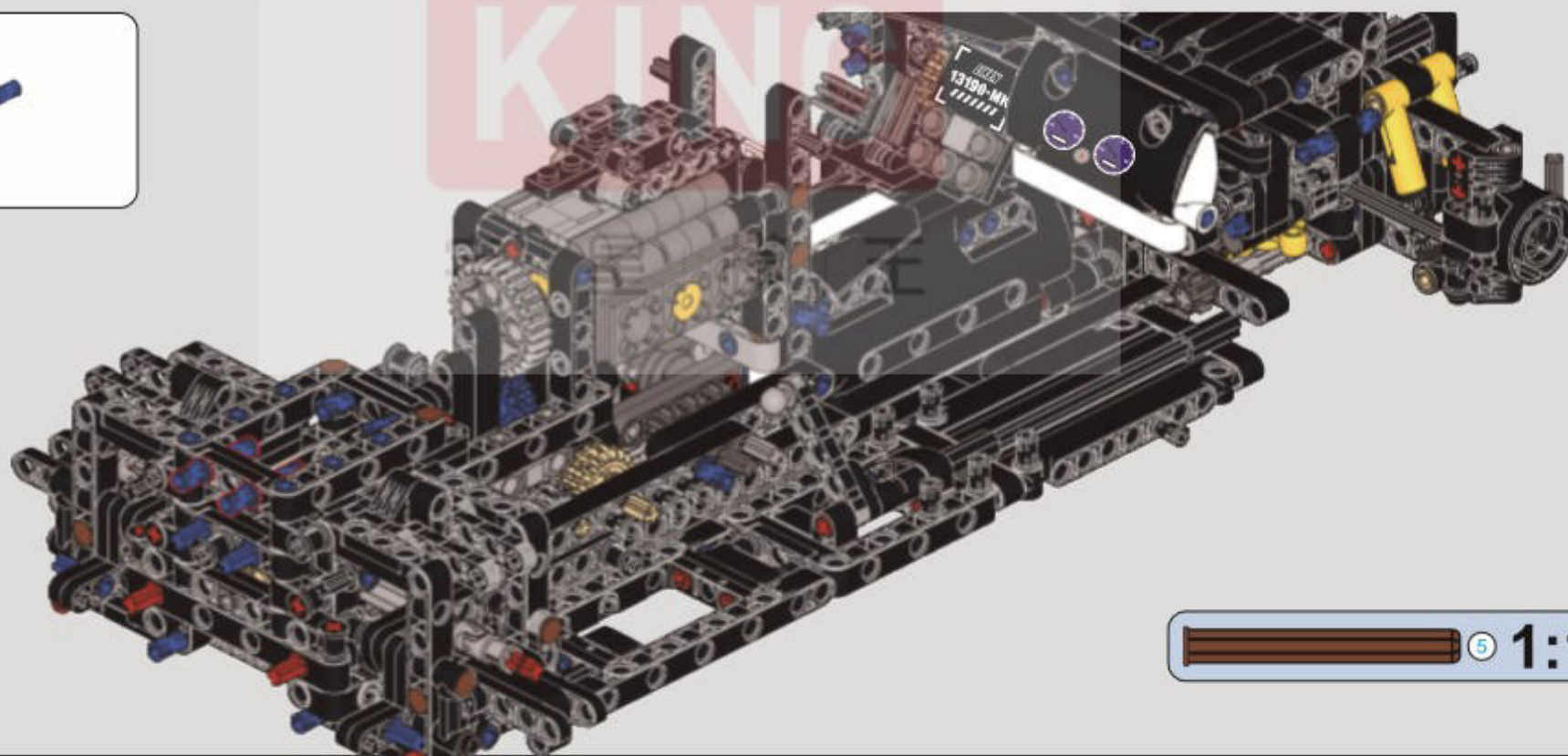




209

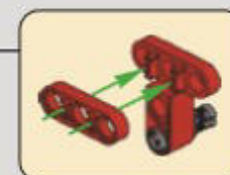
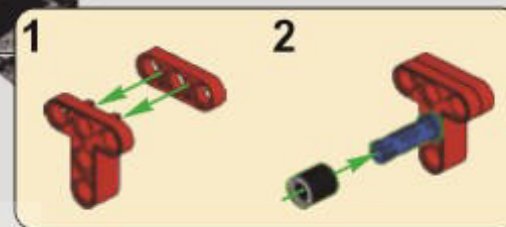
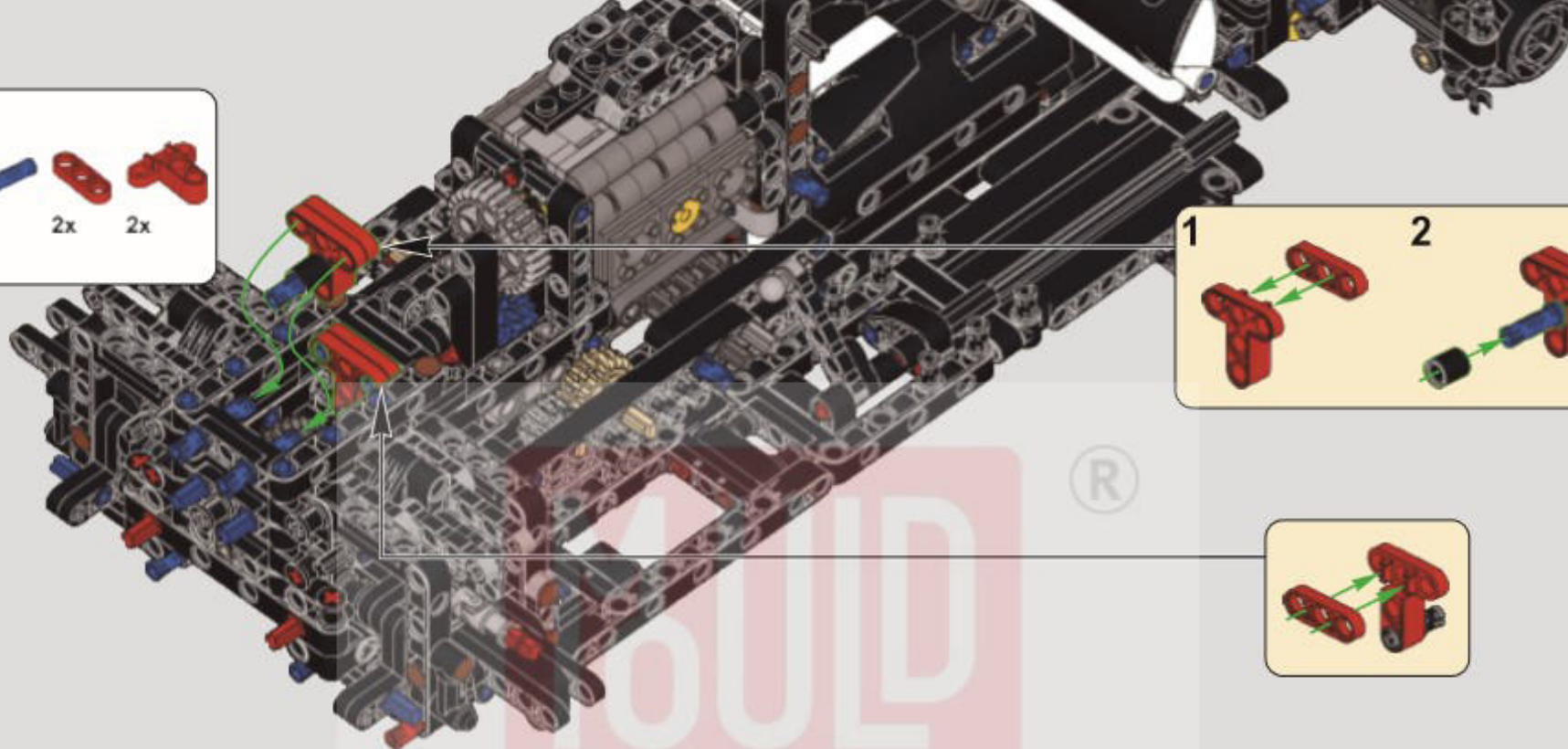


210

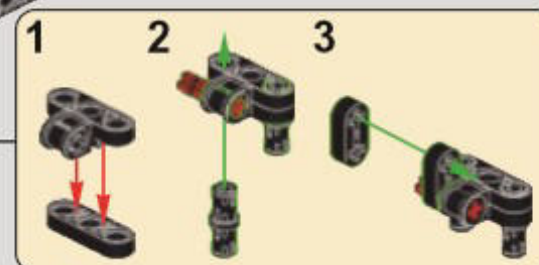
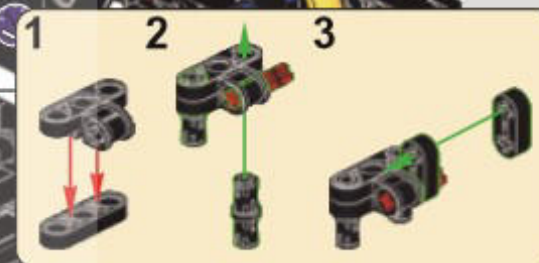
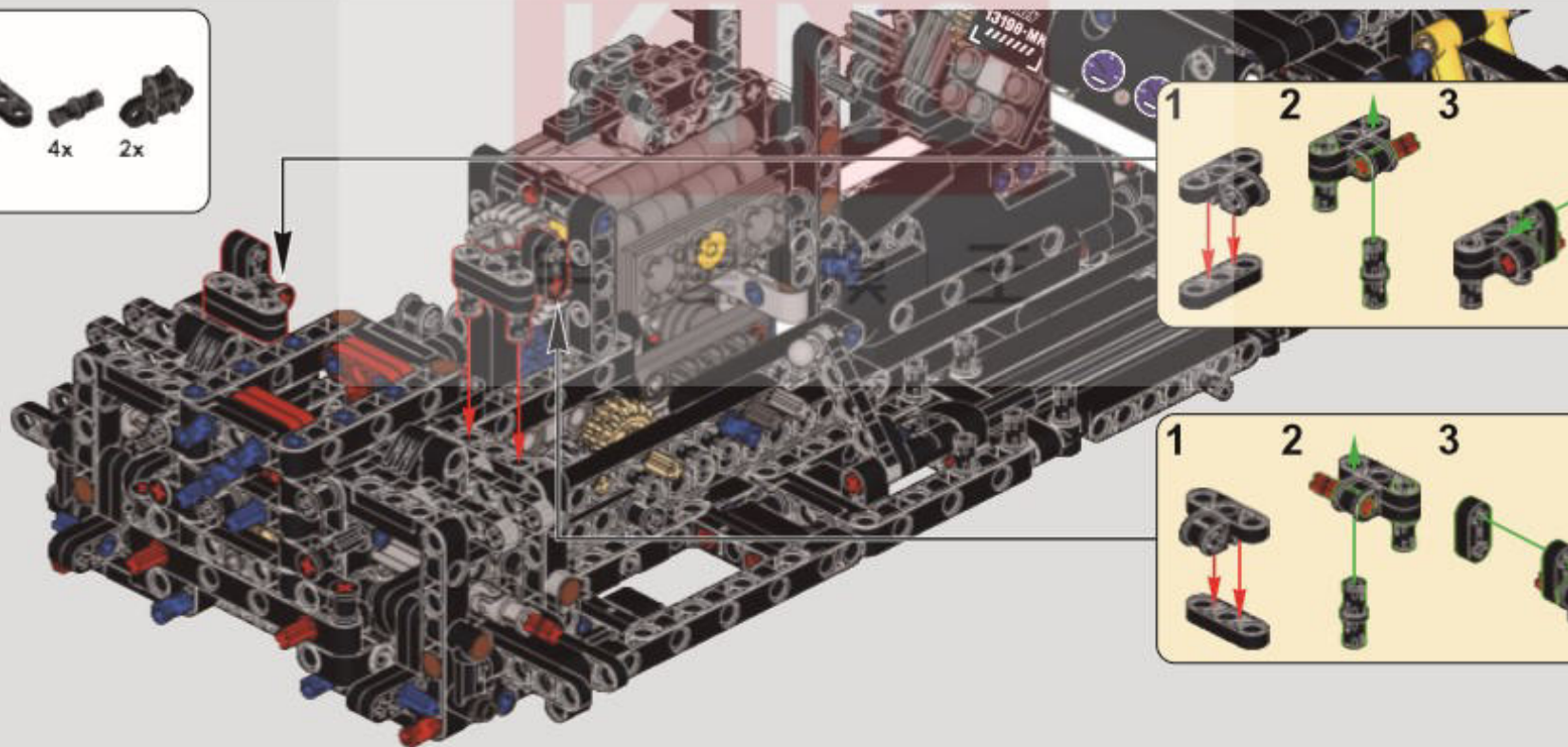




211

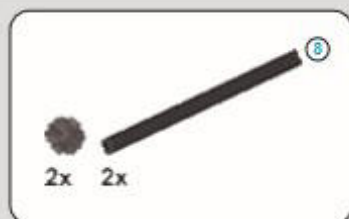
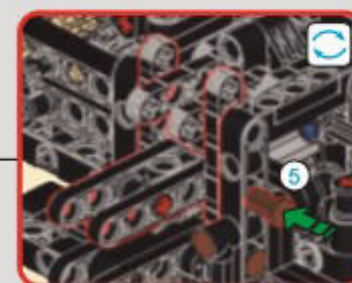
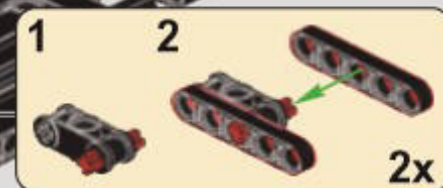
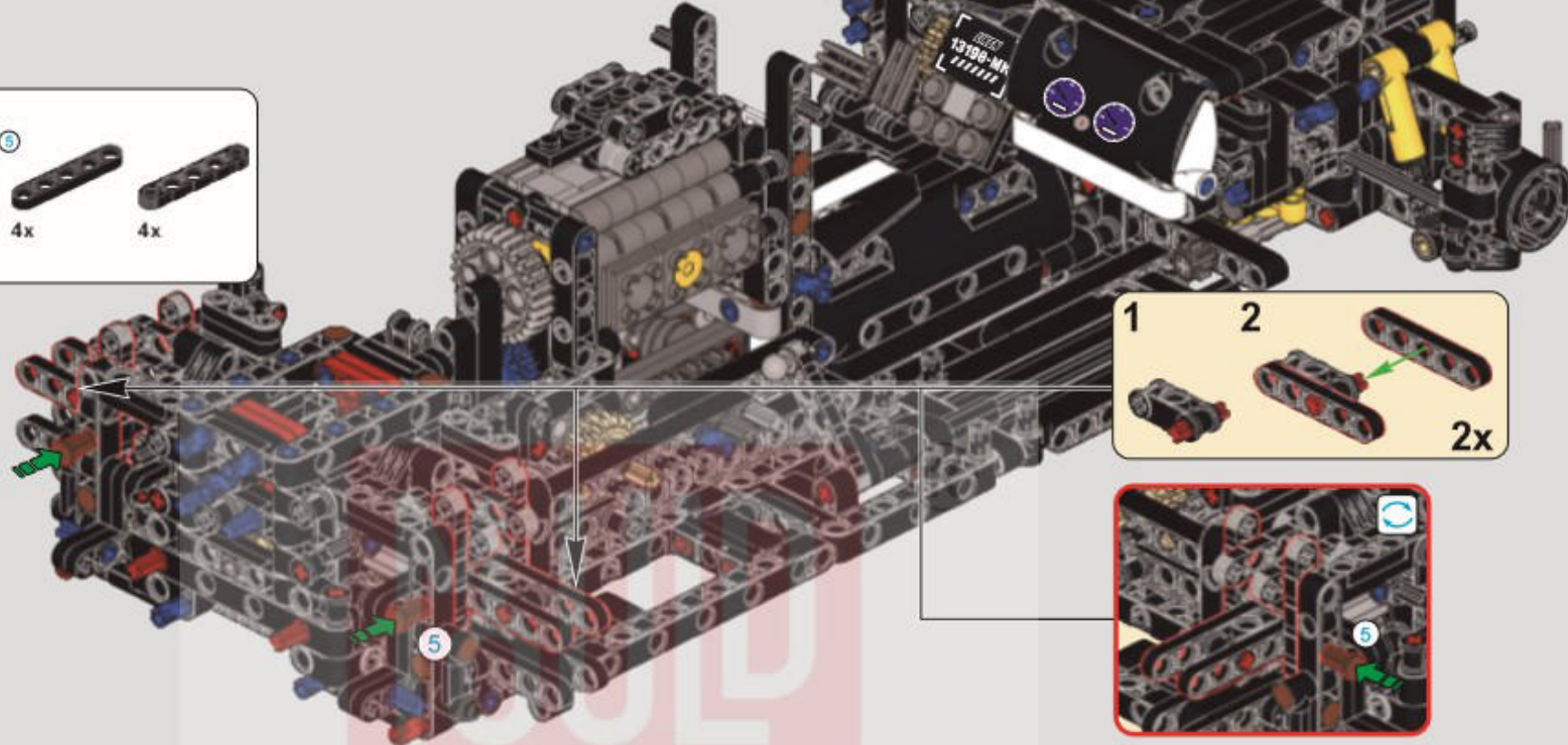


212

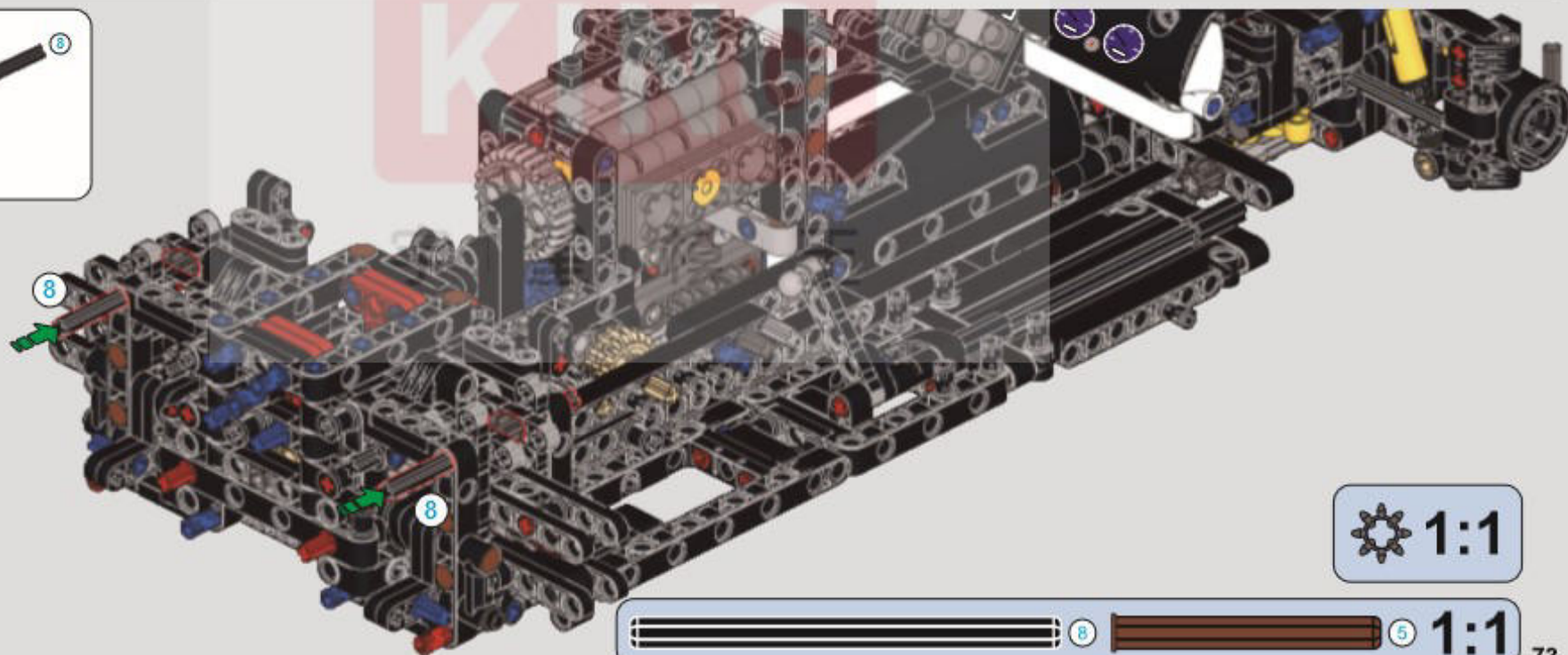




213

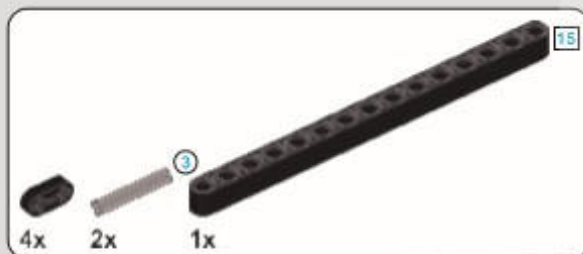
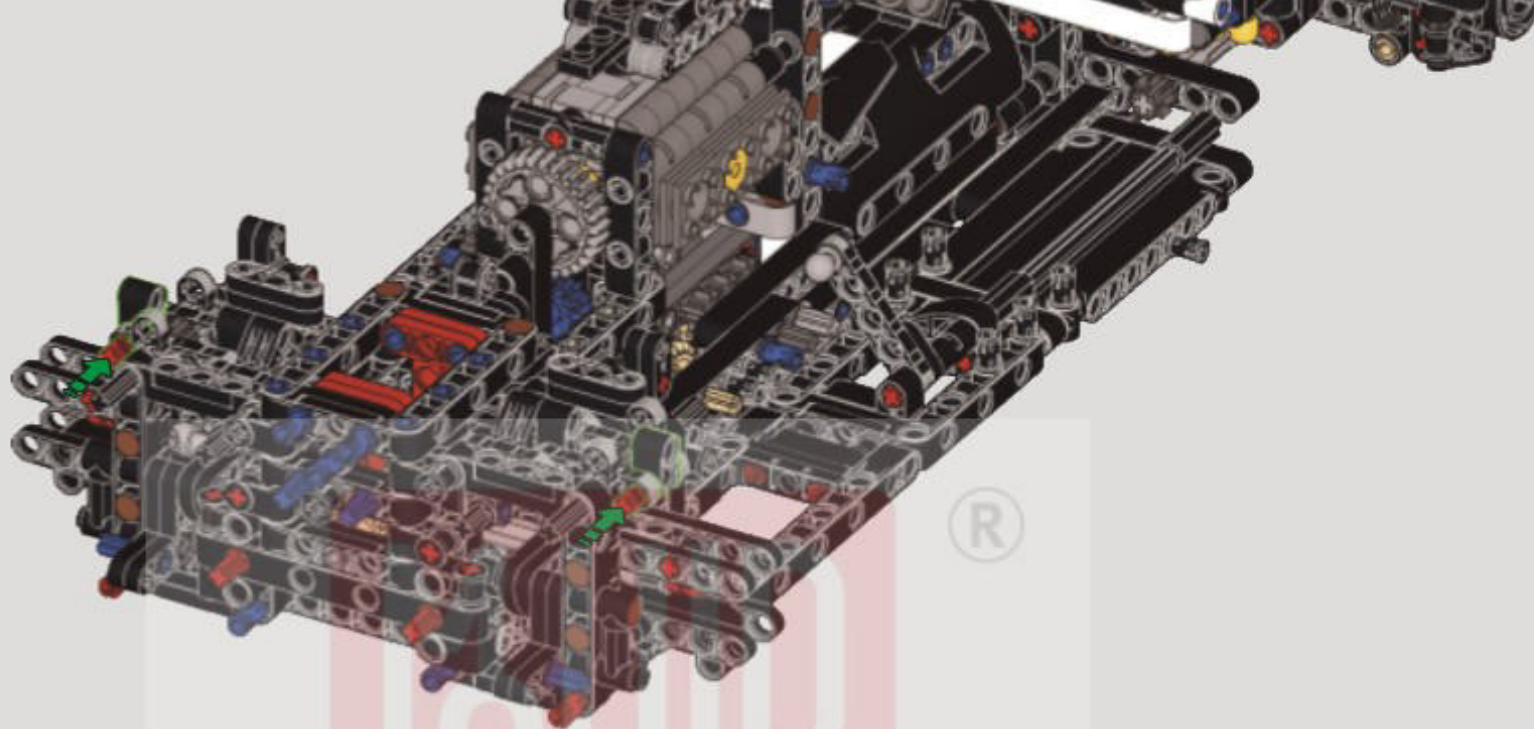


214

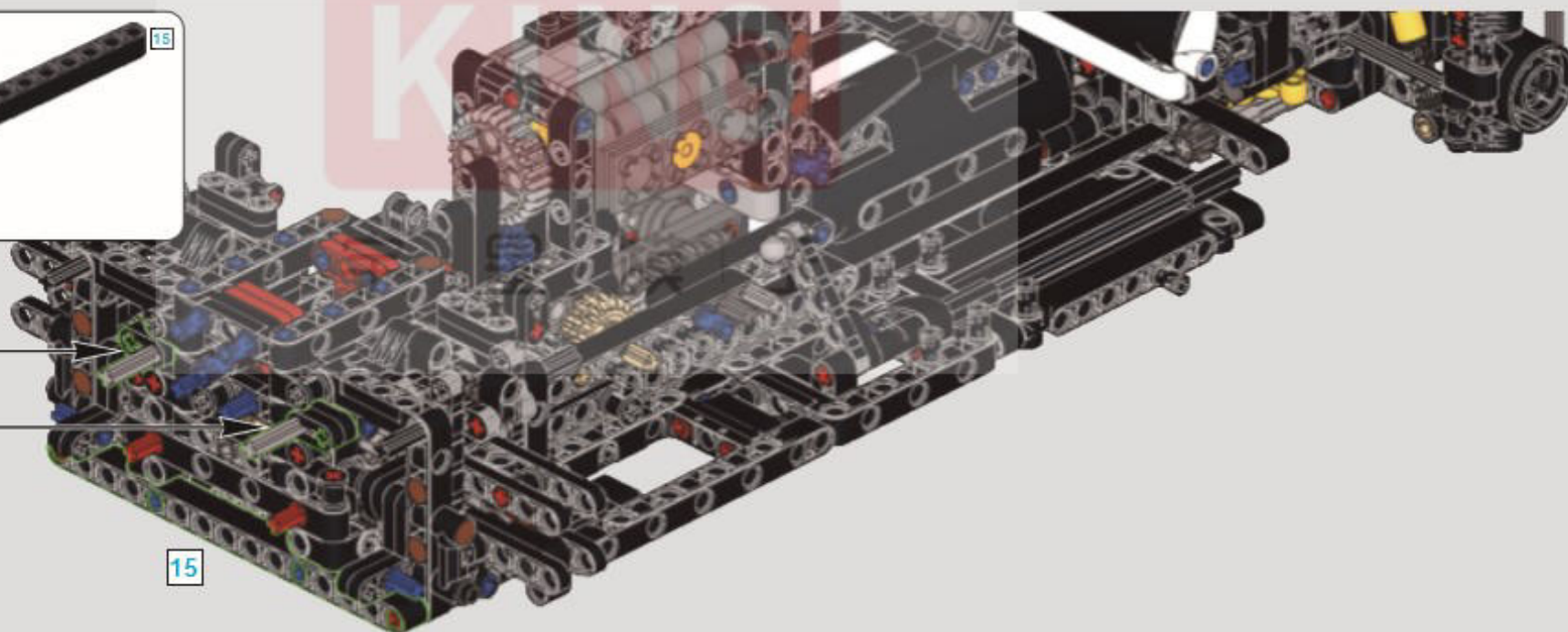
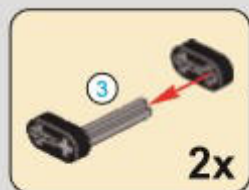




215



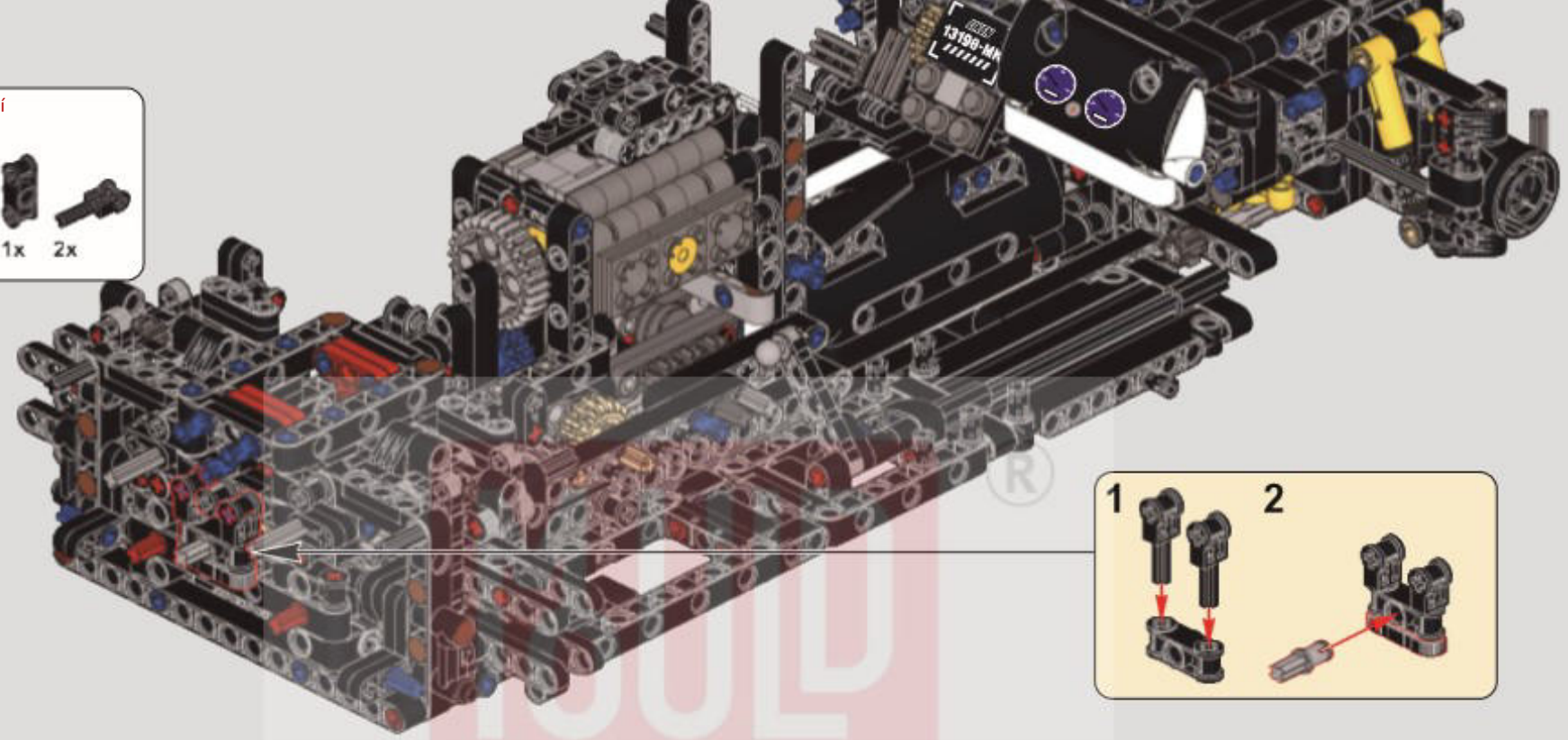
216



Tech. pin bez tření
(Technic Pin without Friction)

1x 1x 1x 2x

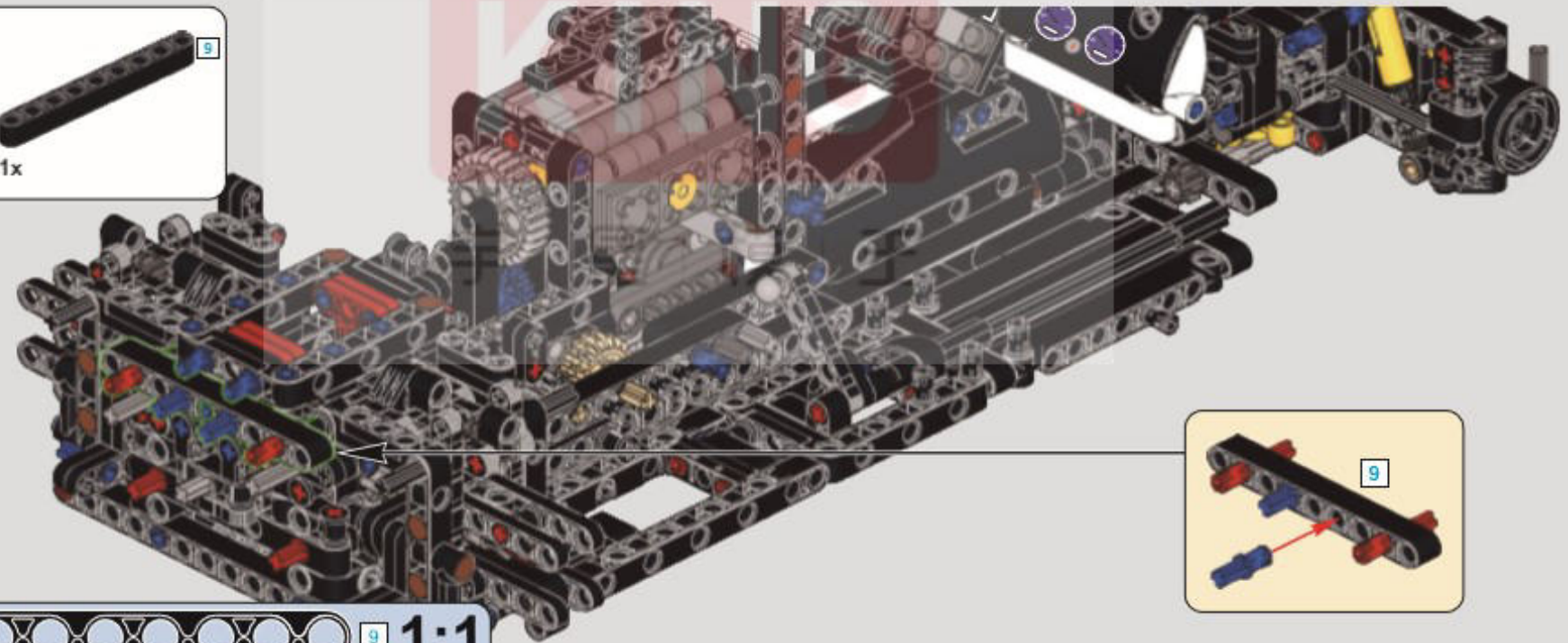
217



1 2

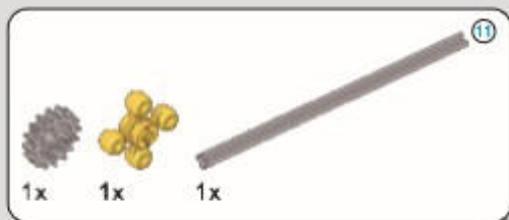
2x 2x 1x

218

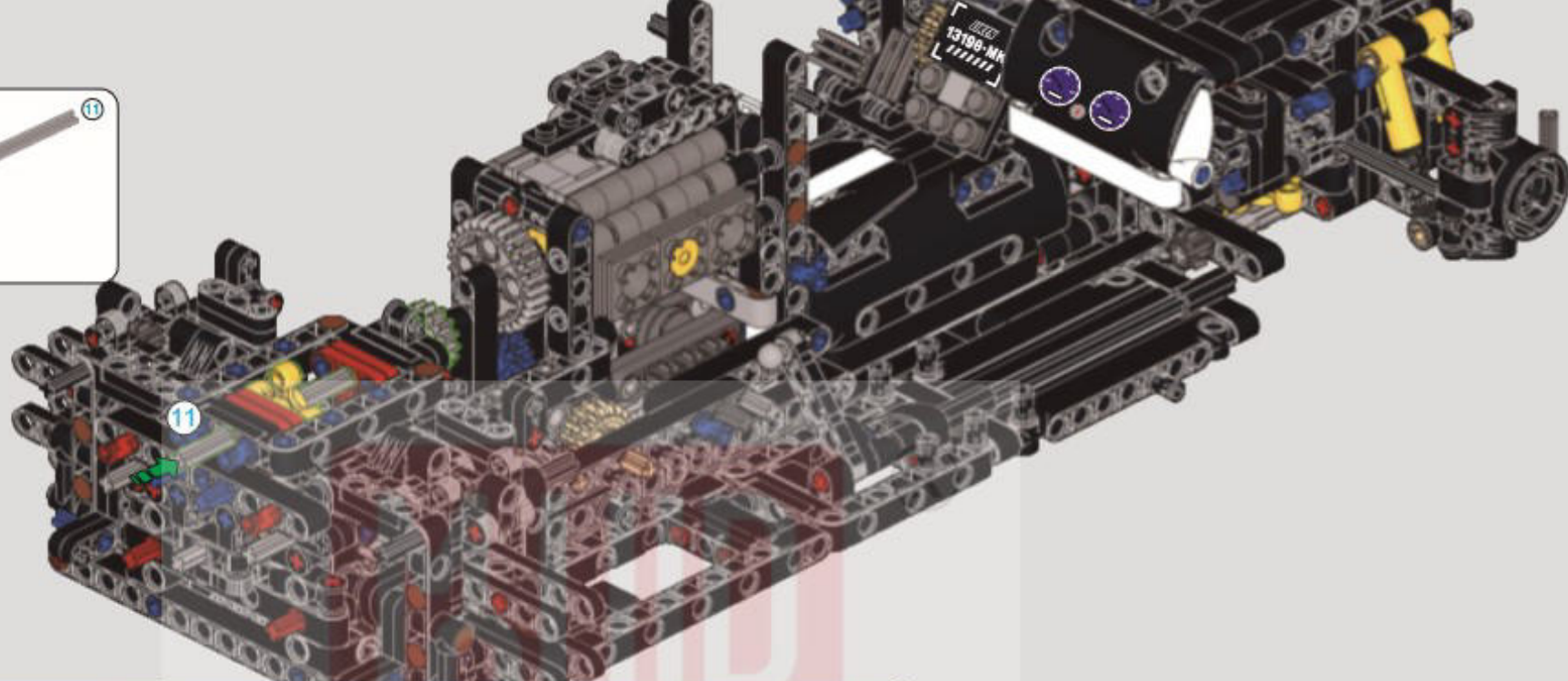


9

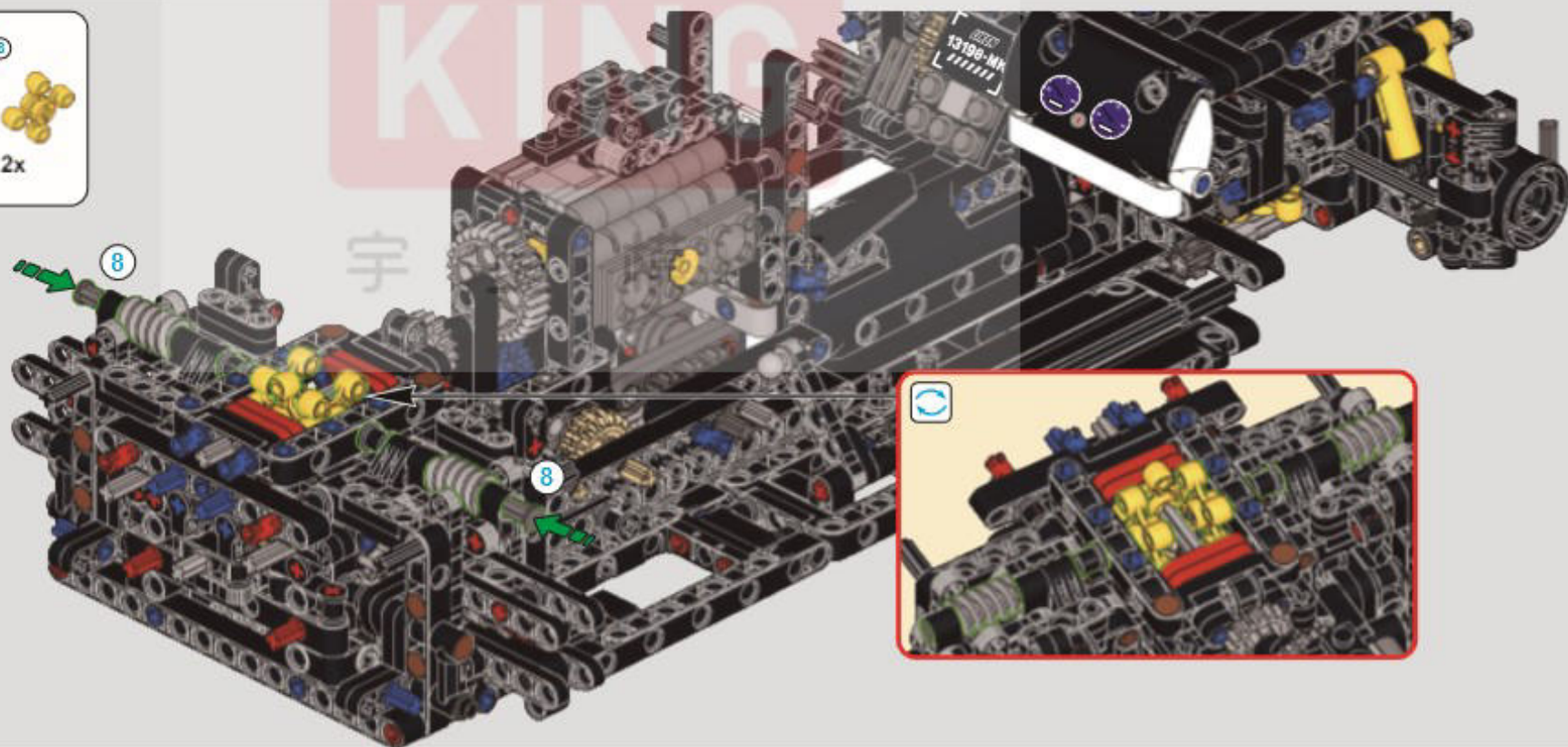
1:1

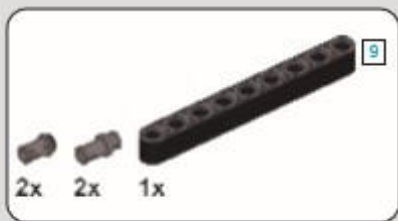


219

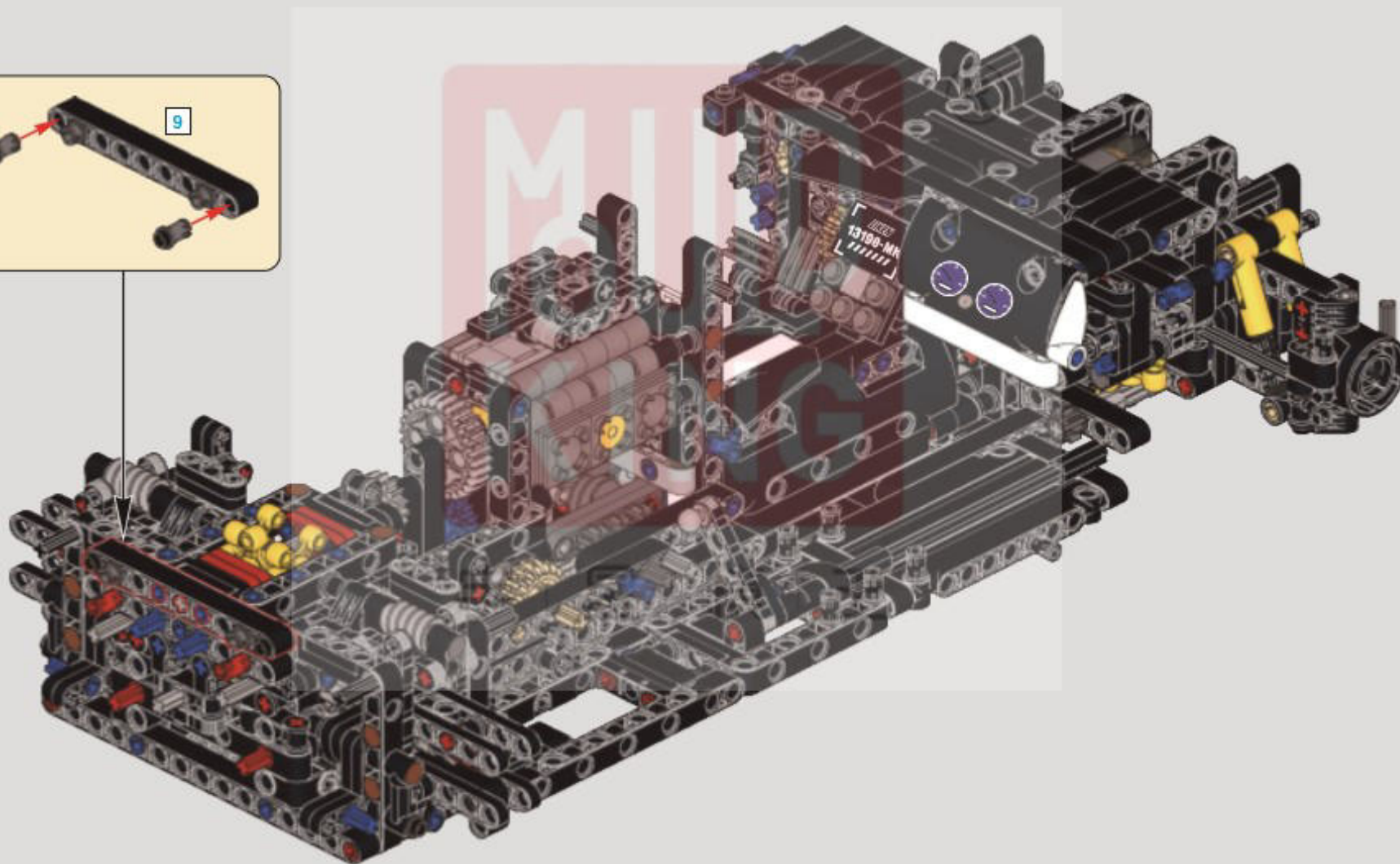
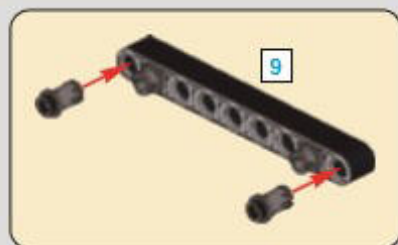


220





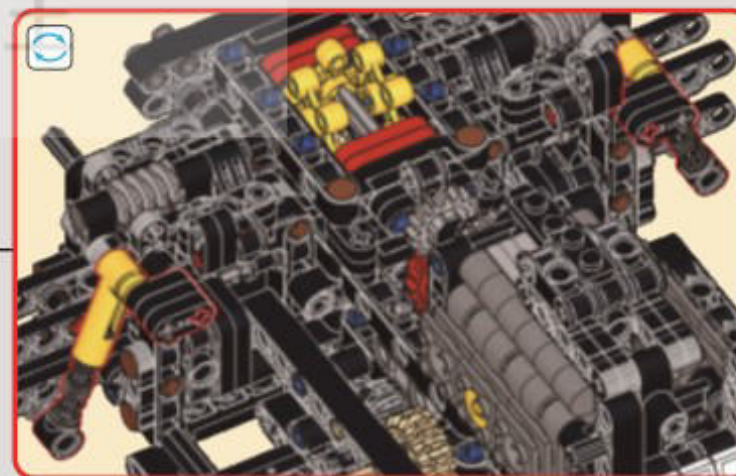
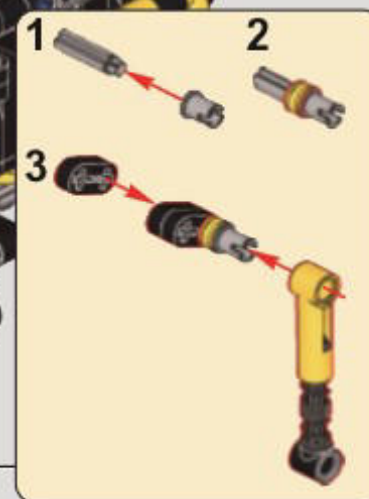
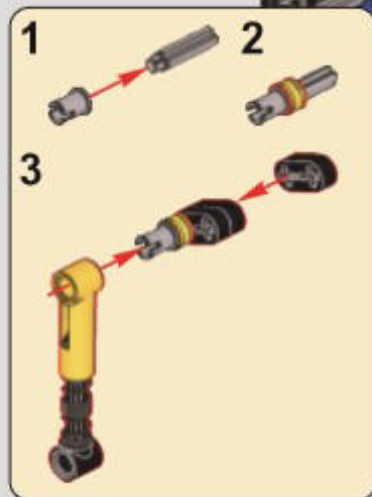
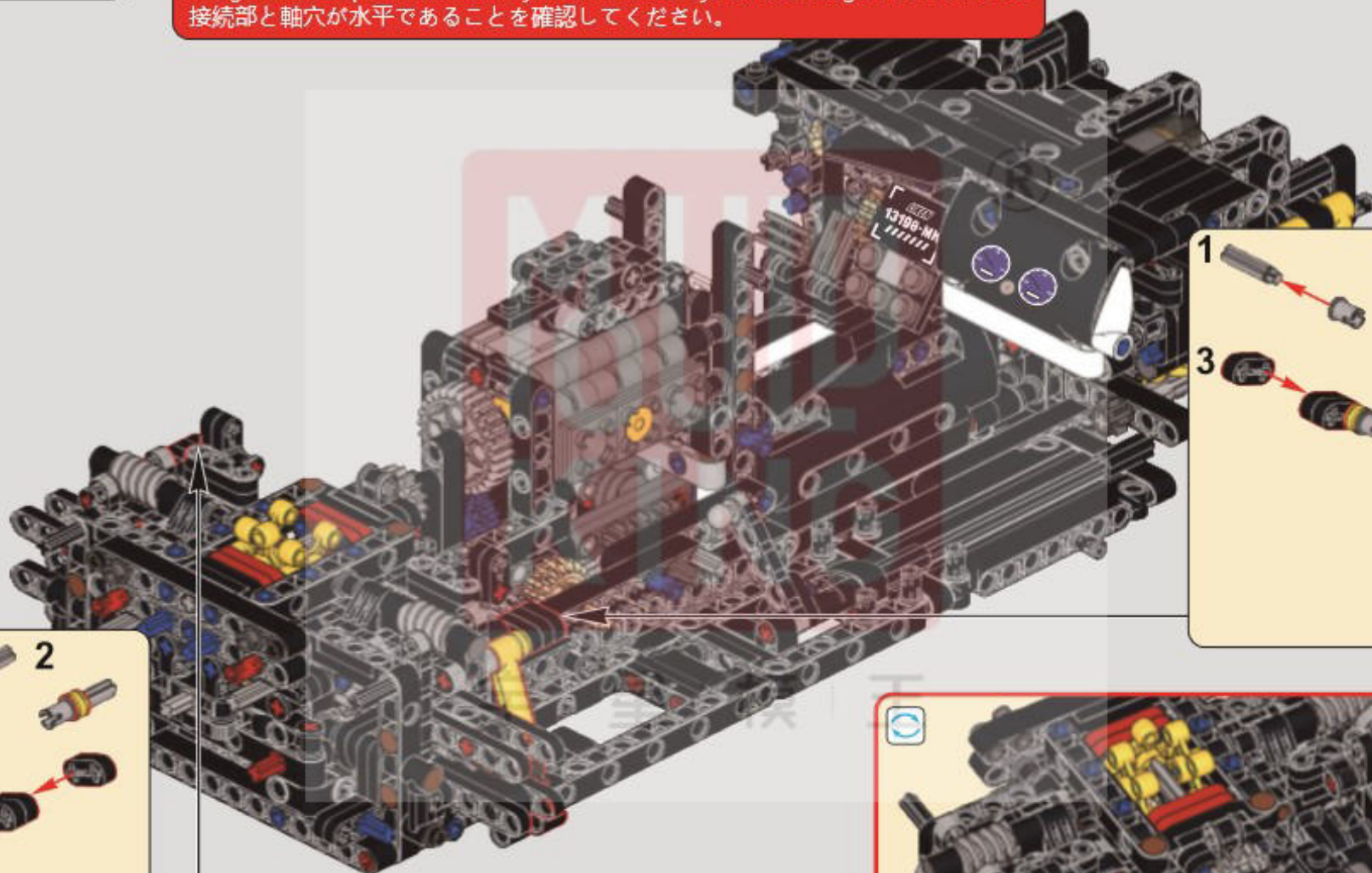
221





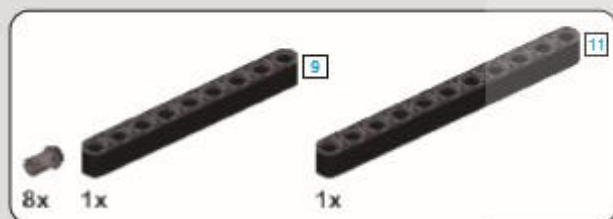
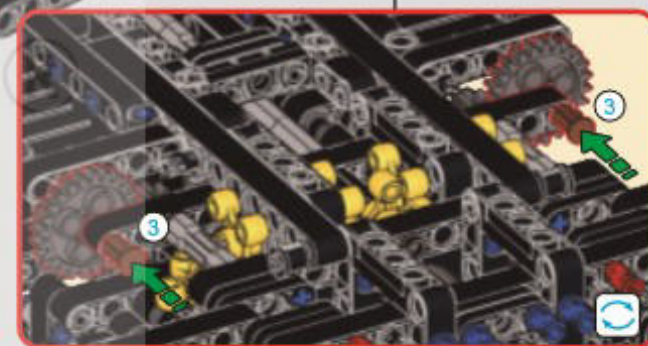
222

Ujistěte se, že spojení a otvor pro nápravu jsou vodorovné.
 Ensure that the connection and the axle hole are kept horizontal.
 Achten Sie darauf, dass die Verbindung und das Achsloch horizontal bleiben.
 Assurez-vous que la connexion et le trou de l'axe restent horizontaux.
 Assicuratevi che il collegamento e il foro dell'asse siano mantenuti orizzontali.
 Asegúrese de que la conexión y el orificio del eje se mantengan horizontales.
 接続部と軸穴が水平であることを確認してください。

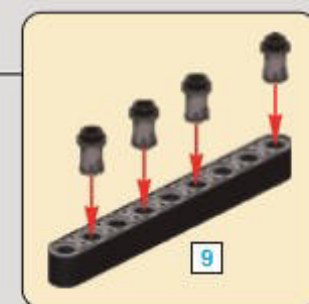
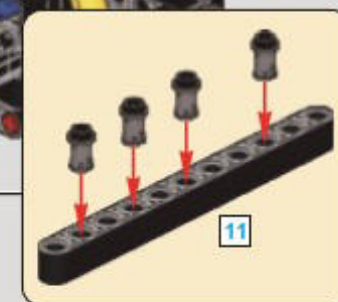


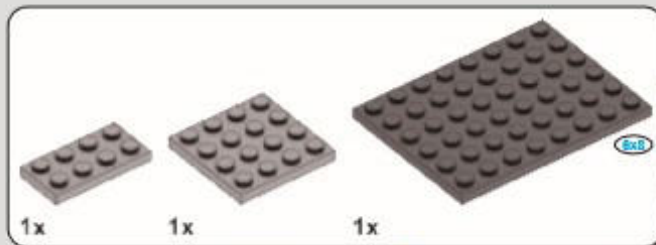


223

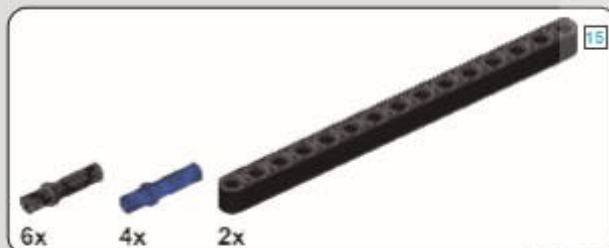
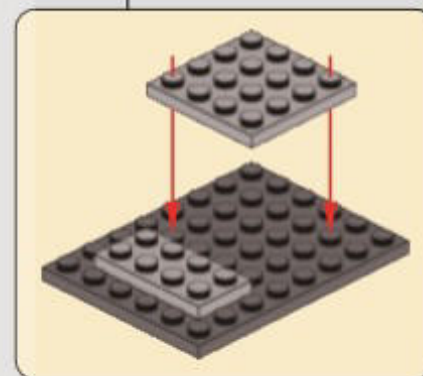


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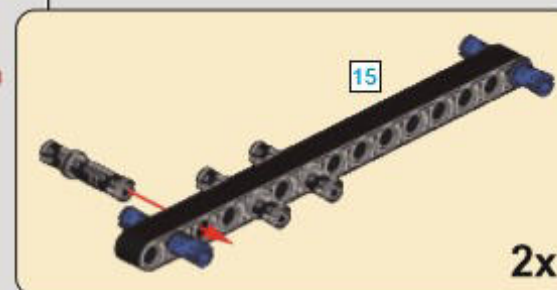


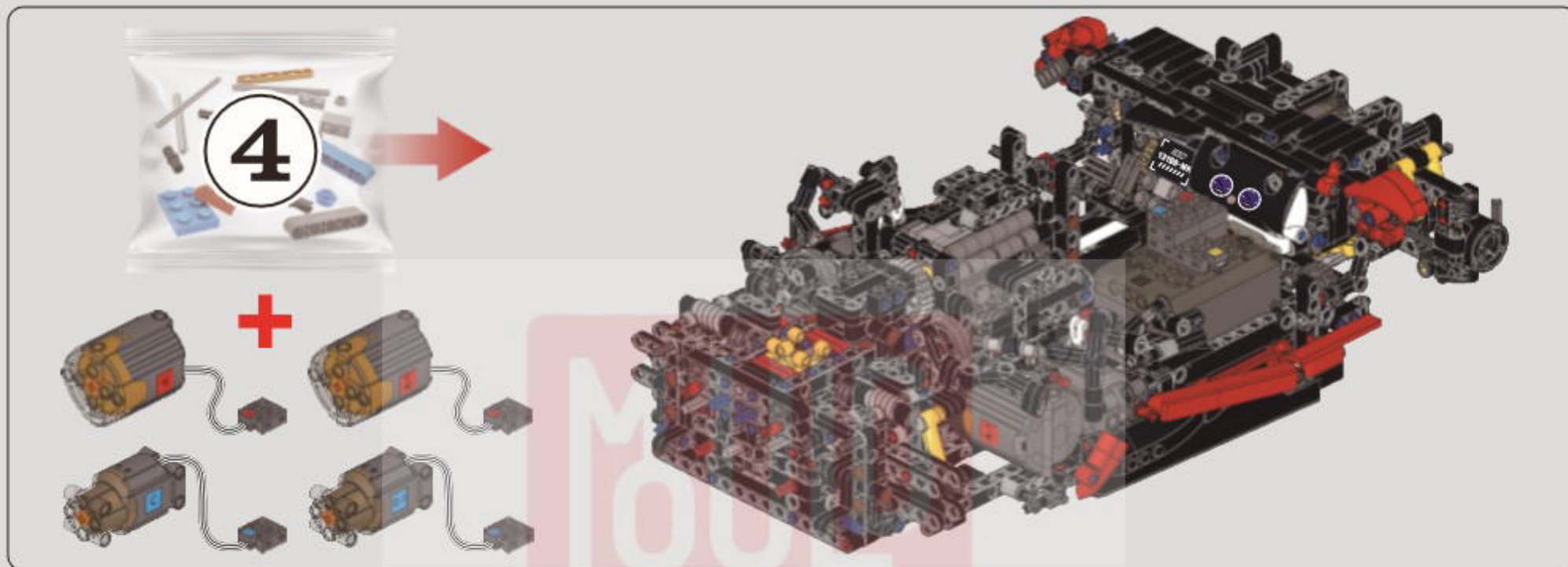


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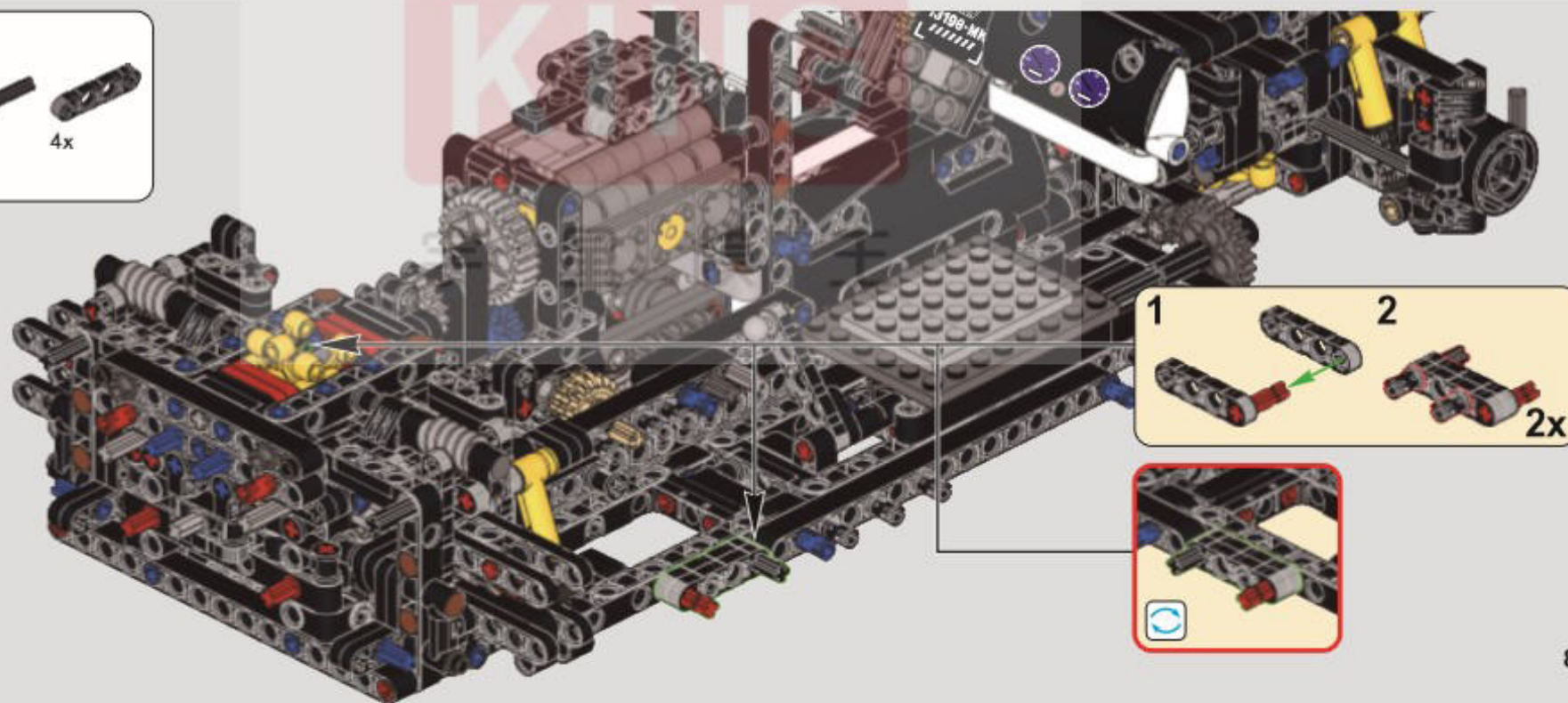


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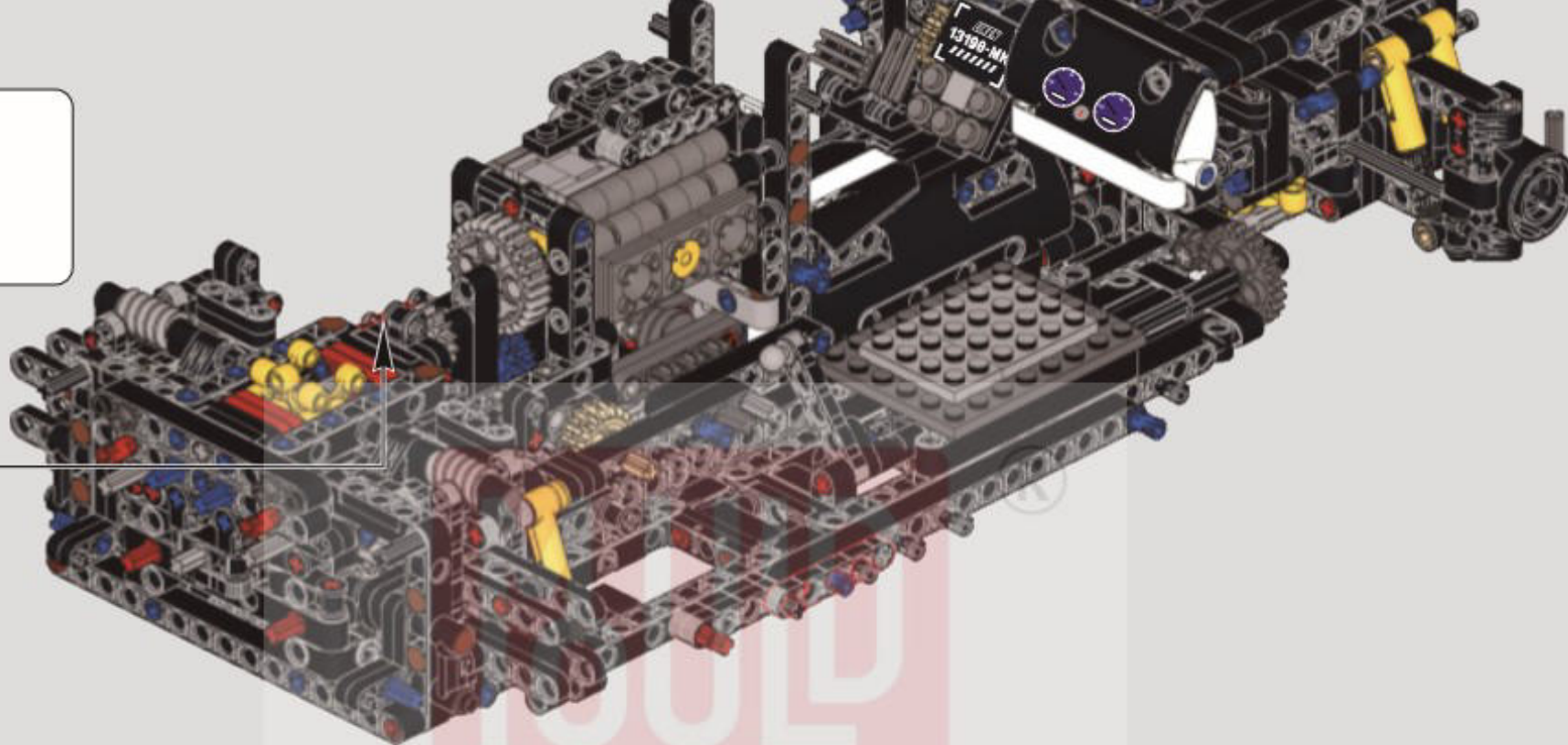


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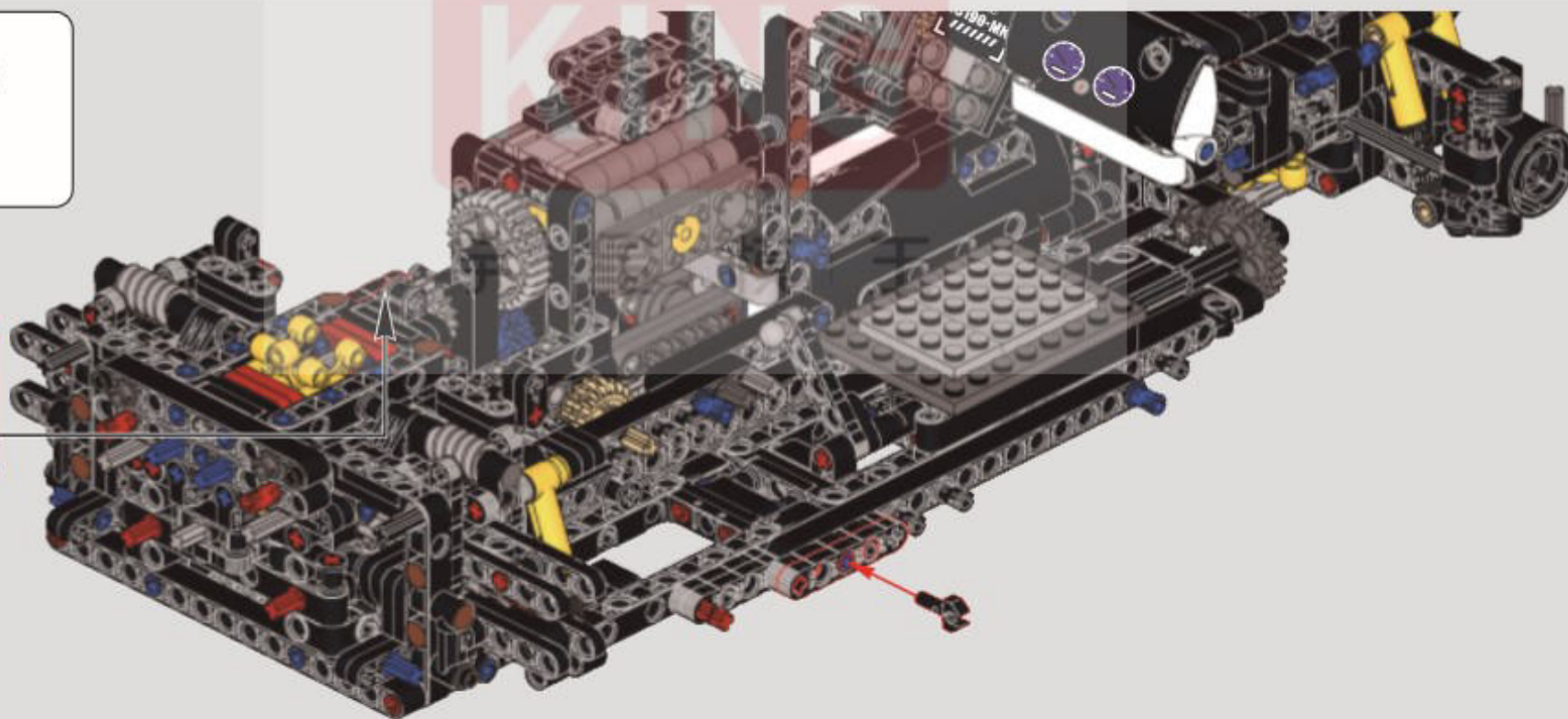
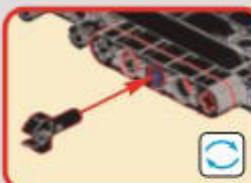




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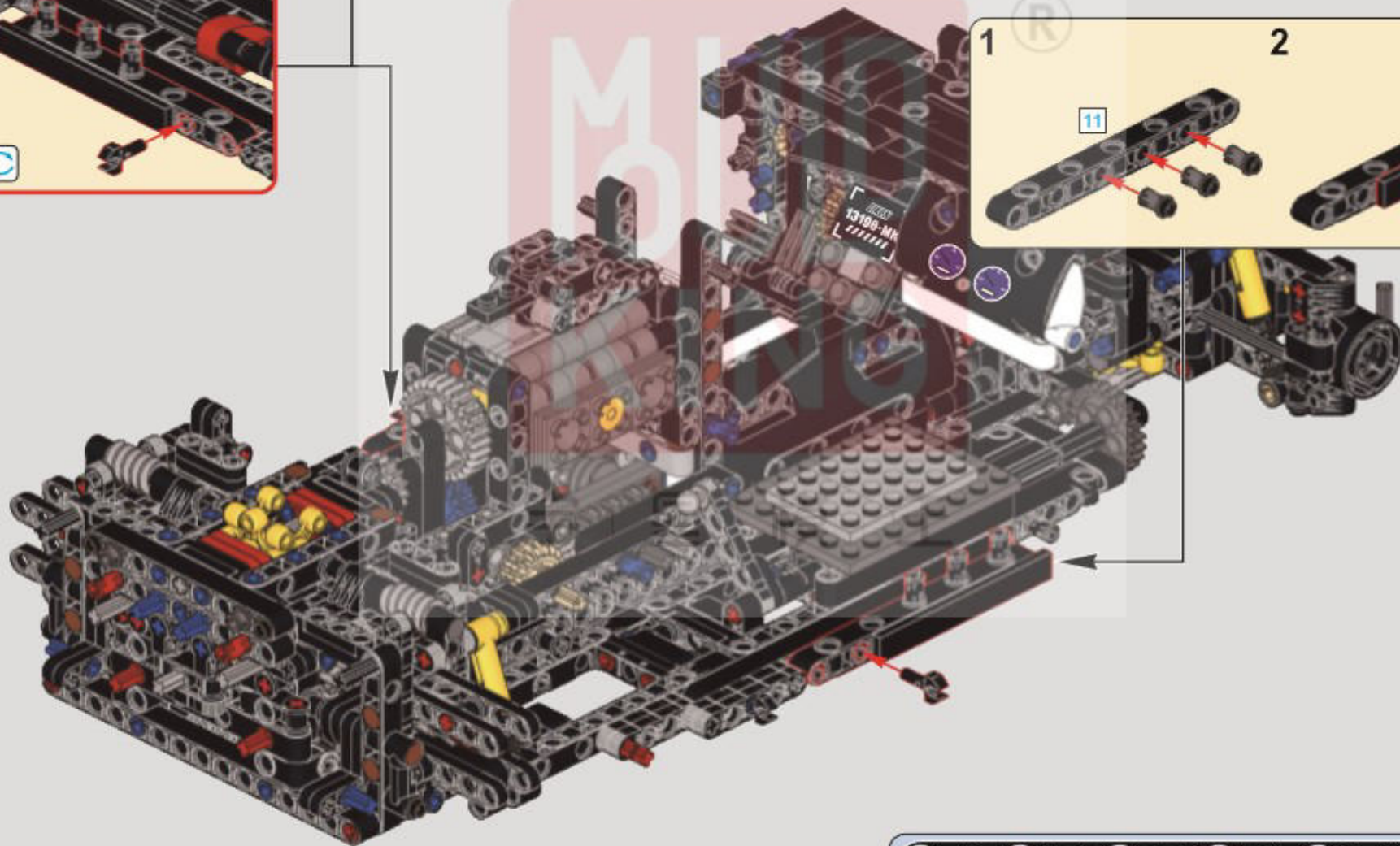
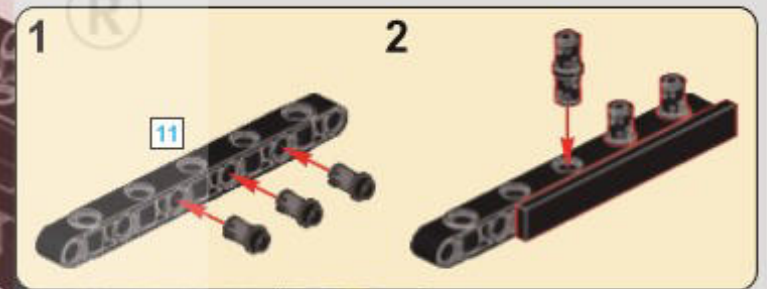
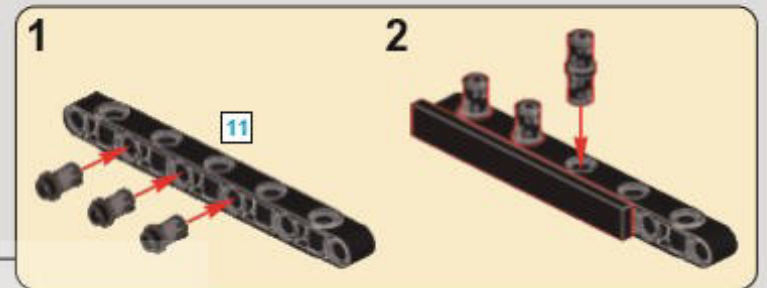
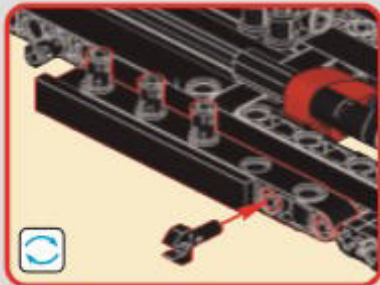


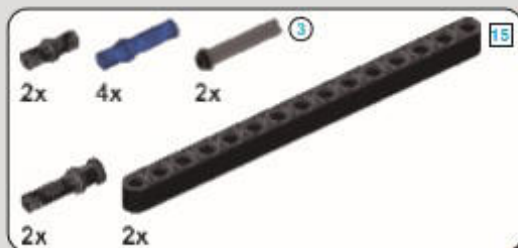
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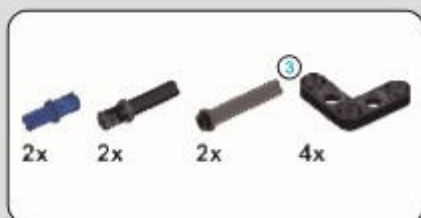
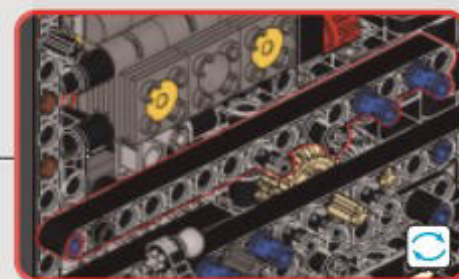
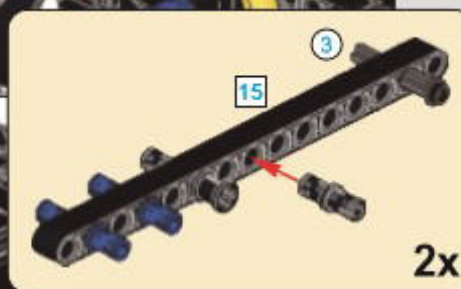
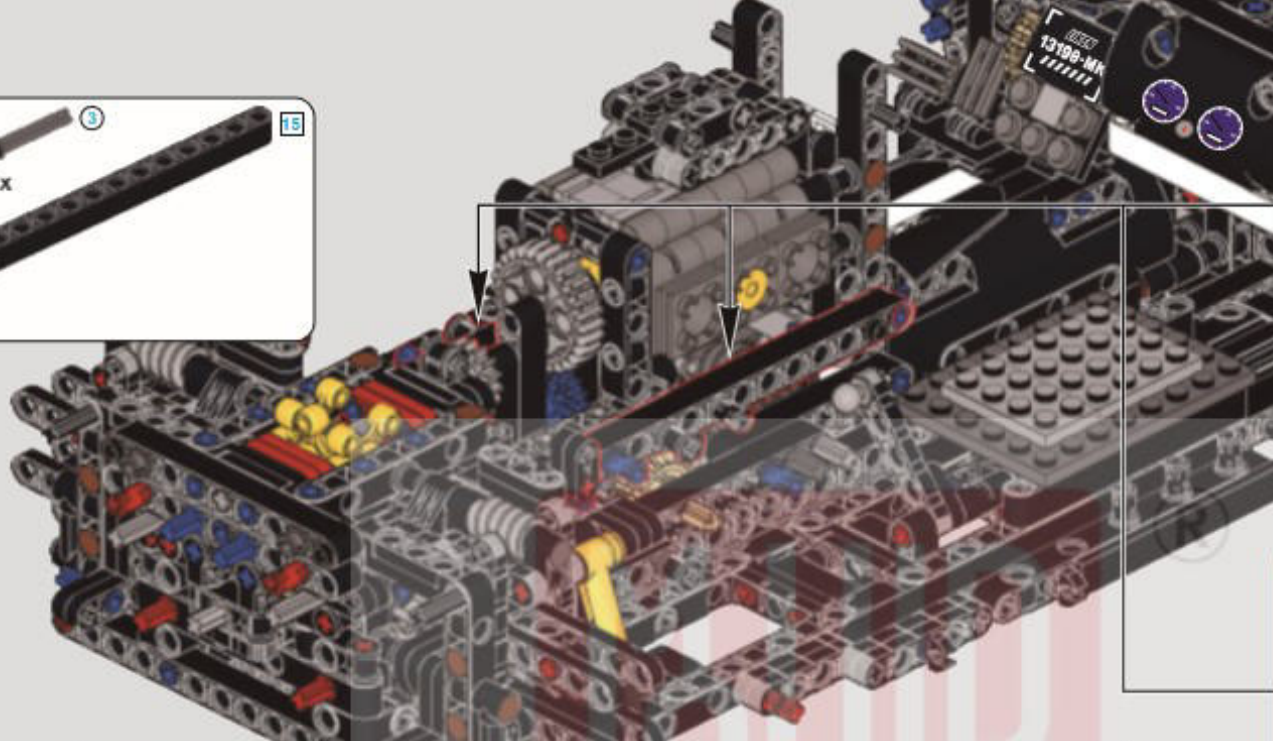


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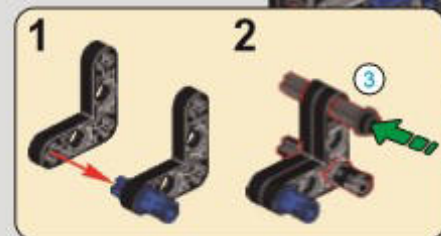
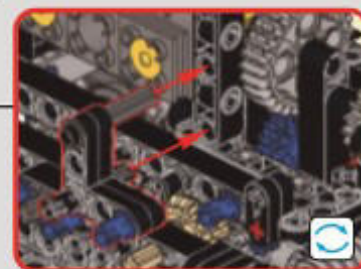
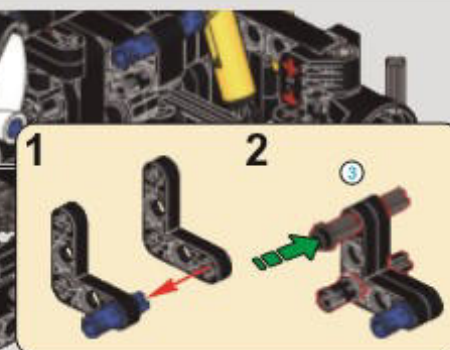
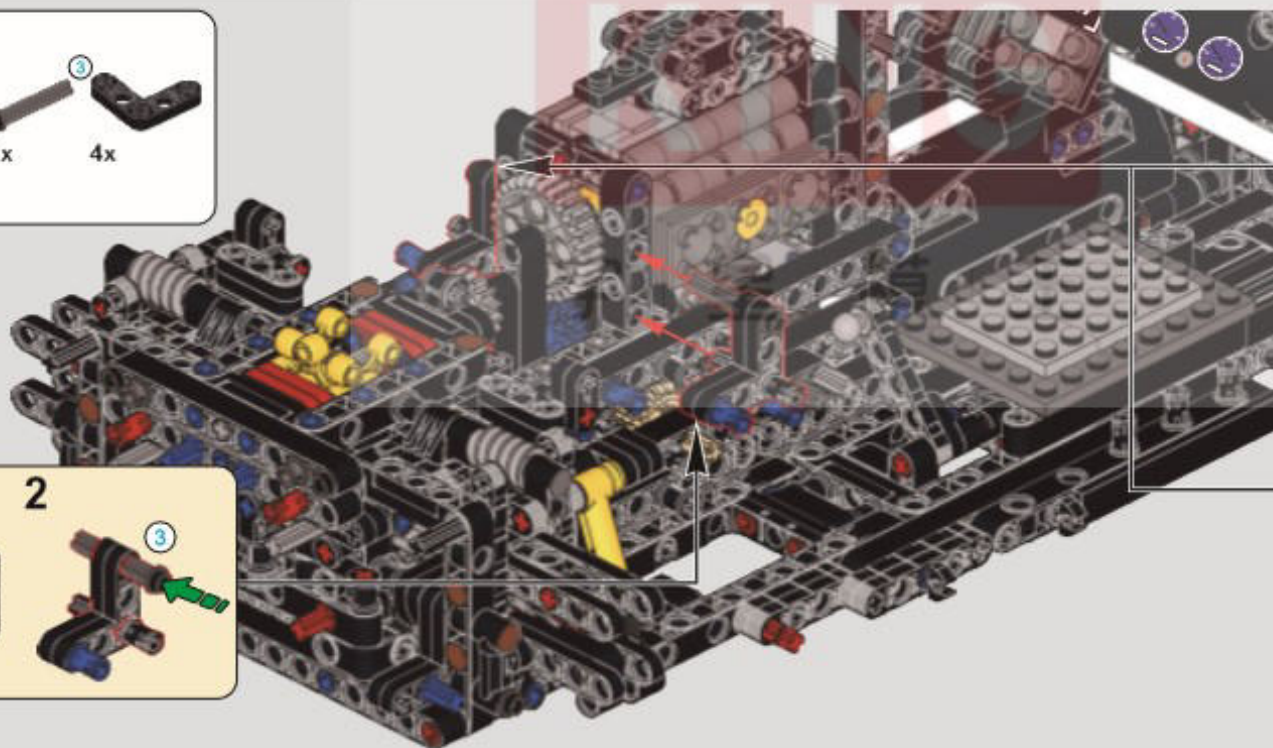




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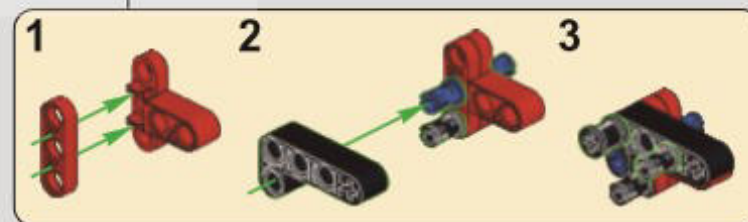
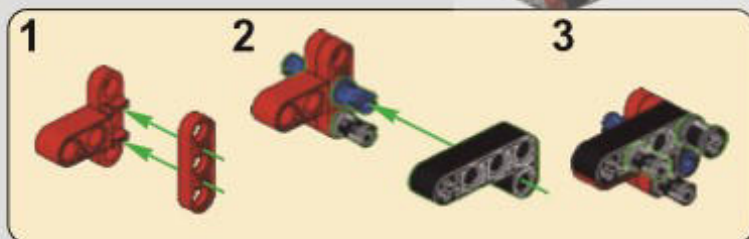
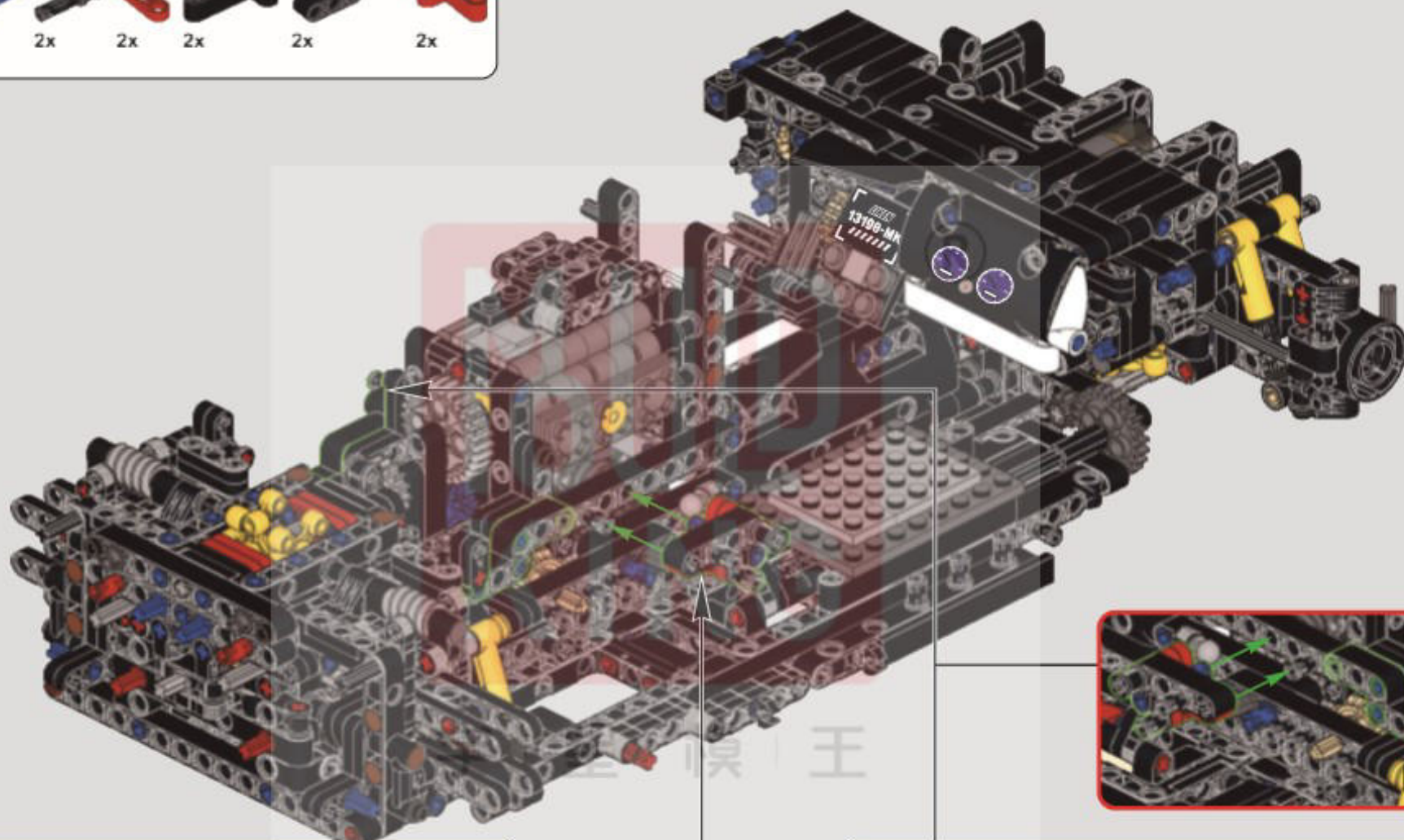


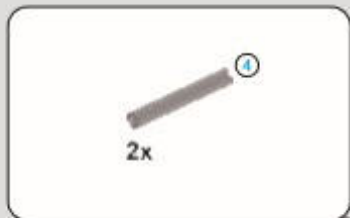
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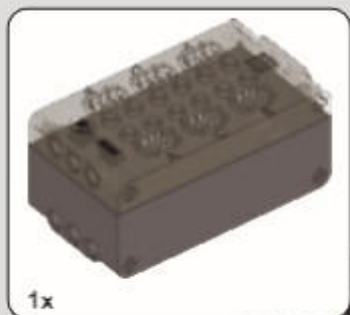
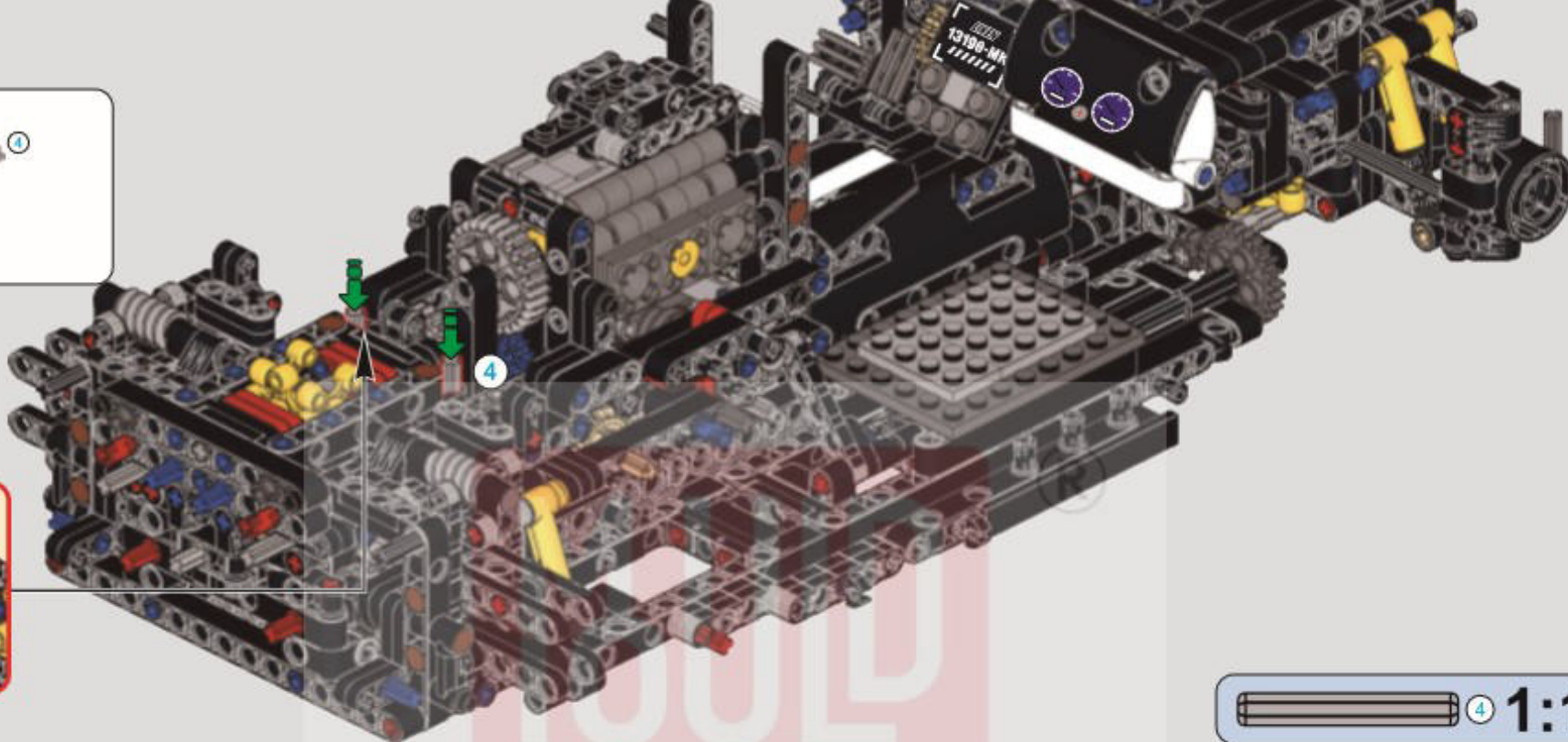
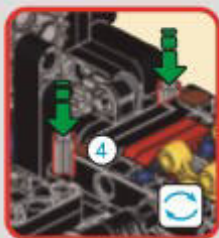


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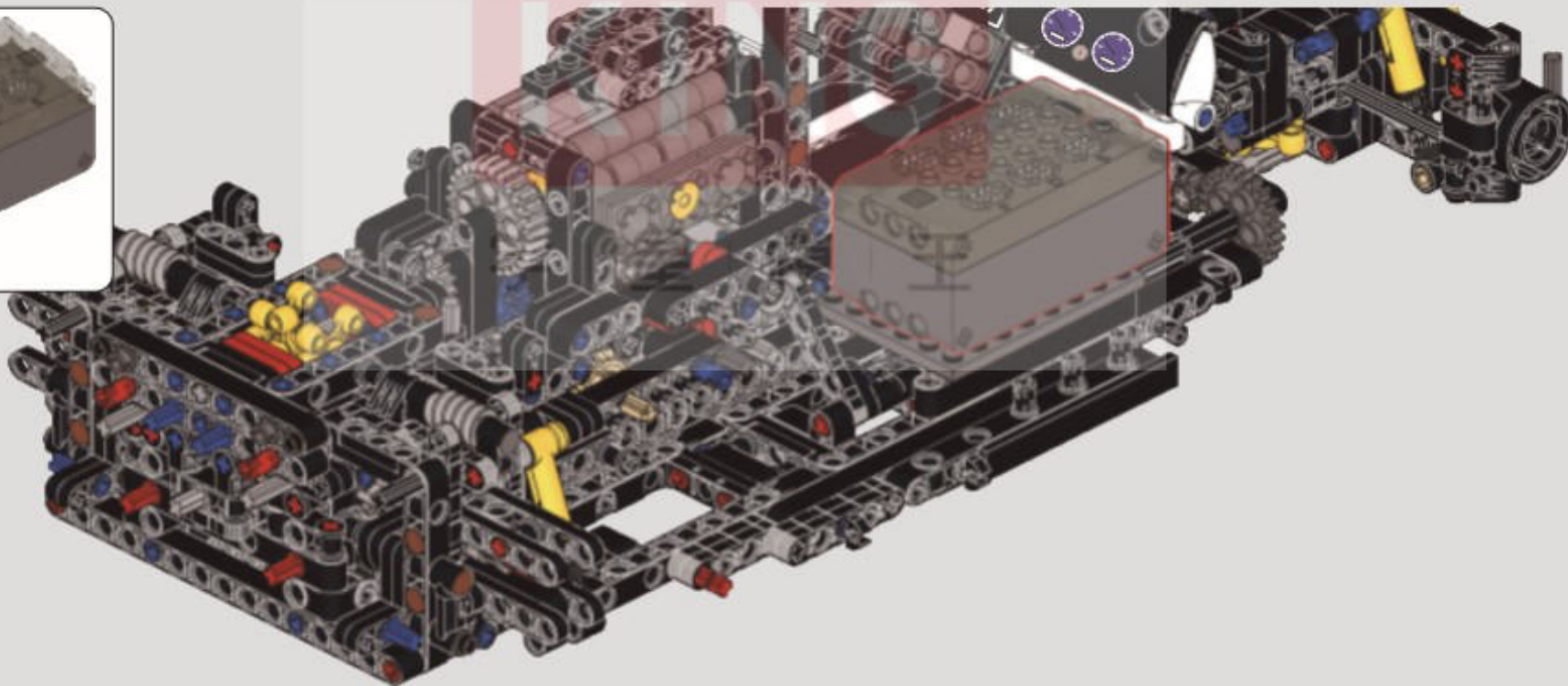




234

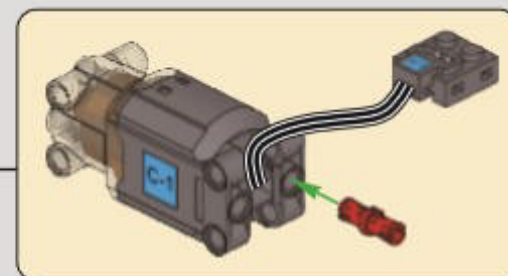
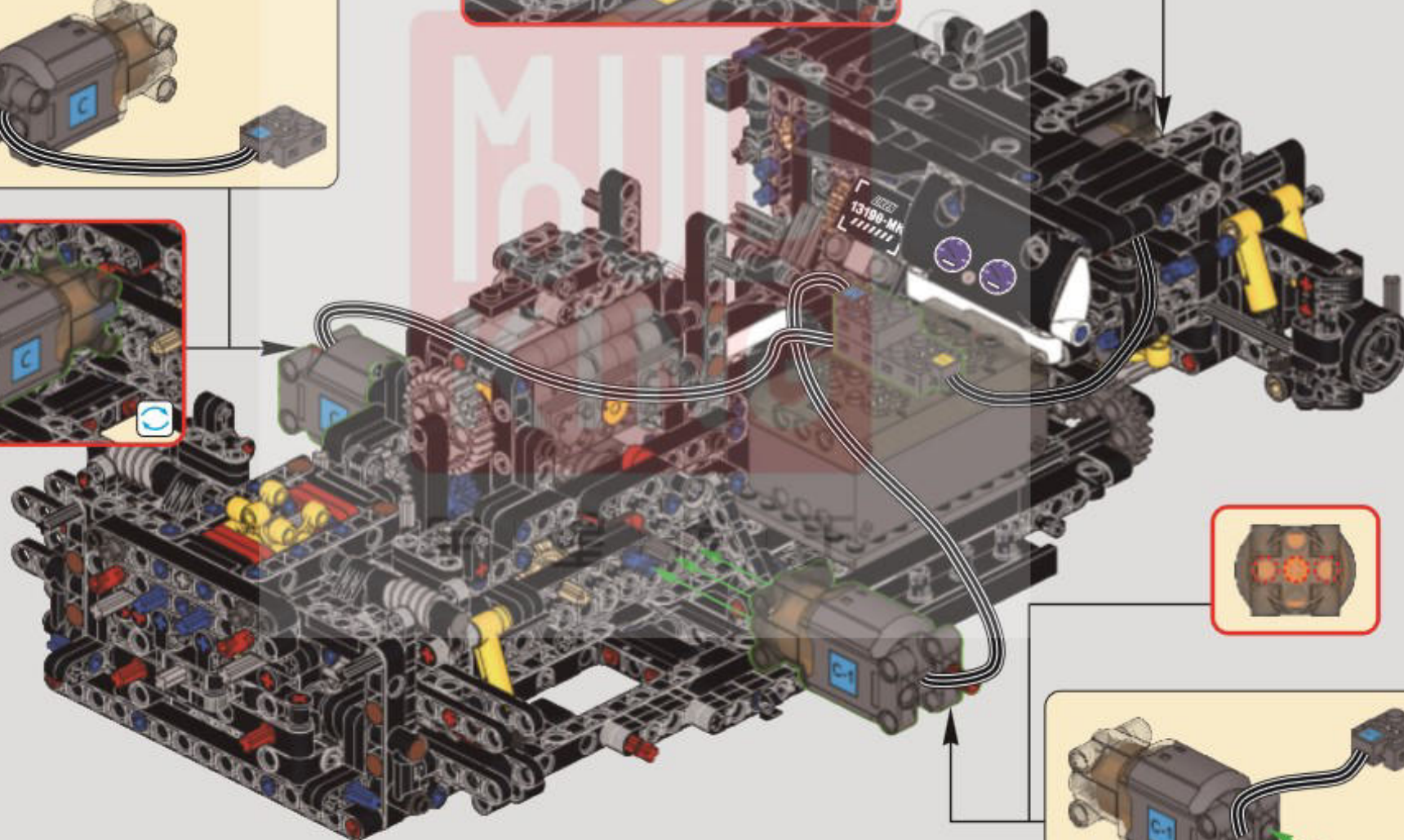
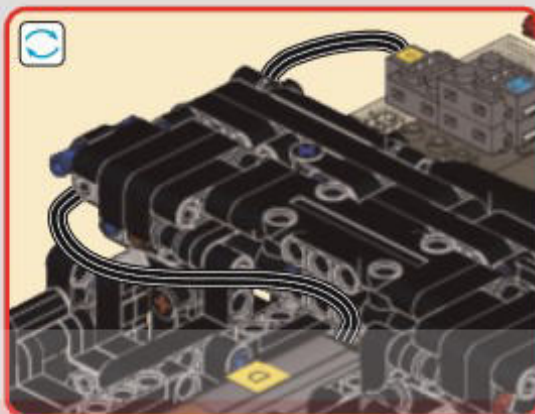
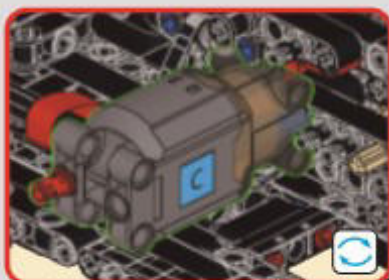
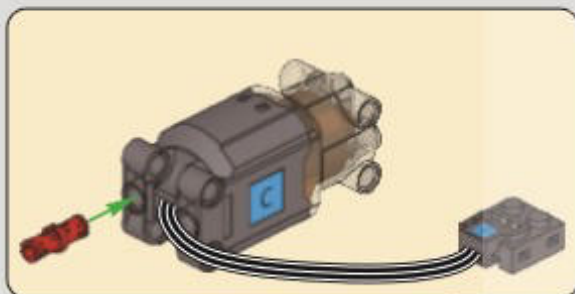


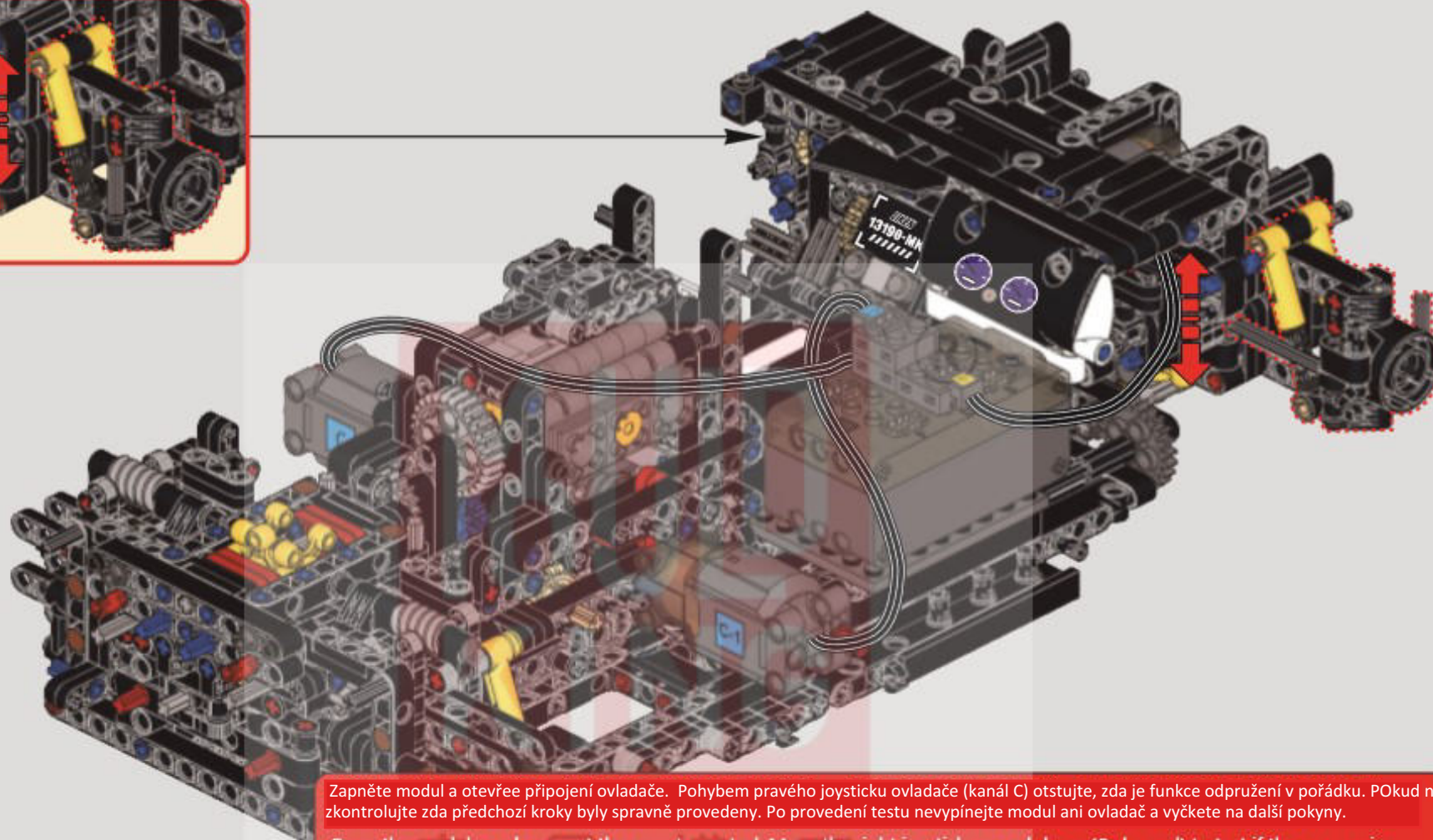
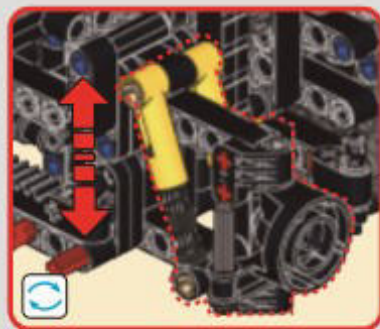
235





236





Zapněte modul a otevřete připojení ovladače. Pohybem pravého joysticku ovladače (kanál C) otstujte, zda je funkce odpružení v pořádku. Pokud ne, zkontrolujte zda předchozí kroky byly správně provedeny. Po provedení testu nevypínejte modul ani ovladač a vyčkete na další pokyny.

Open the module and connect the remote control. Move the right joystick up and down (C channel) to test if the suspension lifting function works properly. If it does not, please check if the previous steps were assembled correctly. Do not turn off the module and remote control after testing, wait for the next instruction.

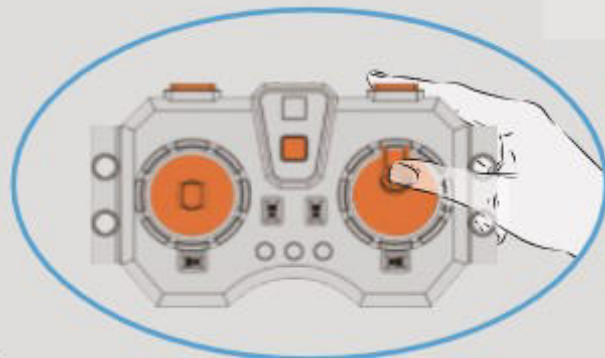
Öffnen Sie das Modul und verbinden Sie die Fernbedienung. Bewegen Sie den rechten Joystick nach oben und unten (C-Kanal), um zu testen, ob die Aufhängehebefunktion ordnungsgemäß funktioniert. Wenn dies nicht der Fall ist, überprüfen Sie, ob die vorherigen Schritte richtig zusammengebaut wurden. Schalten Sie das Modul und die Fernbedienung nach dem Testen nicht aus, warten Sie auf die nächste Anweisung.

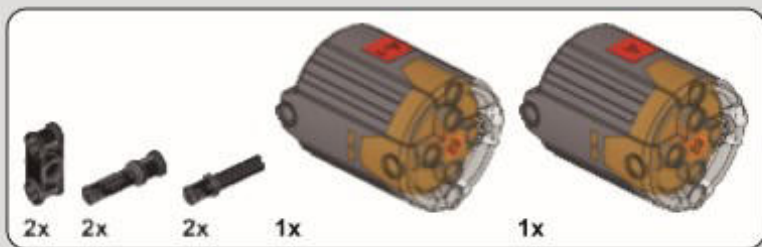
Ouvrez le module et connectez la télécommande. Déplacez le joystick droit vers le haut et vers le bas (canal C) pour tester si la fonction de levage de la suspension fonctionne correctement. Si ce n'est pas le cas, vérifiez si les étapes précédentes ont été correctement assemblées. Ne fermez pas le module et la télécommande après les tests, attendez la prochaine instruction.

Apri il modulo e collega il telecomando. Muovi la levetta destra su e giù (canale C) per testare se la funzione di sollevamento della sospensione funziona correttamente. Se non funziona, verifica se i passaggi precedenti sono stati assemblati correttamente. Non spegnere il modulo e il telecomando dopo il test, attendi il prossimo comando.

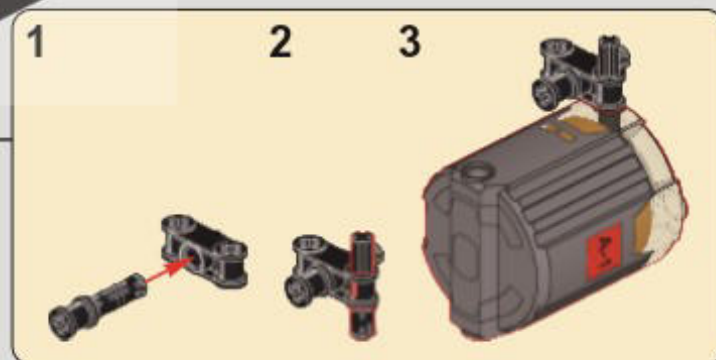
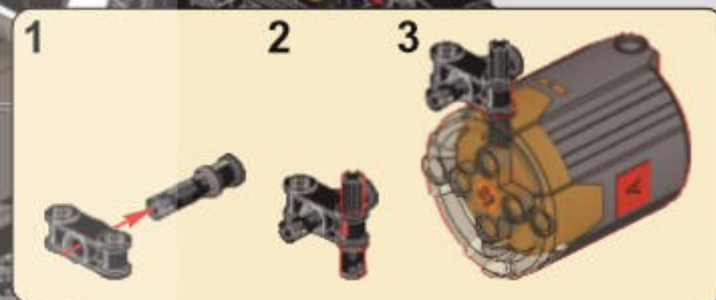
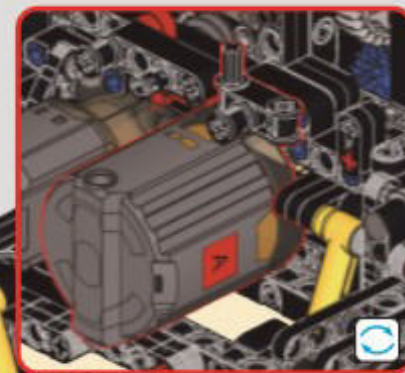
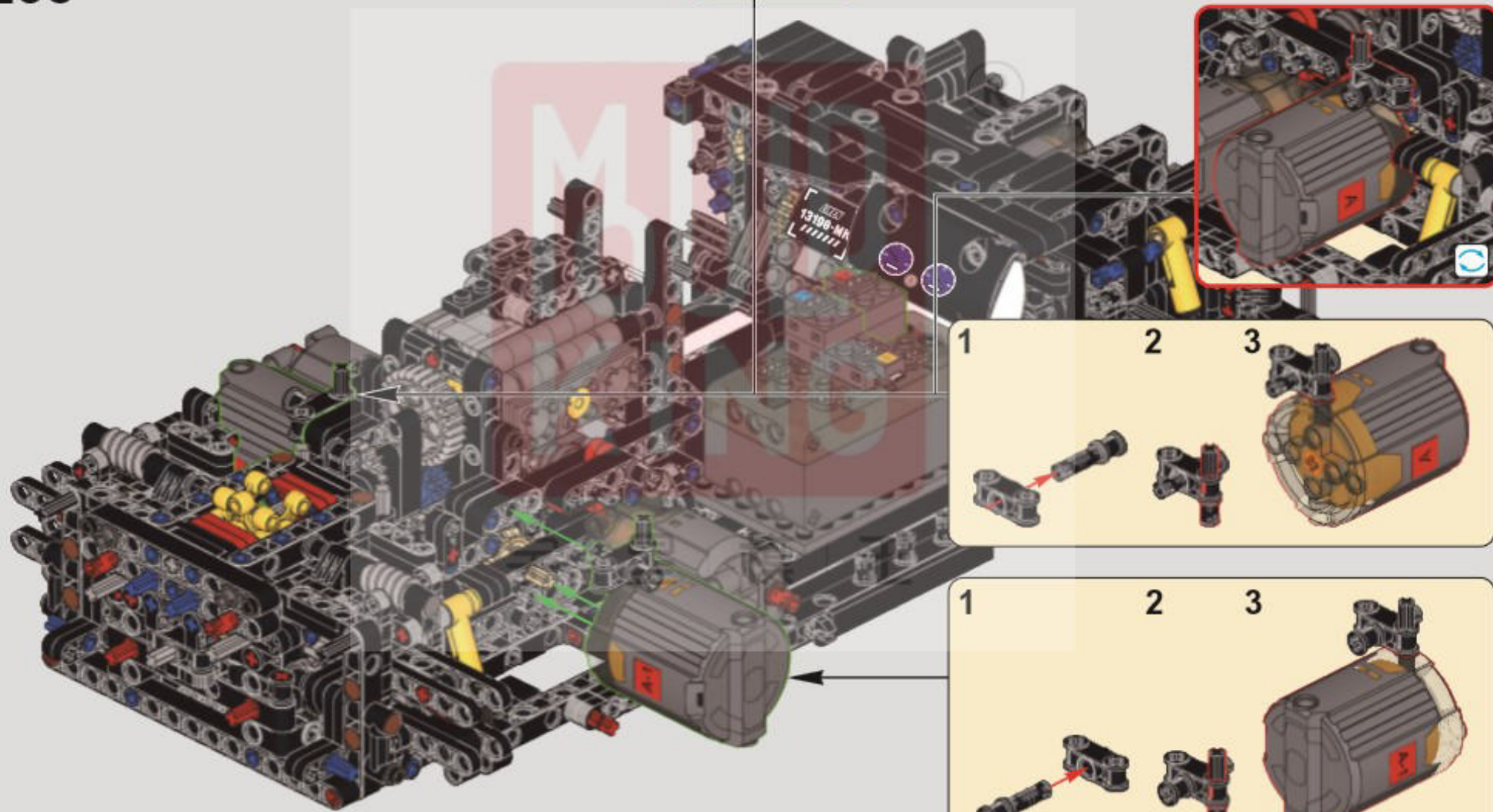
Abra el módulo y conecte el control remoto. Mueva el joystick derecho hacia arriba y hacia abajo (canal C) para probar si la función de elevación de la suspensión funciona correctamente. Si no es así, verifique si los pasos anteriores fueron ensamblados correctamente. No apague el módulo y el control remoto después de la prueba, espere la próxima instrucción.

モジュールを開き、リモコンを接続します。リモコンの右ジョイスティックを上下に動かして（Cチャンネル）、サスペンションのリフティング機能が正常に動作するかテストします。動作しない場合は、前の手順が正しく組み立てられているか確認してください。テスト後、モジュールとリモコンをすぐにはオフにせず、次の指示を待ちます。





238



POhybem levého joysticku ovladače (kanál A) otestujte, zda se příčná osamůžie otáčet ve směru nebo proti směru hodinových ručiček. Pokud ne, zkontrolujte, zda byly předchozí kroky správně provedeny. Po testu vypněte modul a dálkový ovladač.

Move the left joystick up and down (A channel) to test if the cross shaft can rotate clockwise or counterclockwise. If it cannot, please check if the previous steps were assembled correctly. After testing, turn off the module and remote control.

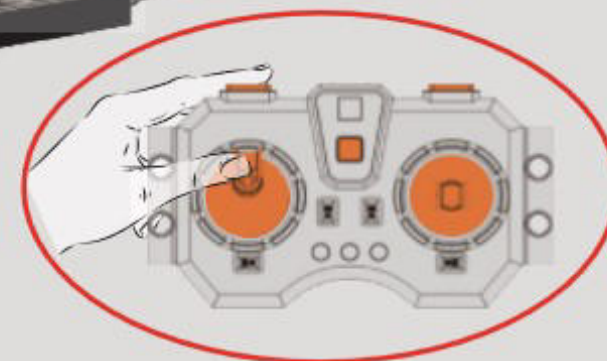
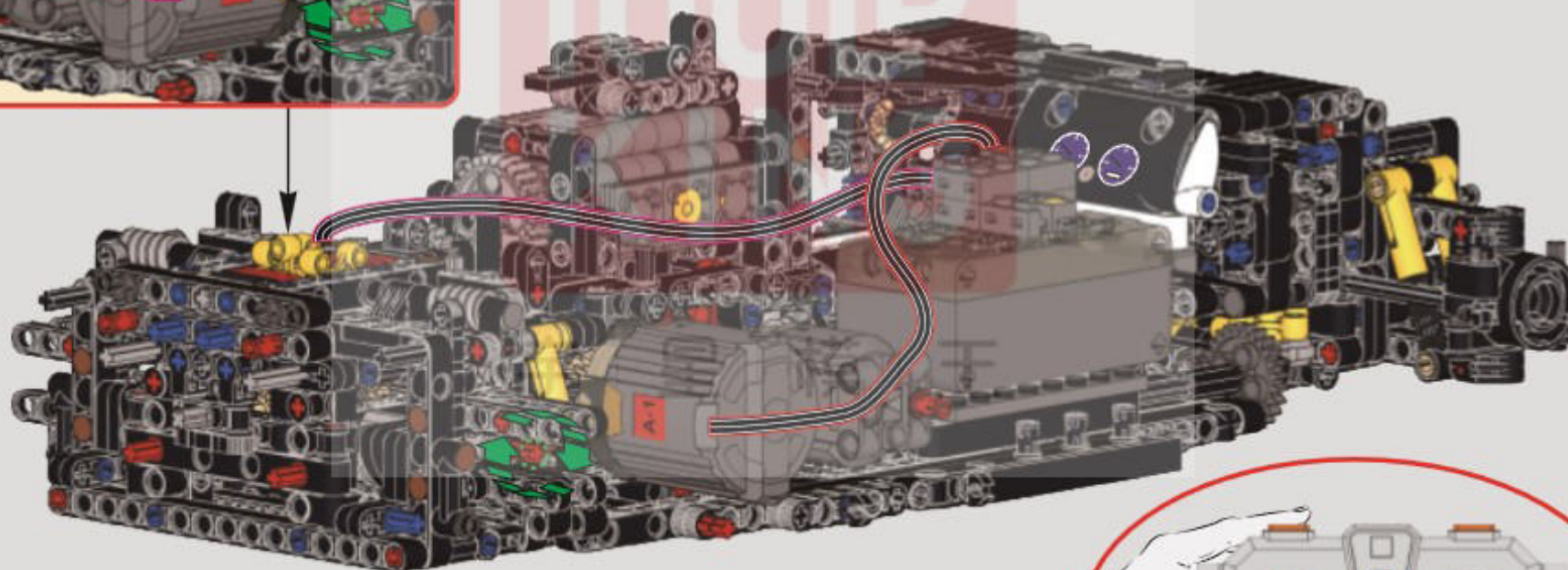
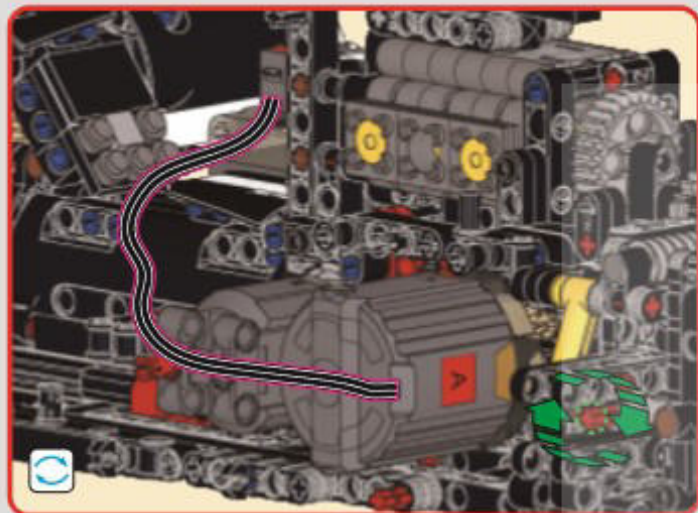
Bewegen Sie den linken Joystick auf und ab (A-Kanal), um zu testen, ob die Kreuzwelle im oder gegen den Uhrzeigersinn drehen kann. Wenn dies nicht möglich ist, überprüfen Sie, ob die vorherigen Schritte richtig montiert wurden. Schalten Sie nach dem Test das Modul und die Fernbedienung aus.

Déplacez le joystick gauche vers le haut et vers le bas (canal A) pour tester si l'arbre transversal peut tourner dans le sens horaire ou antihoraire. Si cela n'est pas possible, vérifiez si les étapes précédentes ont été correctement assemblées. Après le test, éteignez le module et la télécommande.

Muovi la levetta sinistra su e giù (canale A) per testare se l'asse trasversale può ruotare in senso orario o antiorario. Se non può, controlla se i passaggi precedenti sono stati assemblati correttamente. Dopo il test, spegni il modulo e il telecomando.

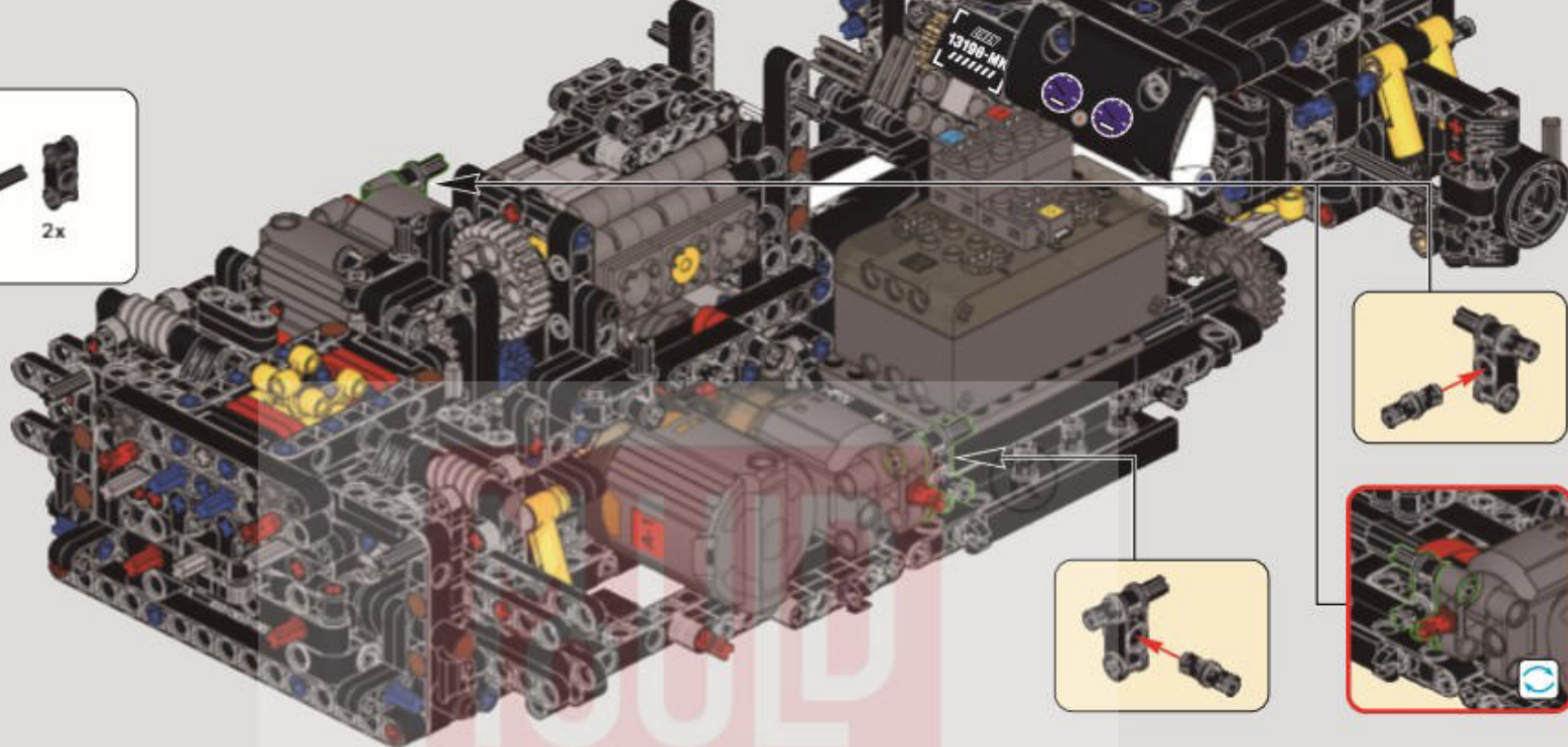
Mueva el joystick izquierdo hacia arriba y hacia abajo (canal A) para probar si el eje transversal puede rotar en sentido horario o antihorario. Si no puede, verifique si los pasos anteriores fueron ensamblados correctamente. Después de la prueba, apague el módulo y el control remoto.

リモコンの左ジョイスティックを上下に動かして (Aチャンネル)、クロスシャフトが時計回りまたは反時計回りに回転できるかテストします。できない場合は、前の手順が正しく組み立てられているか確認してください。テスト後、モジュールとリモコンをオフにしてください。

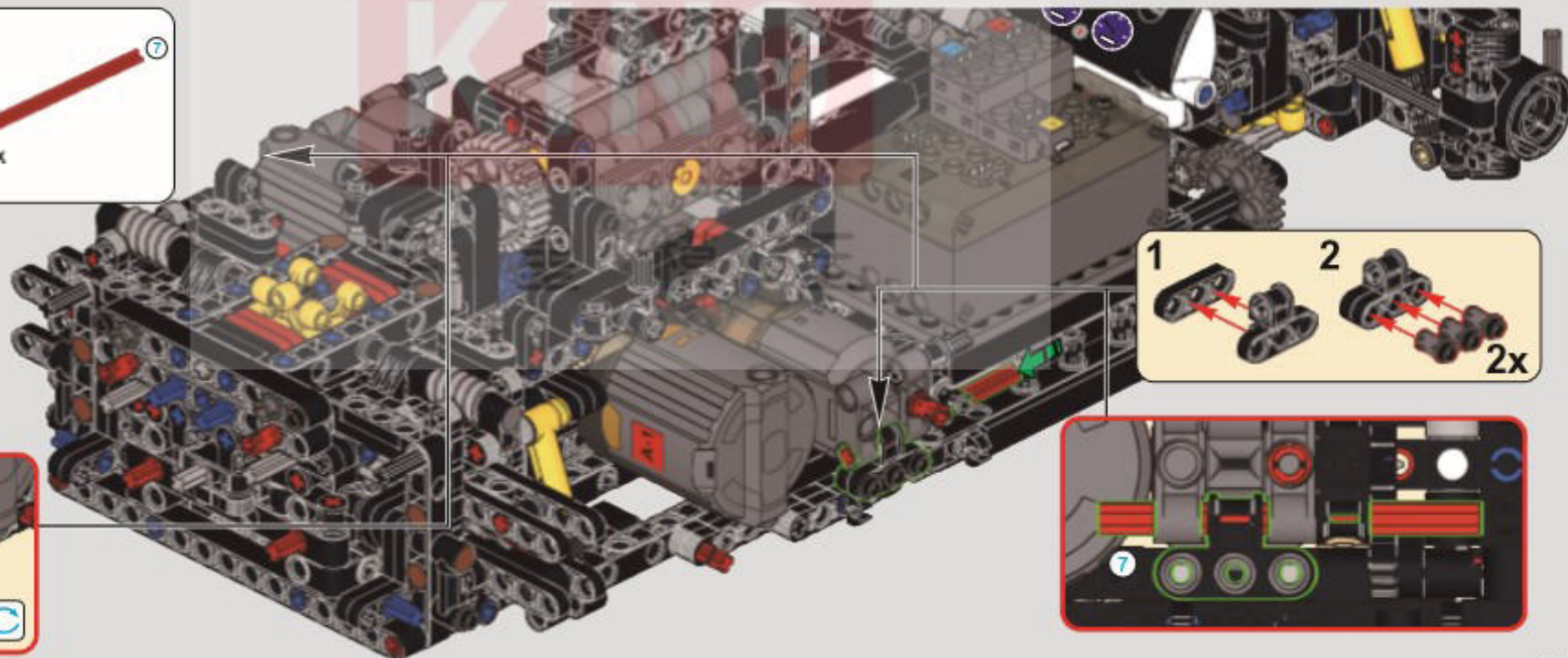




240

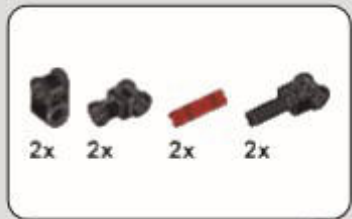
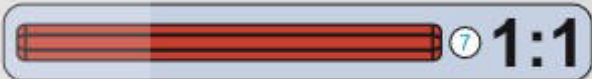
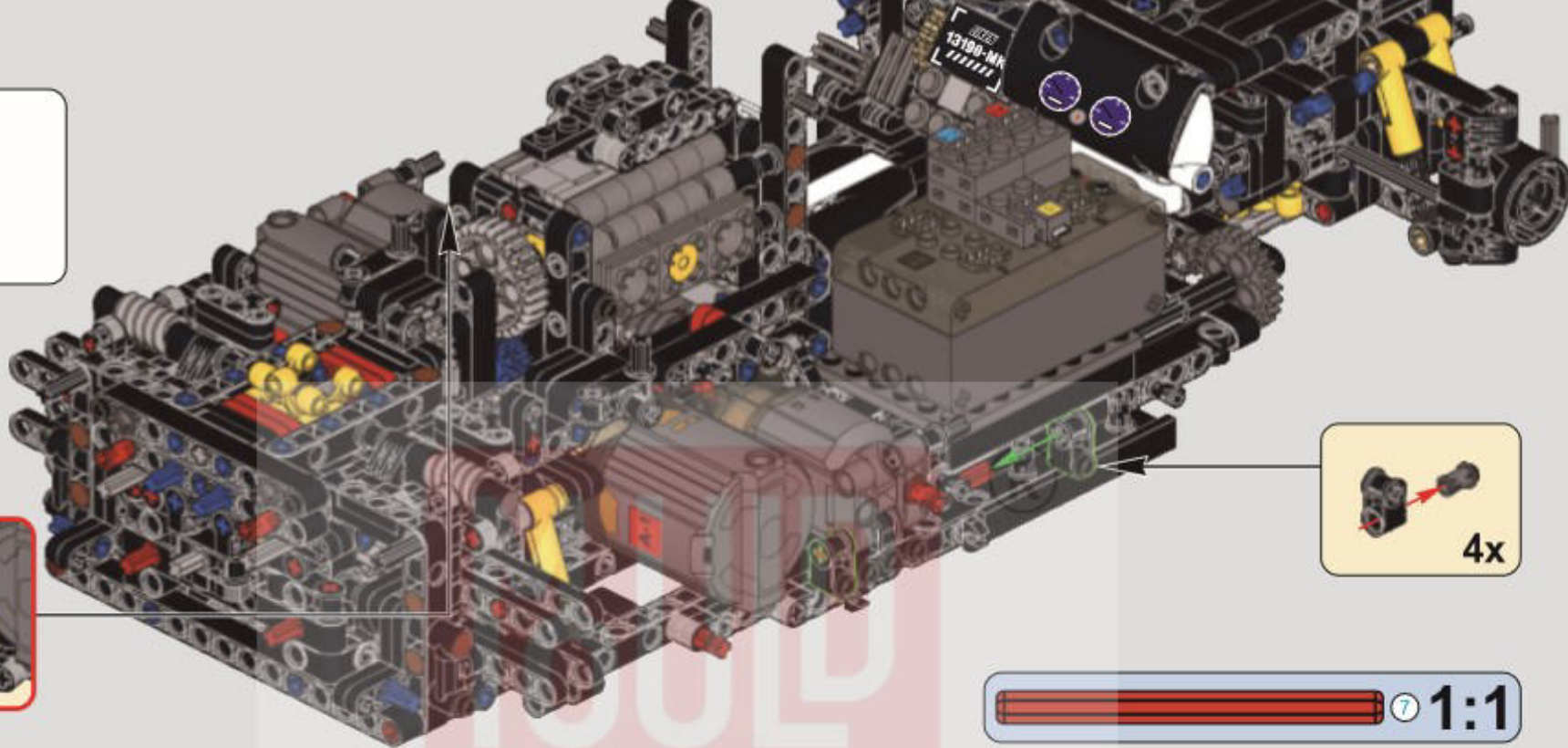
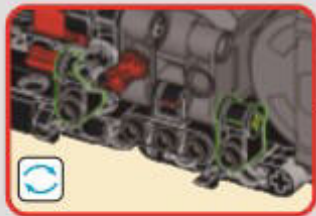


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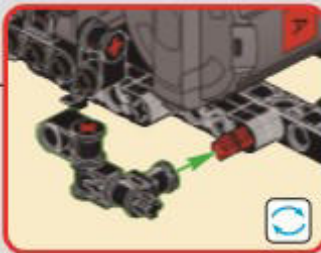
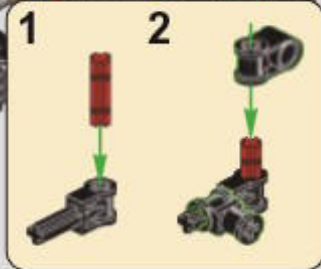
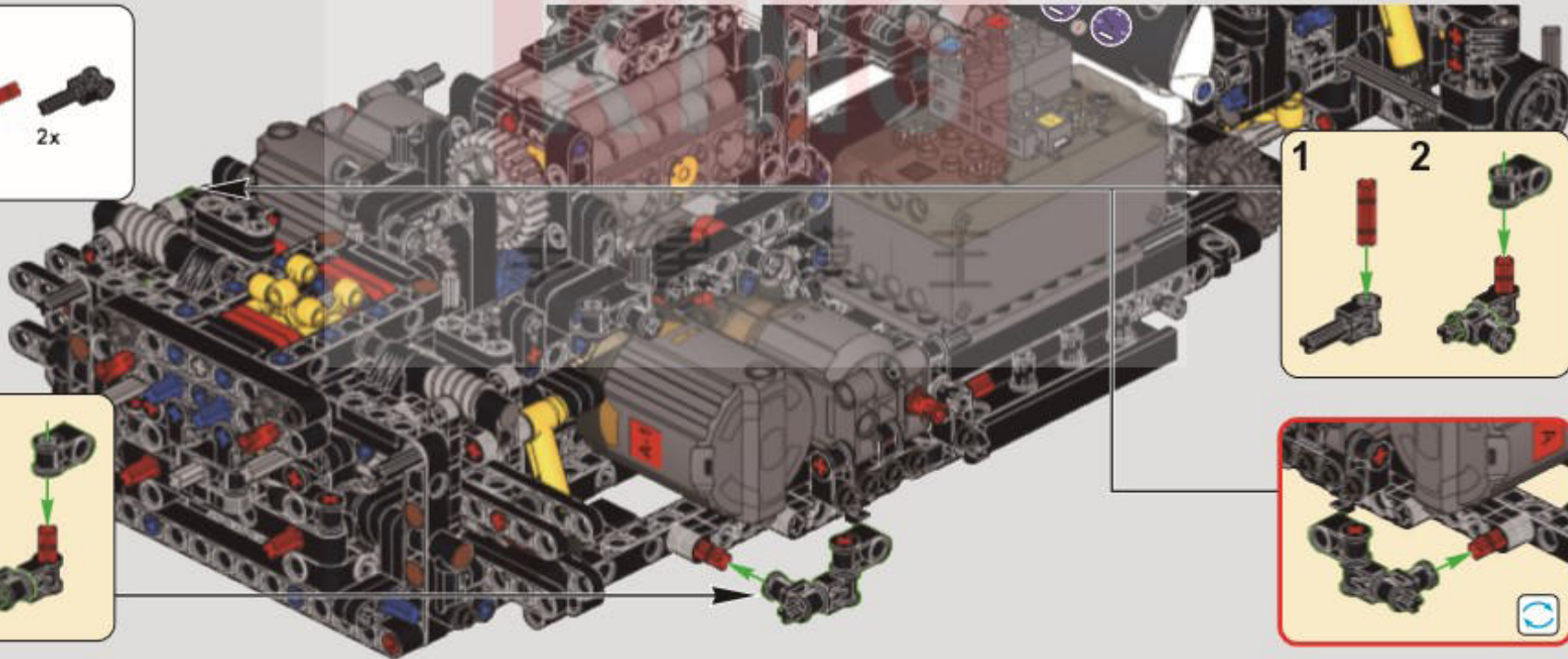
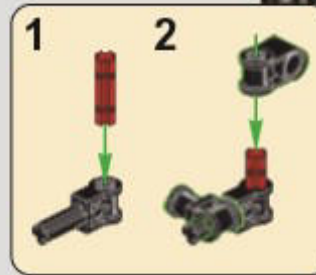


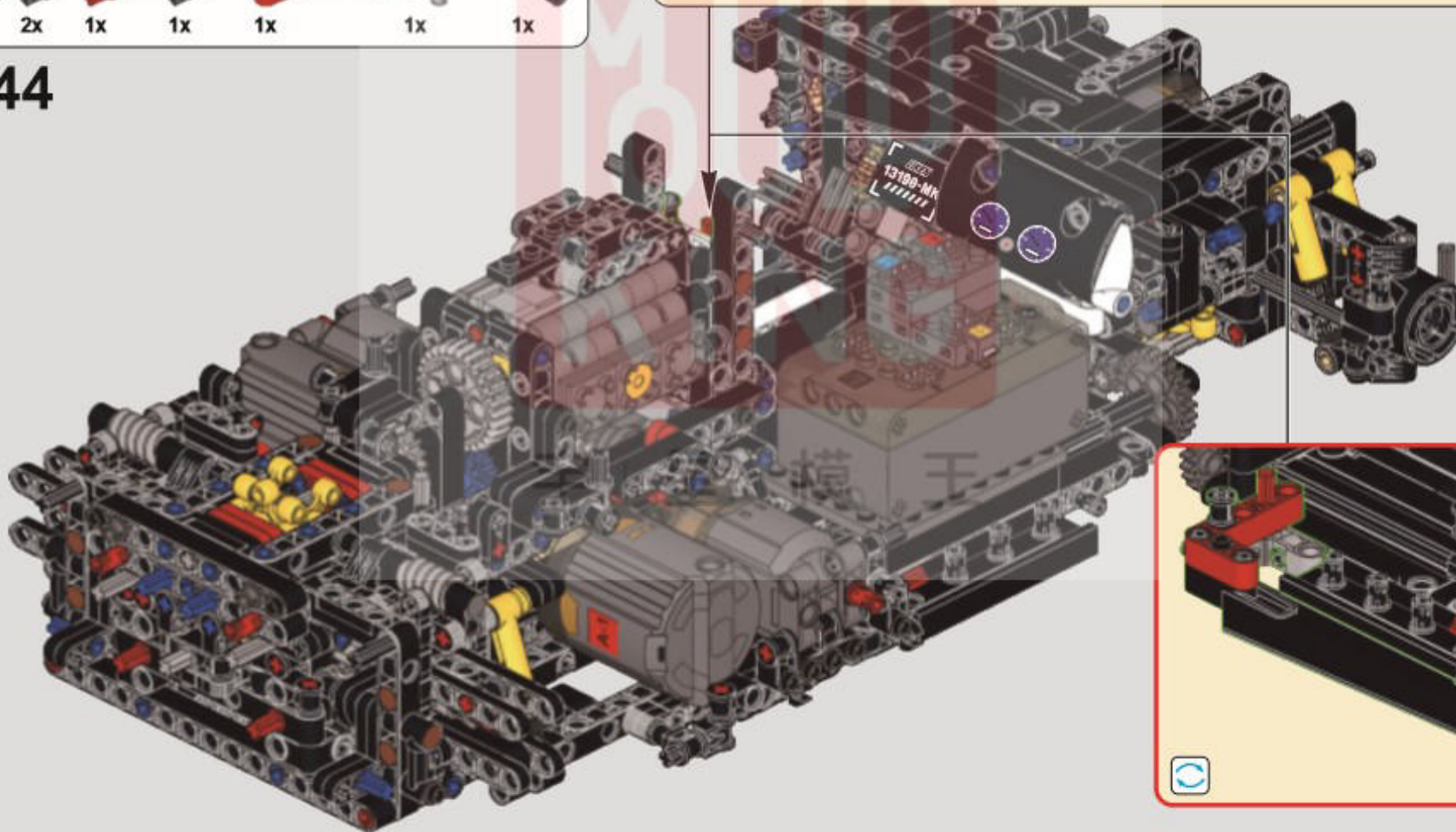


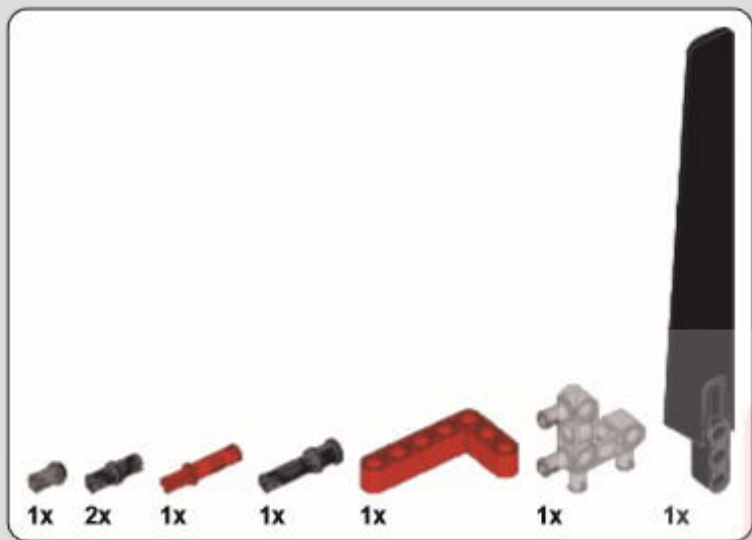
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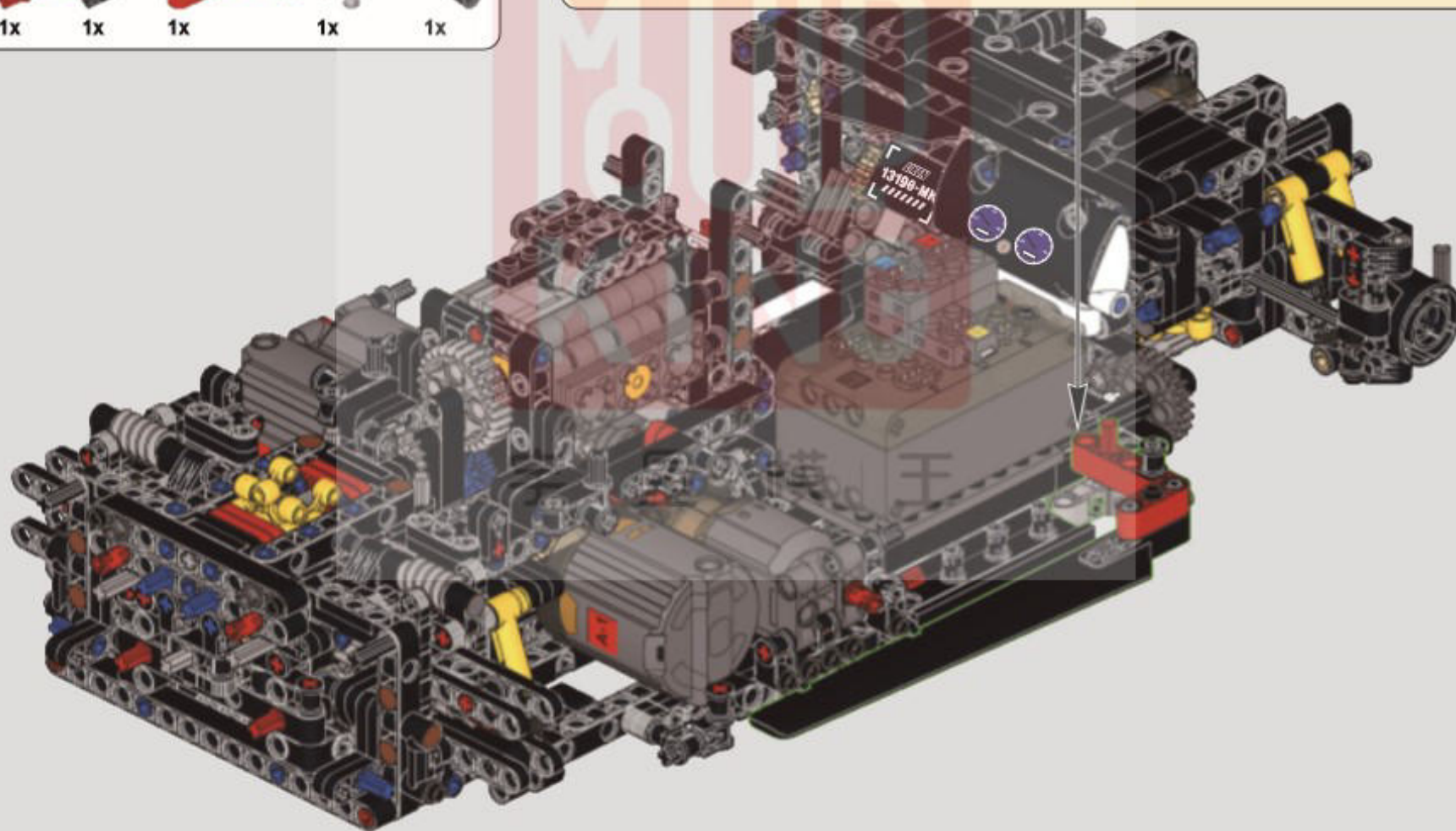
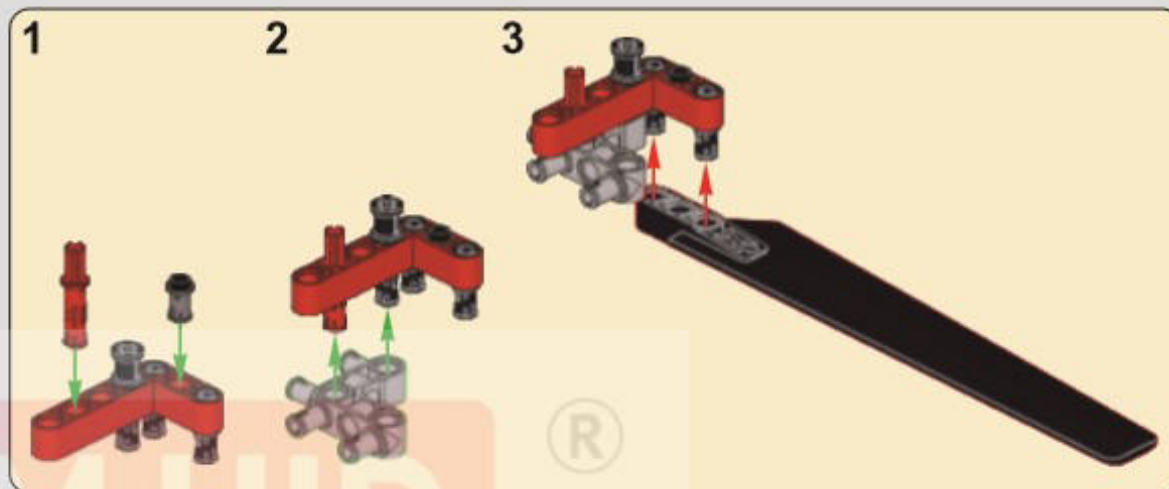
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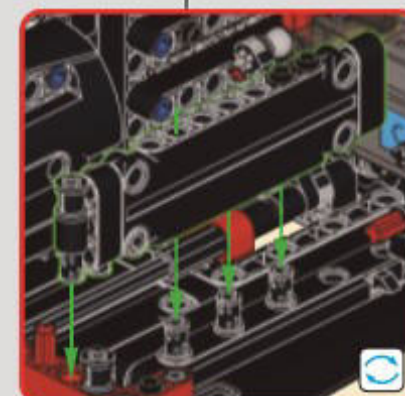
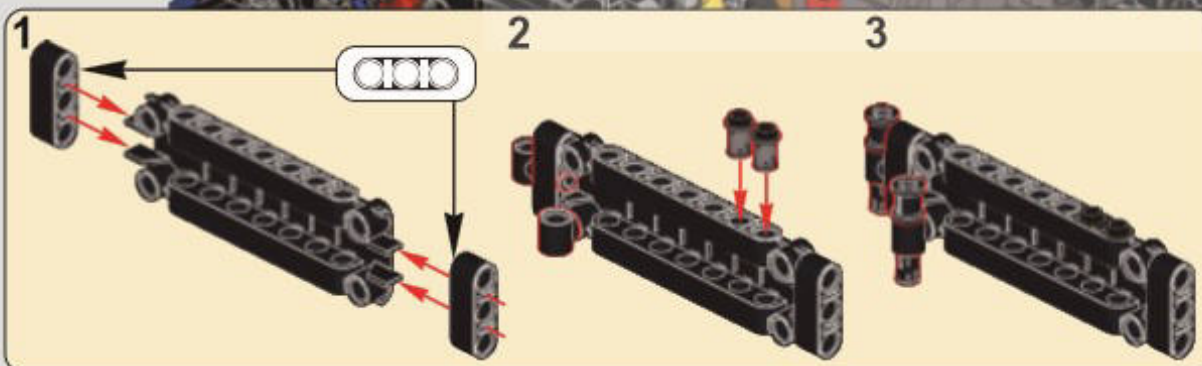
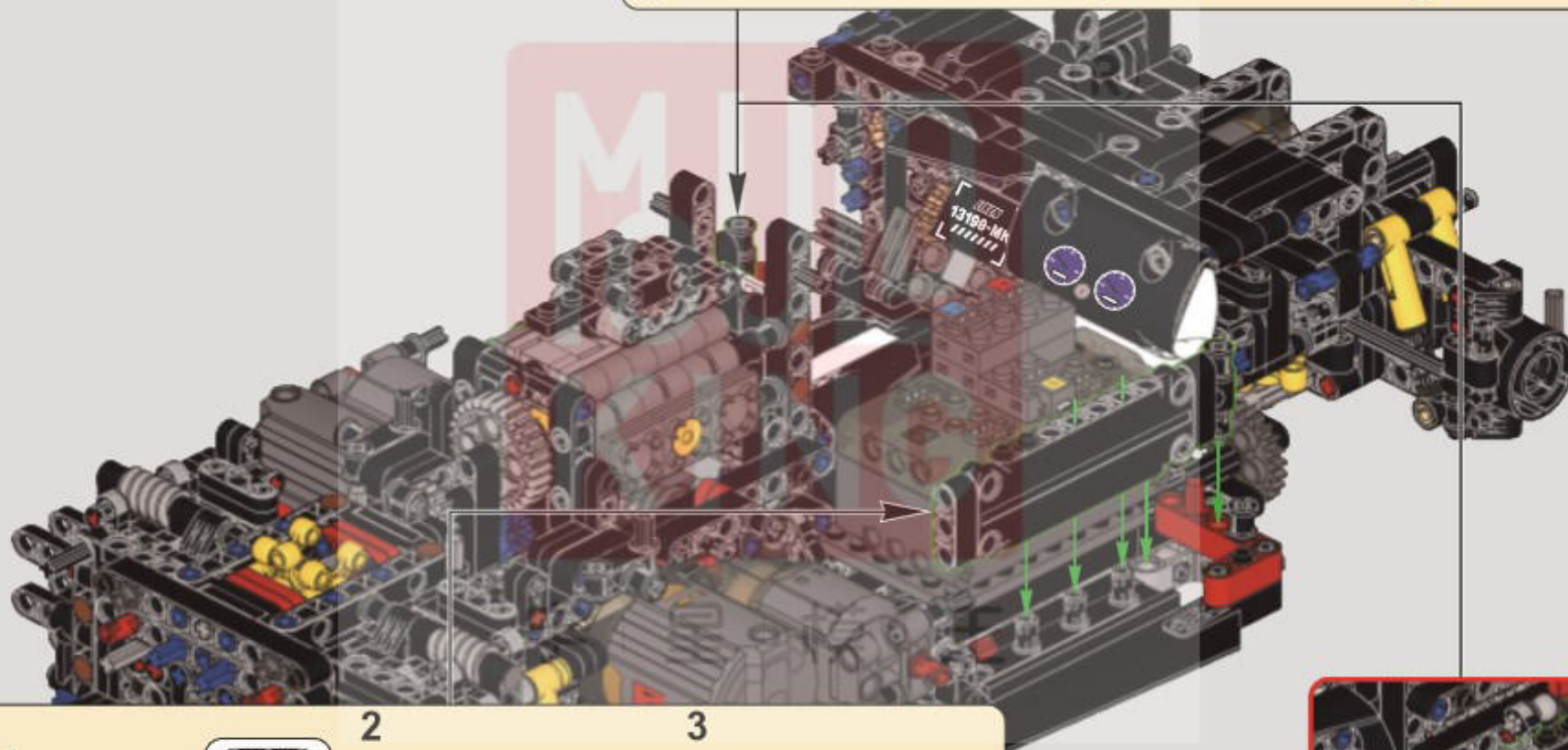
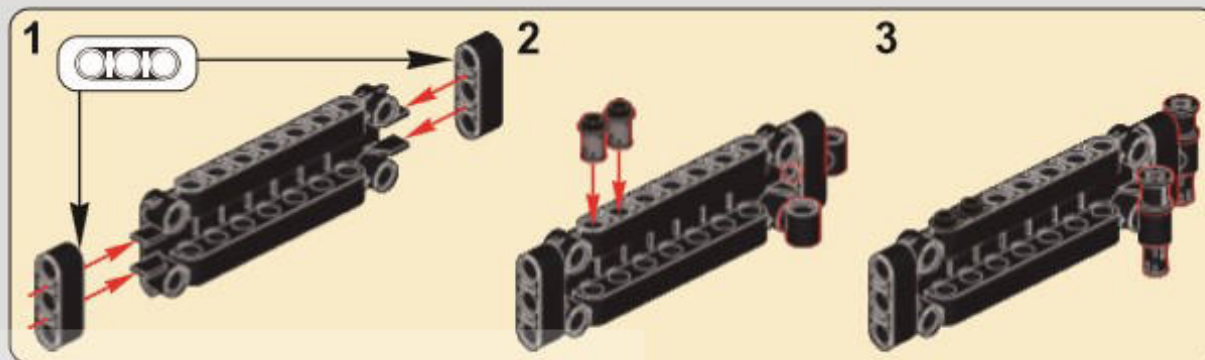


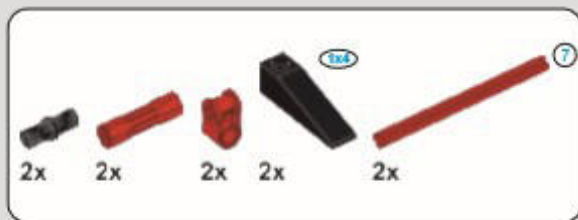
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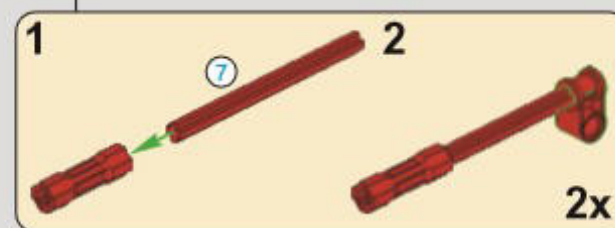
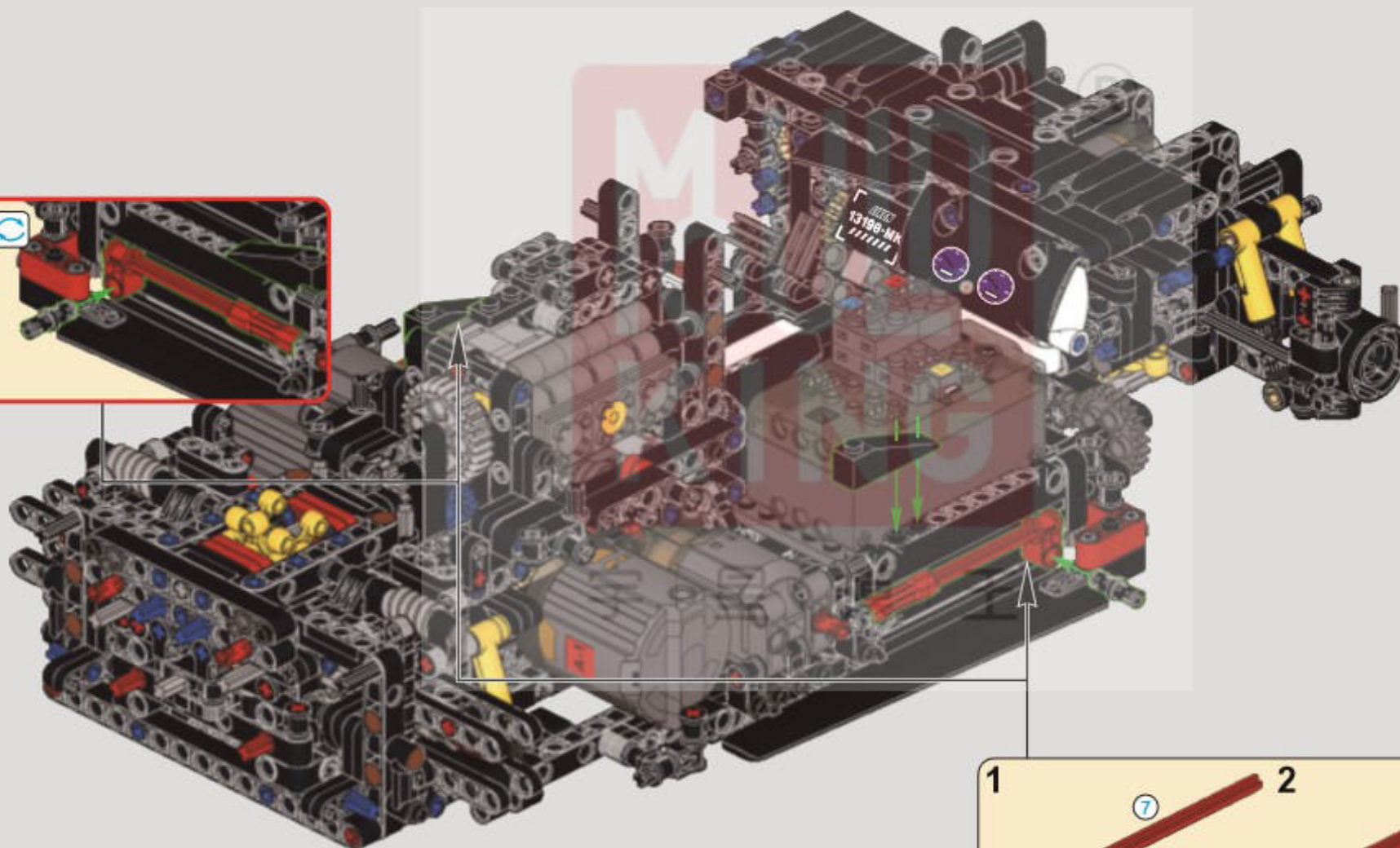
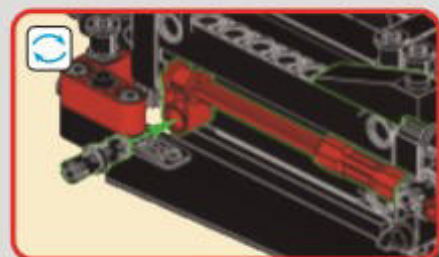


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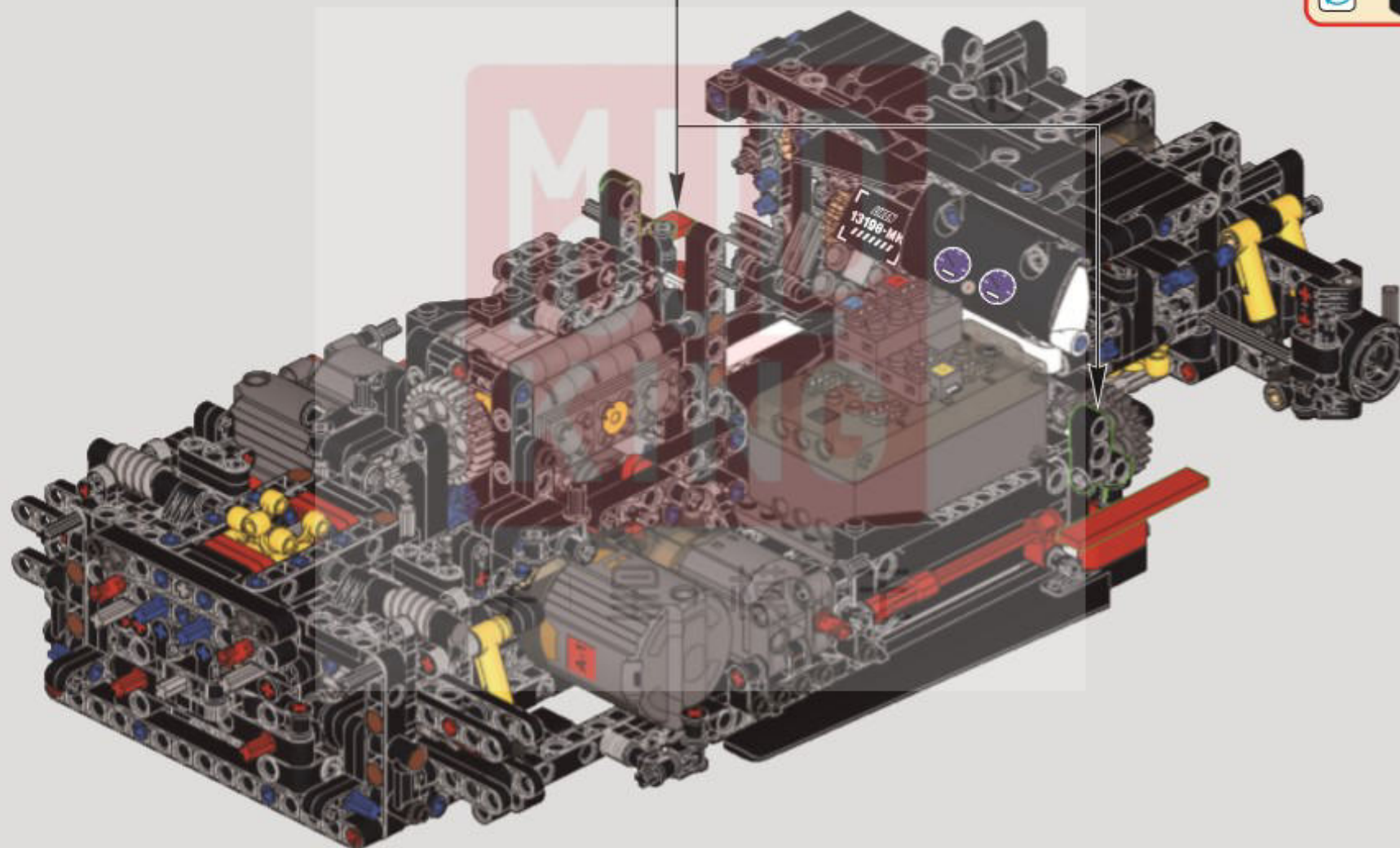
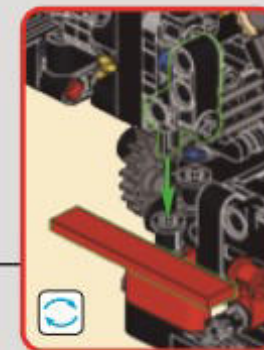


247



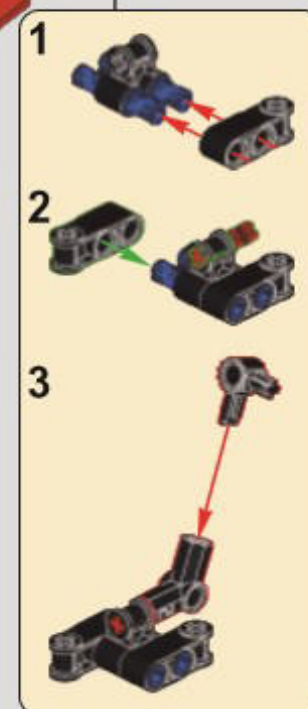
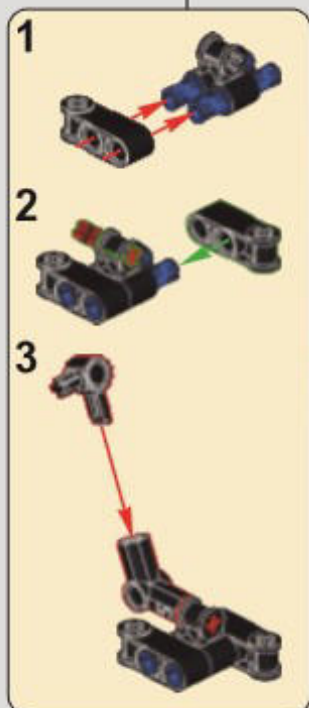
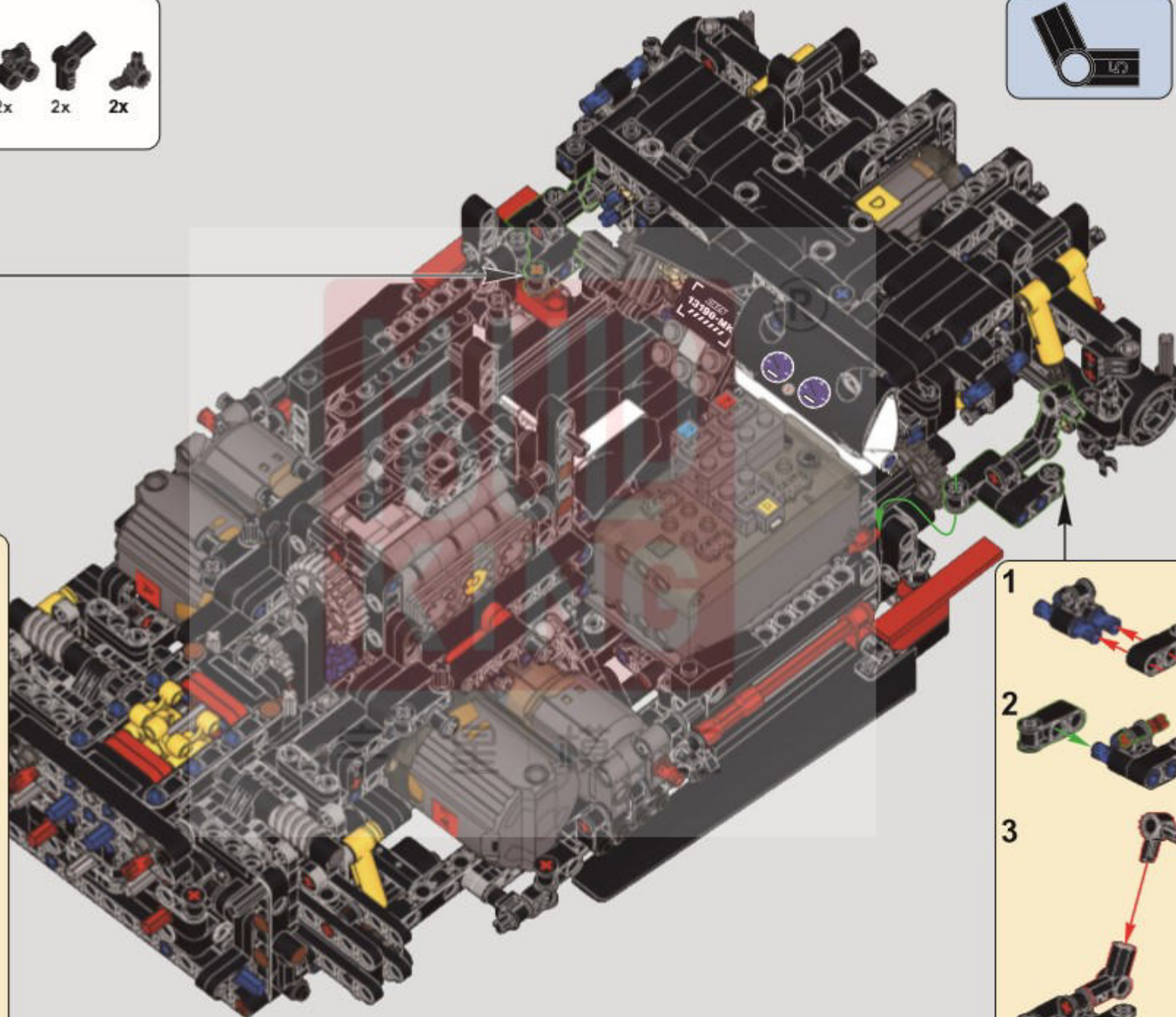


248



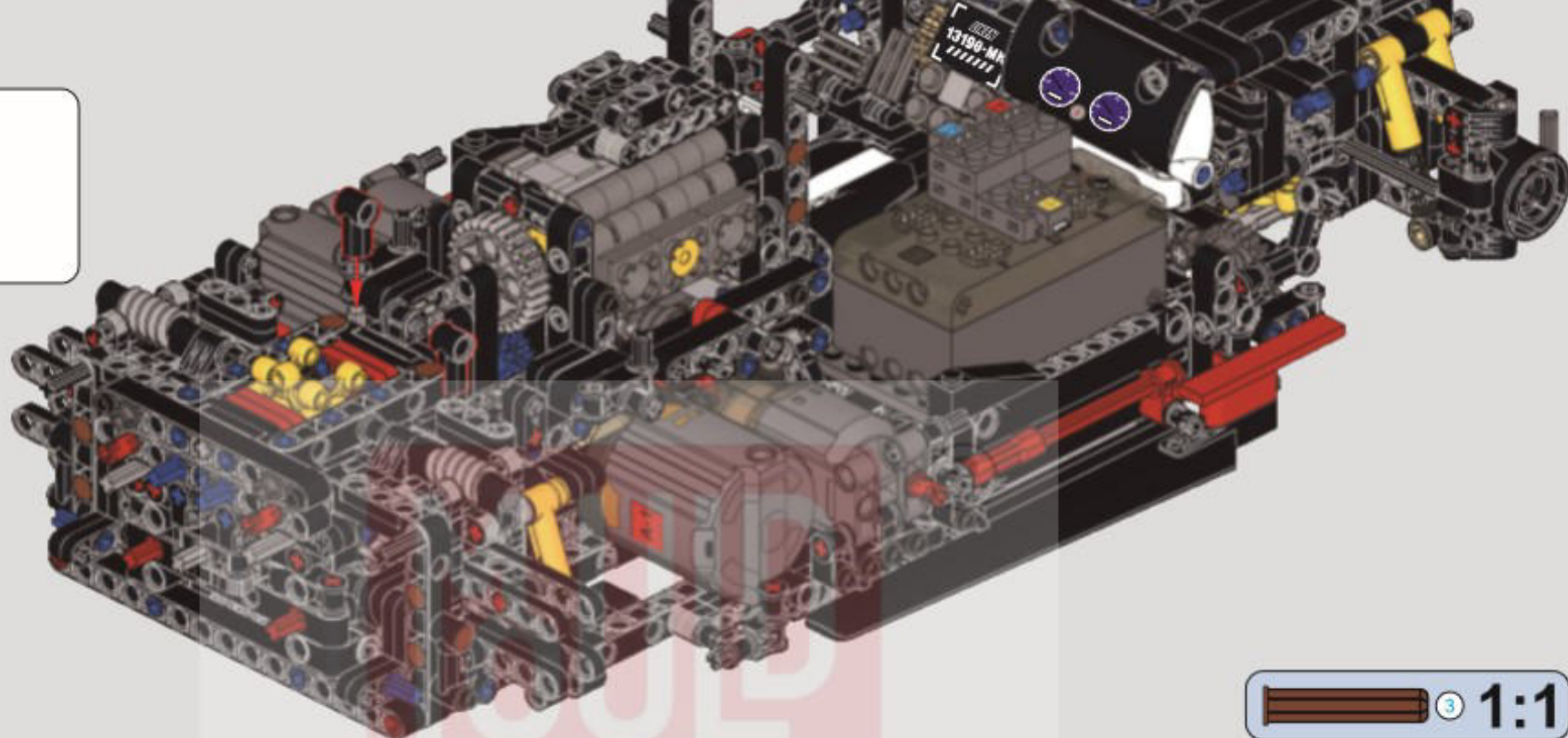


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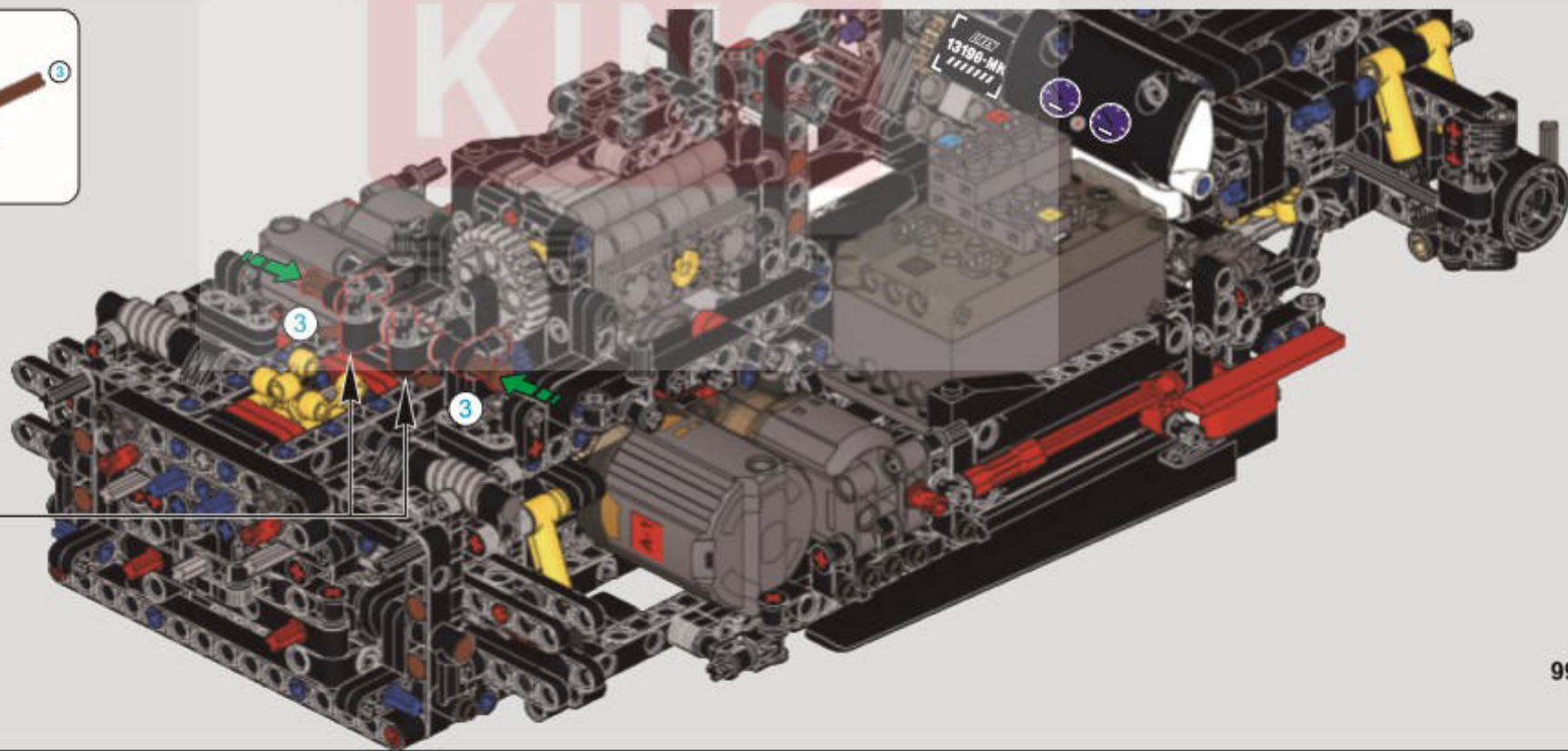




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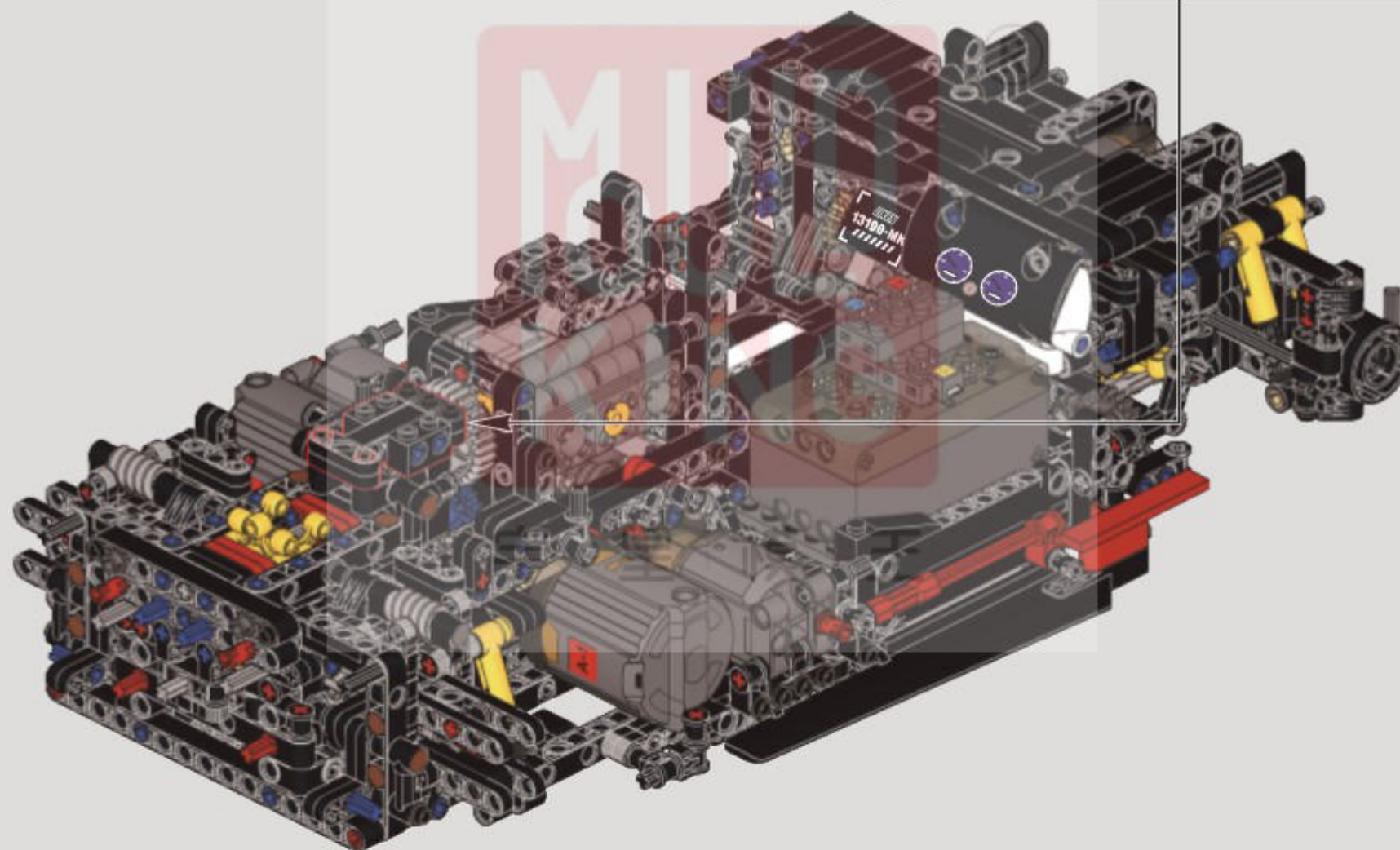
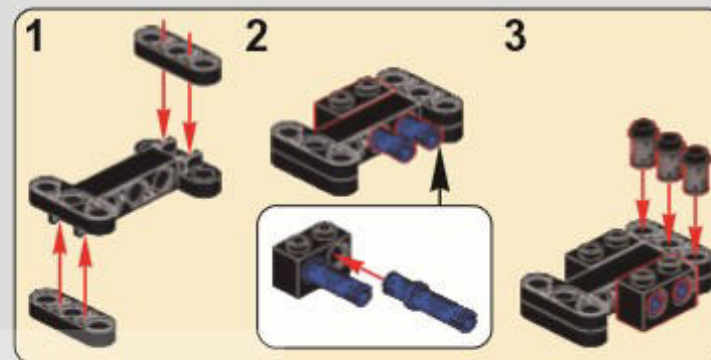


251



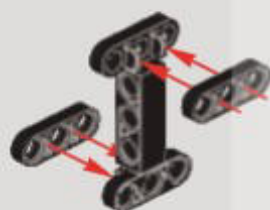


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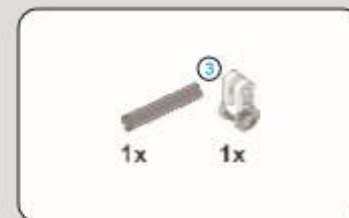
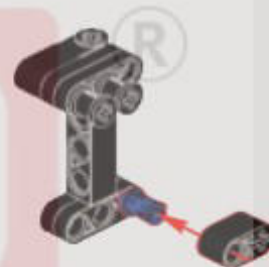
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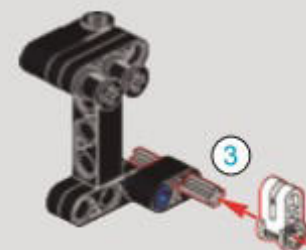
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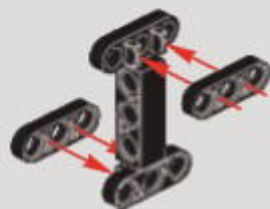
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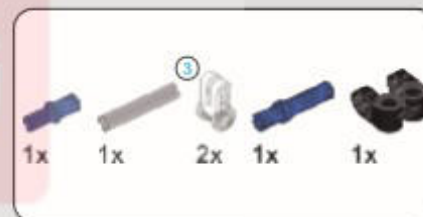
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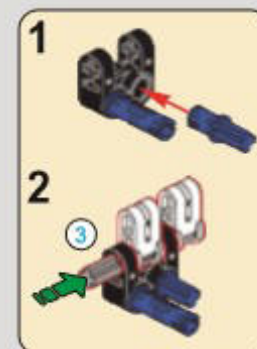
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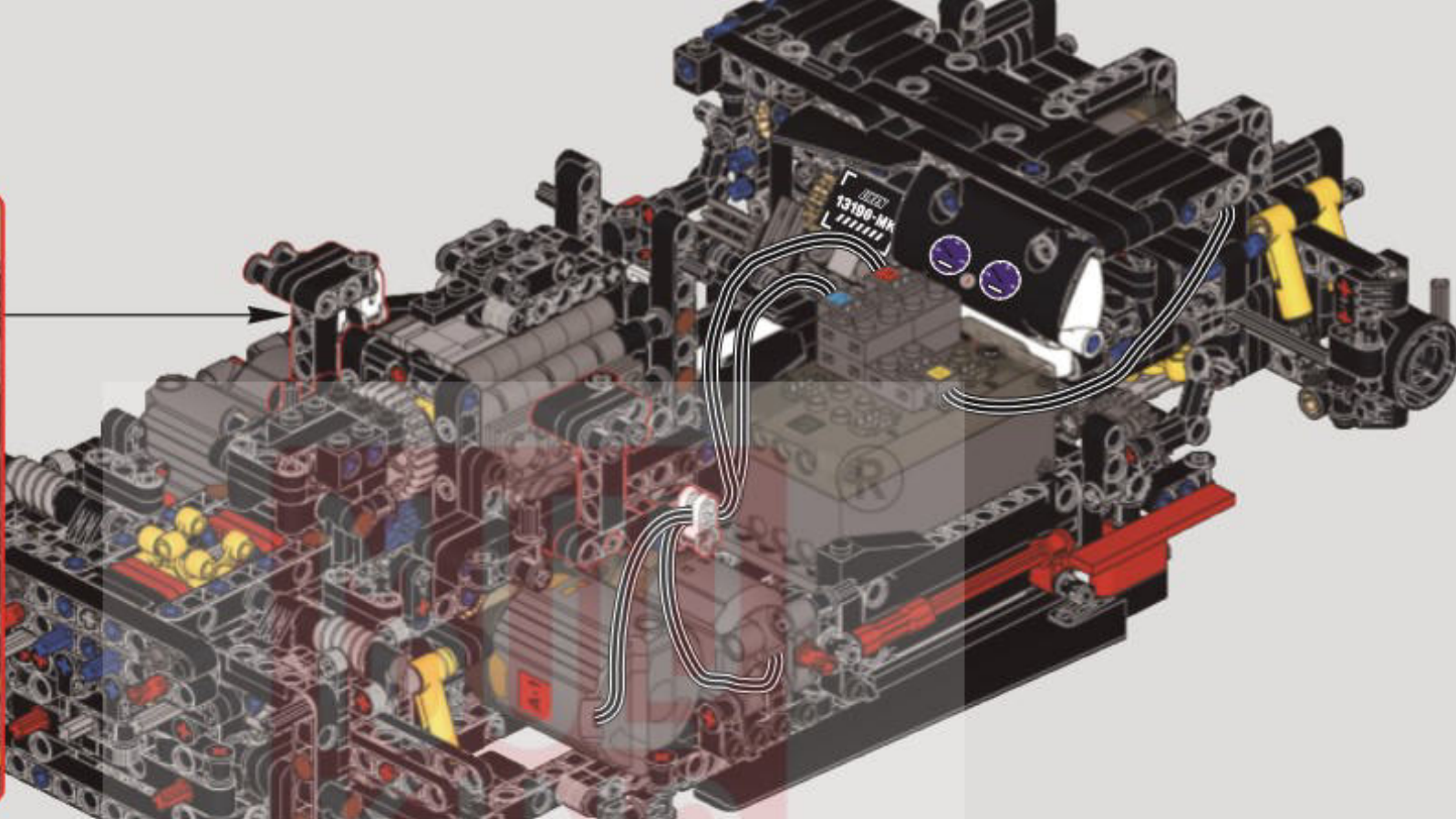
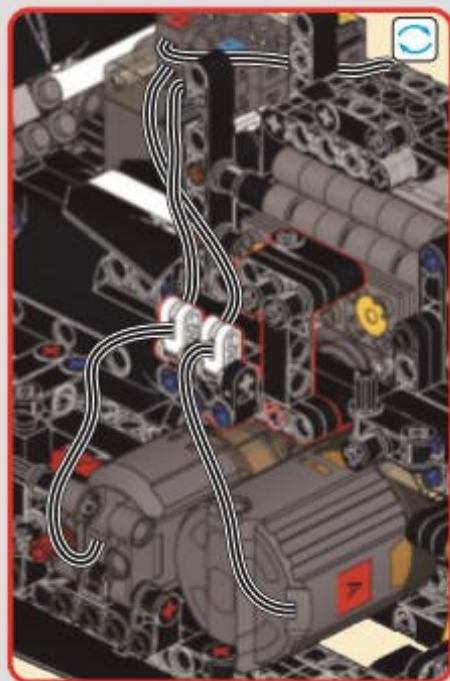
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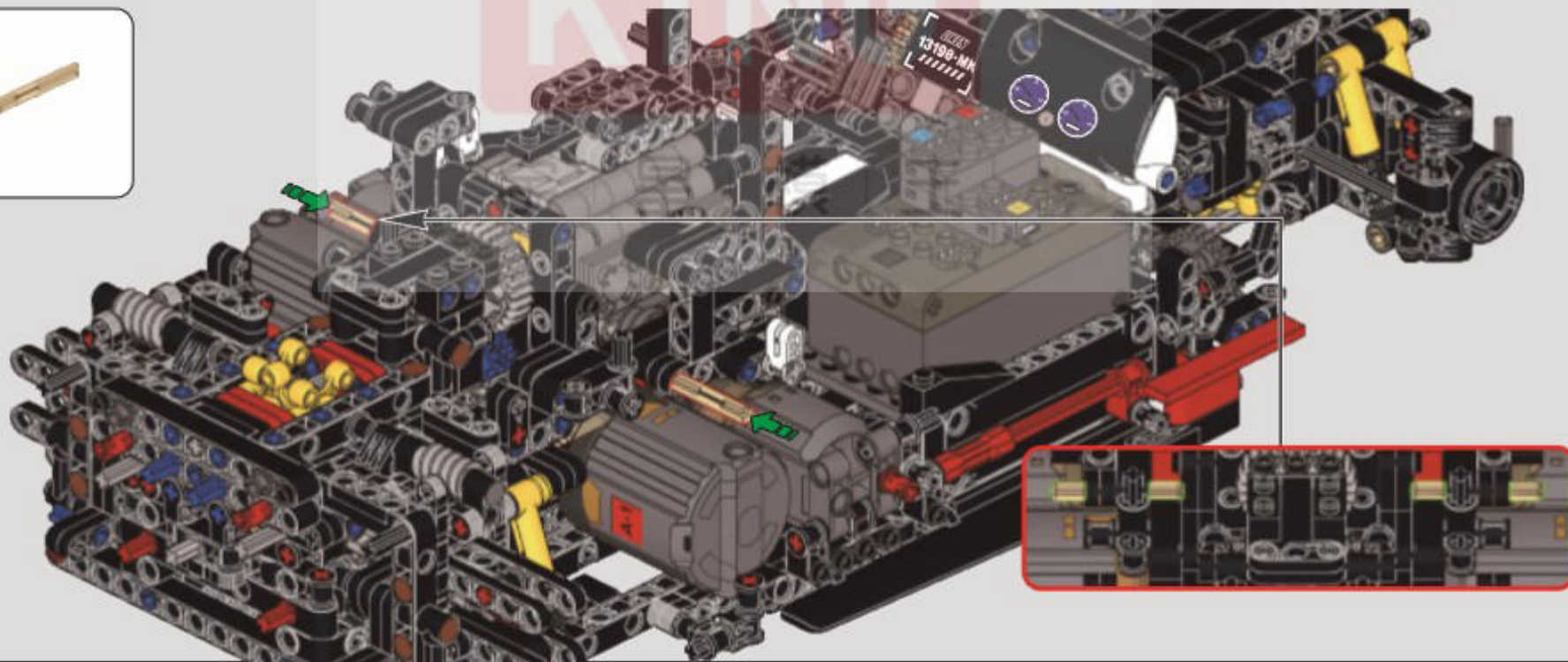
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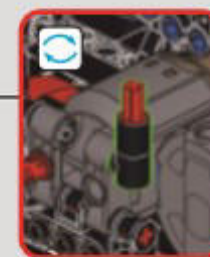
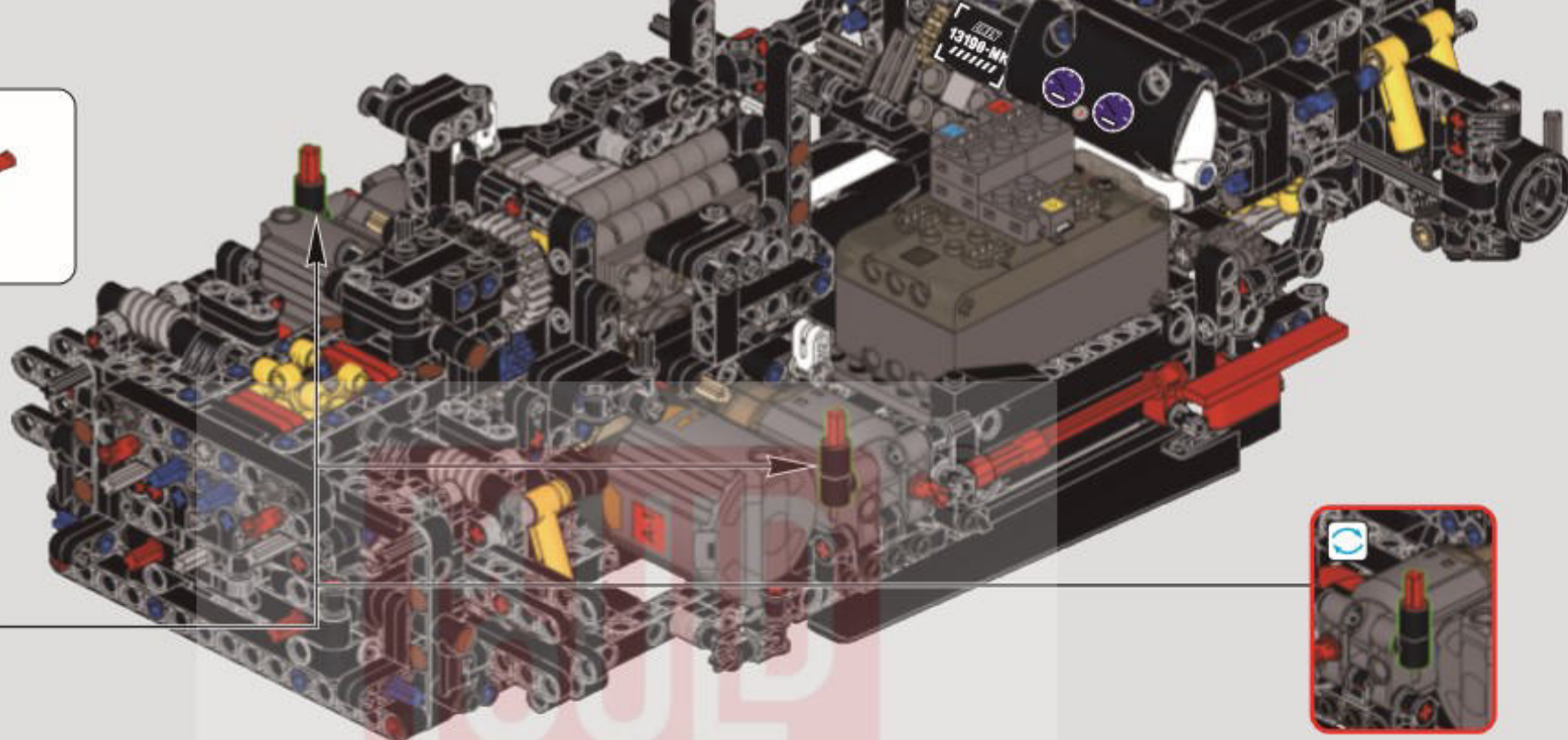


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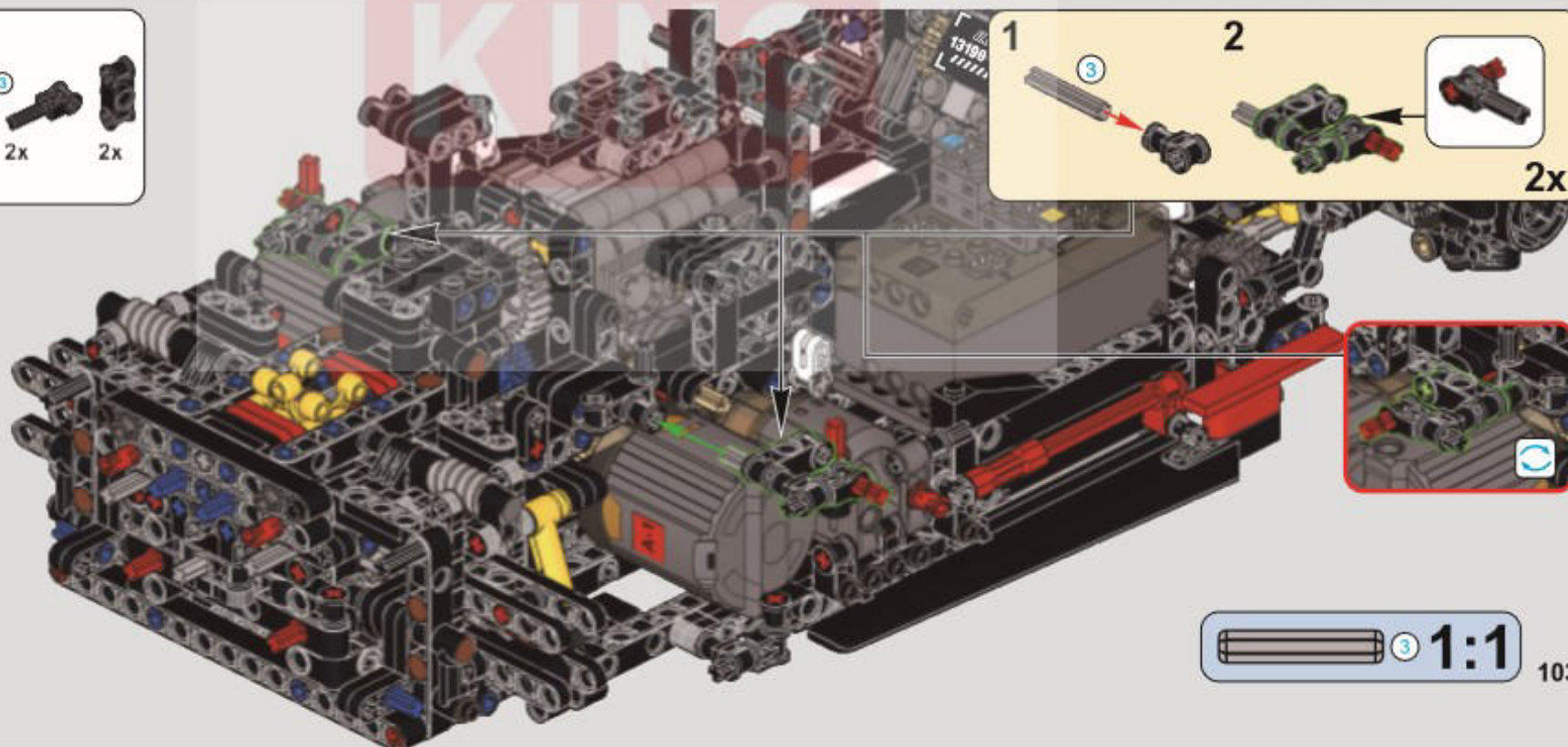




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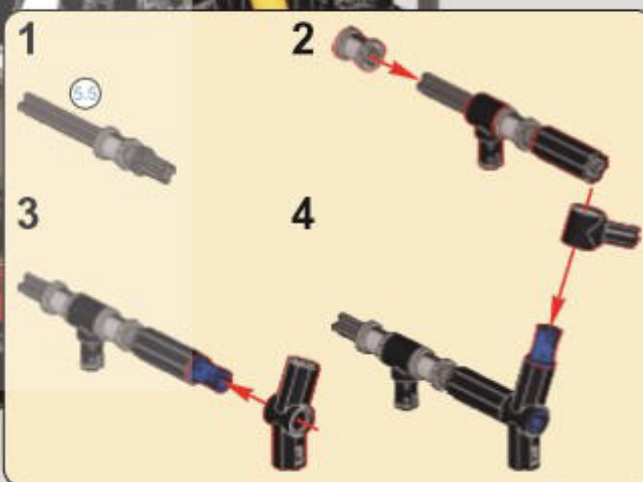
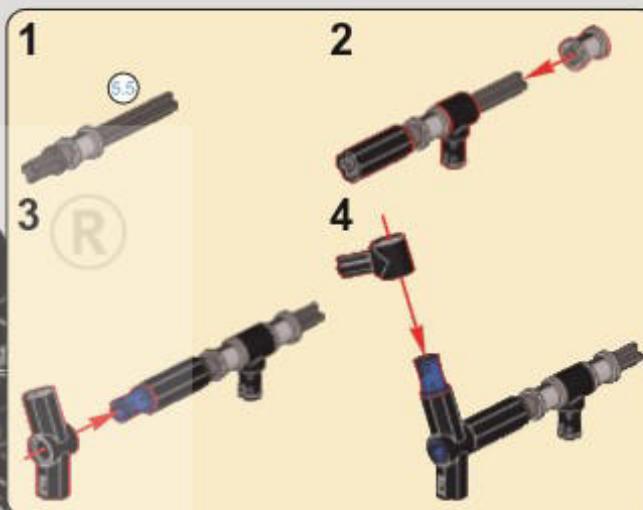
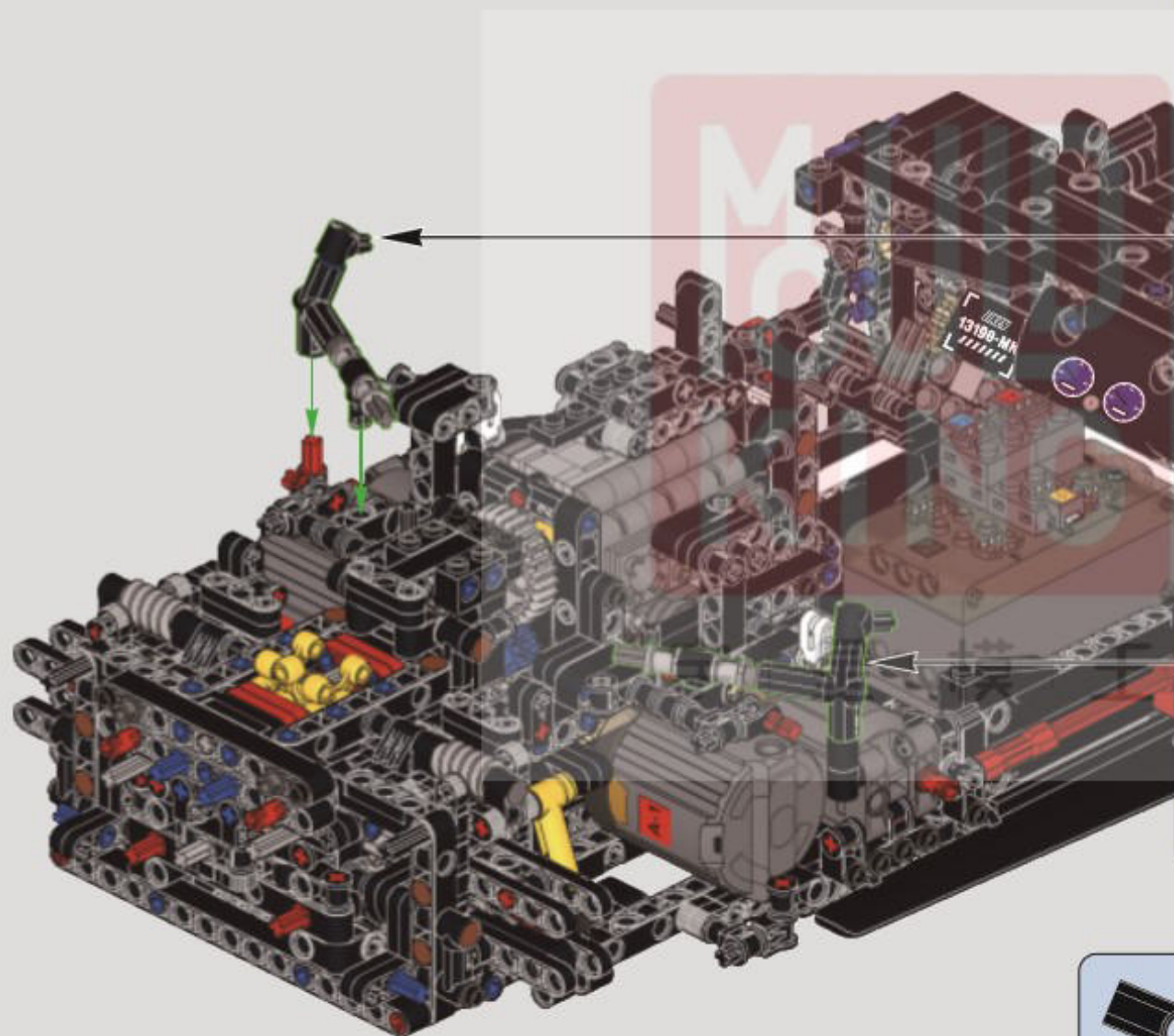


263





264





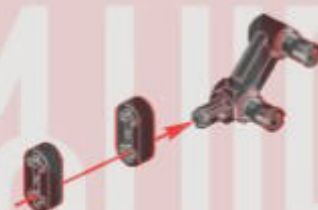
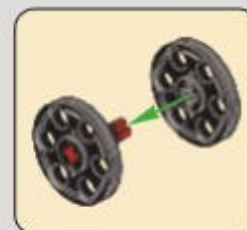
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266



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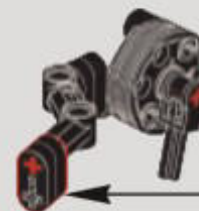
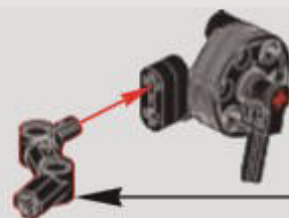
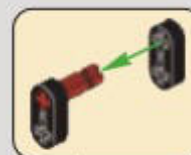
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269



270





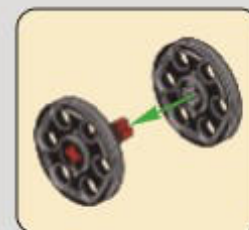
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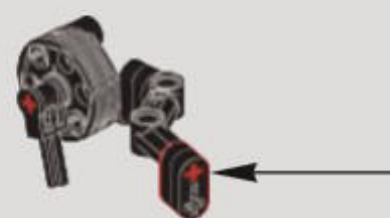
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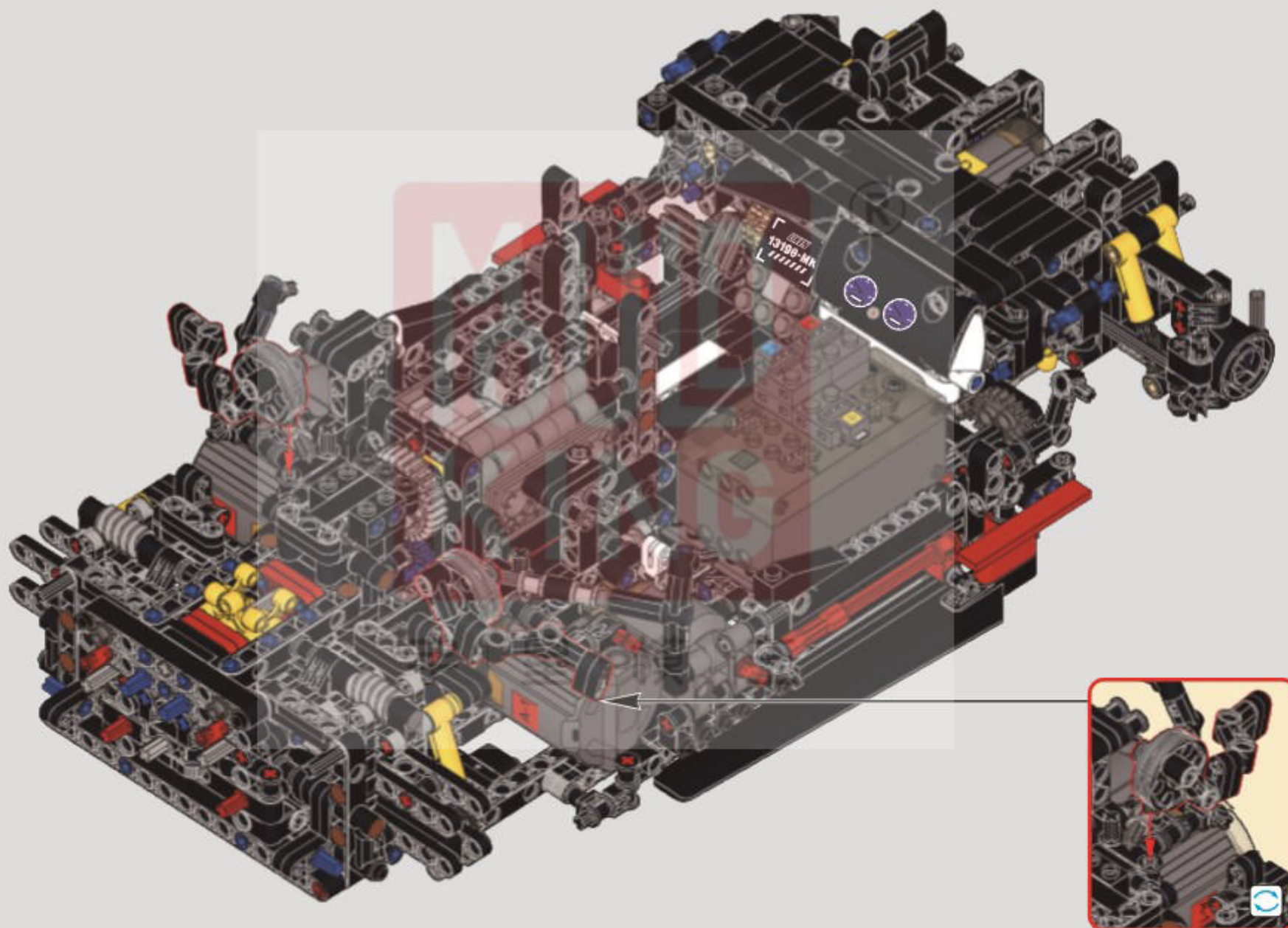


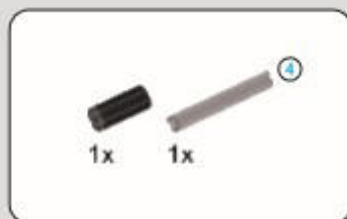
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276



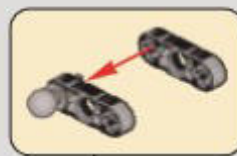




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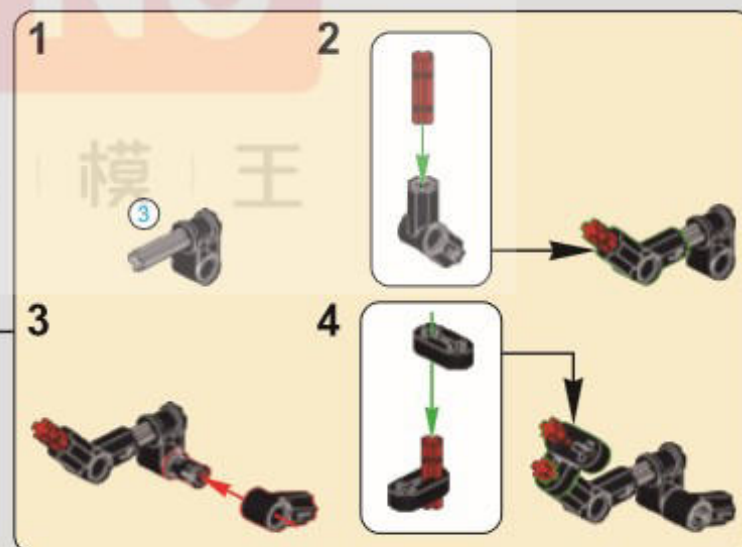
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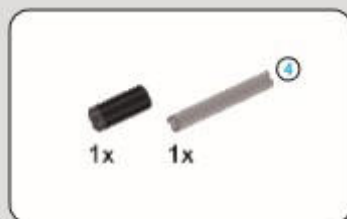


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281





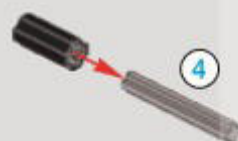
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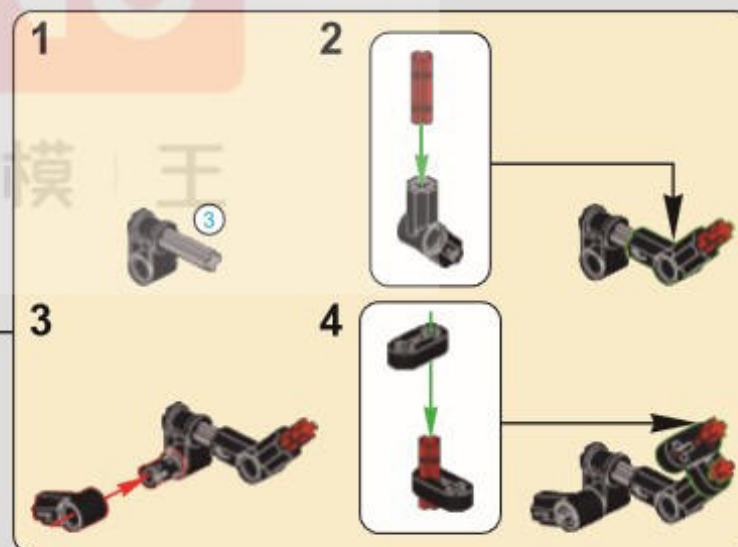
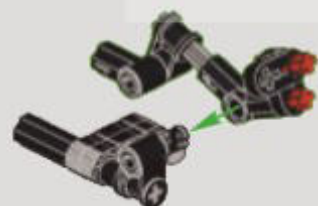
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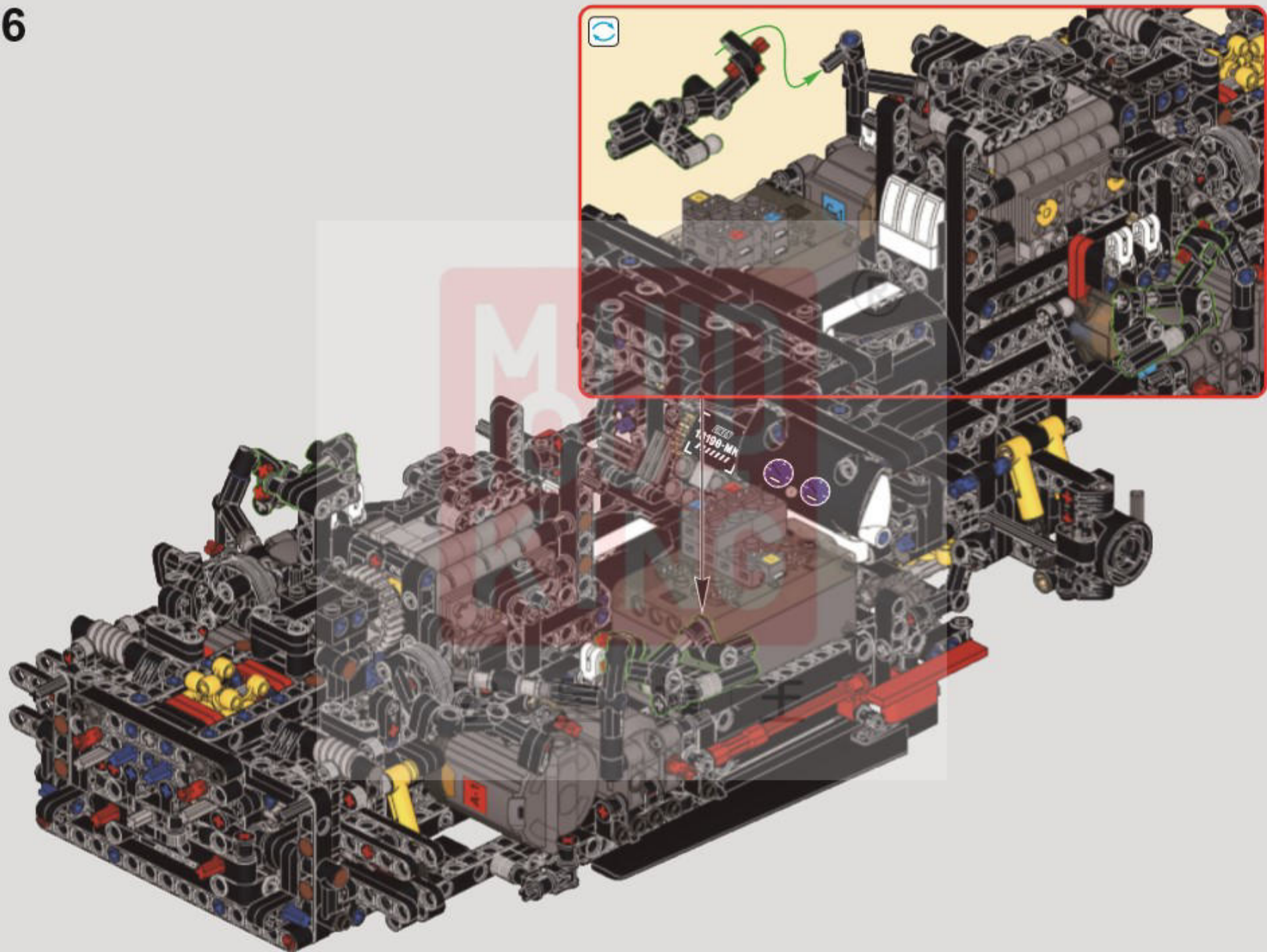


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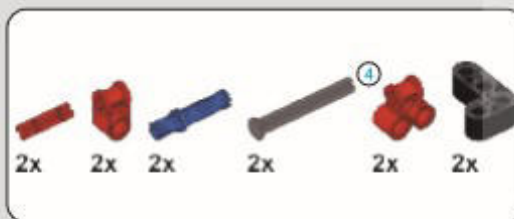
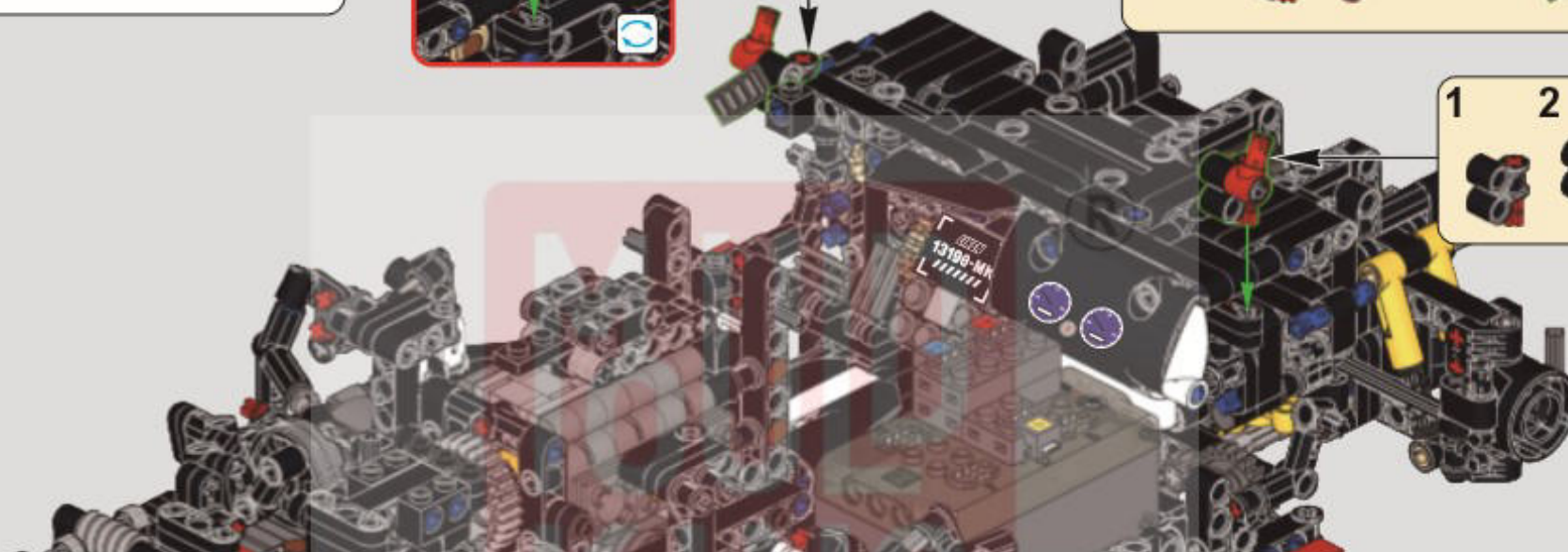
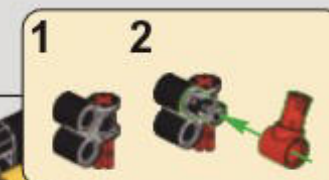
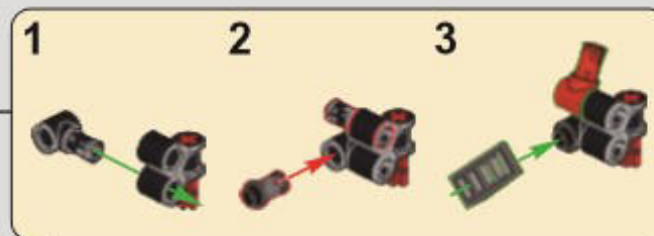
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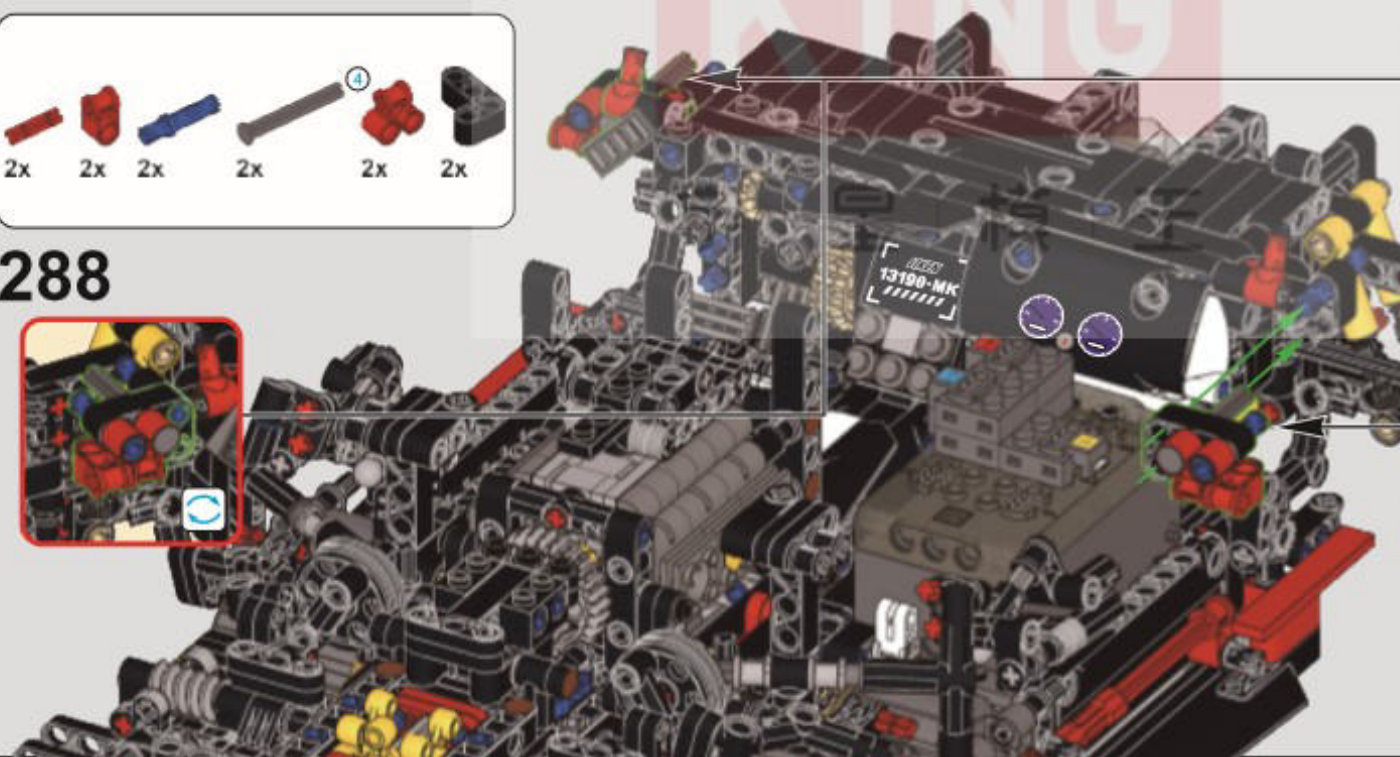
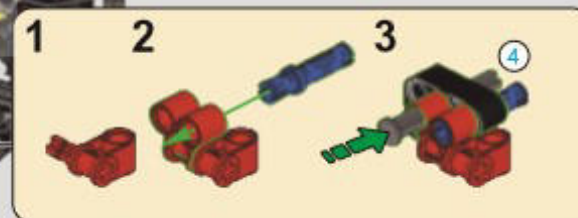
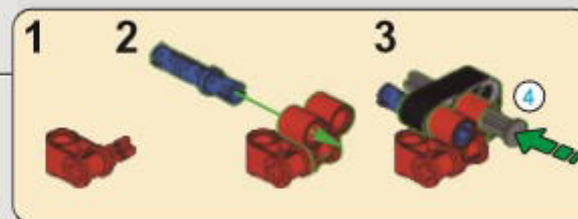


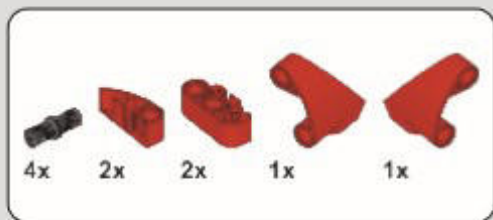


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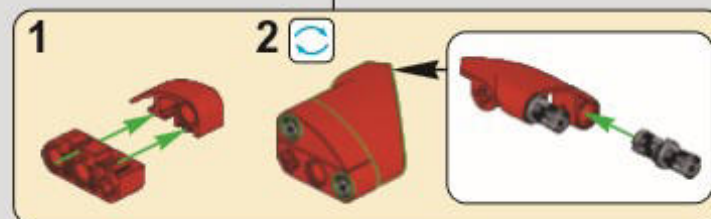
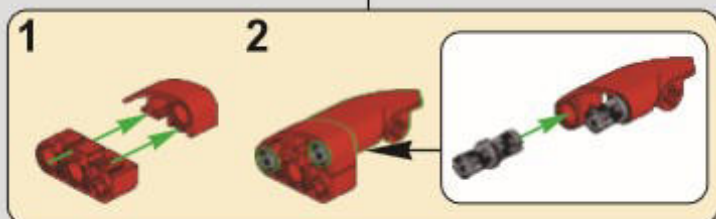
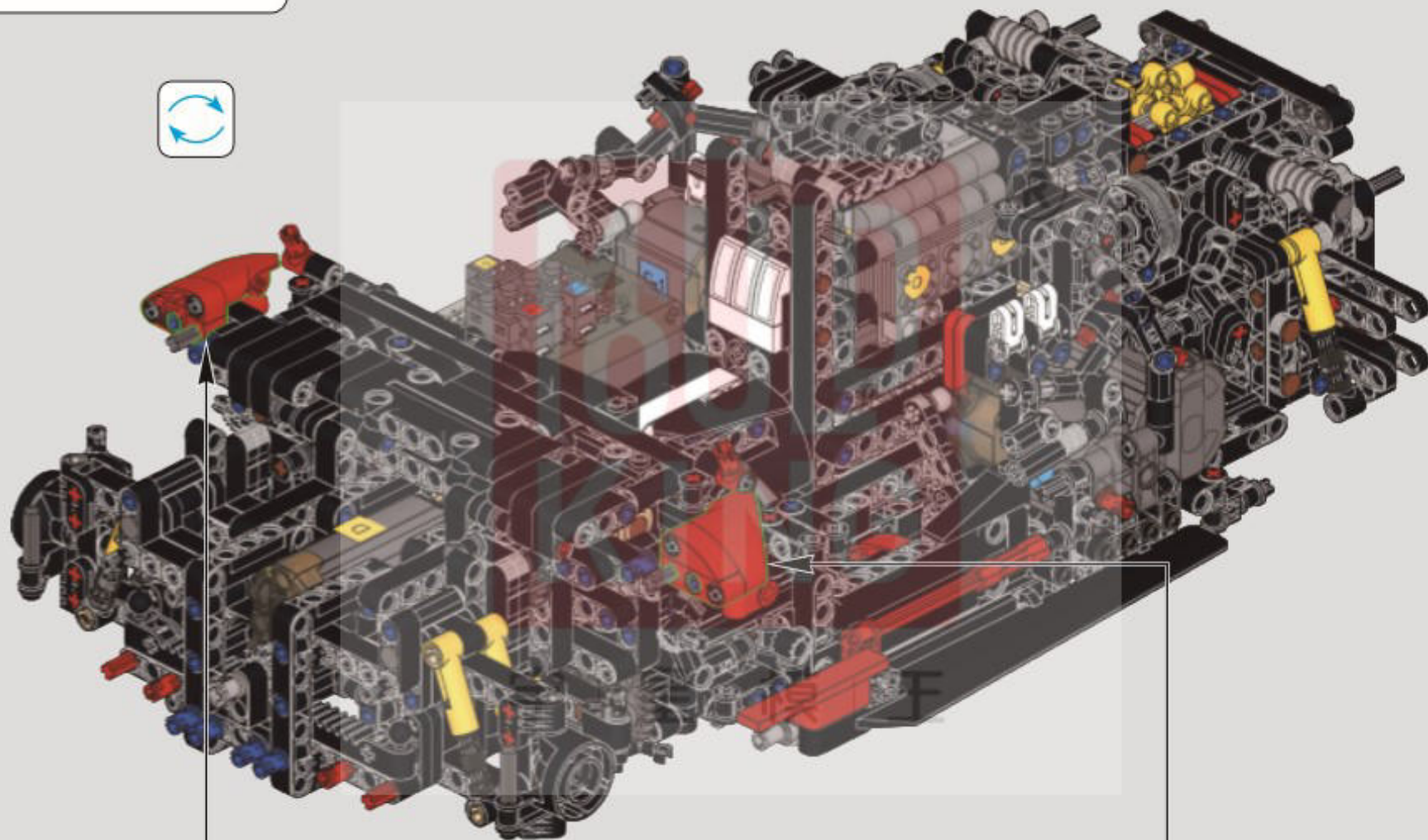


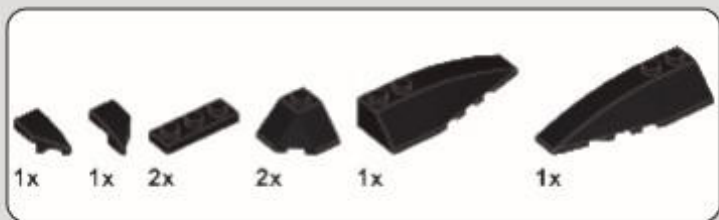
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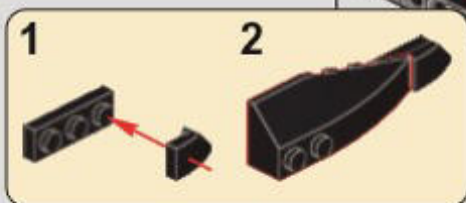
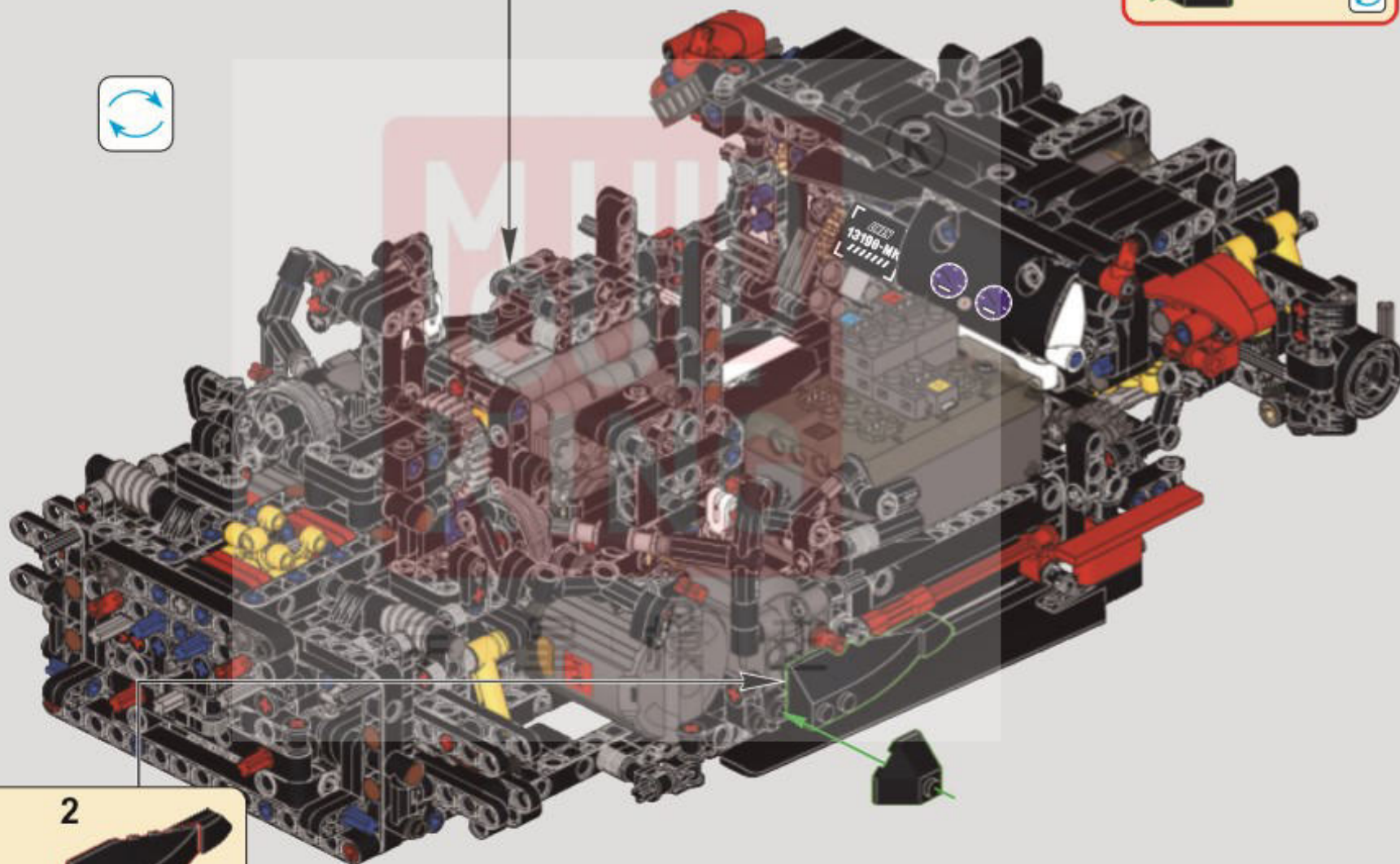
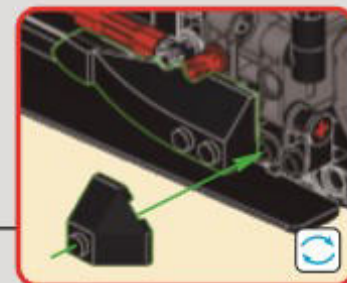
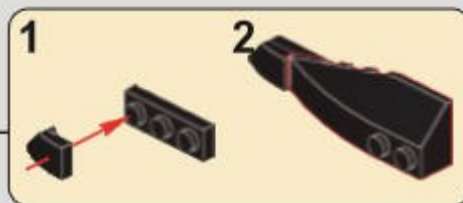


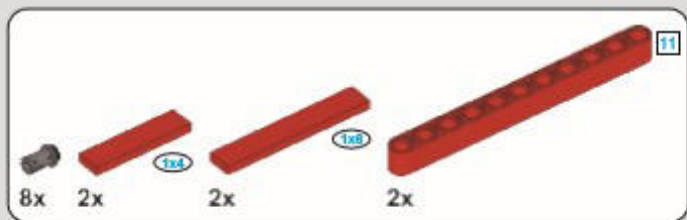
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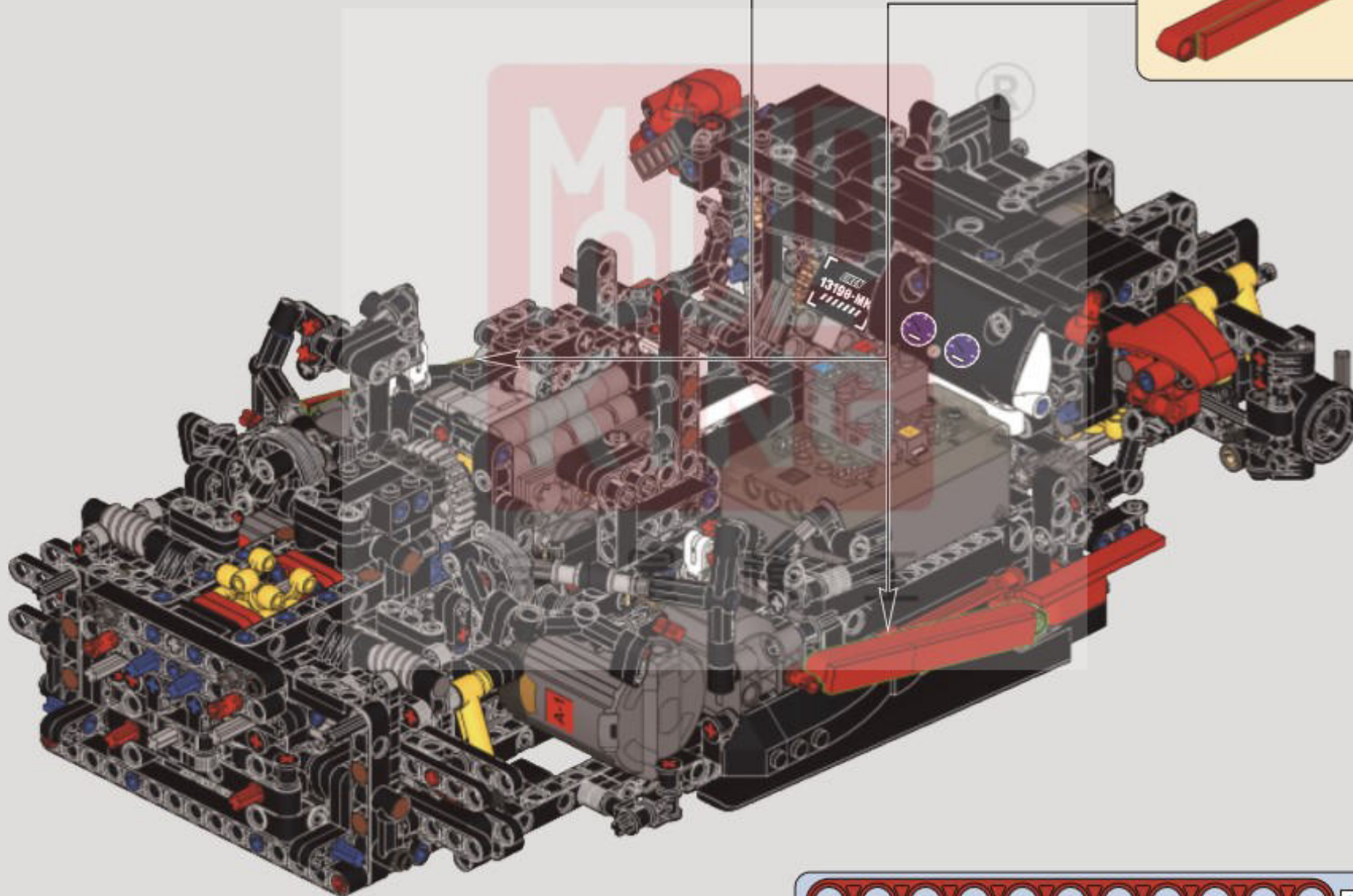
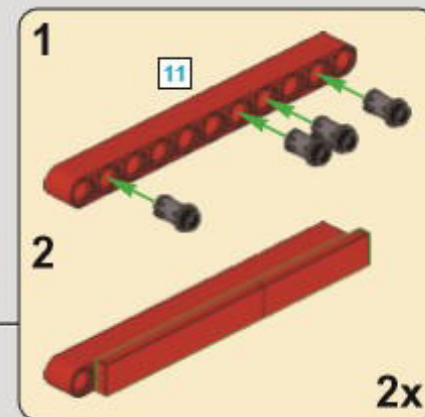
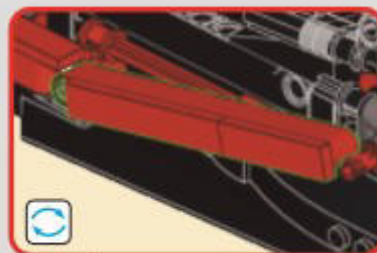


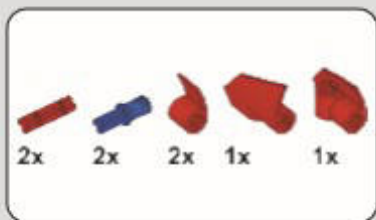
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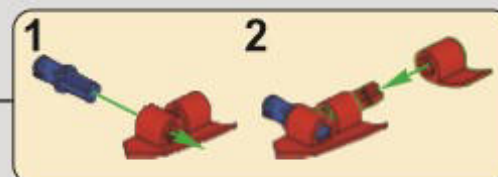
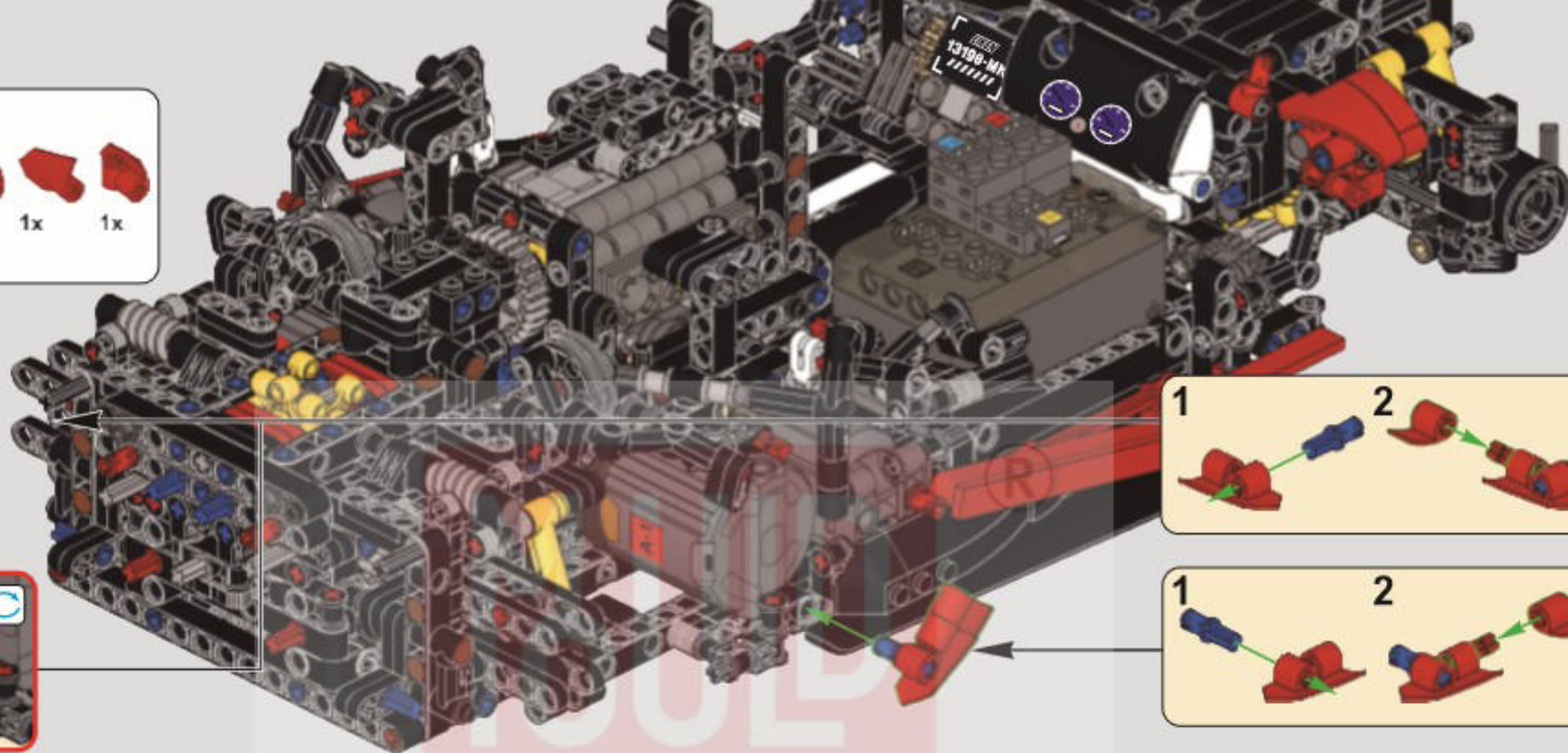
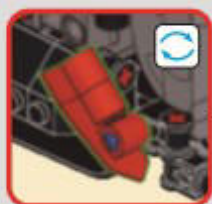


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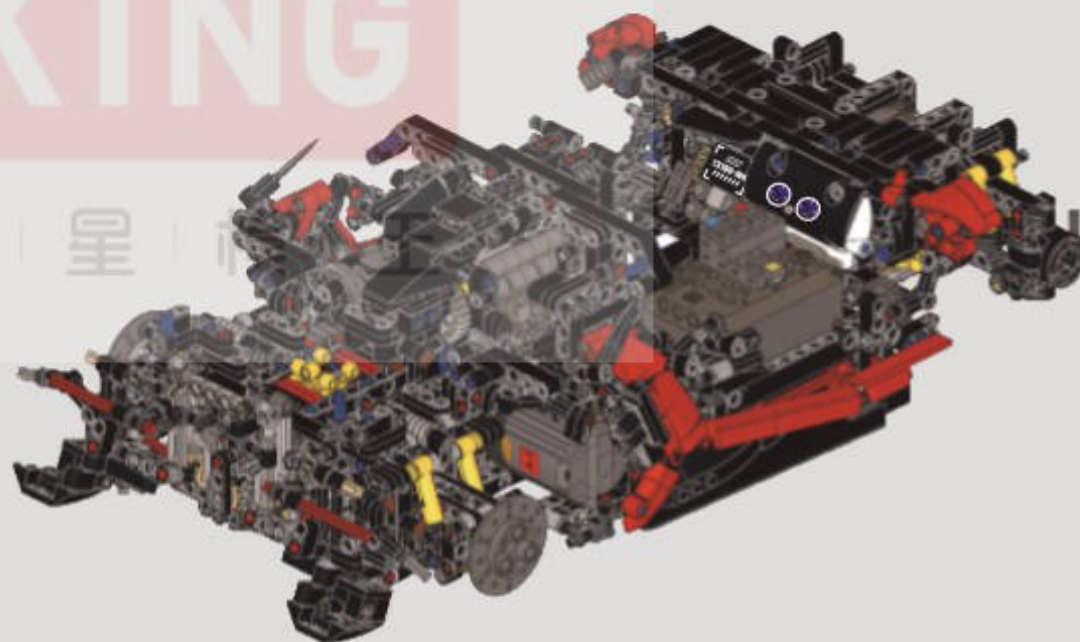




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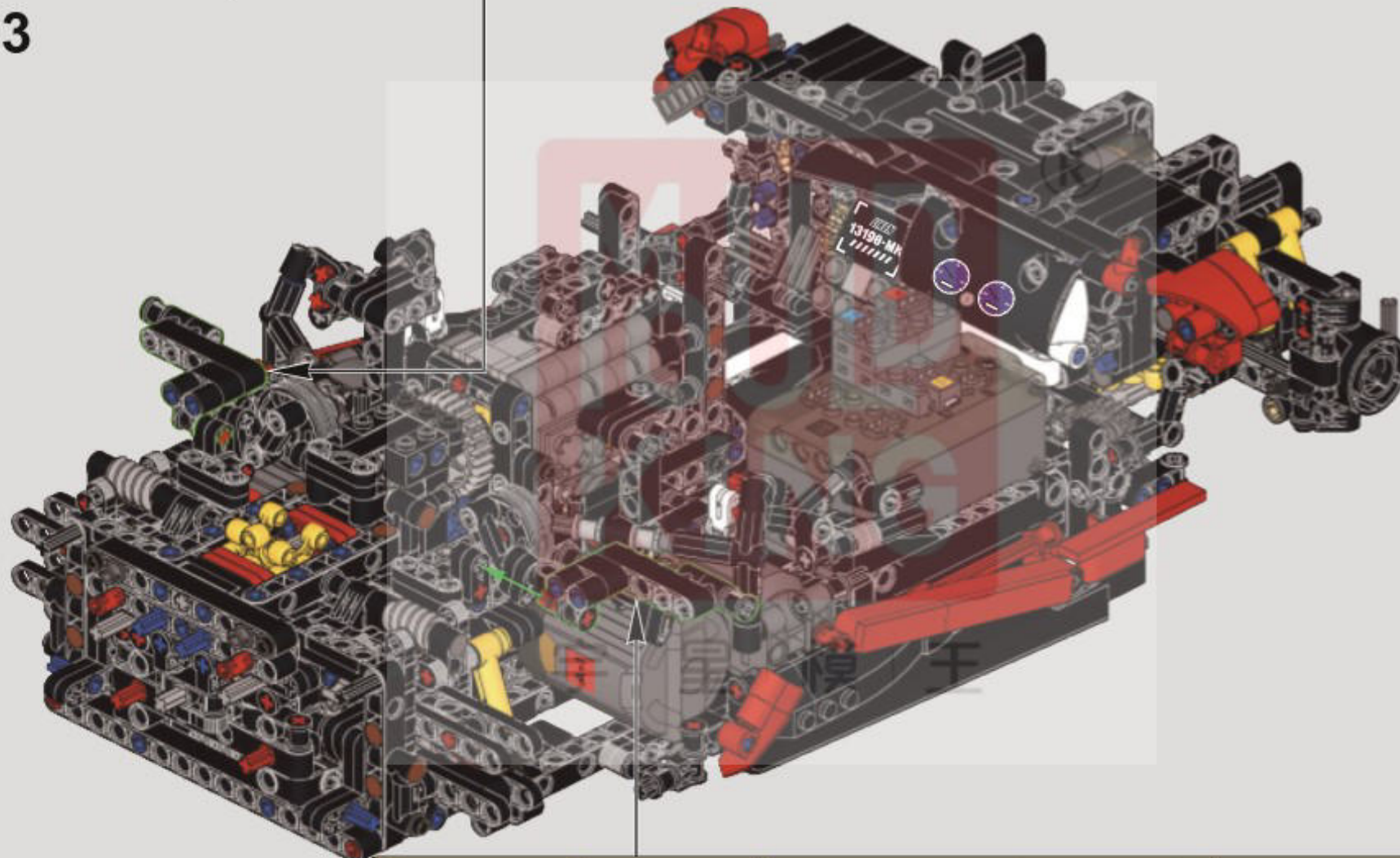
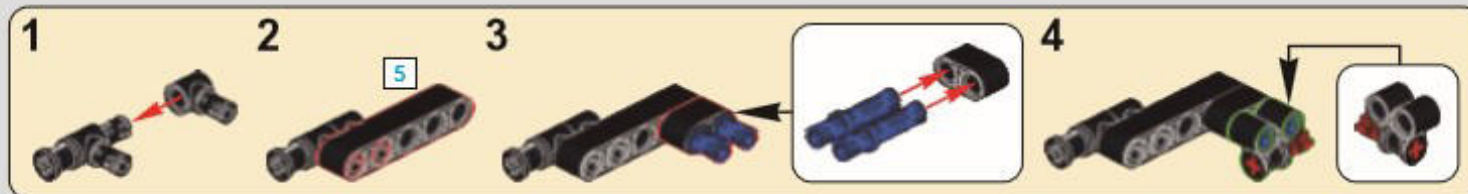


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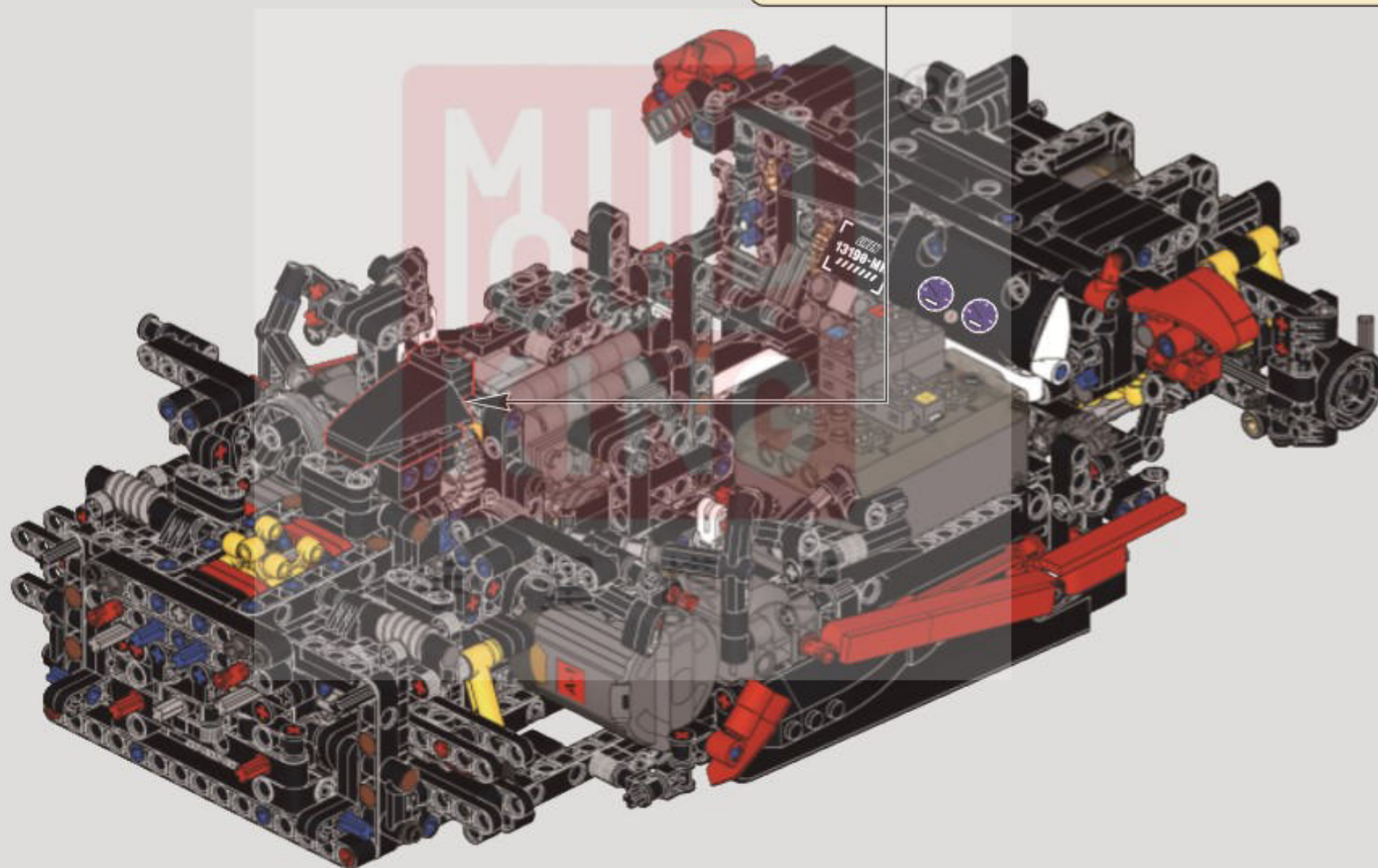
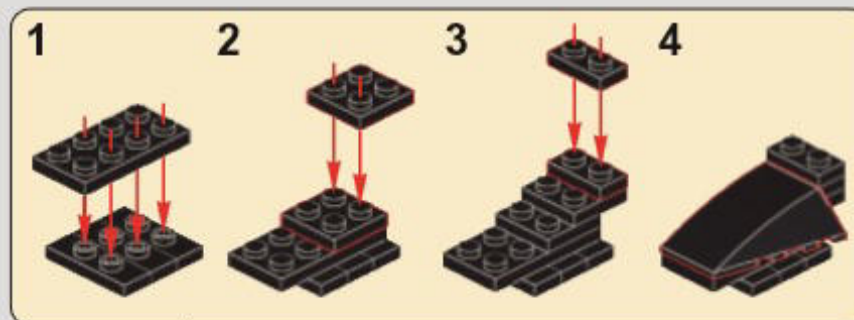


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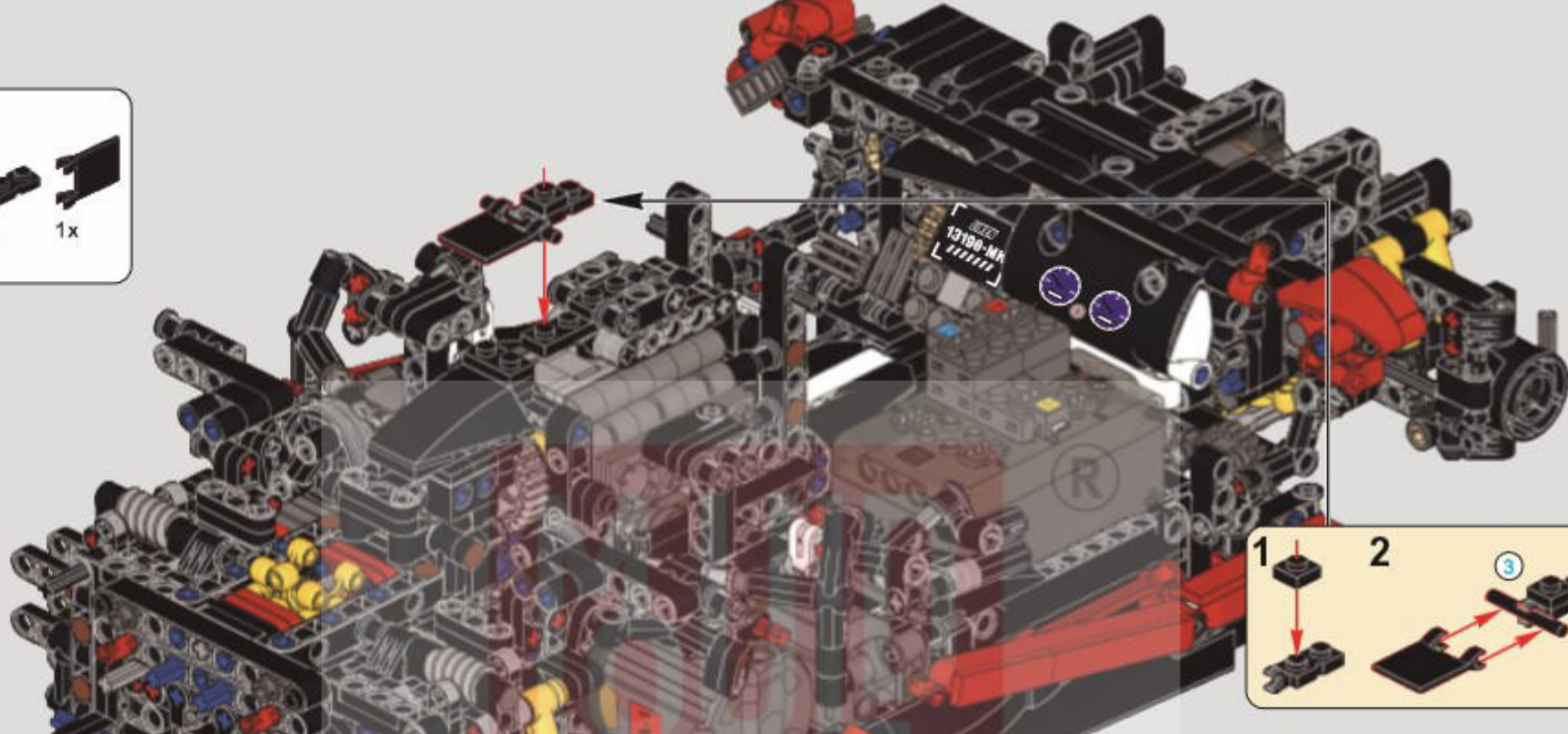


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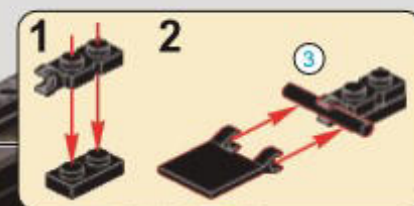
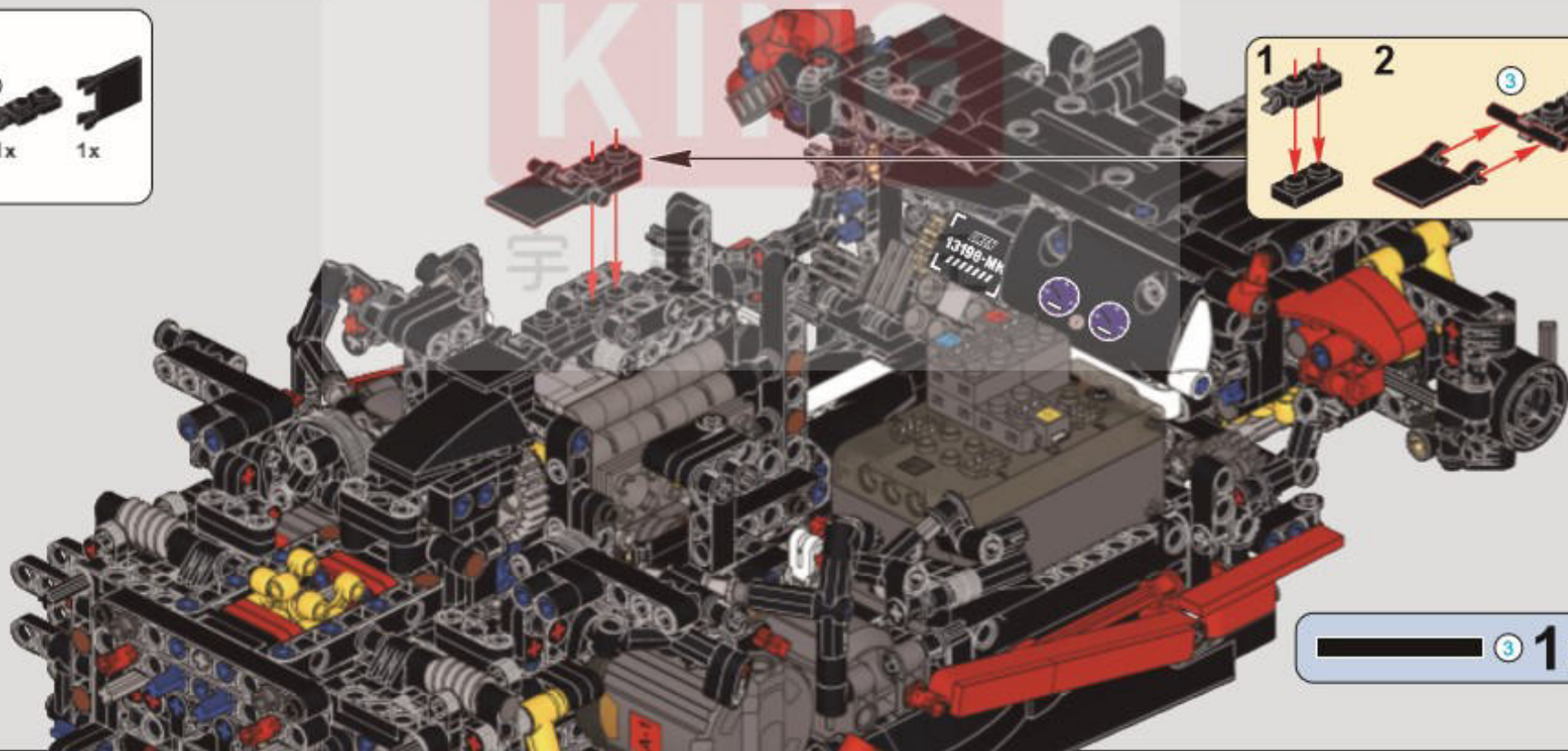




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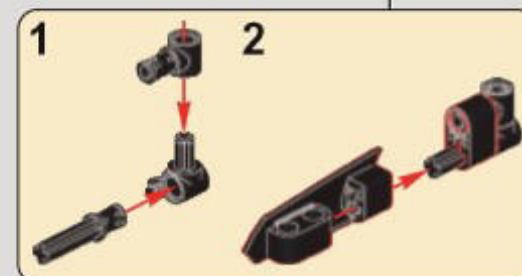
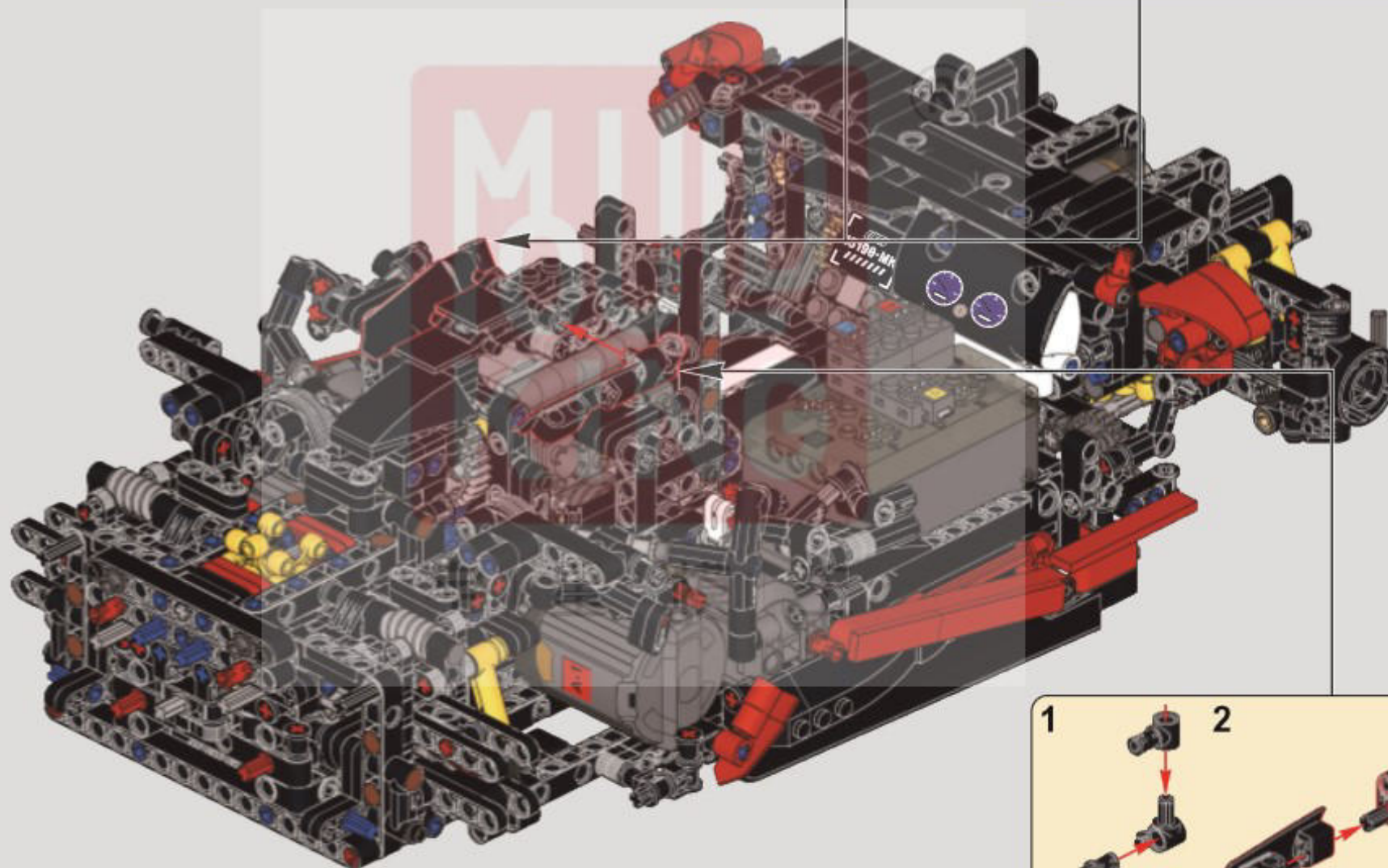
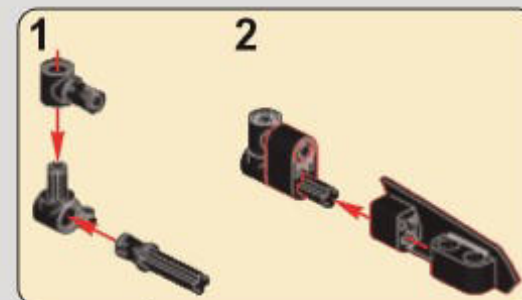
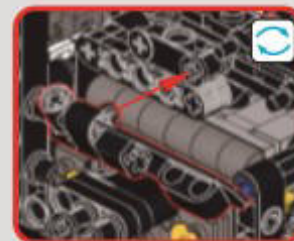
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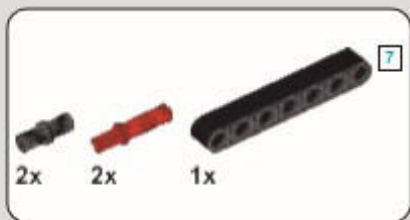


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297

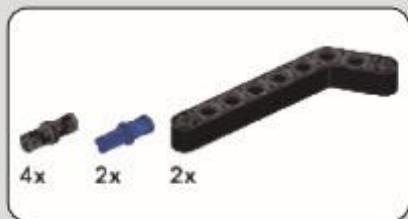
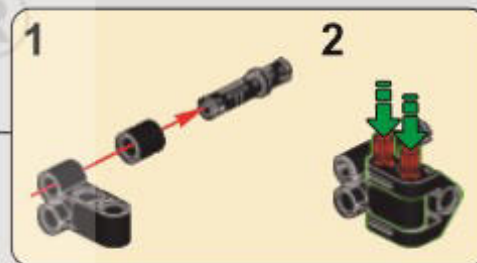
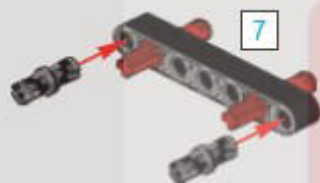
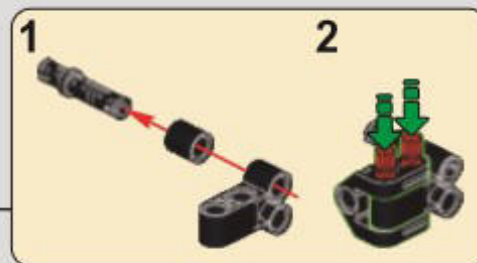




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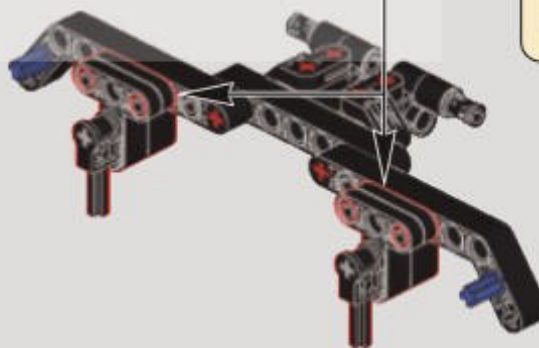
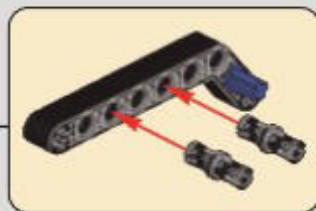
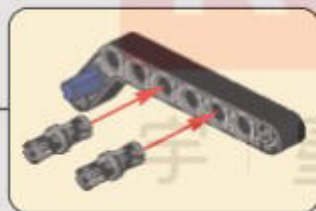
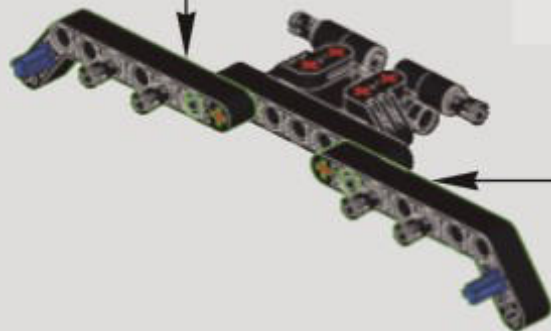
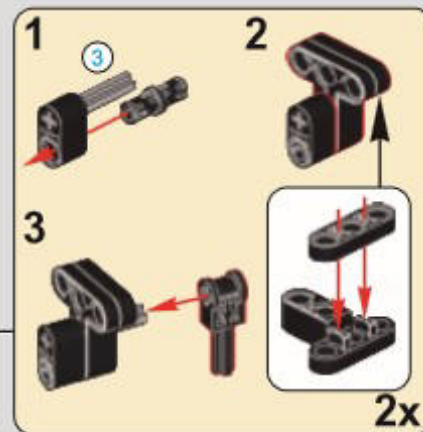
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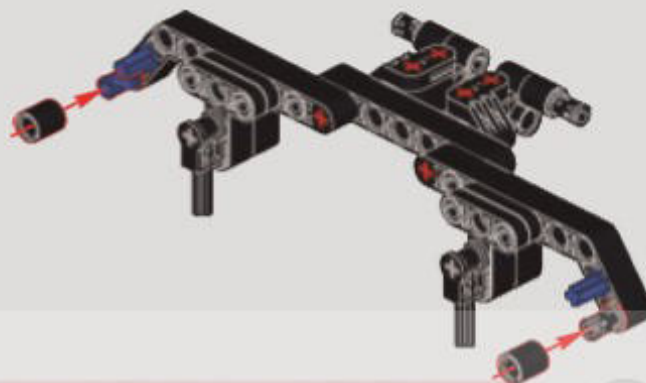


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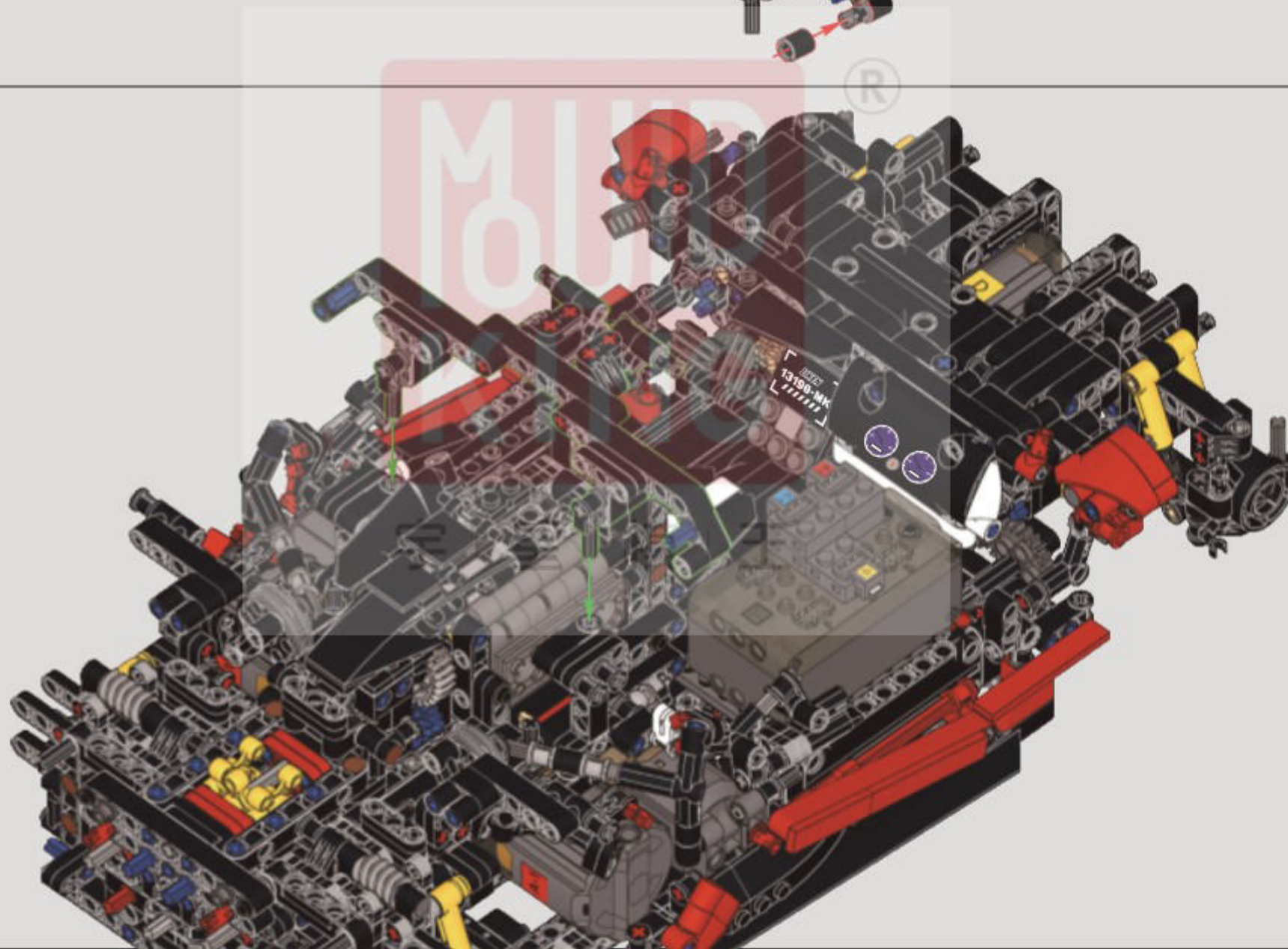




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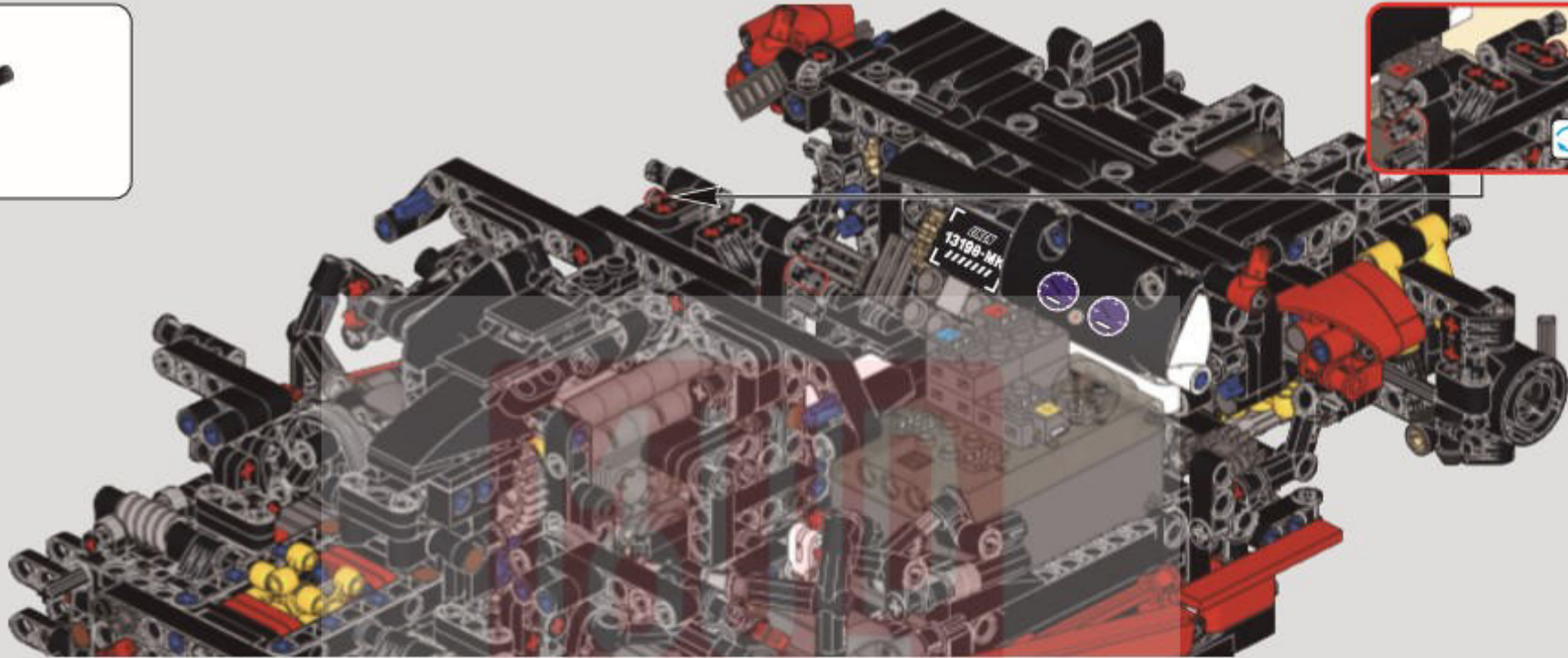


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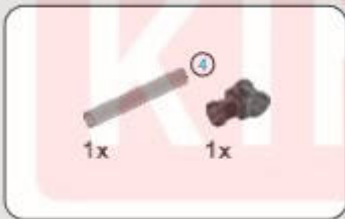




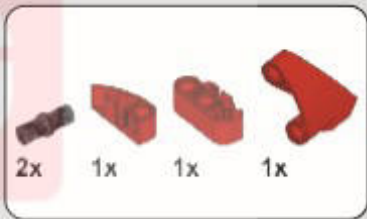
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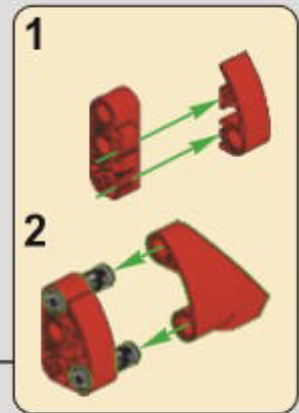
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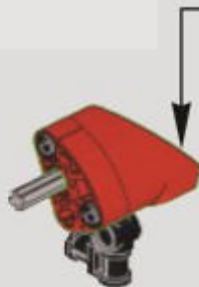
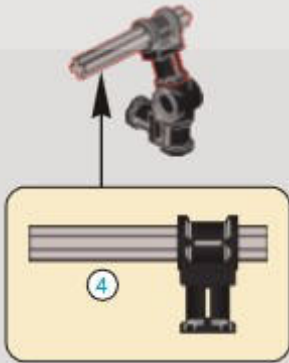
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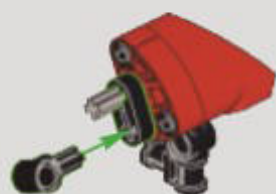


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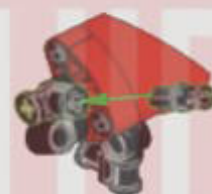




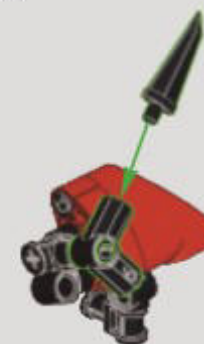
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309



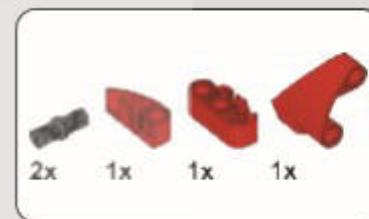
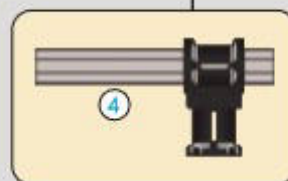
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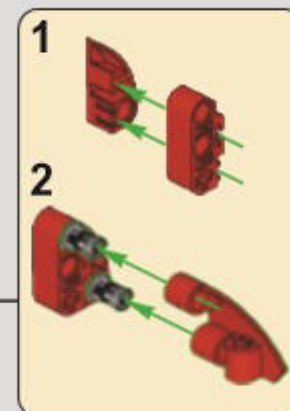
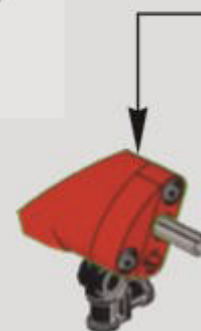
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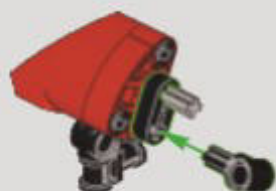


313





314



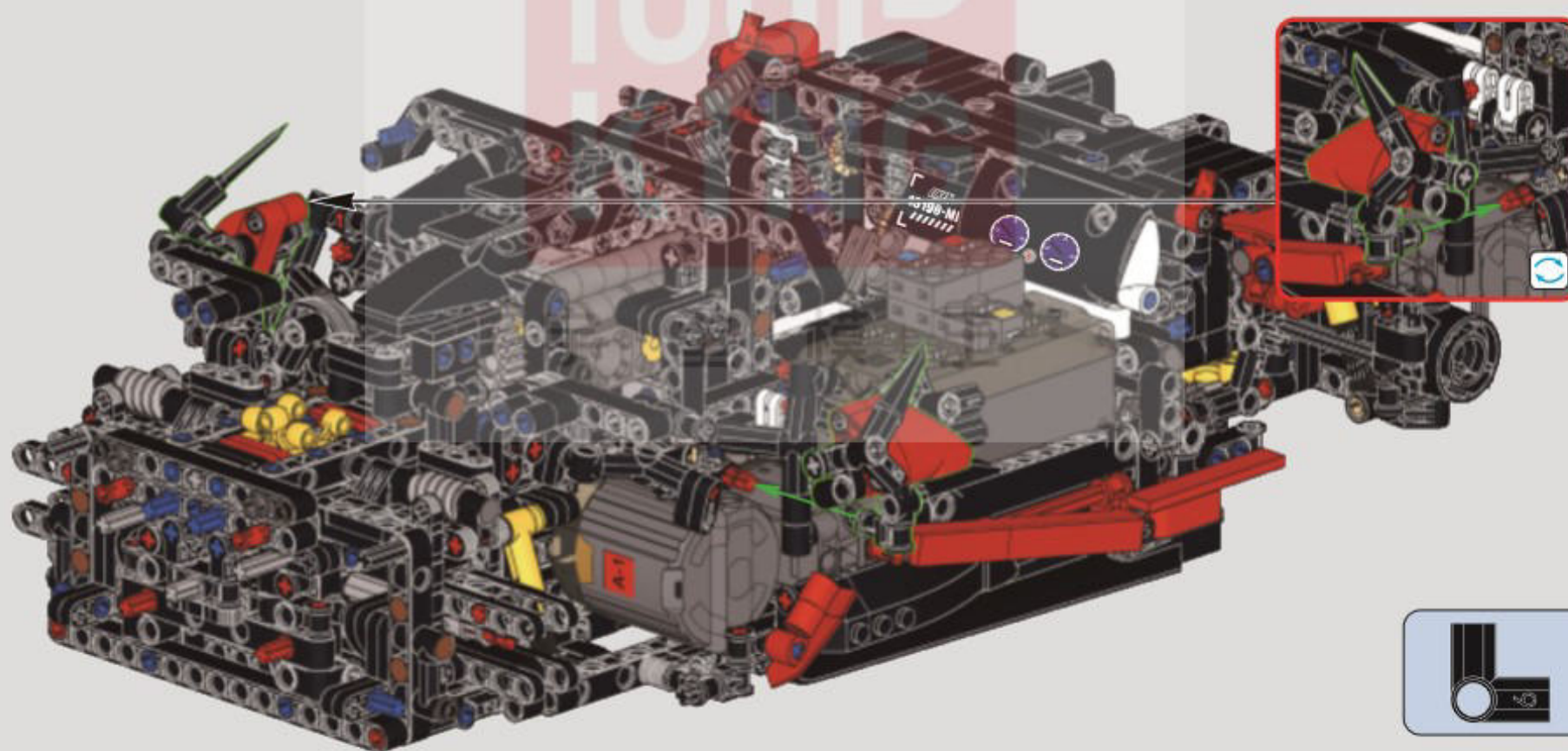
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316

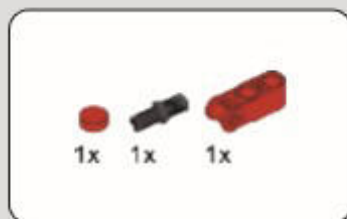


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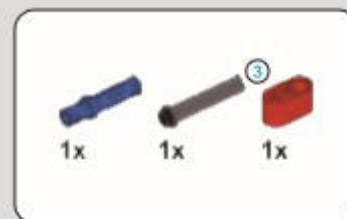




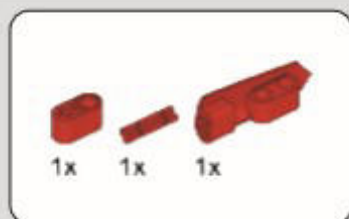
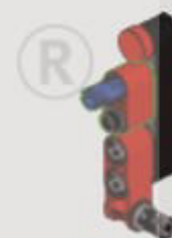
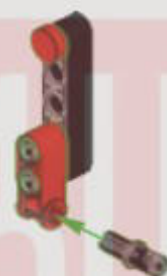
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319



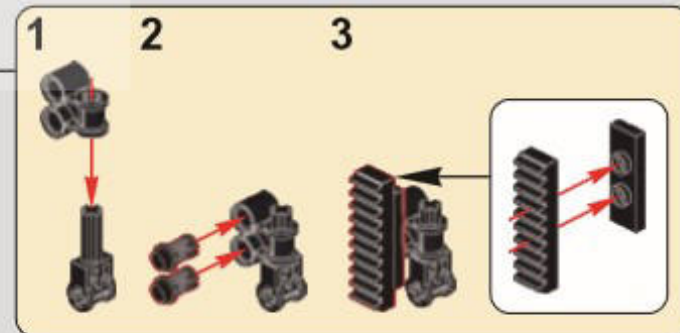
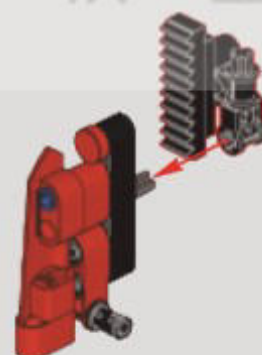
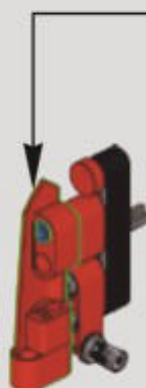
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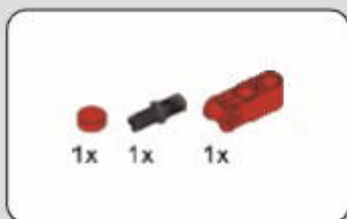


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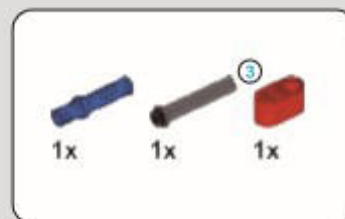




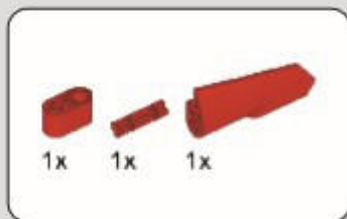
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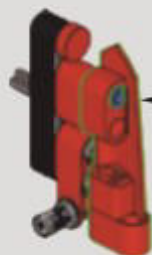
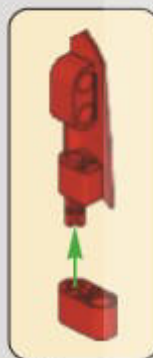
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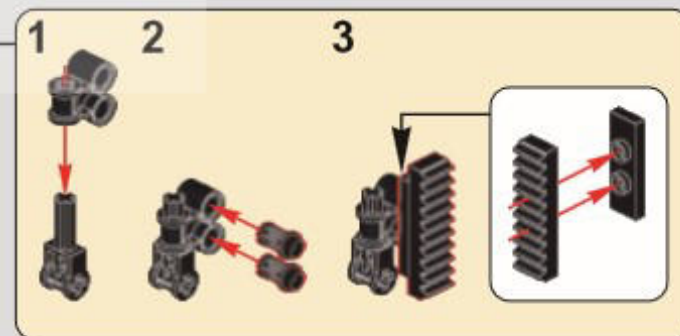
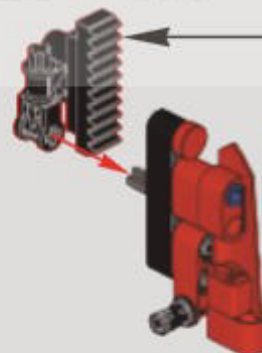
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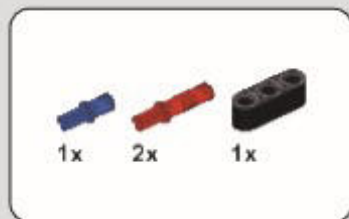
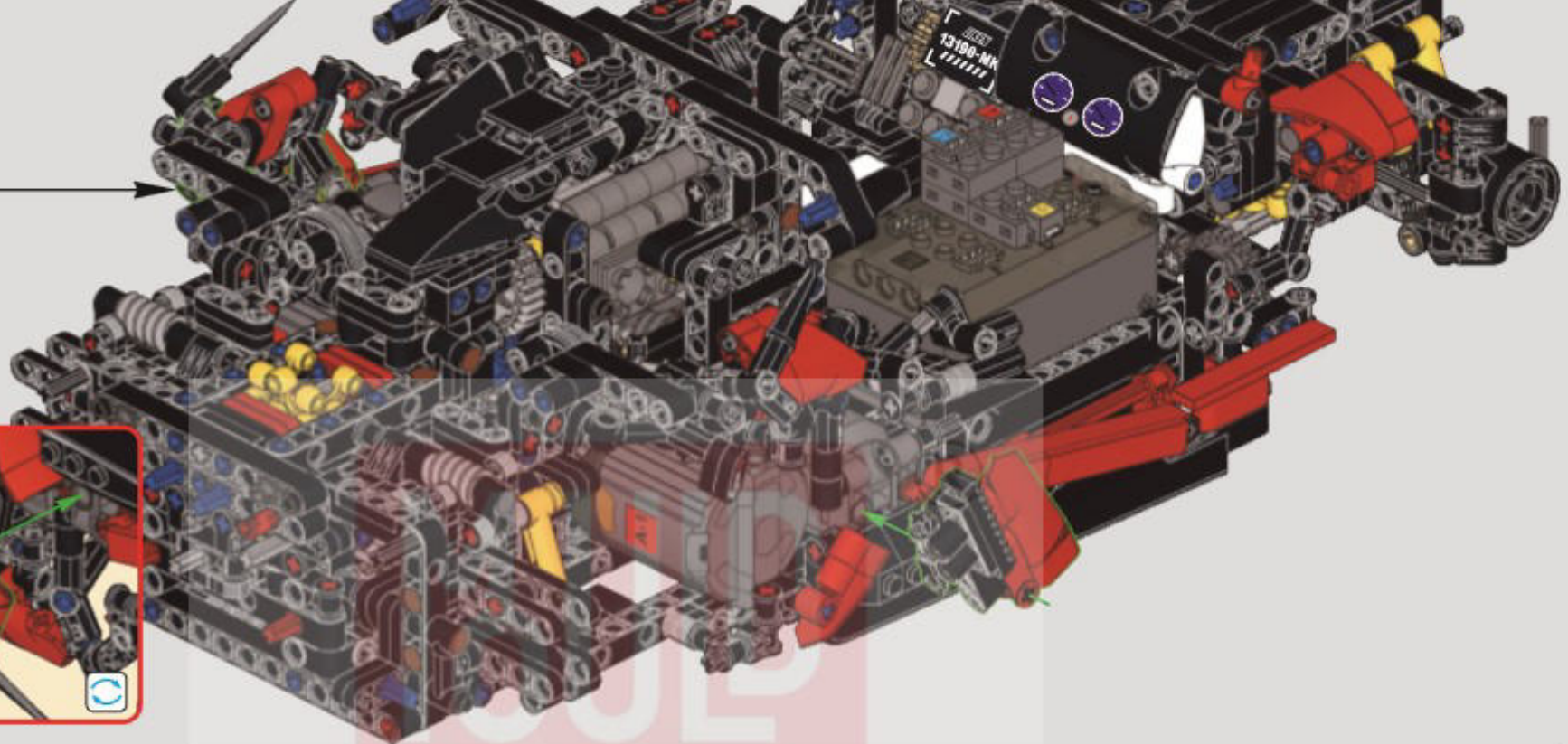
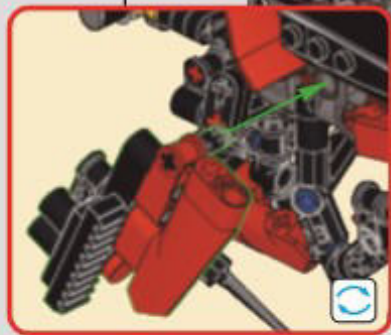
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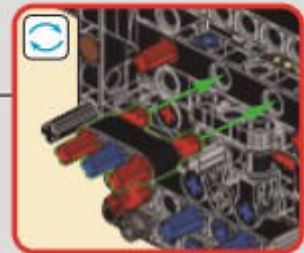
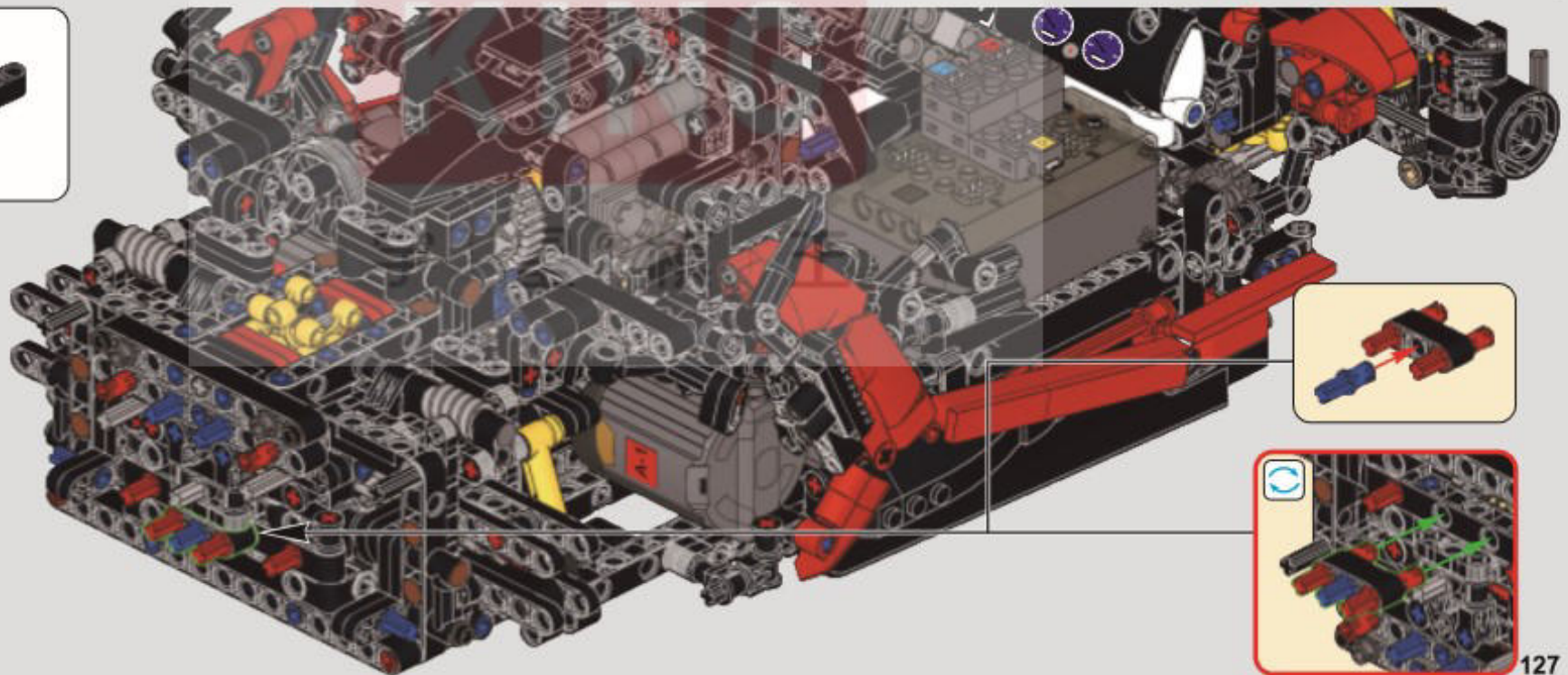
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328

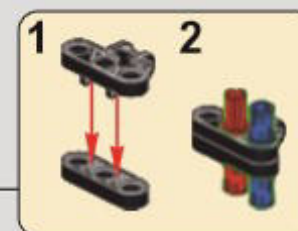
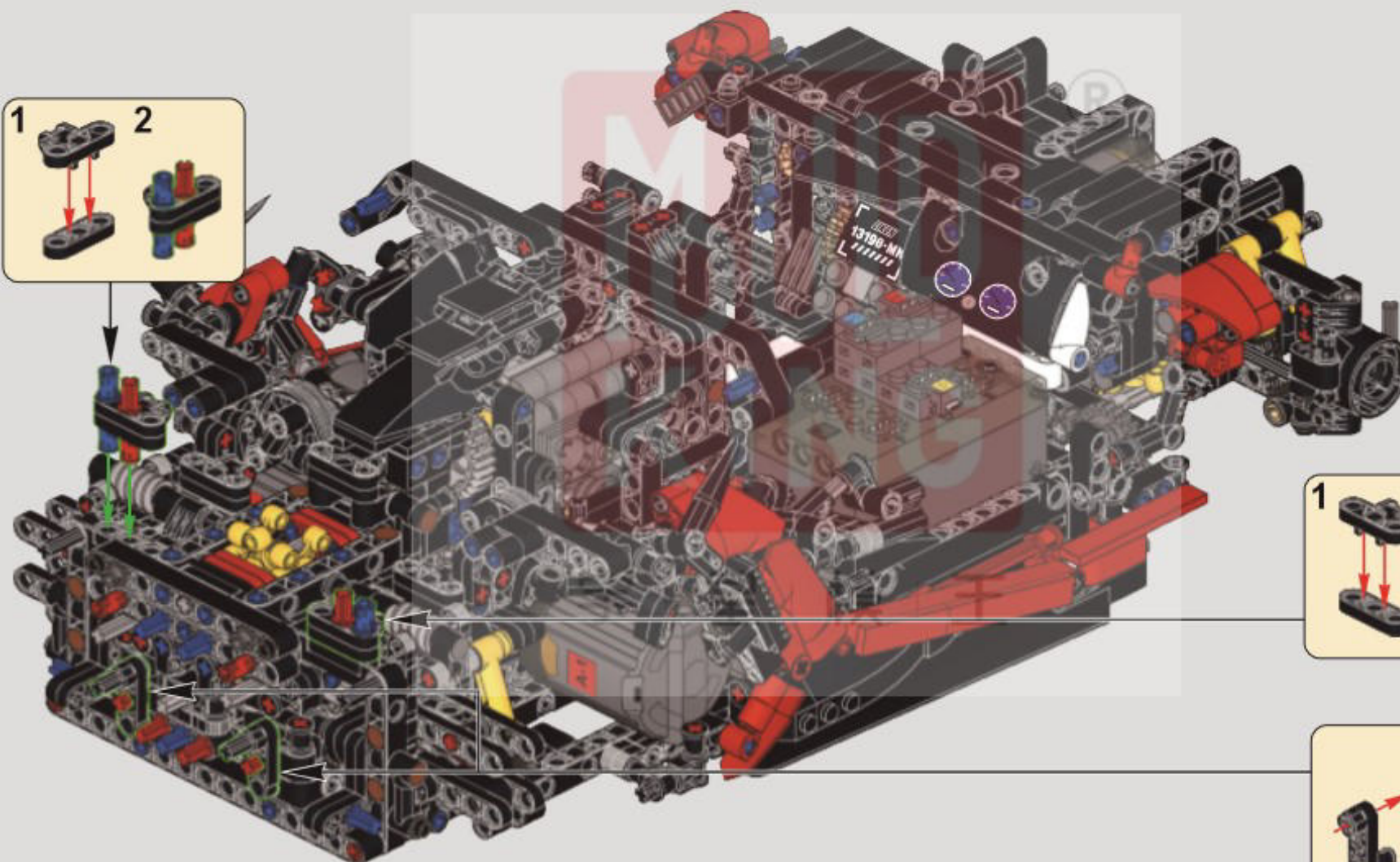
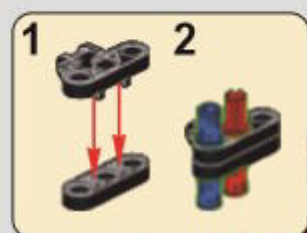


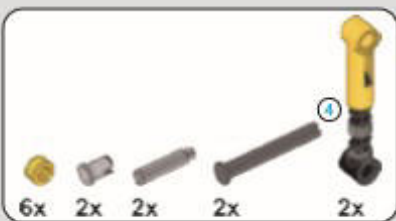
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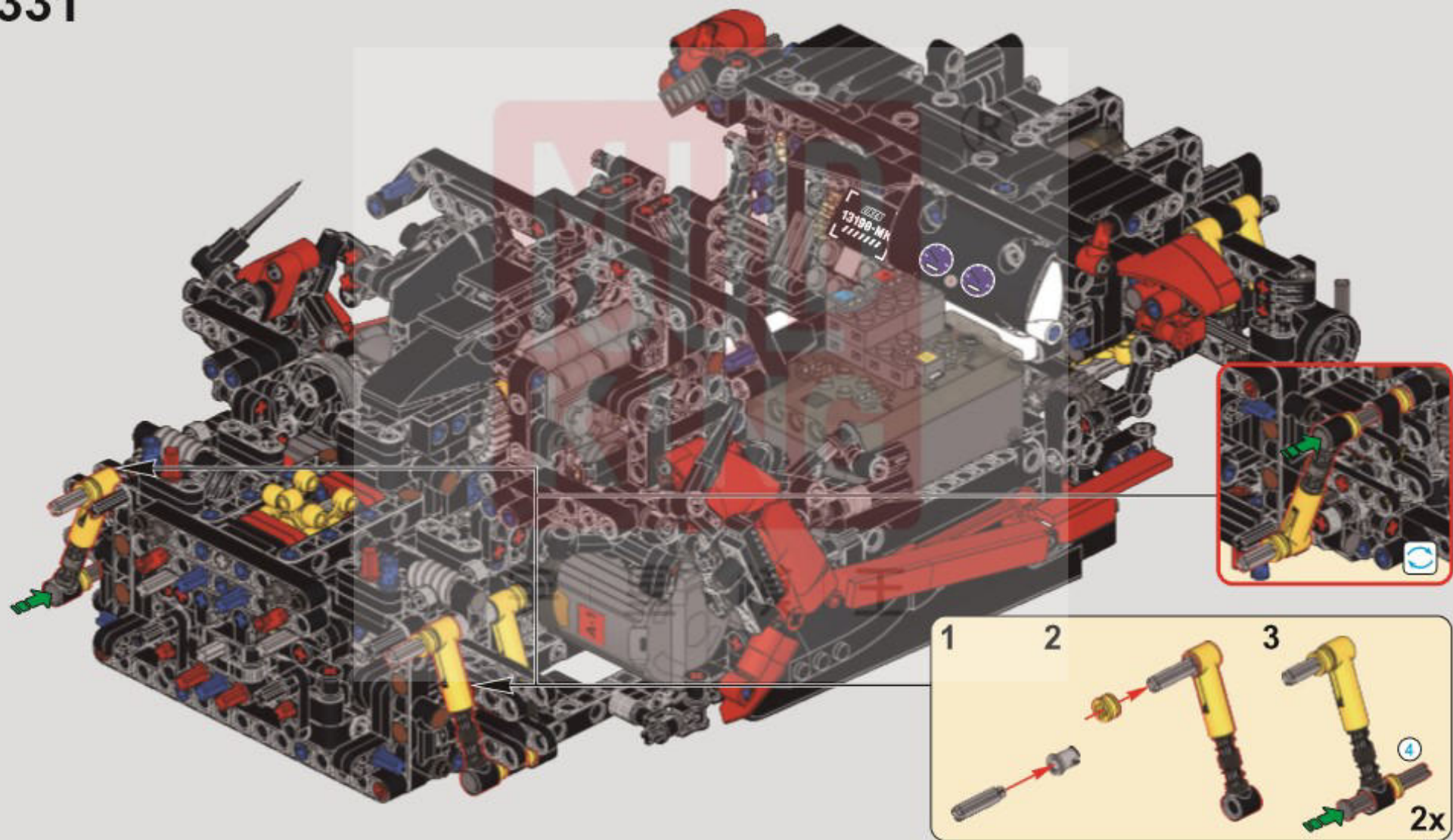
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331

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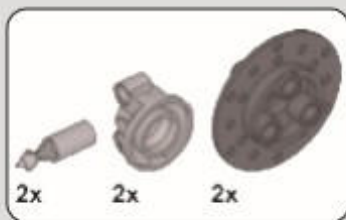
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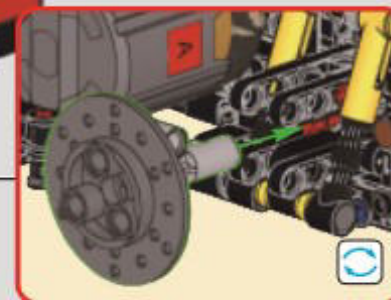
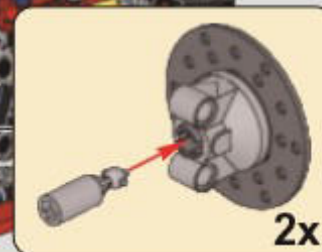
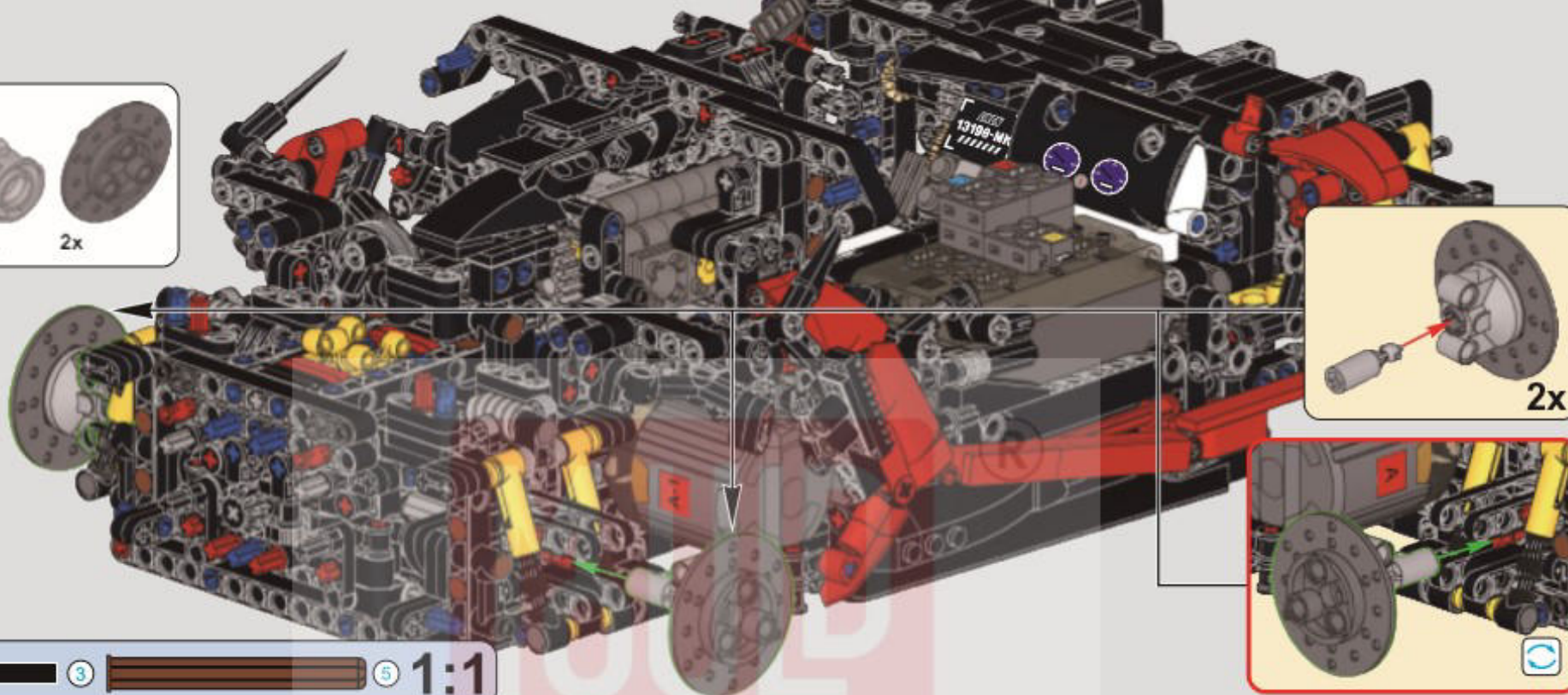
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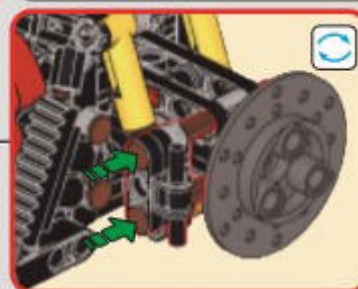
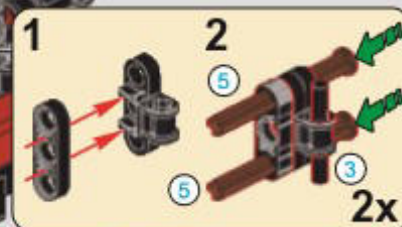
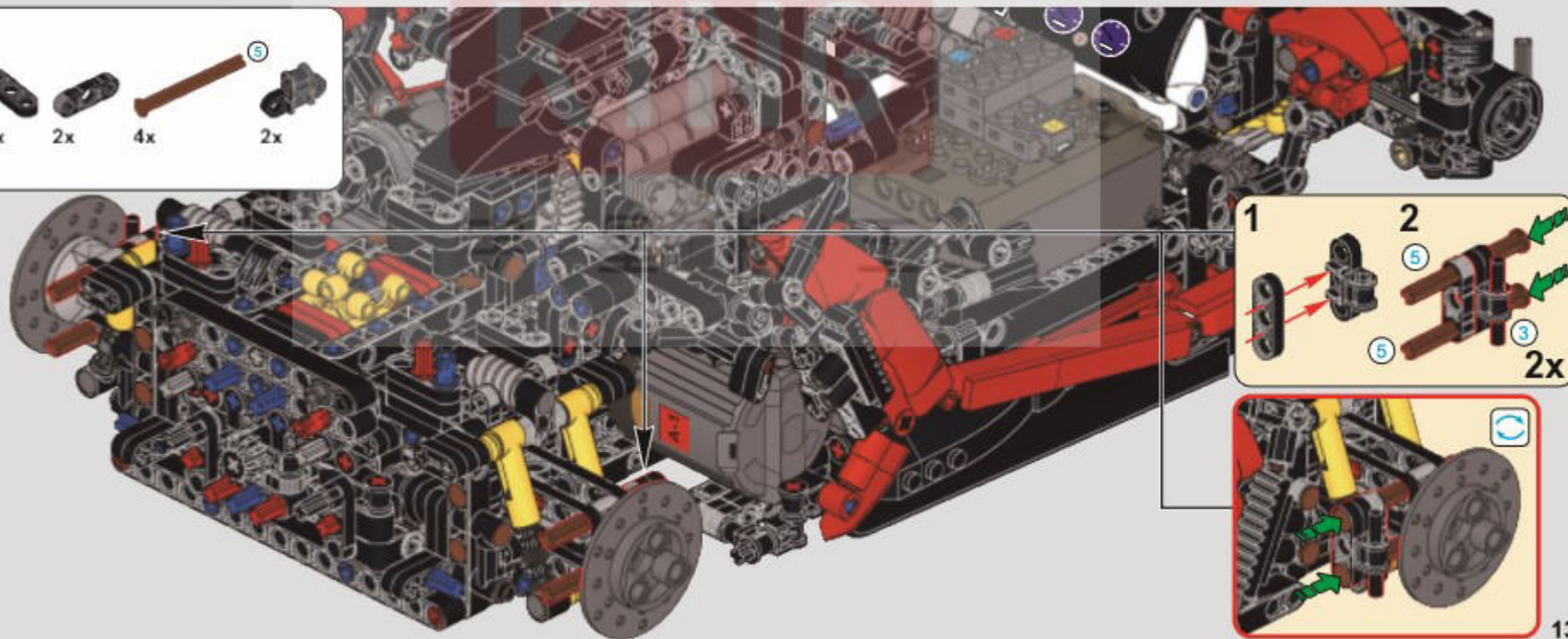
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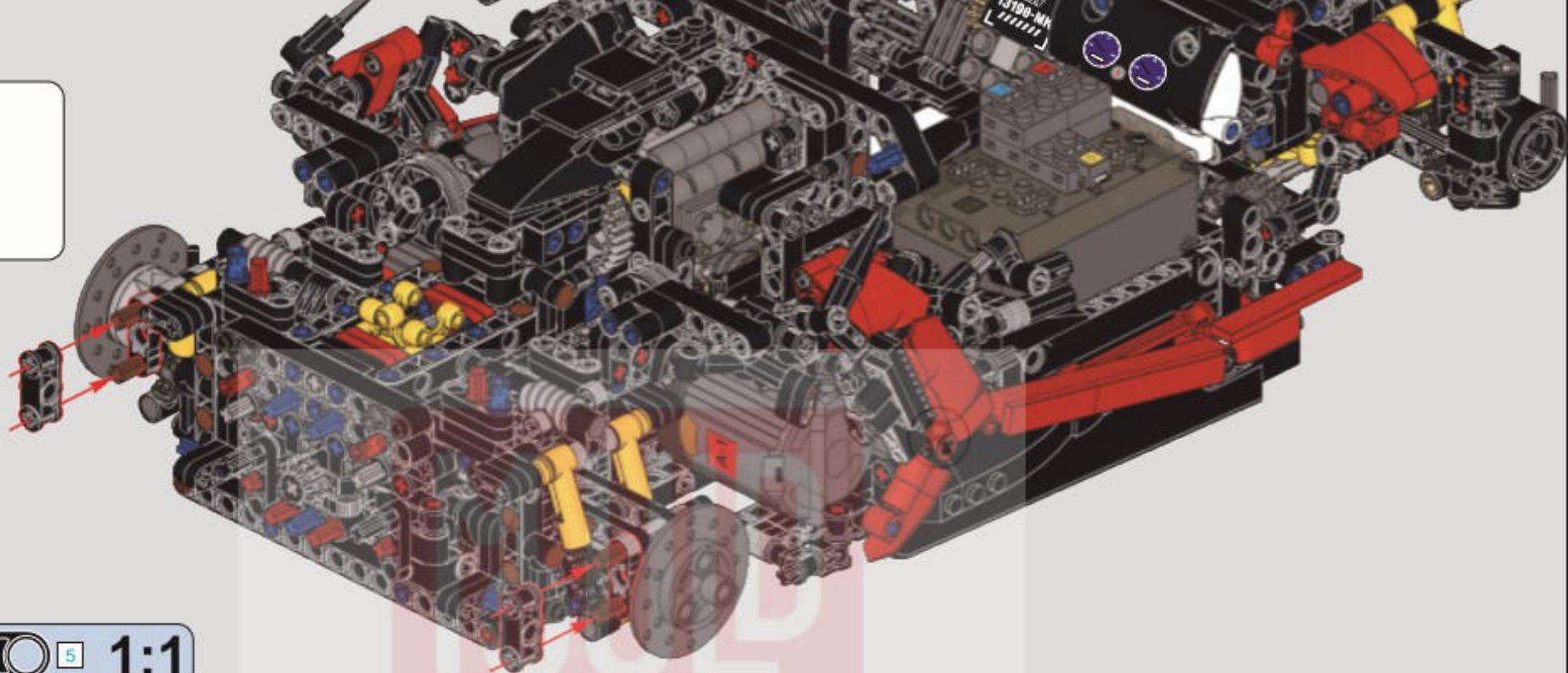


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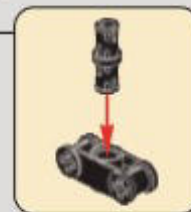
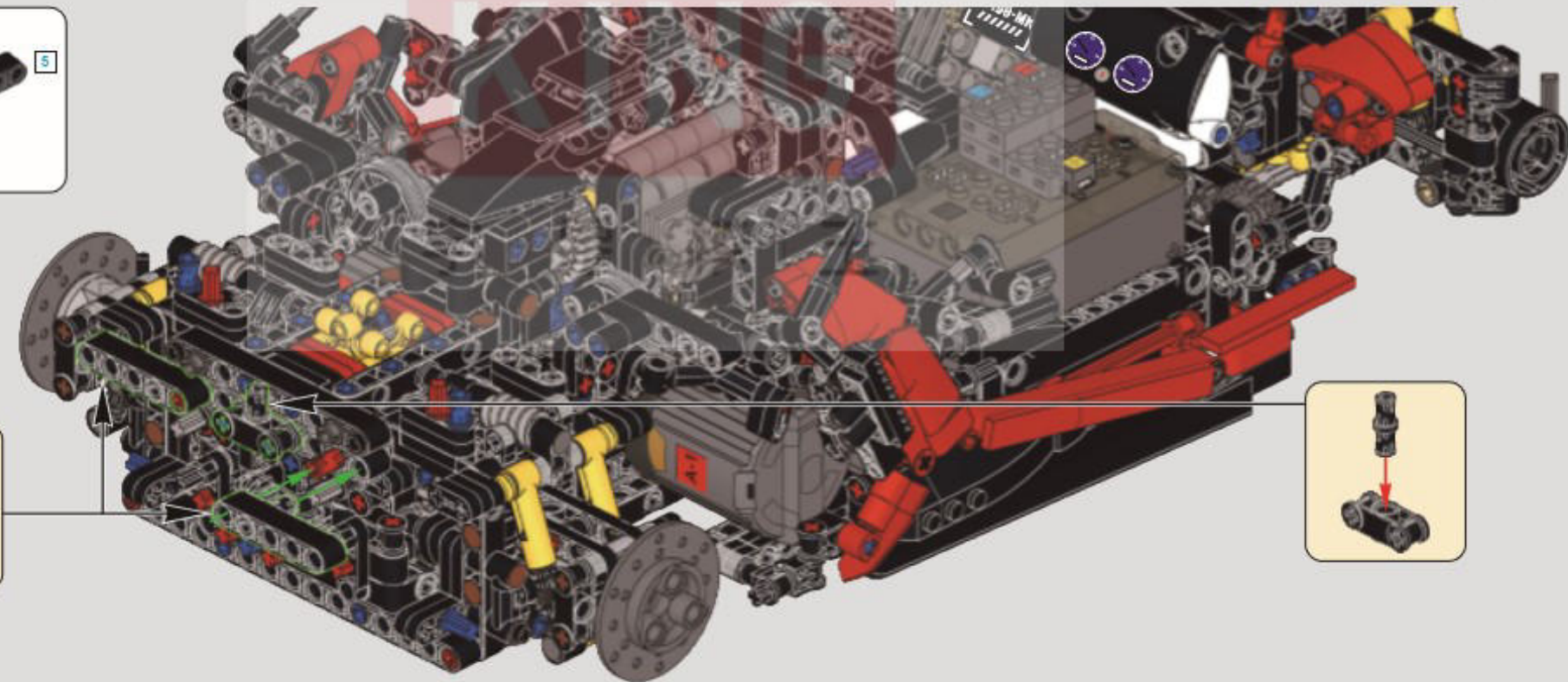




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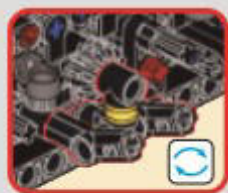


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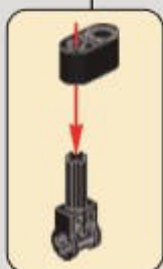




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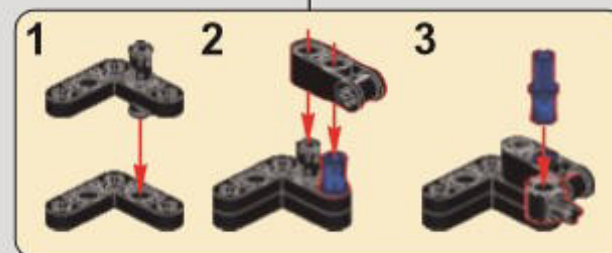
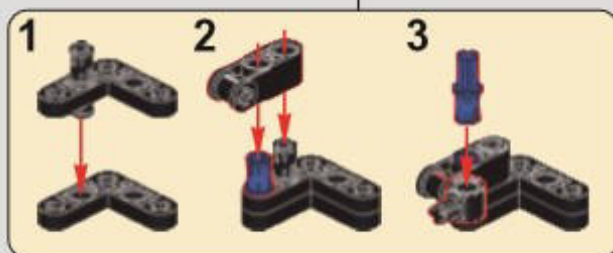
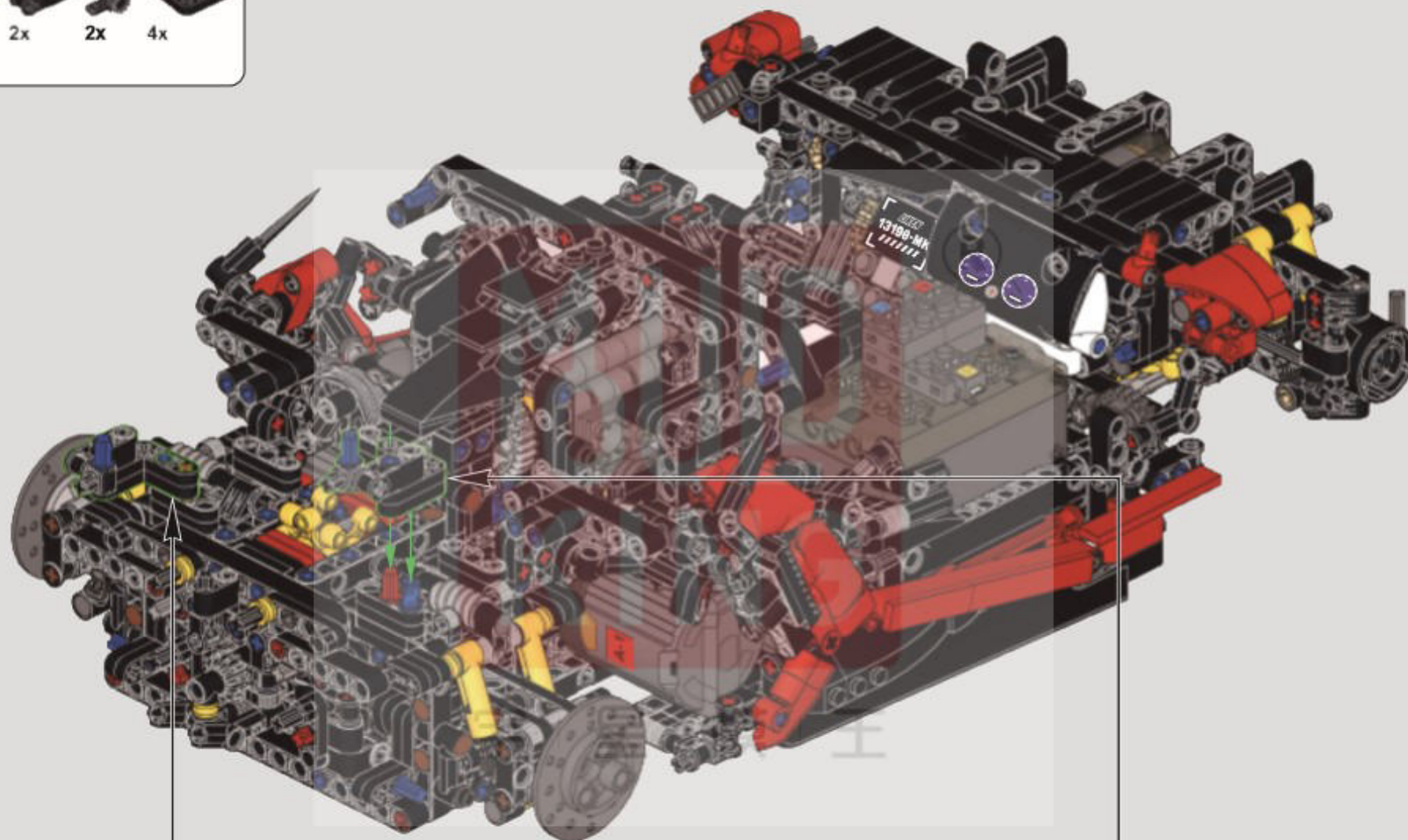


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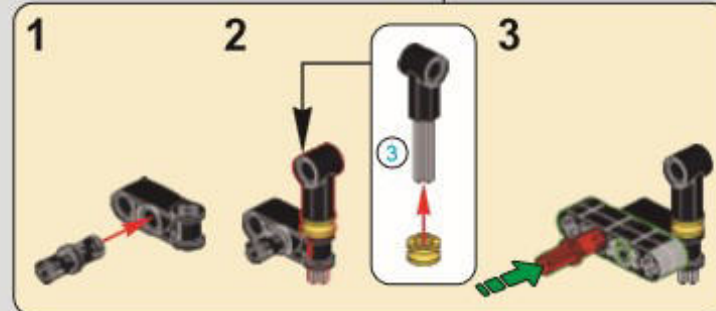
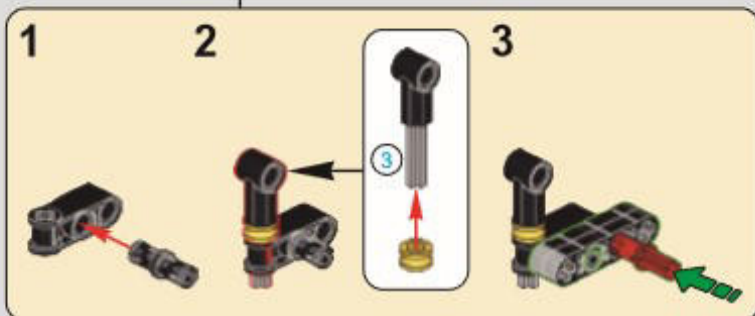
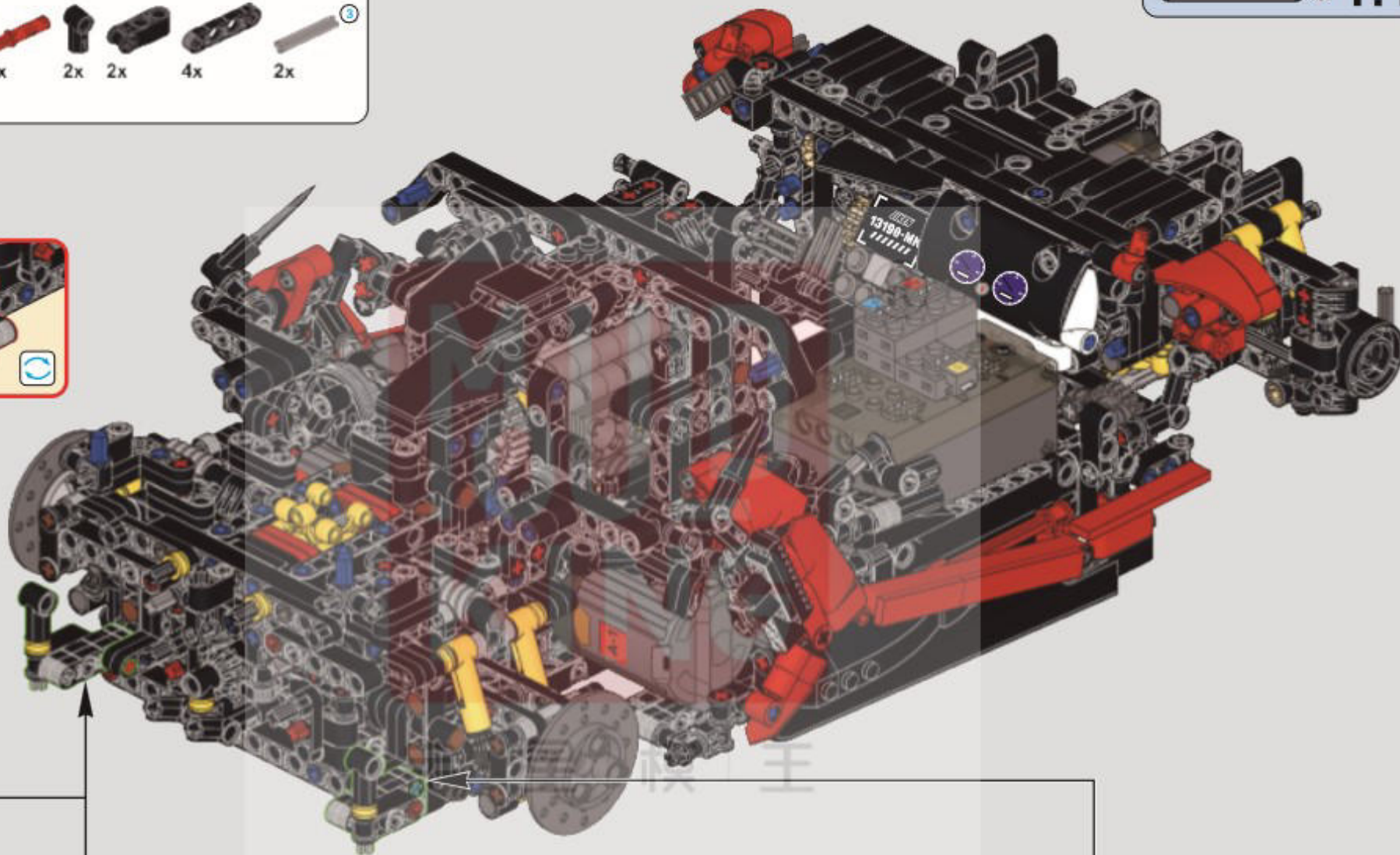
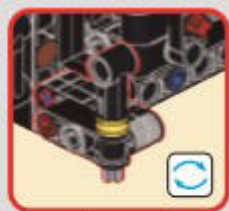


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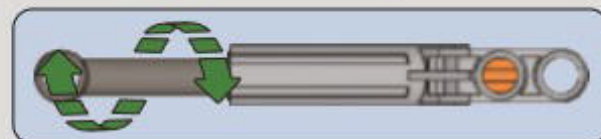
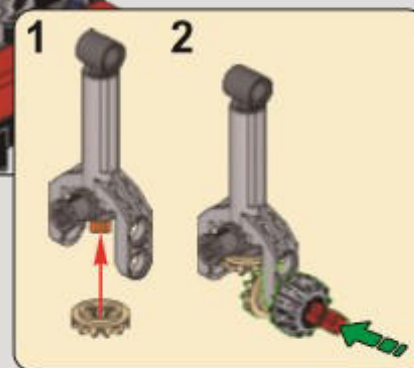
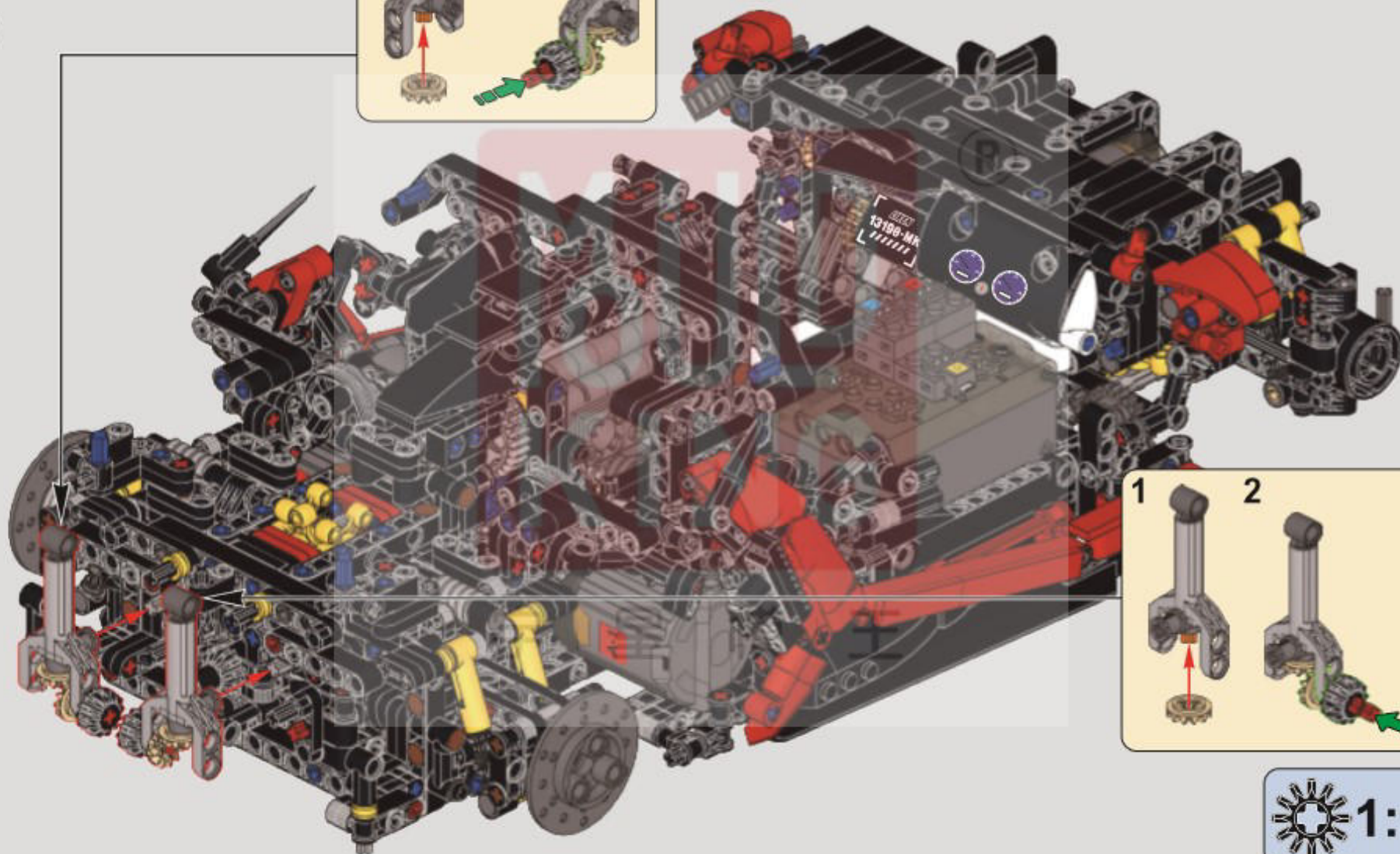
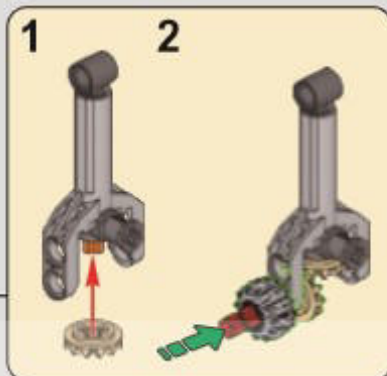


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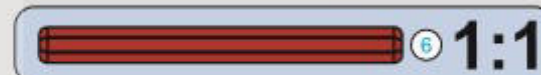
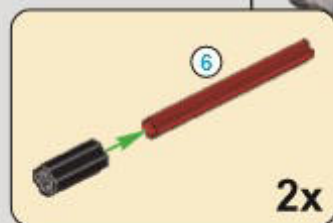


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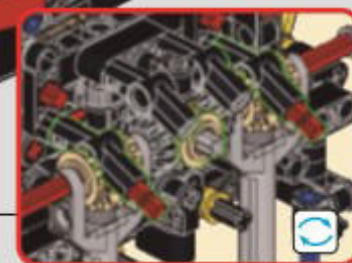


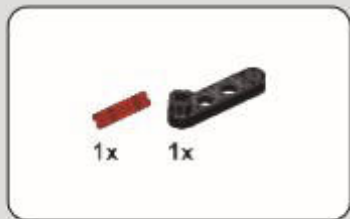


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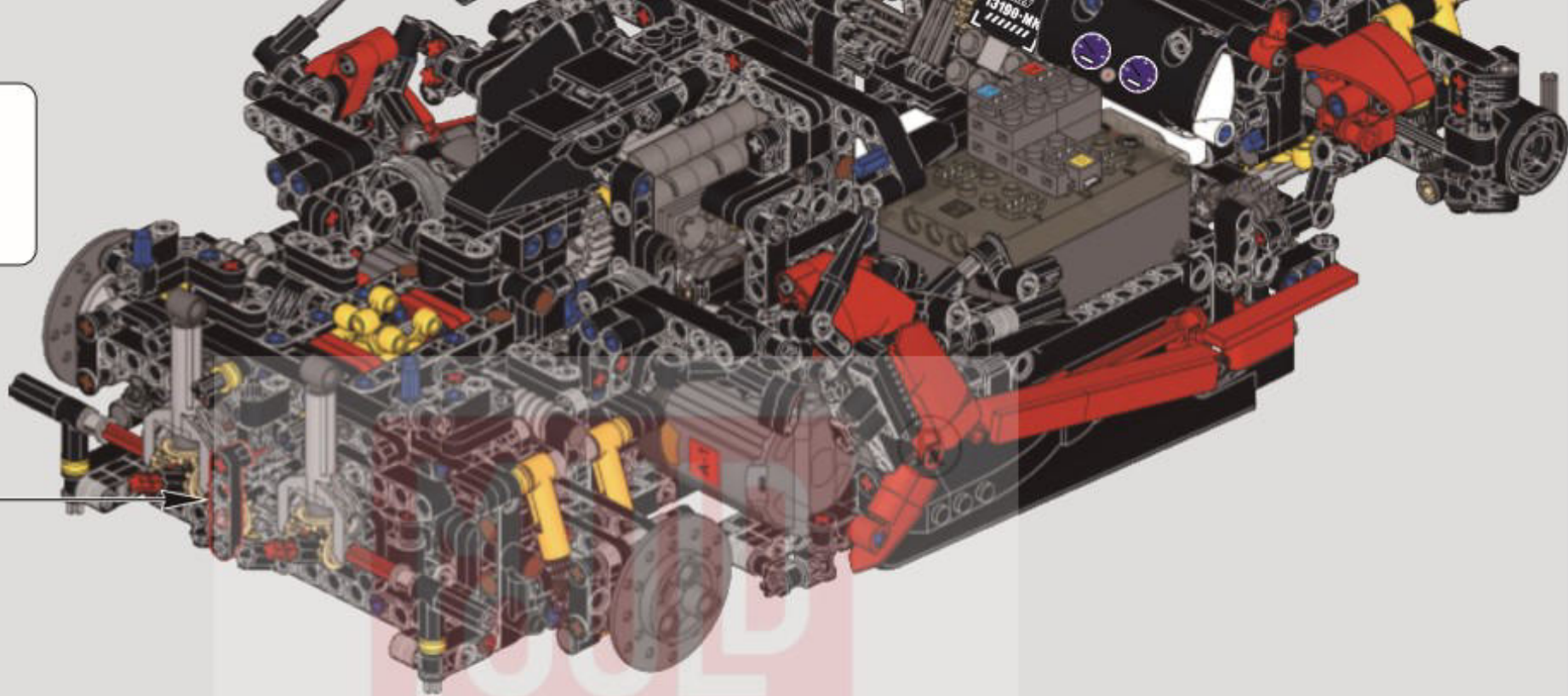


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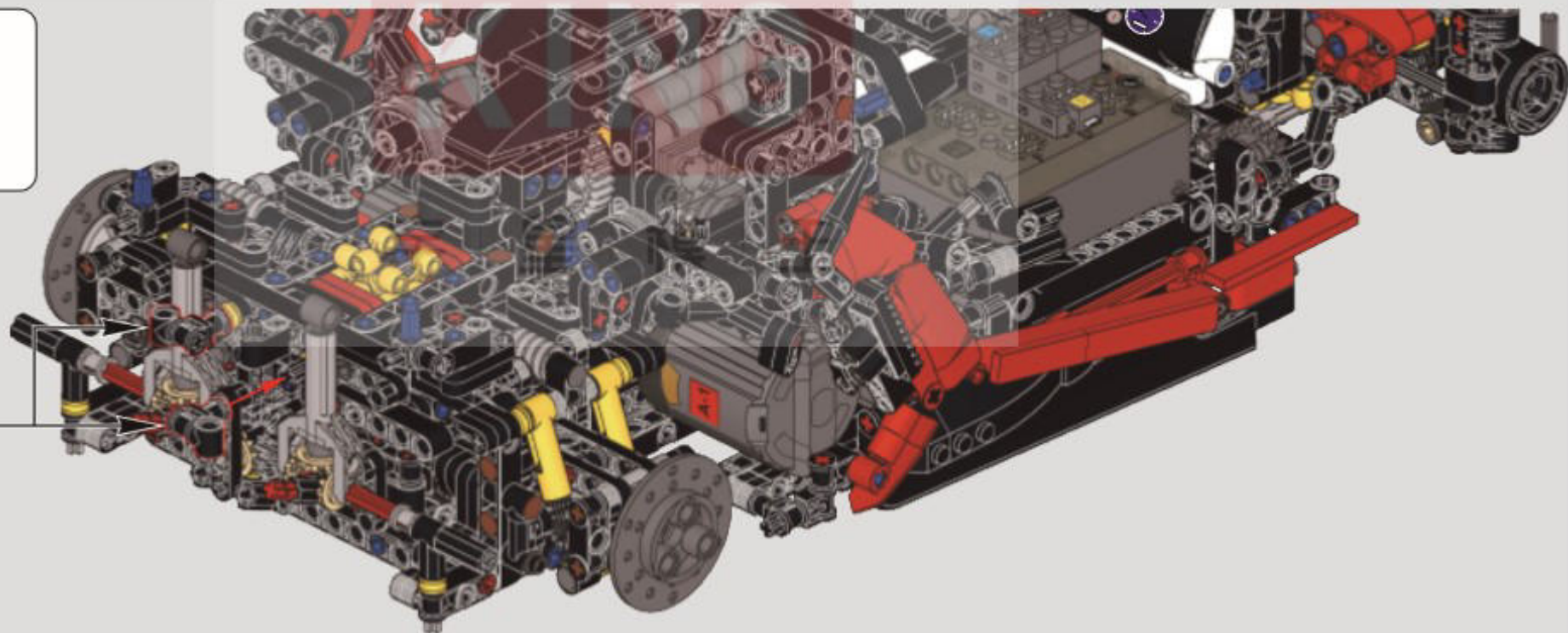




345



346





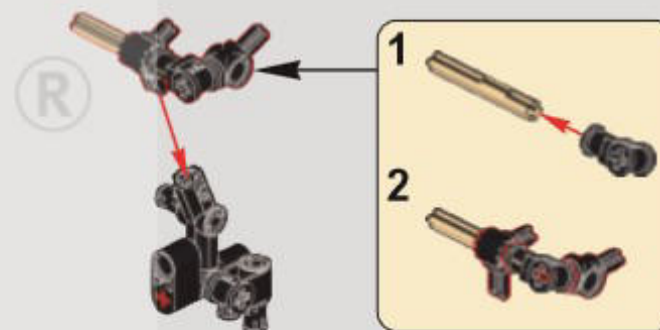
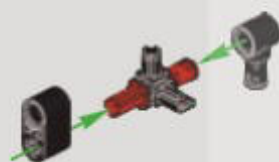
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348



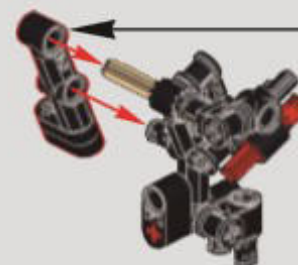
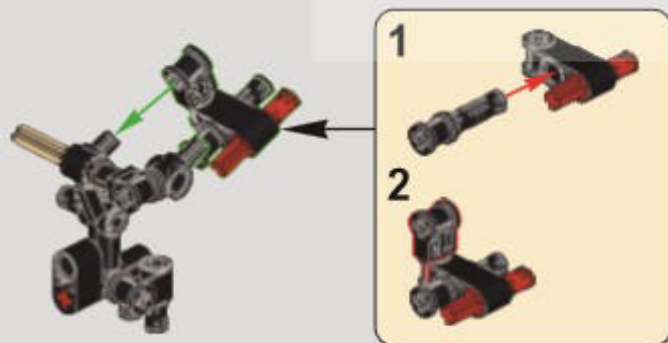
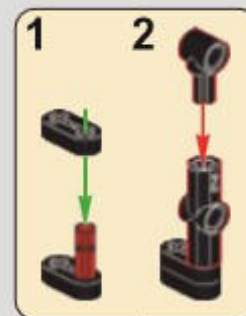
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350



351





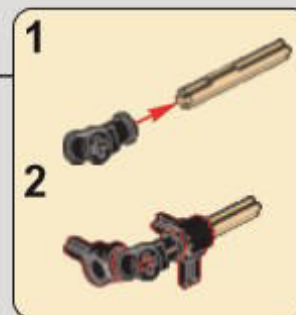
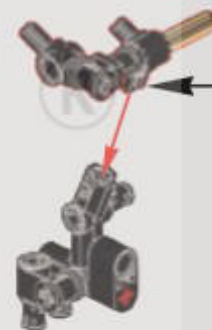
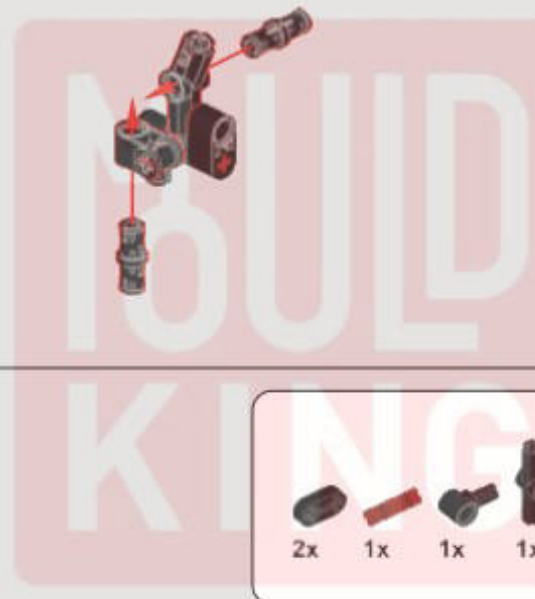
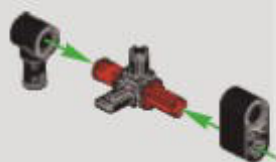
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353



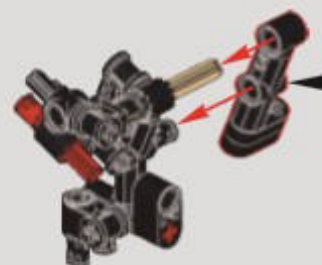
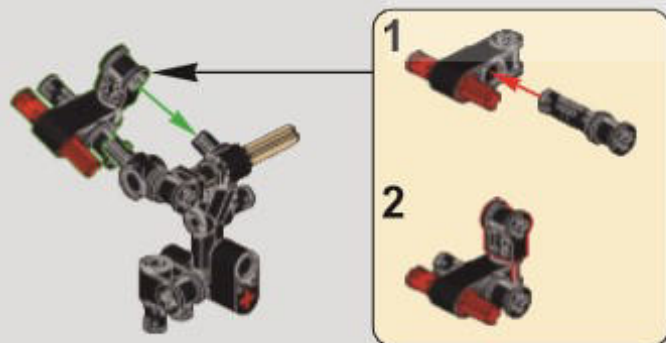
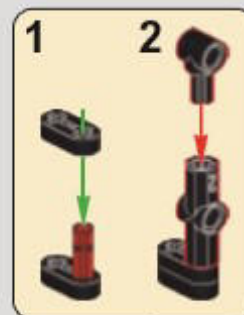
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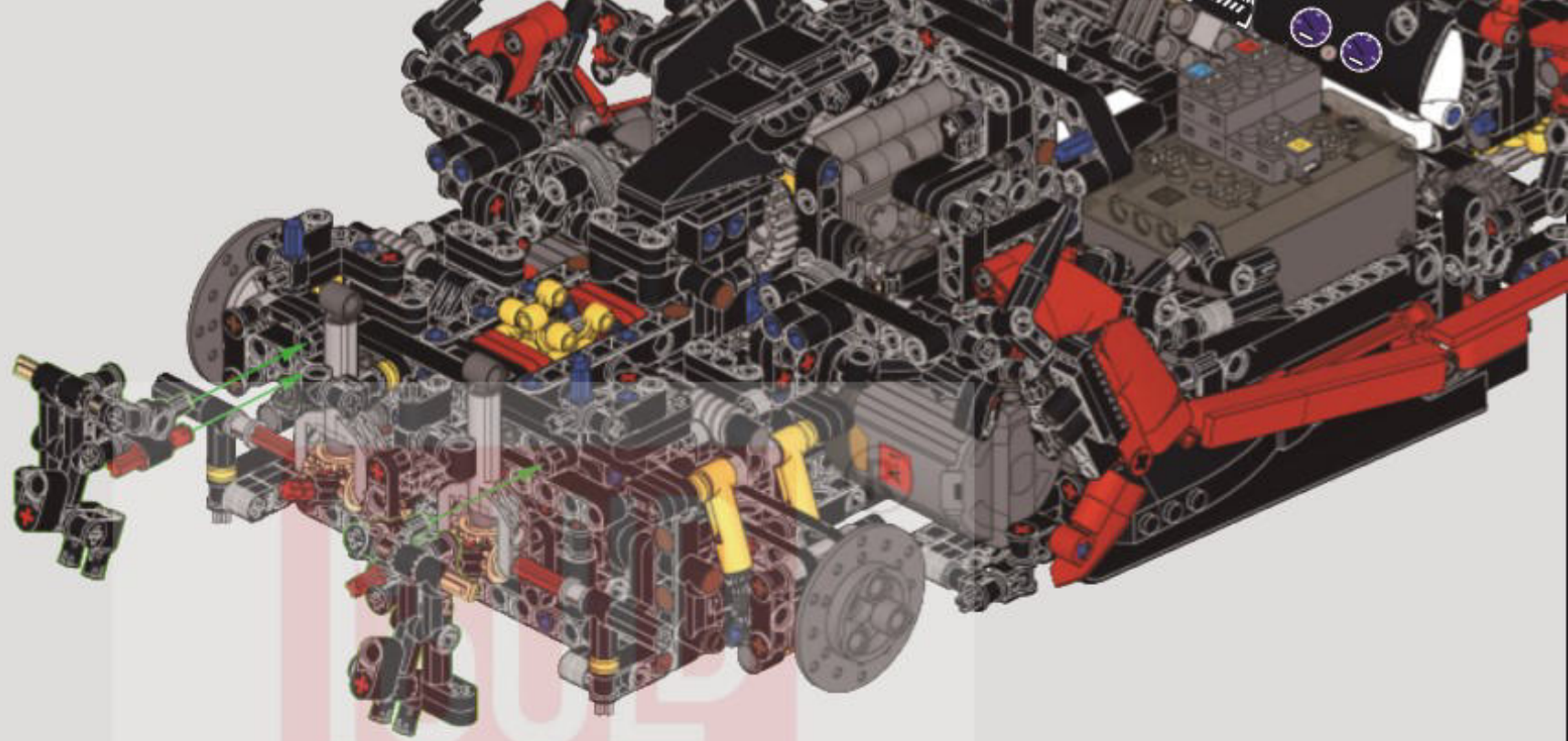
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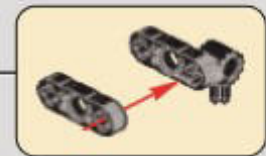
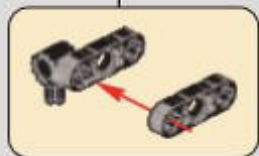
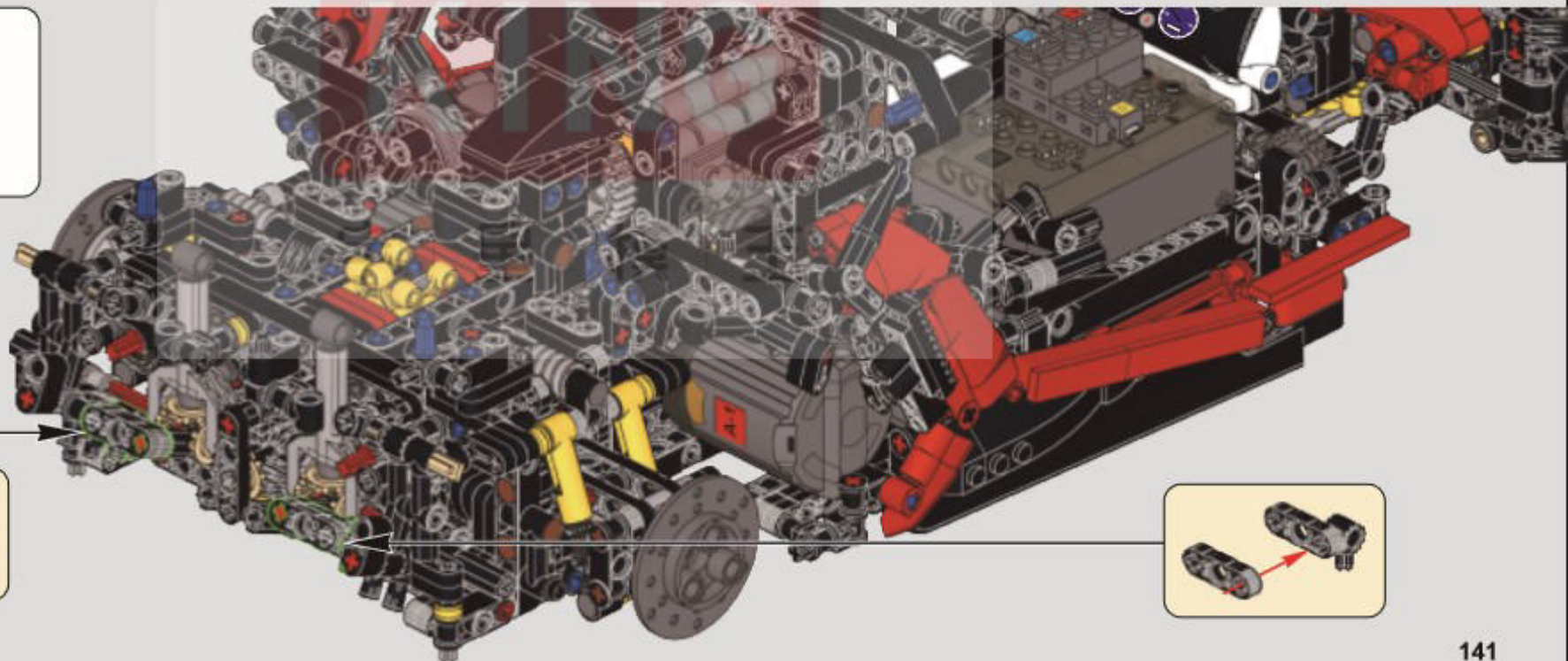
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357

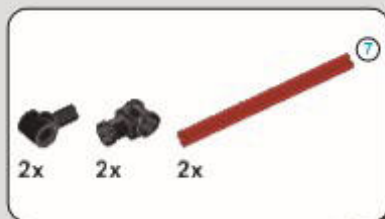
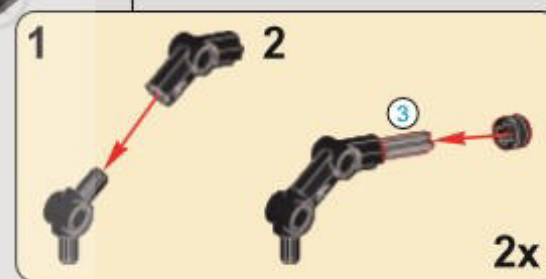
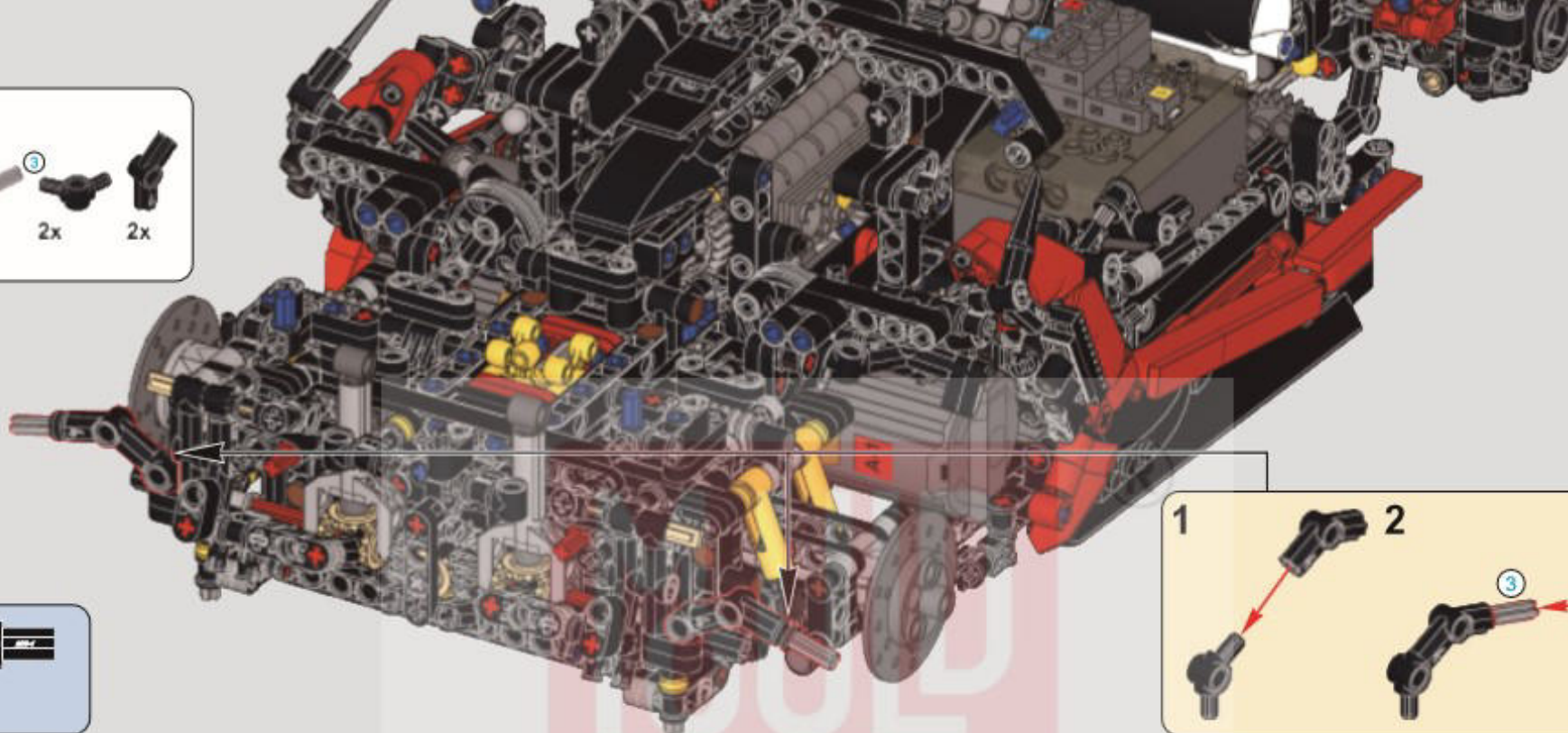


358





359



360

